



## File

## Reactive Plan - plan-1

do the following in serial: 1. move left, 2. wait until a cube shape block is below a gripper that is me, 3. grab, 4. wait until a stop movement command gripper that is me, 5. move right, 6. wait until a pyramid shape block is below a gripper that is me, 7. drop, 8. wait for 8.

Execute

## Reactive Plan - plan-2

do the following in serial: 1. move right, 2. wait until a pyramid shape block is below a gripper that is me, 3. grab, 4. wait until a stop movement command gripper that is me, 5. move left, 6. wait until a cube shape block is below a gripper that is me, 7. drop, 8. wait for 8.

Execute