Random Forest for Classification Problems

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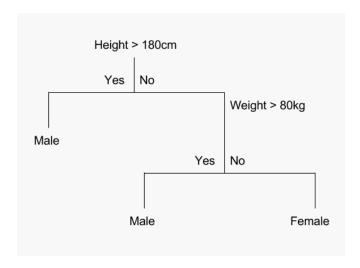
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Overview

- Tree to Random Forest
 - Decision Tree
 - Bias Variance Trade-off
 - Bagging
 - Random Forest
- 2 Mathematical Concept
- Simulation Study
- 4 Real Data

Decision Tree

Example



Decision Tree: Tree Building Process

A tree is grown starting from the root node by repeatedly using the following steps on each node (also called binary splitting):

- (i) Find best split s for each feature X_m
- (ii) Find the best splitof the node
- (iii) Repeat until stopping criterion got satisfied

Decision Tree

Purity Measures

Gini Measure

$$i(t) = \sum_{c \in C} p(c|t)(1 - p(c|t))$$

Information Entropy

$$i(t) = \sum_{c \in C} p(c|t)log(p(c|t))$$

where C is the set of classes c and t a node of the tree.

Bias Variance Trade-off

The Expected Generalization Error

$$y = f(x) + \epsilon$$
 and $\epsilon \sim \mathcal{N}(0, \sigma_{\epsilon}^2)$
Estimate of $f(x)$: $\hat{f}(x)$

The expected generalization error: $\mathbf{Err}(\hat{f}(x))$

The decomposition of a model's expected generalization error is

$$Err(\hat{f}(x)) = \sigma_{\epsilon}^2 + [Bias(\hat{f}(x))]^2 + Var(\hat{f}(x))$$

 σ_ϵ^2 is irreducible and independent of the model.

Trade-off between bias and variance.

Aim: Decrease variance while keeping bias unincreased.



Bias Variance Trade-off

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Bias-Variance Trade-off

Illustration

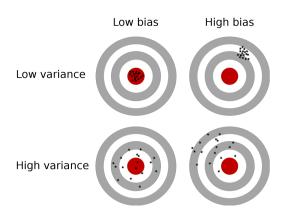


Figure: Illustration of bias-variance trade-off [5]

Bias-Variance Trade-off

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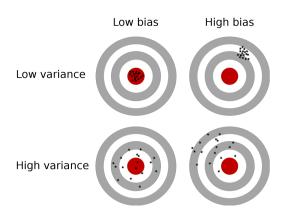
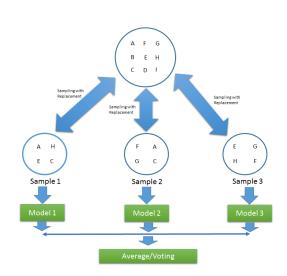


Figure: Illustration of bias-variance trade-off [5]

Decision trees generally have low bias and high variance [2].

Bagging

- created for methods with high variance
- reduces variance and gives better predictions
- improvement of bagging: Random Forest



Random Forest

An ensemble of randomly trained decision trees, so in other words random forest was defined by L. Breiman:

Theorem

A random forest is a classifier consisting of a collection of tree-structured classifiers $\hat{T}_{\theta_b}(\mathbf{x}), b=1,...,B$ where the θ_b are independent identically distributed random vectors and each tree casts a unit vote for the most popular class at input \mathbf{x} .

Random Forest is an extension and improvement over bagging:

- Like in bagging, multiple decision trees are built
- Improvement: an injection of randomness is made

Random Forest: randomness in the model

Two key concepts that makes decision forest "random" are:

- Random sampling of training data points when building trees
- Random subsets of features considered when splitting nodes. Recommended number of variables:
 - **1** For classification: $\lfloor \sqrt{n} \rfloor$
 - **b** For regression: $\lfloor \frac{n}{3} \rfloor$

Random Forest: algorithm

Algorithm 1: Random Forest for Regression or Classification

- **1** For b = 1 to B:
 - **1** Draw a bootstrap sample θ_b of size N from the training data.
 - **6** Grow the Random Forest tree T_{θ_b} to the bootstrapped data, by recursively repeating the following steps for each terminal node of the tree, until the minimum node size n_{min} is reached:
 - \bullet Select m variables at random from the n variables
 - O Pick the best variable/split-point among the m
 - Split the node into two daughter nodes
- ② Output the ensemble of trees $\{T_{\theta_b}\}_1^B$

Section 2

Mathematical Concept

Let $D = \{(x_1, y_1), (x_2, y_2), ..., (x_N, y_N)\}$ and $T_{D,\theta}$ is a fully grown tree trained on set D with using parameters θ . Random Forest estimate of an observation x^* is

Majority Voting

$$RF_{D,\theta_1,\theta_2,...,\theta_B}(x^*) = \underset{c \in Y}{\operatorname{argmax}} \sum_{b=1}^B \mathbb{1}(\hat{T}_b(x^*) = c)$$

Soft Voting

$$\mathbf{RF}_{D,\theta_1,\theta_2,\dots,\theta_B}(x^*) = \underset{c \in Y}{\operatorname{argmax}} \frac{1}{B} \sum_{b=1}^{B} \hat{p}_{D,\theta_b}(Y = c | X = x^*)$$

where $\hat{p}_{D,\theta_b}(Y=c|X=x^*)$ is the probability estimates of a tree.

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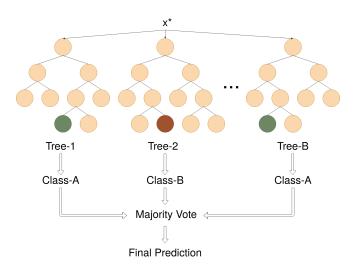
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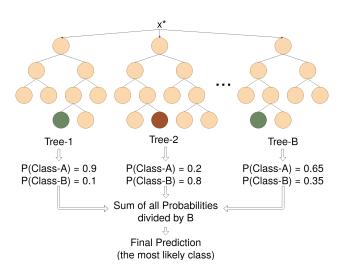
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Majority Voting Illustration



Soft Voting Illustration



The Expected Generalization Error of $T_{D,\theta}$

Given $D = X \cup Y$, the expected generalization error of $T_{D,\theta}$ is

$$Err(T_{D,\theta}(X)) = \mathbb{E}_{X,Y}\{L(Y,T_{D,\theta}(X))\}$$

where $L(Y, T_{D,\theta}(X))$ is the loss function.

The decomposition of $Err(T_{D,\theta})$ is

$$Err(T_{D,\theta}(X)) = Err(\phi_{\beta}(X)) + [Bias(T_{D,\theta}(X))]^2 + Var(T_{D,\theta}(X))$$

similarly

$$Err(RF_{D,\Theta}(X)) = Err(\phi_{\beta}(X)) + [Bias(RF_{D,\Theta}(X))]^2 + Var(RF_{D,\Theta}(X))$$

where
$$\Theta = \{\theta_1, \theta_2, \dots, \theta_B\}.$$

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Residual Error

$$\operatorname{\textit{Err}}(\operatorname{\textit{RF}}_{D,\Theta}(X)) = \operatorname{\textit{Err}}(\phi_{\beta}(X)) + [\operatorname{\textit{Bias}}(\operatorname{\textit{RF}}_{D,\Theta}(X))]^2 + \operatorname{\textit{Var}}(\operatorname{\textit{RF}}_{D,\Theta}(X))$$

Residual Error

$$Err(RF_{D,\Theta}(X)) = Err(\phi_{\beta}(X)) + [Bias(RF_{D,\Theta}(X))]^2 + Var(RF_{D,\Theta}(X))$$

Theoretically, given the probability distribution of P(X,Y)Bayes Model ϕ_{β} i.e the best possible model can be derived and $Err(\phi_{\beta})$ can be calculated [4].

For comparison of $Err(T_{D,\theta}(X))$ and $Err(RF_{D,\Theta}(X))$

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Result: Ensembling has no effect on Bayes Error.

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$$Err(RF_{D,\Theta}(X)) = Err(\phi_{\beta}(X)) + [Bias(RF_{D,\Theta}(X))]^2 + Var(RF_{D,\Theta}(X))$$

Bias² of Tree

Bias

$$[\mathit{Bias}(\mathsf{T}_{D, heta}(\mathsf{X}))]^2 = (\phi_eta(\mathsf{X}) - \mathbb{E}_D\{\mathsf{T}_{D, heta}(\mathsf{X})\})^2$$

Bias² of Random Forest

$$[Bias(\mathbf{RF}_{D,\Theta}(X))]^2 = (\phi_{\beta}(X) - \mathbb{E}_{D,\Theta}\{\mathbf{RF}_{D,\Theta}(X))\})^2$$

We need $\mathbb{E}_{D,\theta}\{T_{D,\theta}(X))\}$ and $\mathbb{E}_{D,\Theta}\{RF_{D,\Theta}(X))\}$ for comparison.

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Bias: The Expected Value

We can define
$$\mathbb{E}_D\{T_{D,\theta}(X)\} = \mu_{D,\theta}(X)$$

Random Forest Estimator for regression is;

$$RF_{D,\Theta}(X) = \frac{1}{B} \sum_{b=1}^{B} T_{D,\theta_b}(X)$$

$$\mathbb{E}_{D,\Theta}\{\mathbf{RF}_{D,\Theta}(X)\} = \mathbb{E}_{D,\Theta}\{\frac{1}{B}\sum_{b=1}^{B}T_{D,\theta_b}(X)\}$$

$$= \frac{1}{B}\sum_{b=1}^{B}\mathbb{E}_{D,\theta_b}\{T_{D,\theta_b}(X)\} \qquad (\theta_i \stackrel{d}{=} \theta_j \ \forall i,j \in B)$$

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$$= \mu_{D,\theta}(X)$$

Bias Comparison

$$Err(RF_{D,\Theta}(X)) = Err(\phi_{\beta}(X)) + [Bias(RF_{D,\Theta}(X))]^2 + Var(RF_{D,\Theta}(X))$$

Bias² of Tree

$$[Bias(T_{D,\theta})(X)]^2 = (\phi_{\beta}(X) - \mu_{D,\theta}(X))^2$$

Bias² of a Random Forest

$$[Bias(\mathbf{RF}_{D,\Theta})(X)]^2 = (\phi_{\beta}(X) - \mu_{D,\theta}(X))^2$$

Result: Ensembling trees has no effect on bias

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Variance: Correlation Coefficient

$$Err(RF_{D,\Theta}(X)) = Err(\phi_{\beta}(X)) + [Bias(RF_{D,\Theta}(X))]^2 + Var(RF_{D,\Theta}(X))$$

we can define the correlation coefficient as follows

$$\rho(X) = \frac{\mathbb{E}_{D,\theta',\theta''}\{T_{D,\theta'}(X)T_{D,\theta''}(X)\} - \mu_{D,\theta}^2(X)}{\sigma_{D,\theta}^2(X)}$$

where
$$\sigma_{D,\theta}^2(X) = \mathbb{V}_{D,\theta}\{T_{D,\theta}(X)\}.$$

- Highly correlated trees $\implies \rho(X)$ is close to 1
- Non-correlated trees $\implies \rho(X)$ is close to 0



Variance: Correlation Coefficient

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Variance Comparison

$$Err(RF_{D,\Theta}(X)) = Err(\phi_{\beta}(X)) + [Bias(RF_{D,\Theta}(X))]^2 + Var(RF_{D,\Theta}(X))$$

$$\mathbb{V}_{D,\Theta}\{\mathbf{RF}_{D,\Theta}(X)\} = \rho(X)\sigma_{D,\theta}^2(X) + \frac{1-\rho(X)}{B}\sigma_{D,\theta}^2(X)$$

$$\implies \mathbb{V}_{D,\Theta}\{\mathbf{RF}_{D,\Theta}(X)\} = \rho(X)\sigma_{D,\theta}^2(X) < \sigma_{D,\theta}^2(X) = \mathbb{V}_{D,\theta}\{T_{D,\theta}(X)\}.$$

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As $B \to \infty$, $\mathbb{V}_{D,\Theta}\{RF_{D,\Theta}(X)\}$ converges to $\rho(X)\sigma_{D,\theta}^2(X)$.

Due to randomization $\rho(X) < 1$

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Result: Ensembling trees decreases the variance



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Result: Ensembling trees decreases the variance.



Simulation Study

Simulation Study Linear DGP

The linear DGP generates the data tuples (y, x_1, x_2, x_3) as follows:

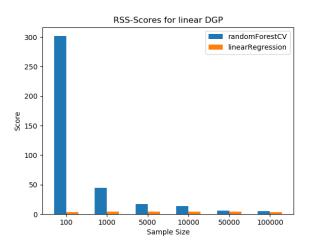
$$y = \beta_0 + \beta_1 x_1 + \beta_2 x_2 + \beta_3 x_3 + \epsilon, \tag{1}$$

whereas

- $(\beta_0 \ \beta_1 \ \beta_2 \ \beta_3) = (0.3 \ 5 \ 10 \ 15)$
- $x_1, x_2, x_3 \sim \mathcal{N}(0, 3)$
- $\epsilon \sim \mathcal{N}(0, 1)$

Simulation Study

Linear DGP Results



Simulation Study Non-Linear DGP

The non-linear DGP generates the data tuples (y, x_1, x_2) as follows:

$$y = \beta_0 + \beta_1 \mathbb{1}(x_1 \ge 0, x_2 \ge 0) + \beta_2 \mathbb{1}(x_1 \ge 0, x_2 < 0) + \beta_3 \mathbb{1}(x_1 < 0) + \epsilon, (2)$$

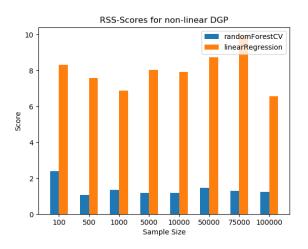
whereas

- $(\beta_0 \ \beta_1 \ \beta_2 \ \beta_3) = (0.3 \ 5 \ 10 \ 15)$
- $x_1, x_2, x_3 \sim \mathcal{N}(0, 3)$
- $\epsilon \sim \mathcal{N}(0, 1)$

are the same as in the previous DGP.

Simulation Study

Non-Linear DGP Results



Real Data

Data: Titanic data

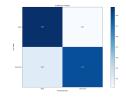
Method used:

- Random Forest
- AdaBoost
- Gradient Boosting Classifier

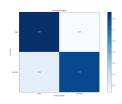
Goal: Given features of passengers predict which passengers survived the Titanic shipwreck

Real Data: results

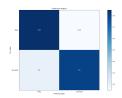
Random Forest Accuracy: 84,32%



AdaBoost Accuracy: 82.8%



Gradient Boosting Accuracy: 82,8%



Contact Data

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