

Random Forest for Classification Problems

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- Decision Tree
- Bagging
- Random Forest

2 Mathematical Concept

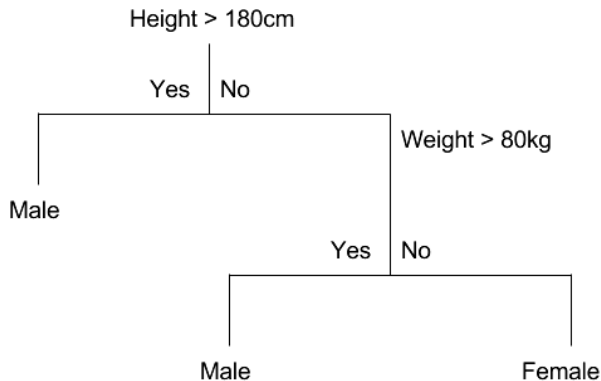
- Prediction Mechanism
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Decision Tree

Example



Decision Tree

Tree Building Process

A tree is grown starting from the root node by repeatedly using the following steps on each node (also called binary splitting)[1]:

- (i) Find best split s for each feature X_m
- (ii) Find the best split of the node
- (iii) Repeat until stopping criterion got satisfied

Decision Tree

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Decision Tree

Purity Measures

Gini Measure

$$i(t) = \sum_{c \in C} p(c|t)(1 - p(c|t))$$

Information Entropy

$$i(t) = \sum_{c \in C} p(c|t) \log(p(c|t))$$

where C is the set of classes c and t a node of the tree.

Bias Variance Trade-off

The Expected Generalization Error

$y = f(x) + \epsilon$ and $\epsilon \sim \mathcal{N}(0, \sigma_\epsilon^2)$

Estimate of $f(x)$: $\hat{f}(x)$

The expected generalization error: ***Err***($\hat{f}(x)$)

The decomposition of a model's expected generalization error is

$$\mathbf{Err}(\hat{f}(x)) = \sigma_\epsilon^2 + [\text{Bias}(\hat{f}(x))]^2 + \text{Var}(\hat{f}(x))$$

σ_ϵ^2 is irreducible and independent of the model.

Trade-off between bias and variance.

Aim: Decrease variance while keeping bias unincreased.

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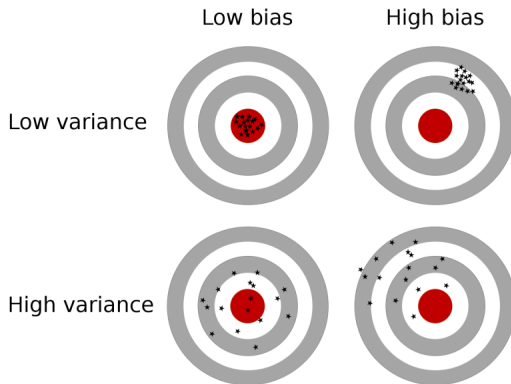
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Bias-Variance Trade-off

Illustration



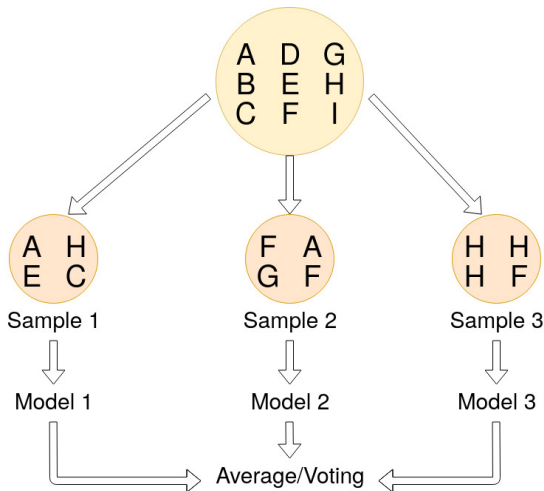
Decision trees generally have low bias and high variance.

Bagging is:

- ① created for methods with high variance
- ② reduces variance and gives better predictions
- ③ improvement of bagging: Random Forest

Bagging

Illustration



Random Forest

Definition

Definition (by L.Breiman [2])

A random forest is a classifier consisting of a collection of tree-structured classifiers $\hat{T}_{\theta_b}(\mathbf{x})$, $b = 1, \dots, B$ where the θ_b are independent identically distributed random vectors and each tree casts a unit vote for the most popular class at input \mathbf{x} .

Random Forest is an extension and improvement over bagging:

- 1 Like in bagging, multiple decision trees are built
- 2 Improvement: an injection of randomness is made

Random Forest

Randomness in the model

Two key concepts that makes decision forest "random" are [3]:

- 1 Random sampling of training data points when building trees
- 2 Random subsets of variables considered when splitting nodes.
Recommended number of variables:

- a For classification: $\lfloor \sqrt{n} \rfloor$
- b For regression: $\lfloor \frac{n}{3} \rfloor$

Random Forest

Algorithm

Algorithm 1: Random Forest for Regression or Classification [3]

- 1 For $b = 1$ to B :
 - a Draw a bootstrap sample D_b of size N from the training data.
 - b Grow the Random Forest tree T_{D_b, θ_b} to the bootstrapped data, by recursively repeating the following steps for each terminal node of the tree, until the minimum node size n_{min} is reached:
 - i Select m variables denoted by θ_b at random from the n variables
 - ii Pick the best variable/split-point among the m
 - iii Split the node into two daughter nodes
- 2 Output the ensemble of trees $\{T_{D_b, \theta_b}\}_{b=1}^B$

Section 2

Mathematical Concept

Mathematical Concept

Prediction Mechanism

Let $D = \{(x_1, y_1), (x_2, y_2), \dots, (x_N, y_N)\}$ and $T_{D,\theta}$ is a fully grown tree trained on set D with using parameters θ . Random Forest estimate of an observation x^* is

Majority Voting

$$RF_{D,\theta_1,\theta_2,\dots,\theta_B}(x^*) = \underset{c \in Y}{\operatorname{argmax}} \sum_{b=1}^B \mathbb{1}(\hat{T}_b(x^*) = c)$$

Soft Voting

$$RF_{D,\theta_1,\theta_2,\dots,\theta_B}(x^*) = \underset{c \in Y}{\operatorname{argmax}} \frac{1}{B} \sum_{b=1}^B \hat{p}_{D,\theta_b}(Y = c | X = x^*)$$

where $\hat{p}_{D,\theta_b}(Y = c | X = x^*)$ is the probability estimates of a tree.

Mathematical Concept

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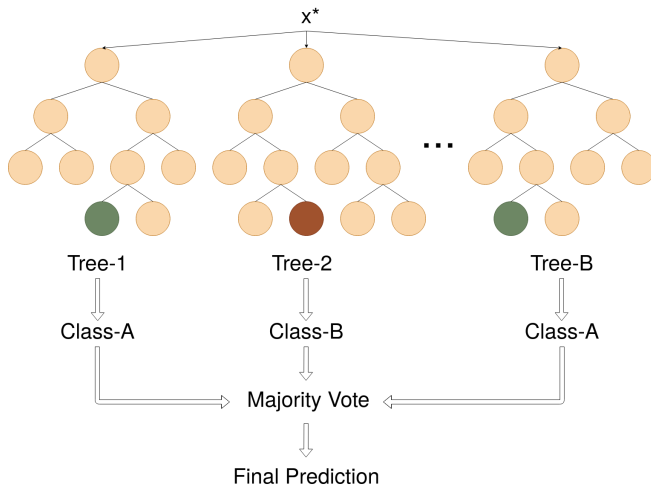
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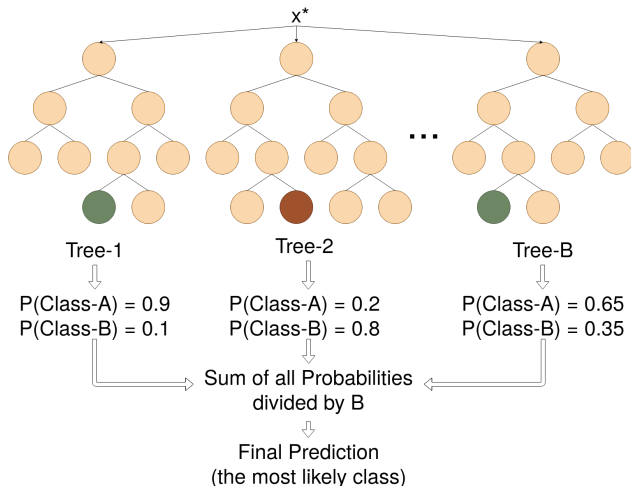
Mathematical Concept

Majority Voting Illustration



Mathematical Concept

Soft Voting Illustration



Mathematical Concept

The Expected Generalization Error of $T_{D,\theta}$

Given $D = (X, Y)$,
the expected generalization error of $T_{D,\theta}$ is

$$\mathbf{Err}(T_{D,\theta}(X)) = \mathbb{E}_{X,Y}\{L(Y, T_{D,\theta}(X))\}$$

where $L(Y, T_{D,\theta}(X))$ is the loss function.

The decomposition of $\mathbf{Err}(T_{D,\theta})$ is

$$\mathbf{Err}(T_{D,\theta}(X)) = \mathbf{Err}(\phi_\beta(X)) + [\mathbf{Bias}(T_{D,\theta}(X))]^2 + \mathbf{Var}(T_{D,\theta}(X))$$

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$$\mathbf{Err}(\mathbf{RF}_{D,\Theta}(X)) = \mathbf{Err}(\phi_\beta(X)) + [\mathbf{Bias}(\mathbf{RF}_{D,\Theta}(X))]^2 + \mathbf{Var}(\mathbf{RF}_{D,\Theta}(X))$$

where $\Theta = \{\theta_1, \theta_2, \dots, \theta_B\}$.

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Mathematical Concept

Residual Error

$$Err(RF_{D,\Theta}(X)) = Err(\phi_\beta(X)) + [Bias(RF_{D,\Theta}(X))]^2 + Var(RF_{D,\Theta}(X))$$

Theoretically, given the probability distribution of $P(X,Y)$ Bayes Model ϕ_β i.e the best possible model can be derived and $Err(\phi_\beta)$ can be calculated [4].

For comparison of $Err(T_{D,\theta}(X))$ and $Err(RF_{D,\Theta}(X))$ the residual error is the same.

Result: Ensembling has no effect on Bayes Error.

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Bias

$$Err(\mathbf{RF}_{D,\Theta}(X)) = Err(\phi_\beta(X)) + [Bias(\mathbf{RF}_{D,\Theta}(X))]^2 + Var(\mathbf{RF}_{D,\Theta}(X))$$

With Squared Loss Function: $L(Y, T_{D,\theta}(X)) = \mathbb{E}_D\{(Y - T_{D,\theta}(X))^2\}$

$Bias^2$ of Tree

$$[Bias(T_{D,\theta}(X))]^2 = (\phi_\beta(X) - \mathbb{E}_D\{T_{D,\theta}(X)\})^2$$

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$$[Bias(\mathbf{RF}_{D,\Theta}(X))]^2 = (\phi_\beta(X) - \mathbb{E}_{D,\Theta}\{\mathbf{RF}_{D,\Theta}(X)\})^2$$

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Bias: The Expected Value

We can define $\mathbb{E}_D\{T_{D,\theta}(X)\} = \mu_{D,\theta}(X)$

Random Forest Estimator for regression is;

$$\mathbf{RF}_{D,\Theta}(X) = \frac{1}{B} \sum_{b=1}^B T_{D,\theta_b}(X)$$

Taking expectation gives;

$$\begin{aligned}\mathbb{E}_{D,\Theta}\{\mathbf{RF}_{D,\Theta}(X)\} &= \mathbb{E}_{D,\Theta}\left\{\frac{1}{B} \sum_{b=1}^B T_{D,\theta_b}(X)\right\} \\ &= \frac{1}{B} \sum_{b=1}^B \mathbb{E}_{D,\theta_b}\{T_{D,\theta_b}(X)\} \quad (\theta\text{'s are i.i.d.}) \\ &= \mu_{D,\theta}(X)\end{aligned}$$

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$\forall T_{D,\theta'}, T_{D,\theta''}$ such that $\theta' \neq \theta''$, the correlation coefficient can be written as follows

$$\rho(X) = \frac{\mathbb{E}_{D,\theta',\theta''}\{T_{D,\theta'}(X)T_{D,\theta''}(X)\} - \mu_{D,\theta}^2(X)}{\sigma_{D,\theta}^2(X)}$$

where $\sigma_{D,\theta}^2(X) = \mathbb{V}_{D,\theta}\{T_{D,\theta}(X)\}$.

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- Non-correlated trees $\implies \rho(X)$ is close to 0

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Variance of Random Forest

$$\mathbb{V}_{D,\Theta}\{\mathbf{RF}_{D,\Theta}(X)\} = \rho(X)\sigma_{D,\theta}^2(X) + \frac{1 - \rho(X)}{B}\sigma_{D,\theta}^2(X)$$

As $B \rightarrow \infty$, $\mathbb{V}_{D,\Theta}\{\mathbf{RF}_{D,\Theta}(X)\}$ converges to $\rho(X)\sigma_{D,\theta}^2(X)$.

Due to randomization $\rho(X) < 1$

$$\implies \mathbb{V}_{D,\Theta}\{\mathbf{RF}_{D,\Theta}(X)\} = \rho(x)\sigma_{D,\theta}^2(X) < \sigma_{D,\theta}^2(X) = \mathbb{V}_{D,\theta}\{T_{D,\theta}(X)\}.$$

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Mathematical Concept

Variance Comparison

$$Err(\mathbf{RF}_{D,\Theta}(X)) = Err(\phi_\beta(X)) + [Bias(\mathbf{RF}_{D,\Theta}(X))]^2 + Var(\mathbf{RF}_{D,\Theta}(X))$$

Variance of Random Forest

$$\mathbb{V}_{D,\Theta}\{\mathbf{RF}_{D,\Theta}(X)\} = \rho(X)\sigma_{D,\theta}^2(X) + \frac{1 - \rho(X)}{B}\sigma_{D,\theta}^2(X)$$

As $B \rightarrow \infty$, $\mathbb{V}_{D,\Theta}\{\mathbf{RF}_{D,\Theta}(X)\}$ converges to $\rho(X)\sigma_{D,\theta}^2(X)$.

Due to randomization $\rho(X) < 1$

$$\implies \mathbb{V}_{D,\Theta}\{\mathbf{RF}_{D,\Theta}(X)\} = \rho(x)\sigma_{D,\theta}^2(X) < \sigma_{D,\theta}^2(X) = \mathbb{V}_{D,\theta}\{T_{D,\theta}(X)\}.$$

Result: Ensembling trees decreases the variance.

Section 3

Simulation Study

The linear DGP generates the data tuples (y, x_1, x_2, x_3) as follows:

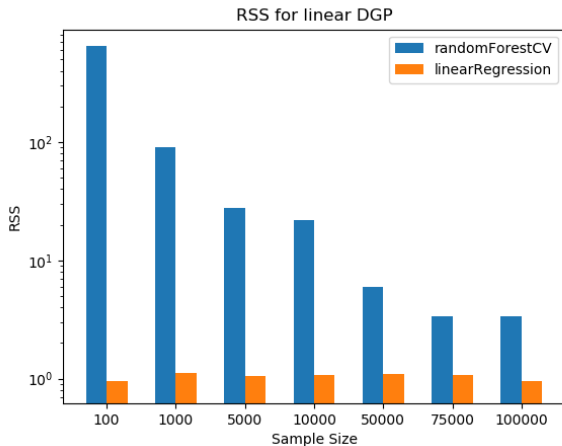
$$y = \beta_0 + \beta_1 x_1 + \beta_2 x_2 + \beta_3 x_3 + \epsilon,$$

whereas

- $(\beta_0, \beta_1, \beta_2, \beta_3) = (0.3, 5, 10, 15)$
- $x_1, x_2, x_3 \sim \mathcal{N}(0, 3)$
- $\epsilon \sim \mathcal{N}(0, 1)$

Simulation Study

Linear DGP Results



Simulation Study

Non-Linear DGP

The non-linear DGP generates the data tuples (y, x_1, x_2) as follows:

$$y = \beta_0 + \beta_1 \mathbb{1}(x_1 \geq 0, x_2 \geq 0) + \beta_2 \mathbb{1}(x_1 \geq 0, x_2 < 0) + \beta_3 \mathbb{1}(x_1 < 0) + \epsilon,$$

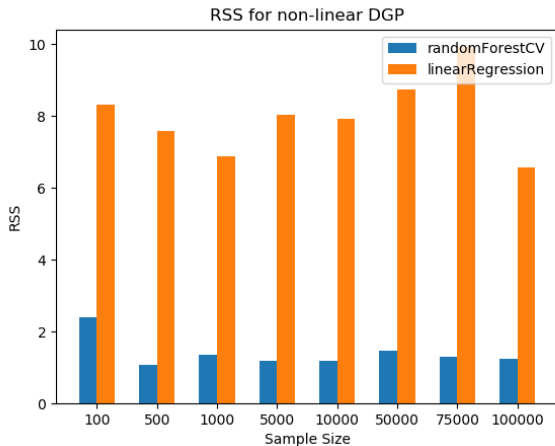
whereas

- $(\beta_0, \beta_1, \beta_2, \beta_3) = (0.3, 5, 10, 15)$
- $x_1, x_2 \sim \mathcal{N}(0, 3)$
- $\epsilon \sim \mathcal{N}(0, 1)$

are the same as in the previous DGP.

Simulation Study

Non-Linear DGP Results



Section 4

Real Data

Data: Titanic data

Method used:

- 1 Random Forest
- 2 Adaptive Boosting
- 3 Gradient Boosting

Goal: Predict which passengers survived the Titanic shipwreck given characteristics of passengers

Real Data

Results

Random Forest

Accuracy: 84.32%

Adaptive Boosting

Accuracy: 82.8%

Gradient Boosting

Accuracy: 82.8%

	D_{pred}	S_{pred}
D_{real}	88%	12%
S_{real}	21%	79%

	D_{pred}	S_{pred}
D_{real}	86%	14%
S_{real}	21%	79%

	D_{pred}	S_{pred}
D_{real}	85%	15%
S_{real}	20%	80%

where D stands for died and S is for survived.

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The link to presentation's repository:



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