

# Learning-NUM: Network Utility Maximization With Unknown Utility Functions and Queueing Delay

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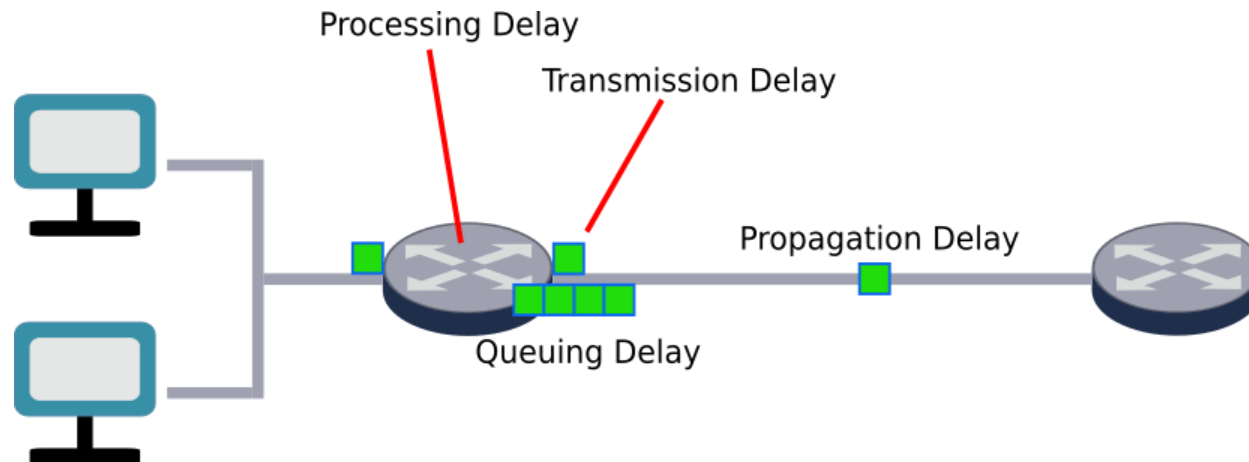
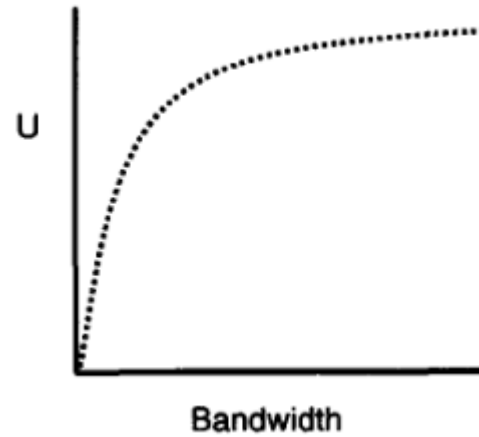
# Introduction

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- Network utility maximization
- Fundamental problem in communication networks
- Unknown utility functions and queueing delay
- Learning-NUM: Maximizes utility over time

# Background

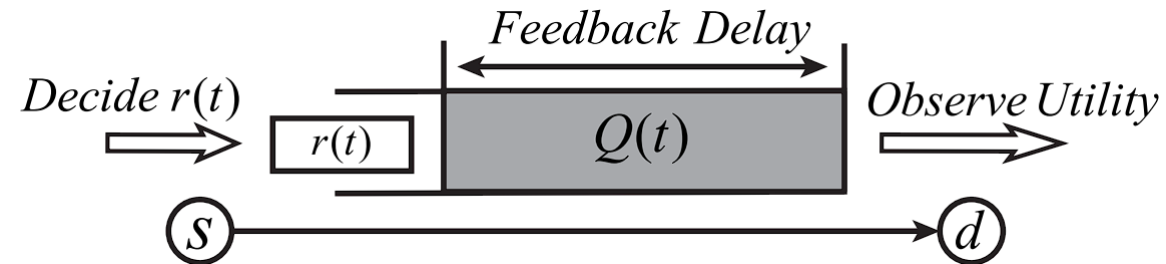
- Utility functions:
  - Defined over  $[0, +\infty)$
  - Continuously differentiable
  - Non-decreasing
  - Concave
- Queueing delay



# Challenges

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- Utility functions and queueing delay are unknown
- Optimizing an unknown function
- Delays depends on decisions



# Related Work

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- Static – stochastic approaches
- Utility functions are **known**
- When utility depends on more constraints, it gets hard to estimate

# Learning-NUM

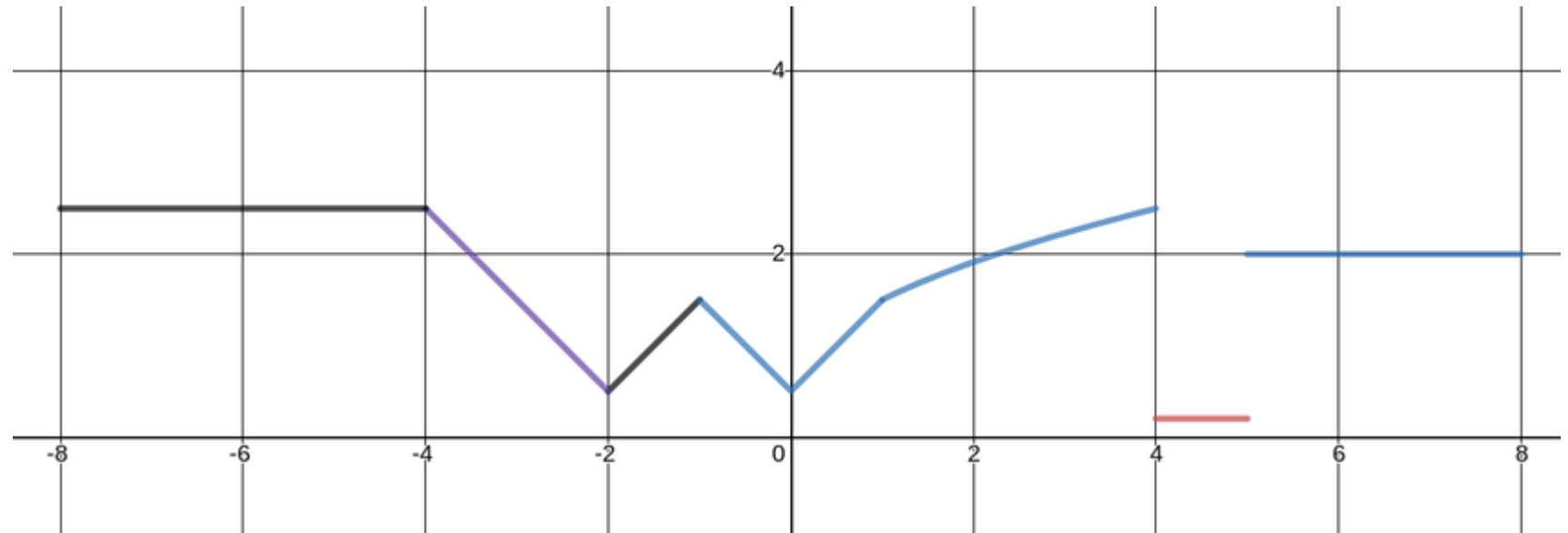
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- A new framework
- Utility values can be learned over time
- Value is observed after the job gets to the destination
- Determines job sizes and actions

# Learning-NUM

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- Online learning: Minimizing regret value
- Regret: Gap between expected and optimal
- Gradient sampling



# GSMW Algorithm

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- Gradient Sampling Max-Weight
  - Gradient sampling
  - Drift-plus-penalty
  - Backpressure routing
  - Max-Weight scheduling
- No-delay setting:  $\tilde{O}(\sqrt{T})$ -regret

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**Algorithm 1** The Gradient Sampling Max-Weight Algorithm.

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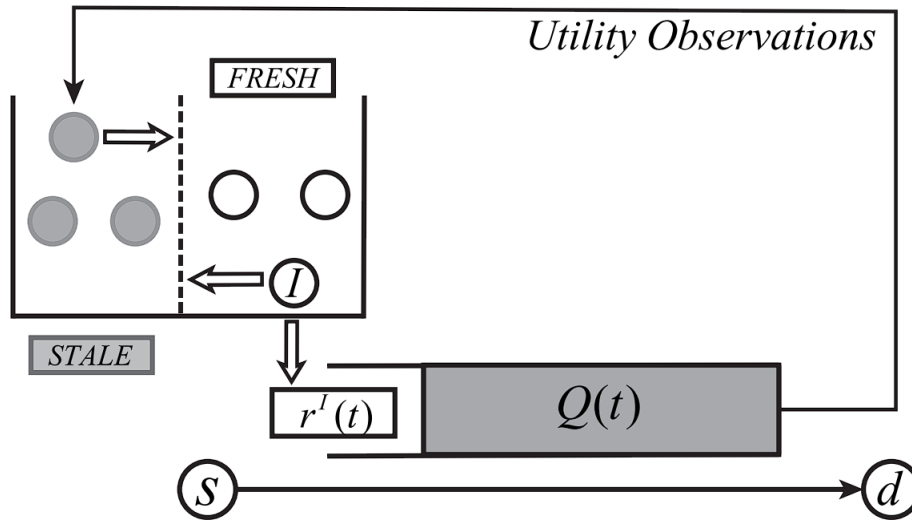
**Input:** Network  $\mathcal{G}(\mathcal{V}, \mathcal{E})$ , parameters  $V, \delta, \alpha$

- 1: **Initialize:**  $\mathbf{x}(0) \in \mathcal{X}, \hat{r}_k(0) = \delta$ .
  - 2: **for**  $t = 1, 2, \dots, T$  **do**
  - 3:    $\mathbf{x}(t) := \arg \max_{\mathbf{x} \in \mathcal{X}} \sum_{i,j \in V} \sum_{k=1}^K A_{ij}^k(\omega(t), \mathbf{x}) [Q_i^k(t) - Q_j^k(t)]$
  - 4:   **for**  $k = 1, \dots, K$  **do**
  - 5:      $s_k$  injects job of size  $\hat{r}_k(t) + \delta$  and observes  $f_k(\hat{r}_k(t) + \delta)$ .
  - 6:      $s_k$  injects job of size  $\hat{r}_k(t) - \delta$  and observes  $f_k(\hat{r}_k(t) - \delta)$ .
  - 7:      $\hat{\nabla} f_k(\hat{r}_k(t)) := \frac{f_k(\hat{r}_k(t) + \delta) - f_k(\hat{r}_k(t) - \delta)}{2\delta}$
  - 8:   Update queue lengths according to  $r_k(t), \mathbf{x}(t)$ .
  - 9:   **for**  $k = 1, \dots, K$  **do**
  - 10:      $\hat{r}_k(t+1) := \mathcal{P}_{[\delta, B-\delta]} \left[ \hat{r}_k(t) + \frac{1}{\alpha} (V \cdot \hat{\nabla} f_k(\hat{r}_k(t)) - Q_{s_k}^k(t)) \right]$
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# P-GSMW Algorithm

- Parallel-instance Gradient Sampling Max-Weight
- Two status: FRESH and STALE




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## Algorithm 2 The Parallel-Instance GSMW Policy.

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**Input:** Network  $\mathcal{G}(\mathcal{V}, \mathcal{E})$ , parameters  $V, \delta, \alpha$ , instance reservoir  $\mathcal{I}$

- 1: **for**  $t = 1, 2, \dots, T$  **do**
  - 2:    $\mathbf{x}(t) := \arg \max_{\mathbf{x} \in \mathcal{X}} \sum_{i,j \in V} \sum_{k=1}^K A_{ij}^k(\omega(t), \mathbf{x}) [Q_i^k(t) - Q_j^k(t)]$
  - 3:   **if** There exists a FRESH instance  $I_t \in \mathcal{I}$  **then**
  - 4:     **for**  $k = 1, \dots, K$  **do**
  - 5:        $\hat{r}_k^{I_t}(t) := \mathcal{P}_{[\delta, B-\delta]} \left[ \hat{r}_k^{I_t}(t-1) + \frac{1}{\alpha} (V \cdot \hat{\nabla} f_k(\hat{r}_k^{I_t}(t-1)) - Q_{s_k}^k(t)) \right]$
  - 6:        $s_k$  injects job of size  $\hat{r}_k^{I_t}(t) + \delta$  and another job of size  $\hat{r}_k^{I_t}(t) - \delta$ .
  - 7:       Change the status of  $I_t$  to STALE.
  - 8:     **else**
  - 9:       Create a new instance  $I_t$
  - 10:       For each  $k$ , initialize  $\hat{r}_k^{I_t}(t) := \delta$ , and  $s_k$  injects job of size  $\hat{r}_k^{I_t}(t) + \delta$  and another job of size  $\hat{r}_k^{I_t}(t) - \delta$
  - 11:       Update queue lengths according to  $r_k(t), \mathbf{x}(t)$ .
  - 12:        $\{\hat{r}_k^J(t)\} := \{\hat{r}_k^J(t)\}$  for  $J \in \mathcal{I}, J \neq I_t$ .
  - 13:       Collect utility observations from delivered jobs and form gradient estimates  $\hat{\nabla} f_k(\hat{r}_k^I(t)) := \frac{f_k(\hat{r}_k^I(t) + \delta) - f_k(\hat{r}_k^I(t) - \delta)}{2\delta}$
  - 14:     **for** STALE instance  $I \in \mathcal{I}$  **do**
  - 15:       Change the status of  $I$  to FRESH if it has obtained all outstanding gradient estimates.
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# Applications

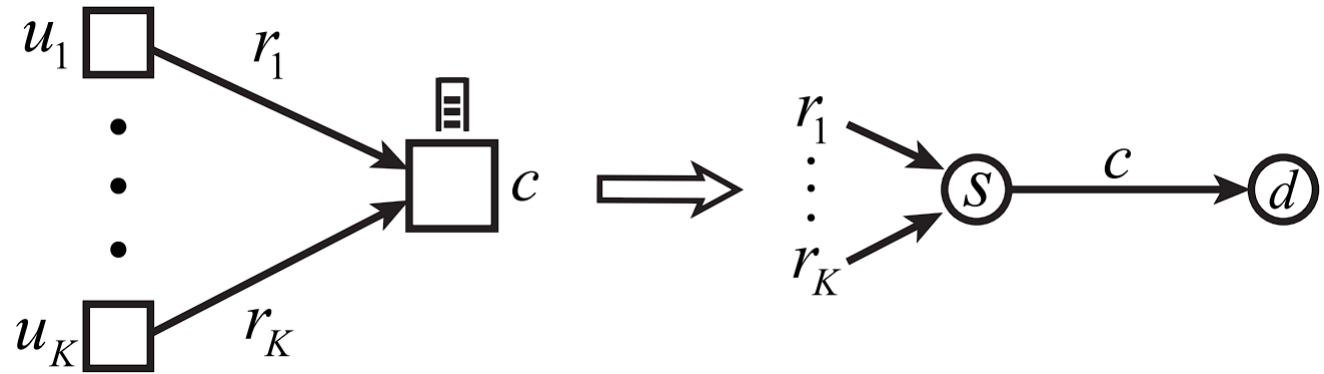
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- Database query
- Job scheduling
- Video streaming

# Database Query

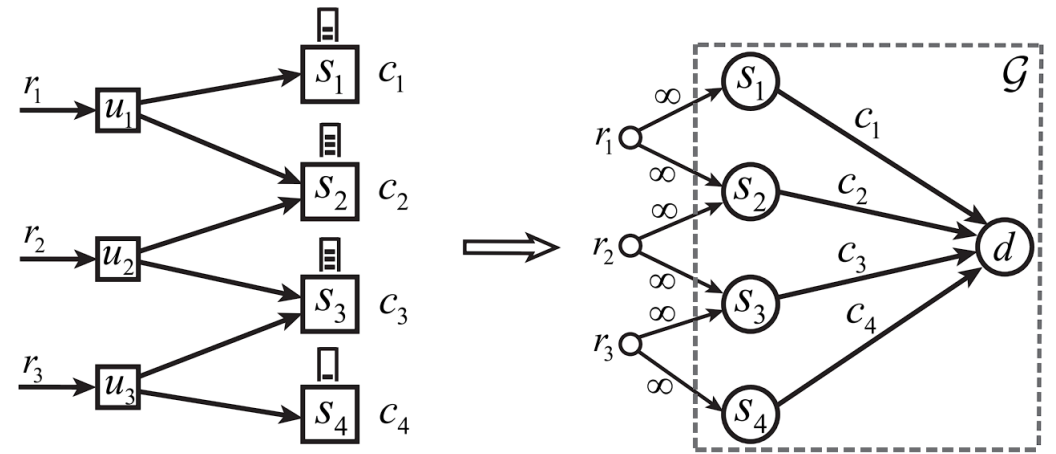
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- K users querying a central database
- Maximize total utility of the processed queues
- Sublinear regret value:  $\tilde{O}(T^{3/4})$ -regret



# Job Scheduling

- 3 Job schedulers and 4 servers
- Dispatcher determines resource
- Maximize the total utility gained from jobs
- Example of ML in Cloud
- Sublinear regret value:  $\tilde{O}(T^{3/4})$ -regret



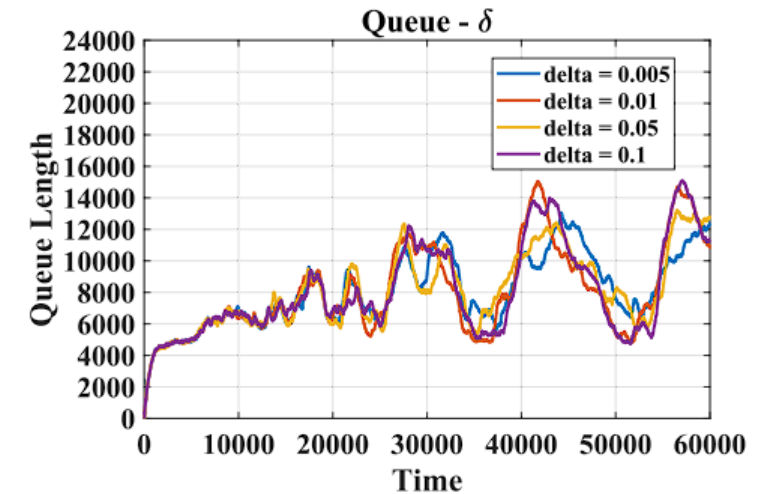
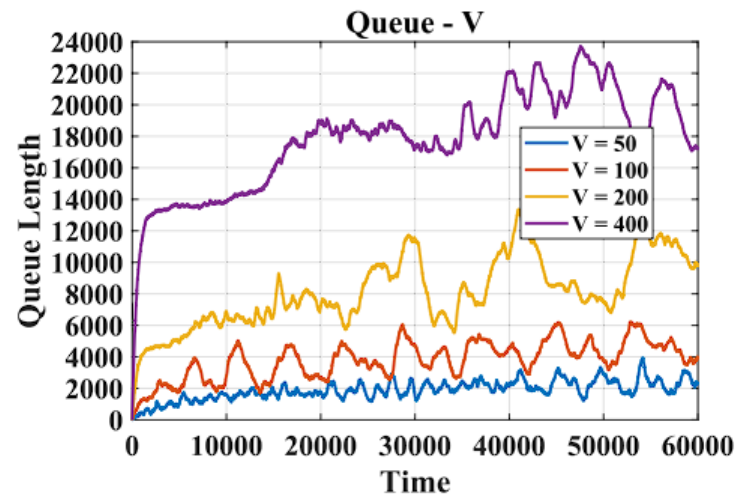
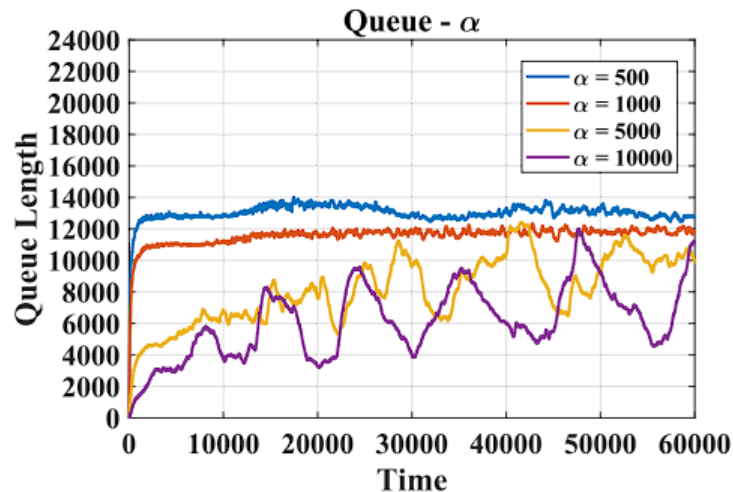
# Video Streaming

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- Discuss the advantages of Learning-NUM, such as accuracy and efficiency
- K users streaming video from K servers
- Servers send chunks to users
- Determining size of the video chunks
- Maximizing delivered video chunks
- Sublinear regret value:  $\tilde{O}(T^{3/4})$ -regret

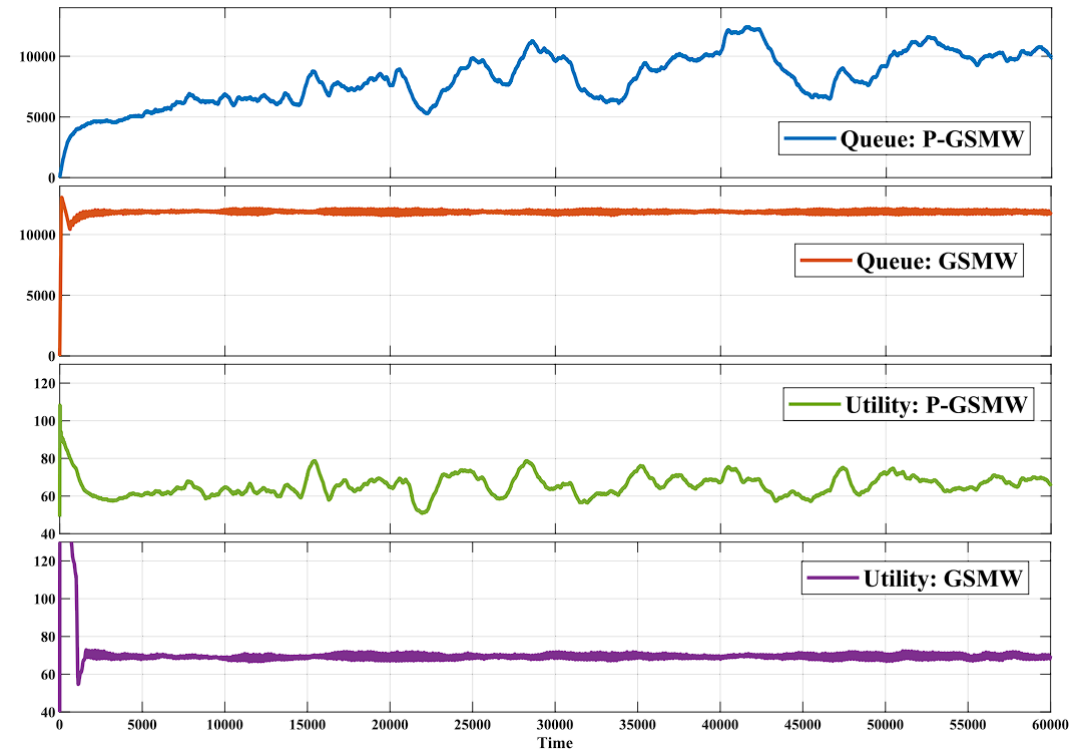
# Evaluation: Parameters

- $\alpha$ : Controls the step size with a larger  $\alpha$  indicating a smaller step size.
- $V$ : Adjusts the relative weights on utility maximization and queue stability, with a larger  $V$  indicating that the policy tries to increase the job sizes more aggressively.
- $\delta$ : Controls the approximation error of our estimate gradients with respect to the true gradients.



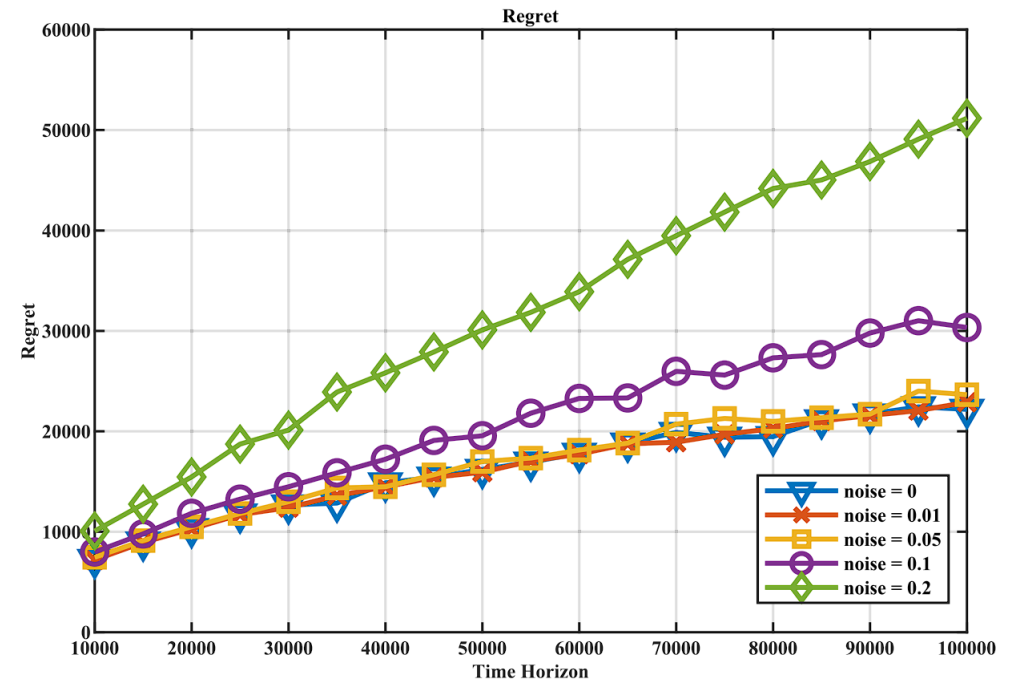
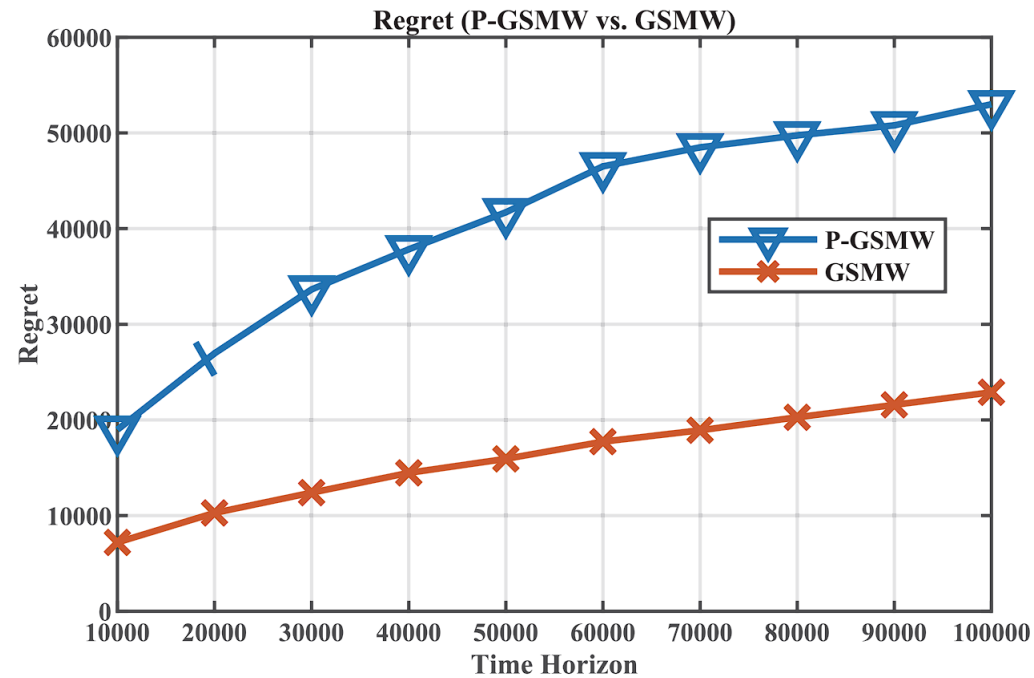
# Evaluation

- Queue length and instantaneous utility behavior under P-GSMW and GSMW:



# Evaluation

- Regrets of P-GSMW and GSMW:





# Conclusion

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- A new framework: Learning-NUM
- With unknown utility functions and queueing-style delay
- Achieved sub-linear regret
- Future work:
  - Noiseless, no-delay case does not achieve lower bound of regret
  - More robust policies for noisy scenarios

# References

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