The BUQEYE Cheatsheet for Pointwise Truncation Errors (arXiv:1904.10581)

From observable y, extract coefficients

$$\vec{y}_k \equiv \{y_0, y_1, \cdots, y_k\} \Rightarrow \vec{c}_k \equiv \{c_0, c_1, \cdots, c_k\}$$

Choose ν_0 and τ_0 . Update hyperparameters

$$\nu = \nu_0 + n_c$$
(A7)
$$\nu \tau^2 = \nu_0 \tau_0^2 + \vec{c}_k^2$$
(A8)

Compute posterior

$$\mathsf{pr}(y \,|\, ec{y_k}, Q) \sim t_
u \Bigg[y_k, y_\mathsf{ref}^2 rac{Q^{2(k+1)}}{1 - Q^2} au^2 \Bigg] \, ext{(A13)}$$

```
import numpy as np
y_ref = 20.0; Q = 0.3; k = 3
y_k = [21.7, 27.3, 25.4, 26.2]
c_k = np.array([y_k[0] / y_ref] + [
    (y_k[n] - y_k[n-1]) / (y_ref * Q**n)
    for n in range(1, k+1)])
nu_0 = 1; tau_0 = 1 # ~Uninformative
nu = nu_0 + len(c_k)
tau_sq = \
```

```
from scipy.stats import t
scale = y_ref * Q**(k+1) * \
  ( tau_sq / (1 - Q**2) )**0.5
y = t(nu, y_k[-1], scale)
dob = y.interval(0.95) # (25.7, 26.7)
```

 $(nu_0 * tau_0 **2 + c_k @ c_k) / nu$