Antidiffusion techniques to refine the numerical solution of the advection equation Case study: Smolarkiewicz' iterative approach

Gerhard Burger Jelmer Wolterink

Scientific Computing
Department of Mathematics
Utrecht University

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Outline

- 1 The advection equation in climate modelling
 - Importance
 - Diffusion
 - Antidiffusion methods
- 2 Case study: Smolarkiewicz
 - Analyzing the scheme
 - Implementation
 - Numerical Results
 - Progress



Advection

Transport mechanism of a **substance** by a *fluid*, due to the fluids motion in a particular direction.

Examples in ocean, atmosphere and climate modelling

- Transport of trace gasses by air due to wind
- Transport of heat by ocean water due to <u>currents</u>
- Transport of warm and moist air over a colder surface by air due to wind: advection fog







Advection equation

Continuity equation describing the advection of a nondiffusive quantity in a flow field:

$$\frac{\partial \psi}{\partial t} + \operatorname{div}(V\psi) = 0 \tag{1}$$

where $\psi(x,y,z,t)$ is the nondiffusive scalar quantity, V=(u,v,w) is the velocity vector and x,y,z,t are space and time independent variables.



Advection simulation

Constraints on advection simulation [?]

- Solutions should contain no unphysical overshoot or undershoot: positive definite schemes
- Methods should be volume preserving. No loss of matter
- The solutions should be local: the solution at any one point should not be influenced by what is going on far away from that point
- The numerical solution should not introduce new extrema in the solution, because the continuous form of the solution would not
- The method should be cost effective: memory and computational requirements should be sufficiently small so that practical problems may be solved

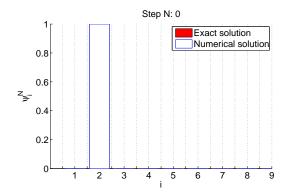
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Problem: diffusion

- When simulating an advective process, we need to discretize space. When doing so, we introduce numerical constraints on the calculation and we get diffusion.
- The numerical solution spreads out.
- We get interactions, our simulations become less reliable.
- $\bullet \implies \mathsf{example}$

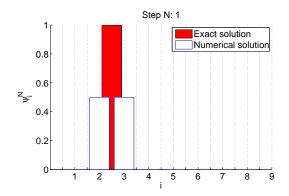






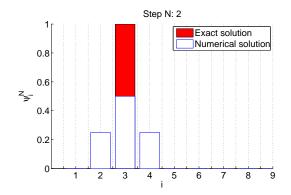




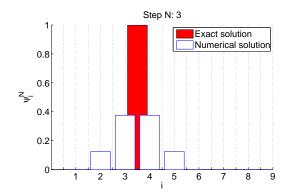




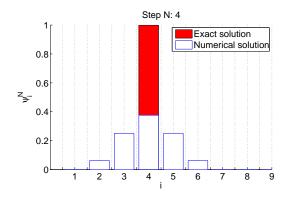






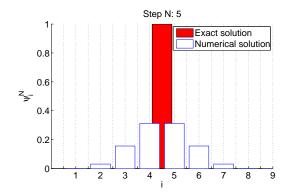




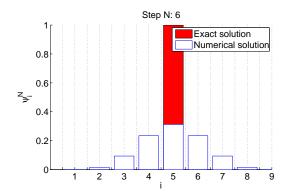






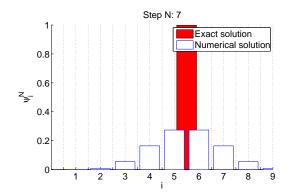














Antidiffusion methods

- Flux-corrected transport (FCT) method (Boris and Book, 1973),
- self-adjusting hybrid scheme (SAHS) (Harten en Zwas, 1972),

Both can be very accurate but require excessive computing time, better is the

 hybrid-type scheme based on a Crowley advection scheme (Clark and Hall, 1979),

with more diffusion but half the computation time.



Antidiffusion methods

Smolarkiewicz' iterative correction, 1983

- Less time consuming while results are comparable to those of the more complex hybrid schemes
- Positive semidefinite
- Iterative method
- Does not contain strong implicit diffusion





Basis: upstream on a staggered grid

We start with the following upstream advection equation on staggered grid:

$$\psi_{i}^{n+1} = \psi_{i}^{n} - \left(F\left(\psi_{i}^{n}, \psi_{i+1}^{n}, u_{i+1/2}^{n}\right) - F\left(\psi_{i-1}^{n}, \psi_{i}^{n}, u_{i-1/2}^{n}\right) \right),$$

where

$$\begin{split} F\left(\psi_{i}^{n},\psi_{i+1}^{n},u_{i+1/2}^{n}\right) &= \\ &\left(\left(u_{i+1/2}^{n} + \left|u_{i+1/2}^{n}\right|\right)\psi_{i}^{n} + \left(u_{i+1/2}^{n} - \left|u_{i+1/2}^{n}\right|\right)\psi_{i+1}^{n}\right) \frac{\Delta t}{2\Delta x}. \end{split}$$





Writing the scheme out and collecting terms gives

$$\begin{split} \psi_{i}^{n+1} &= \frac{\Delta t}{2\Delta x} \left(u_{i-1/2}^{n} + \left| u_{i-1/2}^{n} \right| \right) \psi_{i-1}^{n} \\ &+ \left(1 - \frac{\Delta t}{2\Delta x} \left(u_{i+1/2}^{n} + \left| u_{i+1/2}^{n} \right| - u_{i-1/2}^{n} + \left| u_{i-1/2}^{n} \right| \right) \right) \psi_{i}^{n} \\ &- \frac{\Delta t}{2\Delta x} \left(u_{i+1/2}^{n} - \left| u_{i+1/2}^{n} \right| \right) \psi_{i+1}^{n} \end{split}$$



This can be rewritten to

$$\psi_i^{n+1} = \alpha_i \psi_{i-1}^n + \beta_i \psi_i^n + \gamma_i \psi_{i+1}^n, \text{ for } i = 1, \dots, M-1,$$

where we have that

$$\begin{split} \alpha_i &= \frac{\Delta t}{2\Delta x} \left(u_{i-1/2}^n + \left| u_{i-1/2}^n \right| \right), \\ \beta_i &= \left(1 - \frac{\Delta t}{2\Delta x} \left(u_{i+1/2}^n + \left| u_{i+1/2}^n \right| - u_{i-1/2}^n + \left| u_{i-1/2}^n \right| \right) \right), \\ \gamma_i &= -\frac{\Delta t}{2\Delta x} \left(u_{i+1/2}^n - \left| u_{i+1/2}^n \right| \right). \end{split}$$



We can also write this in matrix form using Direchlet boundary conditions

- y(0) = 0 and y(M) = 0
- using periodic boundary conditions y(0) = y(M)

$$\begin{bmatrix} \psi_{1}^{n+1} \\ \psi_{2}^{n+1} \\ \vdots \\ \psi_{M-2}^{n+1} \\ \psi_{M-1}^{n+1} \end{bmatrix} = \begin{bmatrix} \beta_{1} & \gamma_{1} & & & \mathbf{0} \\ \alpha_{2} & \beta_{2} & \gamma_{2} & & \\ & \ddots & \ddots & \ddots & \\ & & \alpha_{M-2} & \beta_{M-2} & \gamma_{M-2} \\ \mathbf{0} & & & \alpha_{M-1} & \beta_{M-1} \end{bmatrix} \begin{bmatrix} \psi_{1}^{n} \\ \psi_{2}^{n} \\ \vdots \\ \psi_{M-2}^{n} \\ \psi_{M-2}^{n} \end{bmatrix}$$

So the values of ψ at timestep N+1 can be obtained by a sparse matrix-vector multiplication





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So the values of ψ at timestep ${\it N}+1$ can be obtained by a sparse matrix-vector multiplication



Antidiffusion 1

To apply antidiffusion we need to redefine the scheme into

$$\begin{split} \psi_{i}^{*} &= \psi_{i}^{n} - \left(F\left(\psi_{i}^{n}, \psi_{i+1}^{n}, u_{i+1/2}^{n}\right) - F\left(\psi_{i-1}^{n}, \psi_{i}^{n}, u_{i-1/2}^{n}\right) \right), \\ \psi_{i}^{n+1} &= \psi_{i}^{*} - \left(F\left(\psi_{i}^{*}, \psi_{i+1}^{*}, \tilde{u}_{i+1/2}^{n}\right) - F\left(\psi_{*}^{n}, \psi_{*}^{n}, \tilde{u}_{i-1/2}^{n}\right) \right), \end{split}$$

were the antidiffusion velocity $\tilde{u}_{i+1/2}$ is defined as

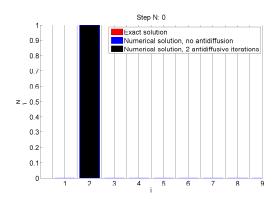
$$\tilde{u}_{i+1/2} = \frac{\left(\left|u_{i+1/2}\right| \Delta x - \Delta t u_{i+1/2}^2\right) \left(\psi_{i+1}^* - \psi_i^*\right)}{\left(\psi_i^* + \psi_{i+1}^* + \epsilon\right) \Delta x}$$

Since the second step is similar to the first we can also apply the 'method of lines' to the second step.



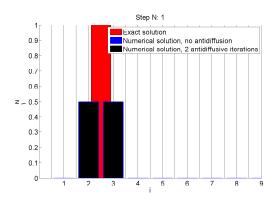
Algorithm

```
input: Initial state \psi^0, velocities u, iter, tsteps, \Delta x, \Delta t
output: Final state \psi^N
\psi \leftarrow \psi^0:
mat1 \leftarrow ComputeMatrix(u, \Delta x, \Delta t);
for i \leftarrow 0 to tsteps do
     \psi \leftarrow \texttt{MatrixMultiplication(mat1,}\psi);
     for j \leftarrow 1 to iter do
          \widetilde{u} \leftarrow \texttt{ComputeAntidiffusionVelocity}(\psi, u);
          mat2 \leftarrow ComputeMatrix(\widetilde{u}, \Delta x, \Delta t);
          \psi \leftarrow \texttt{MatrixMultiplication(mat2,}\psi);
     end
end
```



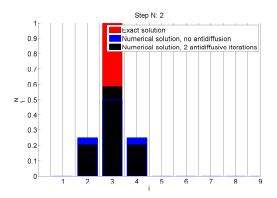






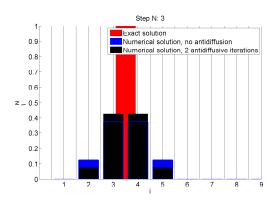






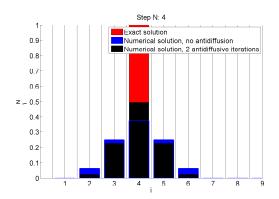






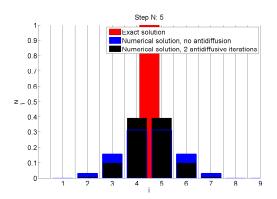






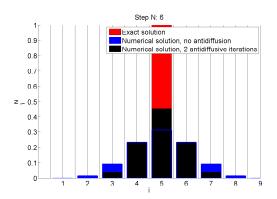






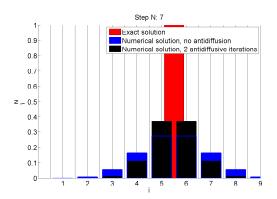










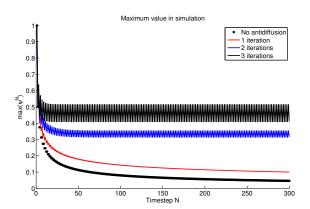






Less diffusion

Iterating with antidiffusion vector reduces diffusion.

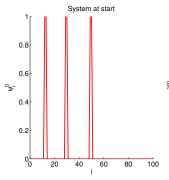


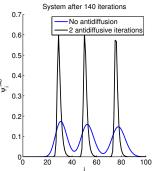




Less interaction

Simulations are more localized, less interaction between neighbouring pockets.







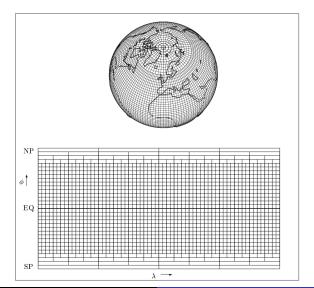


- Since 1983 a lot of progress has been made
- Advection calculations on the sphere pose new problems.





Reduced grid (Spee, 1991)



Spherical hexagonal-pentagonal grid (Lipscomb and Ringler, 2005)

