

# BURAK AKSOY - DRAFT

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Web: TODO

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PRINCIPAL  
INTERESTS

TODO

EDUCATION

**Rensselaer Polytechnic Institute**, Troy, NY  
Ph.D. in Computer Systems Engineering, Advisor: John T. Wen

*August 2018 - Present*  
GPA: 3.69/4.0

**Sabanci University**, Istanbul, Turkey  
B.Sc. in Computer Science and Engineering

*September 2016 - June 2018*  
GPA: 3.90/4.0

**Sabanci University**, Istanbul, Turkey  
B.Sc. in Mechatronics Engineering

*September 2013 - June 2018*  
GPA: 3.90/4.0

RESEARCH  
PROJECTS

**Safe Robotic Handling of Energetic Materials**  
*Graduate Research Assistant, PIs: John T. Wen, Glenn Saunders*  
TODO.

*Troy, NY*  
December 2021 - Present

**Swarm Robotics for Large Structure Manufacturing**  
*Graduate Research Assistant, PIs: John T. Wen, Glenn Saunders*  
TODO.

*Troy, NY*  
May - August 2021

**Open Source Teach Pendant Programming Environment**  
*Graduate Research Assistant, PI: John T. Wen*  
TODO.

*Troy, NY*  
December 2019 - May 2021

**Robot Assistance with Activities of Daily Living for Persons with C4-C7 Spinal Cord Injury**  
*Graduate Research Assistant, PI: John T. Wen*  
TODO.

*Troy, NY*  
May - October 2019

**Vision Based Obstacle Detection and Avoidance for Autonomous Vehicles**  
*Graduation Project, Supervisor: Mustafa Unel*

*Istanbul, Turkey*  
September 2017 - June 2018

TODO. In this project, it is aimed to design a 360-degree obstacle detection and avoidance system using the data obtained from cameras located on autonomous heavy vehicles such as trailer trucks, straight-body trucks and lorries. To use as few number of cameras as possible, in addition to perspective cameras large field of view fish eye cameras are also utilized. State of the art object detection and classification algorithms are used to detect the obstacles around the vehicle using captured images and classify the objects in real time. To quantify detection and classification performance in realistic scenarios, algorithms are implemented in Truck Maker Simulation environment

**CAESAR: Cellularly-Accessible, Expressive, Semi-Autonomous Robot**  
*Summer Research Intern, Supervisor: Vikram Kapila*

*New York, NY*  
June - August 2017

TODO. Researcher on Cellular-Accessible, Expressive, Semi-Autonomous Robot (CAESAR), a social mobile humanoid robot that interacts with users through non-verbal, emotional expressions, and has 30-DOFs which include it's mobile base.

ROBOTICS  
HARDWARE  
EXPERIENCE

**Fixed Base Robots**

- Sawyer, 7 DoF (*Rethink Robotics*),
- JACO Gen2, 6 DoF Curved Wrist (*Kinova Robotics*),
- UR5e, 6 DoF (*Universal Robotics*),
- IRB 1200, 6 DoF (*ABB*)

#### Mobile Robots

- Husky, Skid-steered *TODO* (*Clearpath Robotics*),
- Ridgeback, Omnidirectional (*Clearpath Robotics*),
- TurtleBot3 Waffle, *TODO* (*Robotis*).
- Duckiebot DB17, DB18, *TODO* (*Duckietown Foundation*),
- OARbot, Omnidirectional (*RPI custom made*),

#### SOFTWARE SKILLS

##### Robotics Middleware

- ROS, *Advanced*,
- [RobotRaconteur](#), *Advanced*

##### Languages *TODO* Python

#### AWARDS & HONORS

**Ranked 1st in Mechatronics Engineering 2018 Class**  
*awarded by Sabanci University*

*June 2018*

**Dean's High Honor Certificate**  
*awarded by Sabanci University*

*2014 - 2018*

**Full Tuition Waiver and Stipend**  
*awarded by Sabanci University*

*2013 - 2018*

**Turkish National University Entrance Exam**  
*Ranked 917th amongst 1.9 million candidates*

*June 2013*

**Finalist at International Physics Olympiad National Team Selection**  
*by TUBITAK (The Scientific and Technological Research Council of Turkey)*

*May 2013*

**Finalist at High School Students Research Projects Competition, Physics**  
*by TUBITAK (The Scientific and Technological Research Council of Turkey)*

*May 2013*

**Finalist at High School Students Energy Efficiency Projects Competition**  
*by Turkey Ministry of Energy*

*May 2012*

#### TEACHING EXPERIENCE

**Teaching Assistant, Rensselaer Polytechnic Institute**  
*ECSE 6470: Robotics I*

*Troy, NY  
Fall 2021*

**Teaching Assistant, Rensselaer Polytechnic Institute**  
*ECSE 6470: Robotics I*

*Troy, NY  
Fall 2019*

**Teaching Assistant, Rensselaer Polytechnic Institute**  
*ENGR 2350: Embedded Control*

*Troy, NY  
Spring 2019*

**Teaching Assistant, Rensselaer Polytechnic Institute**  
*ECSE 2010: Electric Circuits*

*Troy, NY  
Spring 2019*

**Teaching Assistant, Rensselaer Polytechnic Institute**  
*ENGR 2350: Embedded Control*

*Troy, NY  
Fall 2018*

**Learning Assistant, Sabanci University**  
*MATH 101: Calculus I*

*Istanbul, Turkey  
Fall 2016*