Manual for Odometry Sim

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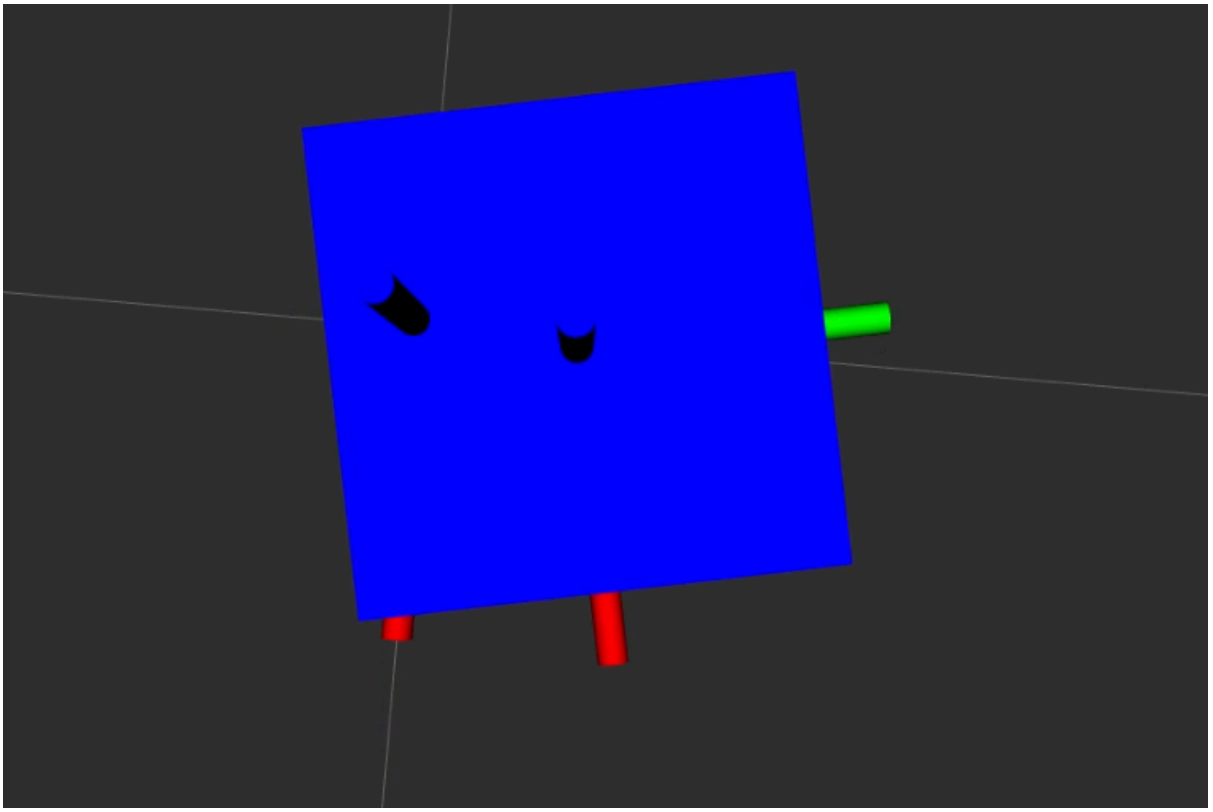

This document will showcase everything needed to launch our package.

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1. Setup

1.1 Setting up the Database

We will set up Mariadb and import our database.

Install components:

```
sudo apt update
sudo apt install libmariadb3 libmariadb-dev libmariadb-dev-compat
mariadb-server mariadb-client
```

Install the c++ connector for mariadb:
https://mariadb.com/docs/connectors/mariadb-connector-cpp/install-mariadb-connector-cpp
Direct download link (ubuntu 24.04 Noble x86, 24.04 has no tar.gz):
https://dlm.mariadb.com/4464930/Connectors/cpp/connector-cpp-1.1.7/mariadb-connector-cpp_1.1.7-1+maria~noble_amd64.deb

Setup mariadb, set up database and user:

```
sudo mariadb-secure-installation #choose anything in configuration
sudo systemctl start mariadb
sudo mariadb -u root
CREATE DATABASE OdometryDB;
CREATE USER 'john_odometry'@'localhost' IDENTIFIED BY '1234';
GRANT ALL PRIVILEGES ON OdometryDB.* TO 'john_odometry'@'localhost';
exit
```

To import our example database in “./backups/baseExample.sql”:

```
//The password for this user is 1234!
//Restore backup:
mysql -u john_odometry -p OdometryDB < ./backups/baseExample.sql

//To Backup into file:
mariadb-dump --user=john_odometry --password --lock-tables
--extended-insert --databases OdometryDB > ./backups/mybackup.sql
```

Without Cmake, one would compile a package using mariadb like this:

```
g++ main.cpp Database.cpp -o appname -lmariadbcpp  #example!
```

We have configured Cmake to work accordingly.

Mysql GUI

We recommend installing an application that lets you view the database through a GUI, this will make testing much easier.
We recommend phpMyAdmin as it is lightweight, free, and easy to use and install.

```
sudo apt install php phpmyadmin
```

When going through the configuration, be careful to actually select Apache2 by pressing spacebar.
Then it is as simple as going to http://localhost/phpmyadmin and logging in as our user.

2. Execution

2.1 Parameters

The configurable parameter file is found in:

```
src/g425_assign4_pkg/config/assign4_params.yaml
```

2.2 Build it

```
cd ../rmb_ws
colcon build
source install/setup.bash
```

2.3 Launch it

To launch with the launch file:

```
ros2 launch g425_assign4_pkg assign4_launch.xml
```

That is all we need to know to launch the package!