

# Boyuan Chen

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## EDUCATION

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Massachusetts Institute of Technology (MIT), PhD student in EECS 2021 - Present  
UC Berkeley, BA Computer Science (EECS Honor Class), Applied Math, Class of 2021, GPA 3.96 2017-2021

**Relevant Coursework:** Reinforcement Learning(A+), Deep Unsupervised Learning (A+), Advanced Robotics(A+), Natural Language Processing(A), Machine Learning(A), Computer Vision(A), AI System(A+), Robotics(A+), Algorithms(A), Data Structure(A), Computer Program(A+), Computer Architecture(A), Stochastic Process(A), Real Analysis(A+), Complex Analysis(A+), Probability(A)

## EXPERIENCE

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### Google X (or X, the Moonshot Factory)

*AI resident, machine learning for robotics (with a return offer at Google's L4)* May 2022 - Aug 2022

- Develop machine learning algorithms for sequential decision making in robotics

### MIT Computer Science and Artificial Intelligence Laboratory (CSAIL)

*Researcher* Sep 2021 - present

- Machine learning for robotics advised by Prof. Russ Tedrake and Prof. Vincent Sitzmann

### Berkeley Artificial Intelligence Research Lab

*Researcher* Jan 2019 - Aug 2021

- Computer vision research Prof. Trevor Darrell; Robotics learning research with Prof. Pieter Abbeel,
- Student researcher on unsupervised learning, 3d vision, visual reinforcement learning and generalizable manipulation.

### Robomooc.com, Chongqing Muke Robotics Inc.

*Startup Founder* Nov 2017 - Mar 2020

- Company providing robotics education solution to K12 education
- Lead the software and hardware development of robot kits that we sell to student participants in robotics competitions

### Robomaster at Berkeley (Robotics Team & Club)

*Founder, Captain* Oct 2018 - 2021

- Lead 20-member robotics team building autonomous shooting robots for ICRA RoboMaster AI Challenge
- Designed and implemented novel methods for data collection, object detection and inference acceleration

### Open Source Project Contributor

- Contributor of DL Framework Pytorch, Torchvision; Physics Engine Bullet3; Robotics framework Drake 2018 - 2021

### MIT Chess club

- Executive at MIT Chess Club Team 2021 - present
- Team member of MIT in collegiate chess league

## SKILLSET

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*Language & Tools:* Python, C++/C, Java, Cmake, ROS, NVIDIA Isaac, PyTorch, Tensorflow, OpenVino, TensorRT, ZeroMQ, Qt5, AWS

*Algorithms:* Computer Vision, Machine Learning, Reinforcement Learning, Path Planning, Kinematics, PID, Dynamics Programming

*Hardware:* CAD (Solidworks), Embedded System, ESC, Cable Management, Lathing, Laser Cutting

## PUBLICATION

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**Extraneousness-Aware Imitation Learning** 2021-2022

R. Zheng, K. Hu, [B. Chen](#), H. Xu. In submission to ICRA 2023

**Open-vocabulary Queryable Scene Representations for Real World Planning** 2022

[B. Chen](#), F. Xia, B. Ichter, K. Rao, K. Gopalakrishnan, M. Ryoo, A. Stone, D. Kappler. In submission to ICRA 2023

**Model-free Reinforcement Learning that Transfers Using Random Reward Features** 2021-2022

[B. Chen](#), C. Zhu, P. Agrawal, K. Zhang, A. Gupta. In submission to ICLR 2023

**Unsupervised 3d Keypoint Learning for control** 2020 - 2021

[B. Chen](#), D. Pathak, P. Abbeel. Accepted to ICML 2021.

**Zero-shot Policy Learning with Spatial Temporal Reward Decomposition on Contingency-aware Observation** 2019 - 2020

[B. Chen](#)\*, H. Xu\*, Y. Gao, T. Darrell. Accepted to ICRA 2021

**Discovering Diverse Multi-Agent Strategic Behavior via Reward Randomization** 2019 - 2020

Z. Tang, C. Yu, [B. Chen](#), H. Xu, X Wang, F. Fang, S. Du, Y. Wang, Y. Wu. Accepted to ICLR 2021

## ACADEMIC SERVICE

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Reviewer of CVPR 2023, IROS 2022

*Feb 2021*

Teaching Assistant, MIT 6.4210/6.4212 Robotic Manipulation

*Sep 2022 – Dec 2022*

## PERSONAL ROBOTIC PROJECTS

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Autonomous multi-floor food delivery robot (Control, Planning, Sensing, Vision, ROS)

*Sep 2019 - Dec 2019*

ICRA Robomaster AI Challenge Autonomous Combat Robot (Vision, Planning, ROS, Control, AI)

*Jan 2019 - May 2019*

Personal drivable RC robot (CAD, Manufacture, Electronics, Control, Embedded System)

*May 2019 - Aug 2019*

Autonomous Multi-Terrain Rover (CAD, Manufacture, Electronics, Computer Vision, Planning)

*Oct 2017 - Aug 2018*

Autonomous Tracking Drone (Computer Vision, Embedded System)

*Sep 2016 - Aug 2017*

## HONOR

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Seneff-Zue CS Fellowship

*Feb 2021*

Winner, Facebook Pytorch Summer Hackathon

*Aug 2019*

Finalist, ICRA 2019 Robomaster AI Challenge

*May 2019*

Winner, Record Keeper, UC Berkeley CS 61C Neural Network Inference Optimization Contest

*Aug 2018*

Winner, CS170 Efficient Algorithms Contest

*Oct 2018*

2<sup>nd</sup> place, Google Puzzlehunt, second fastest prize eligible team out of 800+ teams of Google employees

*Jul 2022*

Honor degree in EECS, High honor in general scholarship, Dean's List, UC Berkeley

*2017-2021*