User Guide VQPCA Matlab

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1 Introduction

This is the User Guide for the MATLAB implementation of the VQPCA algorithm [1] and some of its variants. The repository is available at:

https://github.com/matteosavarese95/Local_PCA_suite_MATLAB

This User Guide will describe how the main code works and the main options and functions the user can specify or use to customize the analysis. Similar work has been implemented in Python, which is available at https://github.com/burn-research/OpenMORe. This work presents the same implementation of that work, with some new customized options for the VQPCA routine. For theoretical backgrounds, please check [1].

2 Main VQPCA function

The main code for the VQPCA routine is local_pca_new.m. The arguments of the function are described below, as follows:

function [idx, infos] = local_pca_new(X, k, stop_rule, inputs, opt)

Inputs:

- X: ndarray raw data containing observations as rows and variables (features) as columns. Its size is then $n_{obs} \times n_{var}$
- k: *int*user selected number of clusters

- stop_rule: int stopping rule used for PCA. For better reference, check the function pca_lt.m. The different rules are listed in 2.1
- inputs: float
 Input for selected stopping rule. For better explanation, check the function pca_lt.m. The inputs corresponding to the different stopping rules are defined in 2.1
- opt: struct Structure variable containing the available options for VQPCA. The main options are described in Section 2.2

Outputs:

- idx: 1d-array (int) Cluster labels' array. Size n_{obs}
- infos: struct dictionary containing several fields and information of the resulting VQPCA routine.

2.1 stop_rule and inputs

Extended documentation is available in the function pca_lt.m, which is the in-house code for PCA. The list of available options for PCA dimensionality selection is reported below.

$stop_rule = 1$

This stopping rule corresponds to the **global amount of variance** to retain. The VQPCA will cut the dimensionality in each cluster such that the selected amount of variance is preserved in each cluster. Therefore, each cluster can have a different number of dimensions q. The corresponding **inputs** must be a float between 0 and 1.

$stop_rule = 2$

This stopping rule corresponds to the **individual variance rule**. We can retain the components whose eigenvalues are greater than the average of the eigenvalues (Kaiser, 1960) or than 0.7 times the average of the eigenvalues (Joliffe 1972). For a correlation matrix, this average equals 1. The corresponding **inputs** are 1 for Kaiser and 2 for Joliffe.

stop_rule = 3

This stopping rule corresponds to the broken stick model. No additional

inputs are required. For the correct compilation of the code, select inputs = 1.

$stop_rule = 4$

This stopping rule corresponds to imposing a fixed number of eigenvectors. The user can select inputs = q, where q is an integer and should not be greater than n_{var} .

stop_rule = 5

This stopping rule corresponds to the **Test of significance of the larger eigenvalues**. The inputs correspond to the confidence level for the critical χ squared value: $\alpha \in [0,1]$

2.2 opt customization

opt.Init = string

This field allows for selecting different types of initialization methods. Available initialization methods are:

- "random" (default): this initializes the clusters by selecting k random centroids from the observation and performing a first iteration of the code considering eigenvectors as I matrix.
- "uniform1": this initializes the clusters by taking k samples uniformly from the dataset
- "uniform2: this initializes the k clusters by binning the data uniformly in k groups.
- "best_db": this initializes the clusters by performing an initial number of random initializations, using different random centroids for every iteration. Then, for each iteration, the VQPCA index described in [ref.] is evaluated, and the best random initial solution is chosen.

opt.Centering = int

Available option for data pre-processing. Available options are:

- opt.Centering = 1 (default): data will be centered around their mean
- opt.Centering = 0: data will not be centered

Refer to the function AuxiliaryFunctions/center.m.

opt.Scaling = string

Available option for data scaling (prior VQPCA, not within the loop, scaling is not performed twice). Available options are:

- "auto" (default): normalizing data by the standard deviation
- "pareto": pareto scaling, normalizing data by the square root of the standard deviation
- "max": normalizing data by their maximum value
- "vast": normalizing data using the vast criterion
- "level": the level criterion is used
- "no": no scaling is performed

Refer to the function AuxiliaryFunctions/scale.m for more info.

opt.Algorithm = string

Available option for the algorithm for the VQPCA routine, available options are:

- "VQPCA" (default): the standard VQPCA routine is chosen
- "FPCA": the variation of VQPCA based on mixture fraction partition is used in this case. This is a semi-supervised routine, and the mixture fraction array must be provided as an option. Namely you need to specify opt.f = f, where f is the n_{obs} array of the mixture fraction, and the stoichiometric mixture fraction opt.fs = fs, where f_s is the stoichiometric mixture fraction value. Please, for reference, see the work of Zdibał et al. [2]

For FPCA, refer to the function AuxiliaryFunctions/condition.m

opt.MaxIter = int

Available option to select the maximum number of iterations. default value is 200.

opt.EpsRecMin = float

The threshold for reconstruction error variance convergence. *default* value is 1.0E-06.

opt.CustomError = string

Available options to select a custom reconstruction error (or VQPCA distortion function). Available options are:

- "Squared" default: squared reconstruction error is used
- "SquareRoot": the L_2 norm of the projection distance is used
- "CustomPower": a custom power for the reconstruction error is selected. The power must be specified by the user via opt.Power = p, where p is a float

Refer to the function CustomPenalties/custom_rec_err.m for more info.

3 Semi-supervised learning: FPCA

This task groups the data in k selected groups by binning them uniformly with respect to a selected variable. For combustion problems, such a variable is mostly represented by the mixture fraction ξ . The sampling can also be non-uniform, provided that the stoichiometric mixture fraction value is provided. The main function that performs this task is fpca_new.m, described as follows:

function [bin_data, idx_clust, idx] = fpca_new(data, z, n_bins,
opt)

Inputs:

• data: ndarray raw data containing observations as rows and variables (features) as columns. Its size is then $n_{obs} \times n_{var}$.

- z: 1-d array Conditioning variable (usually mixture fraction). Its size is then $n_{obs} \times 1$.
- n_bins: *int*Number of bins (analogous to number of clusters *k*).

Outputs:

- bin_data: cell

 Cell array containing the n_bins grouped data. Each element of this array contains the data in that group
- idx_clust: cell

 Cell array containing the n_bins grouped indices of the data.

 Each element of this array contains the indices of the data in that group.
- idx: 1-d darray Cluster labelling vector.

4 VQPCA Evaluation: the I_{LPCA} index

As we know, this routine needs two main hyperparameters as input: the amount of retained variance var (or the number of eigenvectors q, alternatively) and the number of clusters k. Classical indices available in the literature, such as the Davies-Bouldin, Calinski-Harabasz or silhouette indices are valid options, although they rely on Euclidean distance. In this package, a new index is proposed, and the code can be found in the function VQPCAEvaluation/db_pca_new.m. The code can be used as follows:

function db = db_pca(X, idx, stop_rule, inputs)

Inputs:

- X: ndarray raw data containing observations as rows and variables (features) as columns. Its size is then $n_{obs} \times n_{var}$.
- idx: ndarray cluster labels vector. Contains integers ranging from 1 to k. Its length is n_{obs} .
- stop_rule: int
 See Section 2.1. Must be the same as the one used for VQPCA.
- inputs: float
 See Section 2.1. Must be the same as the one used for VQPCA.

Outputs:

• db: *float*Value of the calculated index

5 Examples

Documentation for the examples available soon. For test cases, see the Examples folder.

References

- [1] Nanda Kambhatla and Todd Leen. Dimension reduction by local principal component analysis. *Neural Computation*, 9:1493–1516, 10 1997.
- [2] Kamila Zdybał, Giuseppe D'Alessio, Antonio Attili, Axel Coussement, James C. Sutherland, and Alessandro Parente. Local manifold learning and its link to domain-based physics knowledge. Applications in Energy and Combustion Science, 14:100131, 2023.