Burak Taş

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Fatih/İstanbul

Linkedin: www.linkedin.com/in/buraktronics **Portfolio:** https://burkutken.github.io/portfolio/

Education

High School: Akasya College (2014-2018)

University: Işık University – BEng Mechatronics Engineering (2018-2025)

Summary

Mechatronics Engineering graduate with hands-on experience in mechanical design-prototyping and robotic systems. Proven ability to develop solutions using nTop, Solidworks, ANSYS and Matlab/Simulink across two internships, graduation project and Tübitak project. Contributed to TeknoFest competition project with focus on mechanical design.

Skills

- CAD/CAE: SolidWorks (3yrs), Fusion 360 (6yrs), ANSYS [Structural, Fluent CFD (2D), Transient] (1yr)
- **Programming**: Matlab, Python, C, Arduino (Embedded Systems)
- Control/Simulation: Matlab/Simulink, Proteus
- **Design:** Technical Drawings, nTop
- Languages: English (C1), Spanish/Indonesian (Beginner)

Experiences

- Mechatronics Internship | Arvege Mekatronik San. Tic. LTD ŞTİ
 - o Integrated sensor-actuator system for assembly machines
 - Assembly technics
 - Conveyor System
 - Actuator as pneumatic grippers for assembly machine
- R&D Internship | Altınay Robot Teknolojileri
 - The working principles of Industrial Robotic Arms
 - KUKA and ABB robots and their program environments
 - Work management and group work habit

Projects

Mechanical Team Member | Teknofest IDA Competition - Team Talayhan | June 2024

- Designed full body structural of the unmanned surface vehicle (IDA) using Fusion 360 and Solidworks
- Conducted stress analysis using SolidWorks and ANSYS
- Reached to final video providing section

Research Assistant Student | Mechanical Department Laboratory | June 2025

- Developed CAD models for MQL system project using SolidWorks and Fusion 360
- Developed CFD (2D) analysis using ANSYS Fluent
- Prototyped 3D-printed PLA and SLA components for research purposes

TUBITAK (The Scientific and Technological Research Council of Turkiye) 2209a Project Manager | 2024-1 [1919B012414175] | On-going

- Developing and producing Gyroid structures using 3D SLA Printer and nTop
- Testing developed Gyroid structures for compression, collection data for produces Gyroid structures, using machine learning, selecting the best developed model.