

Random Forest for Classification Problems

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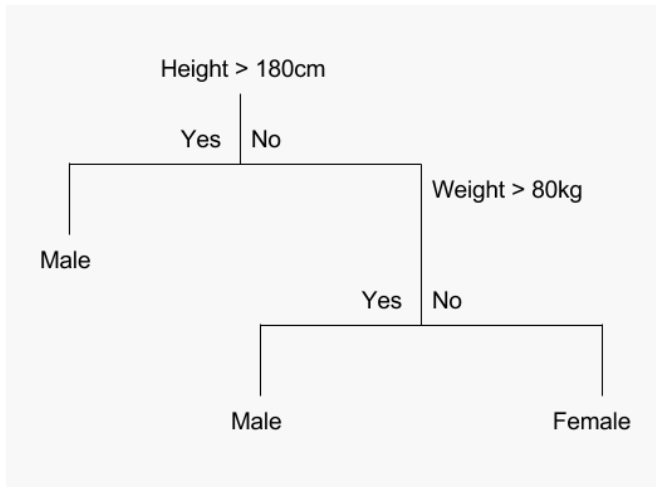
Overview

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Decision Tree: Example



Decision Tree: Tree Building Process

A tree is grown starting from the root node by repeatedly using the following steps on each node (also called binary splitting):

- (i) **Find best split s for each feature X_m :** For each feature X_m , there exist $K - 1$ -many potential splits whereas K is the number of different values for the respective feature. Evaluate each value $X_{m,i}$ at the current node t as a candidate split point (for $x \in X_m$, if $x \leq X_{m,i} = s$, then x goes to left child node t_L else to right child node t_R). The best split point is the one that maximizes the splitting criterion $\Delta i(s, t)$ the most when the node is split according to it. The different splitting criteria will be covered in the next chapter.
- (ii) **Find the node's best split:** Among the best splits for each feature from Step (i) find the one s^* , which maximizes the splitting criterion $\Delta i(s, t)$.
- (iii) **Satisfy stopping criterion:** Split the node t using best node split s^* from Step (ii) and repeat from Step (i) until stopping criterion is satisfied.

Decision Tree: Purity Measures

Gini Measure

$$i(t) = \sum_{c \in C} p(c|t)(1 - p(c|t)) = 1 - \sum_{c \in C} p_c^2 \quad (1)$$

Information Entropy

$$i(t) = \sum_{c \in C} p(c|t) \log(p(c|t)) \quad (2)$$

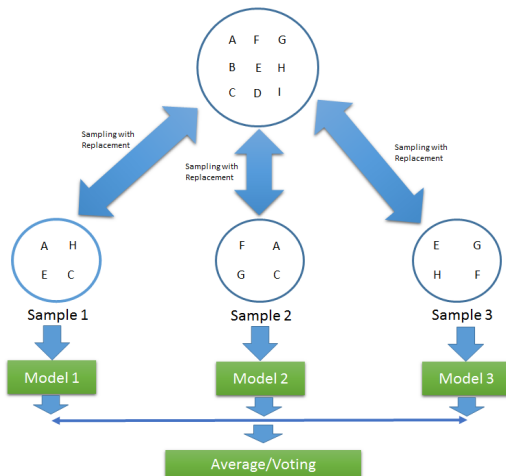
Heading

- 1 Statement
- 2 Explanation
- 3 Example

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Bagging

- ① created for methods with high variance
- ② reduces variance and gives better predictions
- ③ improvement of bagging:
Random Forest



Treatments	Response 1	Response 2
Treatment 1	0.0003262	0.562
Treatment 2	0.0015681	0.910
Treatment 3	0.0009271	0.296

Table: Table caption

Example (Theorem Slide Code)

```
\begin{frame}  
\frametitle{Theorem}  
\begin{theorem}[Mass--energy equivalence]  
$E = mc^2$  
\end{theorem}  
\end{frame}
```

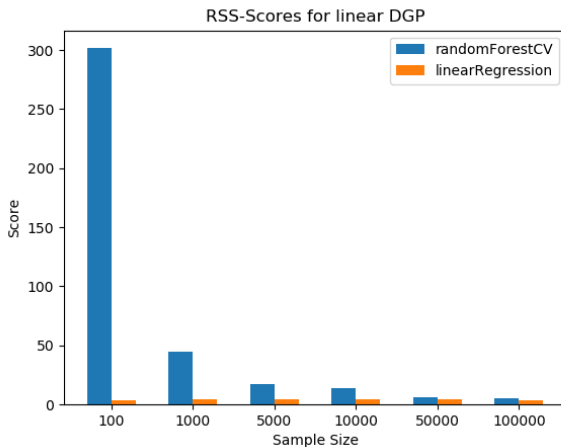
Simulation Study: Linear DGP

The linear DGP generates the data tuples (y, x_1, x_2, x_3) as follows:

$$y = \beta_0 + \beta_1 x_1 + \beta_2 x_2 + \beta_3 x_3 + \epsilon, \quad (3)$$

whereas $(\beta_0, \beta_1, \beta_2, \beta_3) = (0.3, 5, 10, 15)$, $x_1, x_2, x_3 \sim \mathcal{N}(0, 3)$, and $\epsilon \sim \mathcal{N}(0, 1)$.

Decision Tree: Linear DGP Results



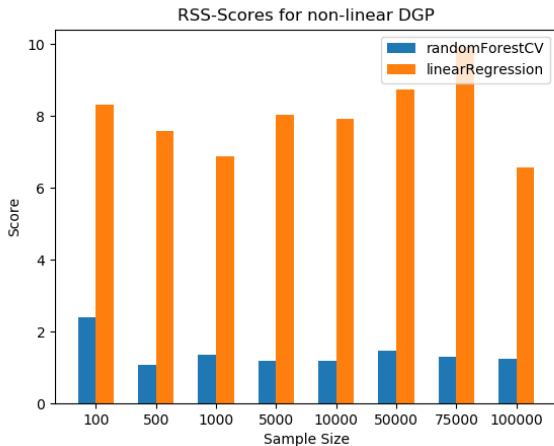
Simulation Study: Non-Linear DGP

The non-linear DGP generates the data tuples (y, x_1, x_2) as follows:

$$y = \beta_0 + \beta_1 \mathbb{1}(x_1 \geq 0, x_2 \geq 0) + \beta_2 \mathbb{1}(x_1 \geq 0, x_2 < 0) + \beta_3 \mathbb{1}(x_1 < 0) + \epsilon, \quad (4)$$

whereas $(\beta_0, \beta_1, \beta_2, \beta_3)$, x_1, x_2 and ϵ are the same as in the previous DGP.

Simulation Study: Non-Linear DGP Results



An example of the `\cite` command to cite within the presentation:

This statement requires citation [**breiman1984classification**].

The End

References