### Random Forest for Classification Problems

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# Overview

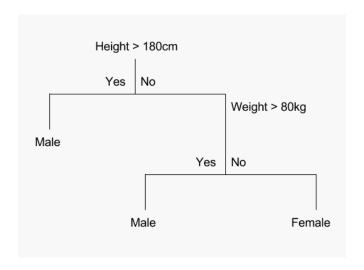
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#### Intro

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# Decision Tree: Example



# Decision Tree: Tree Building Process

A tree is grown starting from the root node by repeatedly using the following steps on each node (also called binary splitting):

- (i) Find best split s for each feature  $X_m$ : For each feature  $X_m$ , there exist K-1-many potiential splits whereas K is the number of different values for the respective feature. Evaluate each value  $X_{m,i}$  at the current node t as a candidate split point (for  $x \in X_m$ , if  $x \leq X_{m,i} = s$ , then x goes to left child node  $t_L$  else to right child node  $t_R$ ). The best split point is the one that maximize the splitting criterion  $\Delta i(s,t)$  the most when the node is split according to it. The different splitting criteria will be covered in the next chapter.
- (ii) Find the node's best split: Among the best splits for each feature from Step (i) find the one  $s^*$ , which maximizes the splitting criterion  $\Delta i(s,t)$ .
- (iii) **Satisfy stopping criterion:** Split the node t using best node split  $s^*$ from Step (ii) and repeat from Step (i) until stopping criterion is satisfied.

# Decision Tree: Purity Measures

#### Gini Measure

$$i(t) = \sum_{c \in C} p(c|t)(1 - p(c|t)) = 1 - \sum_{c \in C} p_c^2$$
 (1)

### Information Entropy

$$i(t) = \sum_{c \in C} p(c|t)log(p(c|t))$$
 (2)

#### Bias Variance

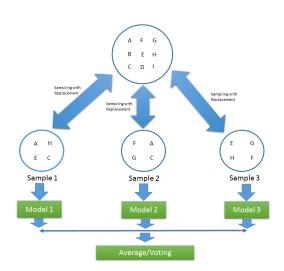
#### Heading

- Statement
- 2 Explanation
- Second Example
  Second Example

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# Bagging

- created for methods with high variance
- reduces variance and gives better predictions
- improvement of bagging: Random Forest



#### Random Forest

An ensemble of randomly trained decision trees, so in other words random forest was defined by L. Breiman:

#### Theorem

A random forest is a classifier consisting of a collection of tree-structured classifiers  $\hat{T}_{\theta_b}(\mathbf{x}), b=1,...,B$  where the  $\theta_b$  are independent identically distributed random vectors and each tree casts a unit vote for the most popular class at input  $\mathbf{x}$ .

Random Forest is an extension and improvement over bagging:

- Like in bagging, multiple decision trees are built
- Improvement: an injection of randomness is made

#### Random Forest: randomness in the model

Two key concepts that makes decision forest "random" are:

- Random sampling of training data points when building trees
- Random subsets of features considered when splitting nodes. Recommended number of variables:
  - **1** For classification:  $\lfloor \sqrt{n} \rfloor$
  - **b** For regression:  $\lfloor \frac{n}{3} \rfloor$

# Random Forest: algorithm

#### Algorithm 1: Random Forest for Regression or Classification

- For b = 1 to B:
  - **1** Draw a bootstrap sample  $\theta_b$  of size N from the training data.
  - **6** Grow the Random Forest tree  $T_{\theta_b}$  to the bootstrapped data, by recursively repeating the following steps for each terminal node of the tree, until the minimum node size  $n_{min}$  is reached:
    - $\bullet$  Select m variables at random from the n variables
    - Open Pick the best variable/split-point among the m
    - Split the node into two daughter nodes
- **②** Output the ensemble of trees  $\{T_{\theta_b}\}_1^B$

### Bias Variance

## Example (Theorem Slide Code)

```
\begin{frame}
\frametitle{Theorem}
\begin{theorem}[Mass--energy equivalence]
$E = mc^2$
\end{theorem}
\end{frame}
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# Simulation Study: Linear DGP

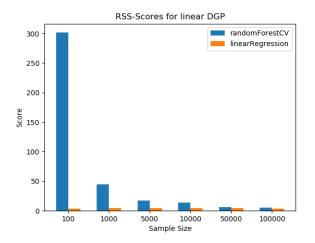
The linear DGP generates the data tuples  $(y, x_1, x_2, x_3)$  as follows:

$$y = \beta_0 + \beta_1 x_1 + \beta_2 x_2 + \beta_3 x_3 + \epsilon, \tag{3}$$

whereas  $(\beta_0, \beta_1, \beta_2, \beta_3) = (0.3, 5, 10, 15)$ ,  $x_1, x_2, x_3 \sim \mathcal{N}(0, 3)$ , and  $\epsilon \sim \mathcal{N}(0, 1)$ .



#### Decision Tree: Linear DGP Results



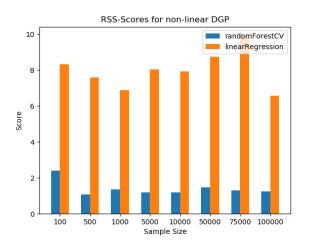
# Simulation Study: Non-Linear DGP

The non-linear DGP generates the data tuples  $(y, x_1, x_2)$  as follows:

$$y = \beta_0 + \beta_1 \mathbb{1}(x_1 \ge 0, x_2 \ge 0) + \beta_2 \mathbb{1}(x_1 \ge 0, x_2 < 0) + \beta_3 \mathbb{1}(x_1 < 0) + \epsilon,$$
 (4)

whereas  $(\beta_0, \beta_1, \beta_2, \beta_3)$ ,  $x_1, x_2$  and  $\epsilon$  are the same as in the previous DGP.

# Simulation Study: Non-Linear DGP Results



#### Real Data

An example of the \cite command to cite within the presentation:

This statement requires citation [breiman1984classification].

### Conclusion

# The End

## References