

## Lecture-03

03/03/2021

23/11/23

### Review of probability, Covariance, Independence

NOTE: The beginning Lecture on Lagrangian Optimization for Complex domain has been written as a continuation of Notes of Lecture-2.

- Random variable :  $X \in \mathbb{R}$
- Probability Measure :  $A \subseteq \mathbb{R} \quad P(A) = \Pr\{x \in A\}$
- Conditional probability :  $A, B \subseteq \mathbb{R} \quad P(A|B) = \frac{P(A \cap B)}{P(B)}$
- Probability Density Function:  
 $\hookrightarrow f_X : \mathbb{R} \rightarrow \mathbb{R}^+$

→ Random variable is something used to attach probabilities to Numbers. (The numbers are result of a probability experiment)

→ The things which we deal are Probability Measures.  
Probability are measures they behave like Volume, Mass ... and they are defined for every subset of Real numbers

$$A \subseteq \mathbb{R} \quad P(A) = \Pr\{x \in A\}$$

Probability Measure is way of attaching measure to a set.

We know other kind of measure ex: Volume,

→ Conditional probability

$$\text{Bayes Rule: } P(A|B) = \frac{P(A \cap B)}{P(B)}$$

→ Probability Density Function:  $f(q)$   
 $X \rightarrow \text{Random Variable}$

In this course it is a Fundamental Quantity

$$f_x: \mathbb{R} \rightarrow \mathbb{R}^+$$

It is defined in such a way that

$$P(A) = \Pr_T \{x \in A\} = \int_A f_x(q) dq$$

'A' is a set

Probability Density Function

$$f_x(q) dq \approx \Pr \left\{ q - \frac{dq}{2} \leq x \leq q + \frac{dq}{2} \right\}$$

This approximation is true for small values of  $q$

→ Cumulative Distribution function:

$$F_x(q) = \Pr \{x \leq q\} = \boxed{\int_{-\infty}^q f_x(t) dt}$$

$$f_x(q) = \frac{d}{dq} F_x(q)$$

$q$  is the value that the Random Variable  $X$  can take

## → Expectation:

$$E[g(x)] = \int_{\mathbb{R}} g(q) f_x(q) dq$$

This expectation of function of RV

$$E[X] = \int_{\mathbb{R}} q f_x(q) dq$$

weighted Average  
w.r.t. probabilities

Note:  $q$  is the value that the RV  $X$  takes

### • Generalization:

$$X \in \mathbb{R}^n$$

A Random vector of  $n$  dimensions

$$f_x: \mathbb{R}^n \rightarrow \mathbb{R}^+$$

$$\text{Therefore } P(A) = P_{\pi} \{x \in A\} \quad A \subseteq \mathbb{R}^n$$

$$P(A) = \int_A f_x(q) dq$$

here  $q \in \mathbb{R}^n$   
i.e. it is an  $n$ -dimensional

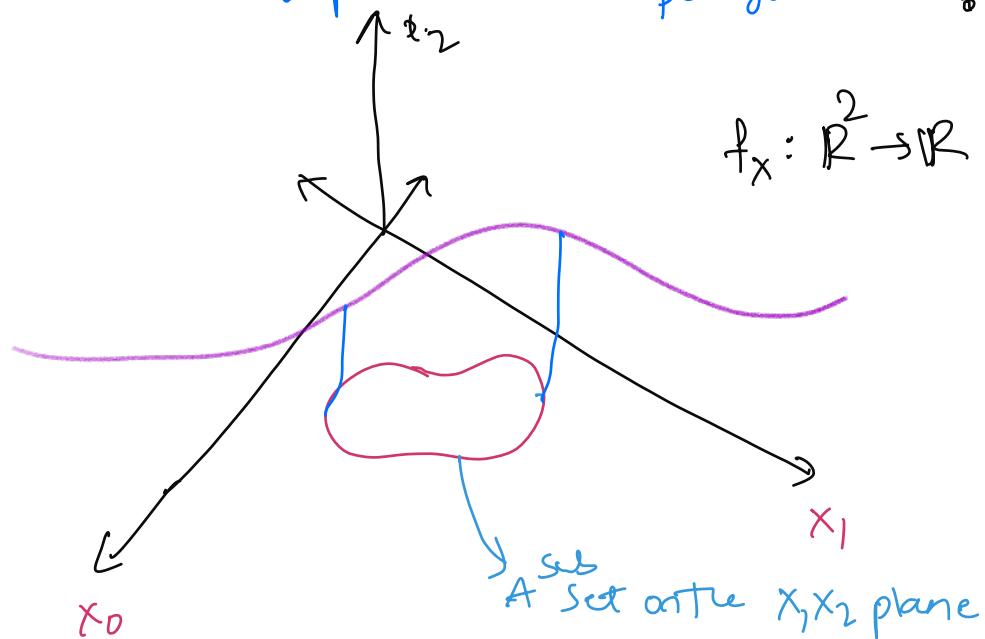
vector -

ex:

$$n=2$$

$$\mathbf{x} = \begin{bmatrix} x_0 \\ x_1 \end{bmatrix}$$

i.e. every possible value belongs to the  $x_0-x_1$  plane



then

$$P(A) = \int_A f_x(y) dy$$

Here the 'x' & v  
is a 2-dimensional  
one

$\therefore y$  is also 2D  
entity

This is similar to multiple Random Variable

→ The concept of Cumulative Distribution Functions can be extended to Multiple R.V's

$$F_X(q) = \int_{-\infty}^q \dots \int_{-\infty}^{t_{n-1}} f_X(t_0, \dots, t_{n-1}) dt_0 \dots dt_{n-1}$$

$X \in \mathbb{R}^n$



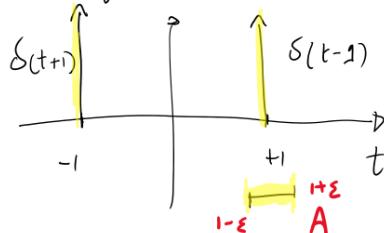
SPECIALIZATION of what we have discussed so far!

Dirac's delta is used to single out discrete values

$$\Pr\{C=+1\} = \frac{1}{2}$$

$$\Pr\{C=-1\} = \frac{1}{2}$$

↑  
tail  
 $t_{\text{tail}}$



$$f_C(t) = \frac{1}{2} \delta(t-1) + \frac{1}{2} \delta(t+1)$$

$$\Pr\{x \in A\} = \int_{1-\varepsilon}^{1+\varepsilon} f_C(t) dt = \frac{1}{2} \underbrace{\int_{1-\varepsilon}^{1+\varepsilon} \delta(t-1) dt}_{1} + \frac{1}{2} \underbrace{\int_{1-\varepsilon}^{1+\varepsilon} \delta(t+1) dt}_{0} \xrightarrow{\int_{-\varepsilon}^{\varepsilon} \delta(t+2) dt}$$

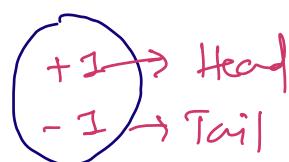
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The specialization is such that the numbers we want are random have generators or pathological in some way. This is the classical case which we would like to make

ex: Tossing of a coin

This is very common to assign to two different values



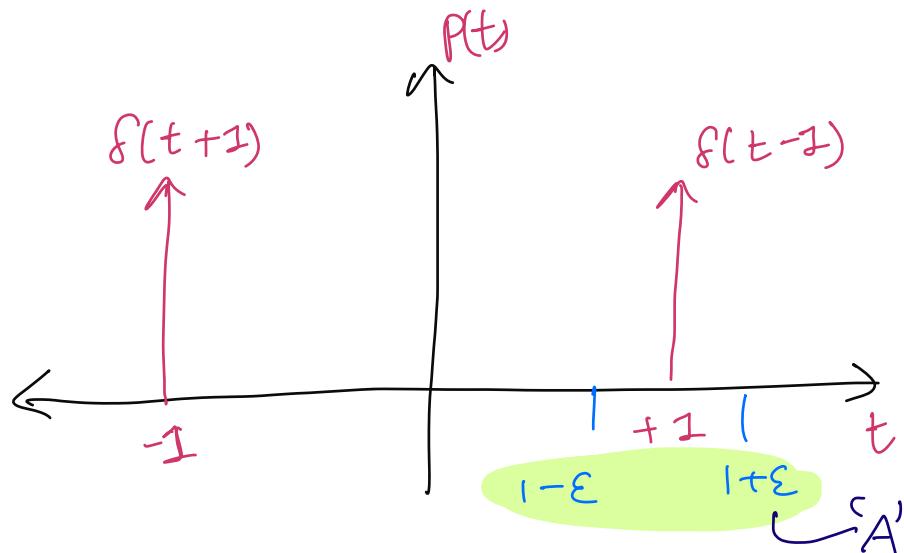
in Tossing a coin example

$$\text{Head} \rightarrow \Pr(C = +1) = \frac{1}{2}$$

$$\text{Tail} \rightarrow \Pr(C = -1) = \frac{1}{2}$$

Q) How do we Model this as Probability Distribution?

We have to resort to Dirac delta, where no of values we have is finite.



Basically, we are laying down a function that has zero all the time except  $t+1$  &  $t-1$  and remut also have the sum of two probability must be equal to 1.

$\therefore$  Integral of my PDF equals 1

$$f_c(t) = \frac{1}{2} f(t-1) + \frac{1}{2} f(t+1)$$

(2): To calculate The Probability of falling in The  
The set A from  $t - \varepsilon$  to  $t + \varepsilon$

Probability is the Integral of the Probability Density function.

$$\int_{t-\varepsilon}^{t+\varepsilon} f_c(t) dt = \frac{1}{2} \int_{t-\varepsilon}^{t-1} f(t-1) dt + \frac{1}{2} \int_{t+1}^{t+\varepsilon} f(t+1) dt$$

$\underbrace{\phantom{\int_{t-\varepsilon}^{t-1} f(t-1) dt}}_{\text{In the domain}}$        $\underbrace{\phantom{\int_{t+1}^{t+\varepsilon} f(t+1) dt}}_{\text{Not in the domain}}$

$$\Rightarrow \frac{1}{2} \cdot 1 = \frac{1}{2}$$

→ Expectation: For Random variable with Prob. distribution.  
It's quite common to define a certain no. of scalars that there are numbers, not random variables, these are fixed.  
These scalars are deterministic and characterize our Random variable.

## BACK TO EXPECTATION

2

### MOMENTS

$$m_x = E[x] = \int_{-\infty}^{+\infty} q f_x(q) dq$$

$$\sigma_x^2 = E[(x - m_x)^2] = \int_{-\infty}^{+\infty} (q - m_x)^2 f_x(q) dq$$

central moments of order p

$$M_x^p = E[(x - m_x)^p]$$

n-central moments of order p

$$m_x^p = E[x^p]$$

absolute moments of order p

$$\mu_x^p = E[|x|^p]$$

complex RV  $z \in \mathcal{C} \Rightarrow \sigma_z^2 = E[|z - m_z|^2]$

modulus

Probably, the well known Expectation is the Average

Expectation:

$$E[x] = \int_{-\infty}^{\infty} q f_x(q) dq$$

1st order

Imp: ' $q$ ' is the numerical value taken up by the our R.V ' $x$ '

Variance:

$$\sigma_x^2 = E[(x - m_x)^2]$$

2nd order

$$\sigma_x^2 = \int_{-\infty}^{\infty} (q - m_x)^2 f_x(q) dq$$

→ The above Expectation and Variance are the special cases of Moments.

$$1) M_x^P = E[(x - m_x)^P] \rightarrow \text{Central Moment of order } 'p'$$

$$2) m_x^P = E[x^P] \rightarrow \text{Non-central Moment of order } 'p'$$

$$= \int_{-\infty}^{\infty} q^P f_x(q) dq$$

$$3) \mu_x^P = E[|x|^P]$$

4) For Complex RV

$$z \in \mathbb{C} \Rightarrow \sigma_z^2 = E[(z - m_z)^2]$$

↑  
modulus

→ Moments describe information about the RV all the information needed to describe a RV is in the Probability Density function.

Just with  $m_x$  &  $\sigma_x^2$  we may know something about the behaviour of the Random Variable.

- The best example about  $P_r$ 's could be the Chebichev inequality.

$$P_r \{ |x - m_x| > \varepsilon \} \leq \frac{\sigma_x^2}{\varepsilon^2}$$

Chebichev inequality

$$P_r \{ |x - m_x| > \varepsilon \} \leq \frac{\sigma_x^2}{\varepsilon^2}$$

Proof

$$\Rightarrow \int f_x(\xi) d\xi = \int_{-\infty}^{+\infty} \chi_{[m_x, \varepsilon]}(\xi) f_x(\xi) d\xi$$

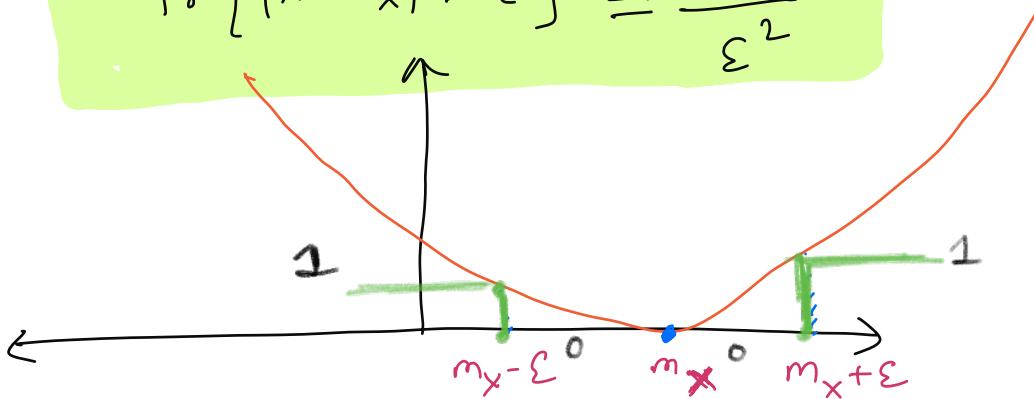
A  $|x - m_x| > \varepsilon$

indicator function

$$\leq \int_{-\infty}^{+\infty} \left( \frac{\xi - m_x}{\varepsilon} \right)^2 f_x(\xi) d\xi = \frac{1}{\varepsilon^2} \int_{-\infty}^{+\infty} (\xi - m_x)^2 f_x(\xi) d\xi = \frac{\sigma_x^2}{\varepsilon^2}$$

It's important to understand the intuitive understanding of Chebichev inequality.

$$P_r \{ |x - m_x| > \varepsilon \} \leq \frac{\sigma_x^2}{\varepsilon^2}$$



→  $|x - m_x|$  is the distance of value of R.V ' $X$ ' L.H.F. from the mean of a random experiment.

→ The probability of  $|x - m_x|$  is the probability of the Deviation.

$$\text{So, } P_{\sigma} \{ |x - m_x| > \varepsilon \} = \frac{\sigma^2}{\varepsilon^2}$$

↓

① This is like asking what is the probability that value of R.V ' $X$ ' deviates from the Average  $m_x$ ?

This is bounded by  $\frac{\sigma^2}{\varepsilon^2}$

The larger the  $\varepsilon$ , the lower is the cap on the deviation. i.e. probability of falling far from the average is always small.

Proof of Chebichev Inequality:

We will use our knowledge of Probability of a set.

$$\rightarrow \int_{|x - m_x| > \varepsilon} f_x(y) dy$$

} It is not comfortable to calculate such integral so we will use the trick for

↓  
Domain of Integration

Indicator Functions

$$\Rightarrow \int_{|x-m_x|>\varepsilon} f_x(q) dq = \int_{-\infty}^{\infty} \chi_{m_x, \varepsilon}(q) f_x(q) dq$$

$$\chi_{m_x, \varepsilon}(q)$$

Indicator function.  
(it is in green in the graph)

The indicator function of the set is a function that evaluates to 1 if the value is inside the set evaluates to 0 if the value is not inside the set.

→ The next set would be to calculate the Bounding

$$\int_{|x-m_x|>\varepsilon} f_x(q) dq \leq \int_{-\infty}^{\infty} \left( \frac{q-m_x}{\varepsilon} \right)^2 f_x(q) dq$$

now putting inside the Integer value larger than what I have to compute.

$\left( \frac{q-m_x}{\varepsilon} \right)^2$  is the parabola indicated above.  
(it is in red in the graph)

≈

$$\Rightarrow \int_{|x - m_x| > \epsilon} f_x(y) dy \leq \frac{1}{\epsilon^2} \left( \int_{-\infty}^{\infty} (y - m_x)^2 f_x(y) dy \right) = \sigma_x^2$$

$$\Rightarrow \frac{1}{\epsilon^2} \sigma_x^2$$

### Covariance :-

→ Now, that we know the moments give us some information about RV we can extend the knowledge to a generalization of Variance.

It is very useful because it helps us to introduce the first processing task that we will see in the course.

It is Covariance, it is useful when the R.V involved is not a single one.

$$\gamma_{z_0 z_1} = E \left[ (z_0 - m_{z_0})^* (z_1 - m_{z_1}) \right]$$

for  $z_0, z_1 \in \mathbb{C}$

$$z = \begin{bmatrix} z_0 \\ z_1 \end{bmatrix} \quad f_z(y) : \mathbb{C}^2 \rightarrow \mathbb{R}^+$$

for  $z_0 = z_1$   $\gamma_{z_0 z_1} = E[(z_0 - m_{z_0})^2]$

this we have seen earlier

→ we think of two R.V's  $z_1, z_2$  as two components of a Random Vector!

i.e

$$\begin{aligned} \cancel{*} \quad & ( \text{Complex Random Vector} ) \\ z = & \begin{bmatrix} z_0 \\ z_1 \end{bmatrix} \end{aligned}$$

\* For this Random Vector we have a PDF attached and just to indicate it is the PDF of two things together it is called Joint PDF.

∴ The PDF of vector containing  $z_0 \& z_1$ ,  
is called Joint PDF of  $z_0 \& z_1$ .

∴ Exploiting this Joint PDF we can simply write the Expectation simply using the definition.

Joint PDF of  $z_0 \& z_1$

Covariance

$$\gamma_{z_0 z_1} = \iint_{\mathbb{R}^2} (q_0 - m_{z_0})^* (q_1 - m_{z_1}) \underbrace{\underbrace{\begin{bmatrix} z_0 \\ z_1 \end{bmatrix}}_{\text{Joint PDF}}} f(q_0, q_1) dq_0 dq_1$$

Q) How do you interpret the above equation?

This is the boiling down of the definition of

## Covariance in terms of Integral and PDF

\* Covariance is a strong indication that I can or cannot do something which is called prediction.

It's a fact that the variables are RV but it doesn't mean that they don't have Links with each other to certain Degree

& Establishing, Finding & Exploiting these Links is almost 50% of Statistical Signal processing.

→ Formally speaking when we want to use the Covariance is we want to predict  $\bar{z}_1$  from value of  $\bar{z}_0$

consider

e.g.:  $\bar{z}_0$  &  $\bar{z}_1$  are simply Temperatures but they are temperatures of two neighbouring rooms.

Temperature in a room being a RV will have to measured to know, But since the room are close to each other the Temperature of one Room will probably affect Temperature of the neighbouring Room.

It's perfectly sensible to say let's measure the Temperature in One of them and let's predict the Temperature in the other.

predict  $\hat{z}_1$  from  $z_0$

$$\hat{z}_1 = H(z_0)$$

Prediction of  $\hat{z}_1$ , it is not a true value it's just a value that I could measure for real.

The Idea is that we would like to make predictors that makes a small error.

→  $e = E \left[ |z_i - \hat{z}_i|^2 \right] \Rightarrow$  Average quadratic error  
(Error)  $\int$  if ref function of  $z_0$   
which is a RV.  $\hat{z}_i$  is also a RV

\* When it comes to predictors for now we will restrict ourselves to linear predictors or affine predictors

$$\hat{z}_i = H(z_0) = a z_0 + b \quad a, b \in \mathbb{C}$$

Affine predictor  $\int$  Predictor parameters

→ The Design of a Predictor task can be thought as an

optimization problem.

Because, what we actually want is this

$$\min_{a,b} E \left[ |z_1 - \hat{z}_1|^2 \right] = \\ \text{s.t } (\text{without any constraints})$$

$a, b$  are our degrees of freedom

$$E \left[ |z_1 - a z_0 - b|^2 \right] = L(a, b)$$

$$\Rightarrow E \left[ (z_1 - a z_0 - b)^* (z_1 - a z_0 - b) \right] - \sum_{j=0}^{m-1} n_j E_j$$

$$\Rightarrow E \left[ (z_1 - a z_0 - b)^* (z_1 - a z_0 - b) \right] = 0 \quad \begin{matrix} \text{(since } n_j = 0 \\ \text{any constraint)} \end{matrix}$$

Here we can't make any complex derivation  
because we have  $\hat{z}^*$

→ But now we can follow Branwood's Recipe  
which we studied earlier

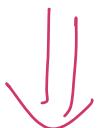
Highlight the conjugate

$$E \left[ (z_1 - a z_0 - b)^* (z_1 - a z_0 - b) \right] = L(a, b) = 0$$

$$(z_1 - az_0 - b)^* = z_1^* - a^* z_0^* - b^*$$

$$\underset{a^*, b^*}{\nabla} L(a, b) = 0$$

Here  $a, b$  are fixed



we can do the derivative w.r.t. non conjugate variables also

$$\text{i.e. } \underset{a, b}{\nabla} L(a, b) = 0$$

Here  $a^*, b^*$  are fixed



$$\left\{ \frac{\partial L}{\partial a^*} = E \left[ z_0^* (z_1 - az_0 - b) \right] = 0 \right.$$

$$\begin{aligned} \frac{\partial}{\partial a^*} E \left[ (z_1^* - a^* z_0^* - b^*) (z_1 - az_0 - b) \right] &= 0 \\ \Rightarrow E[z_0^* (z_1 - az_0 - b)] &= 0 \quad \text{cancel this term} \end{aligned}$$

$$\frac{\partial L}{\partial b^*} = E[-1 (z_1 - az_0 - b)] = 0 \quad \text{---(2)}$$

$$① \Rightarrow E[z_0^* z_1] - a E[z_0]^2 - b E[z_0^*] = 0$$

$$② \Rightarrow E[z_1] - a E[z_0] - \underbrace{E[b]}_{\text{expectation of a constant is equal to constant}} = 0$$

expectation of a constant is equal to constant

$$\textcircled{2} \times E[z_0^*]$$

$$= [E[z_1] E[z_0^*] - a E[z_0] E[z_0^*]] \\ - b E[z_0^*] = 0 \quad \textcircled{3}$$

$$\textcircled{1} - \textcircled{3}$$

$$\Rightarrow [t(z_0^* z_1) - E[z_1] E[z_0^*]] \\ - a (E[z_0]^2) - a E[z_0] E[z_0^*] = 0 \quad \textcircled{4}$$

In this equation we have  
possibility of solving for 'a'

Before doing so let's highlight a property of Covariance  
which is useful.

$$\gamma_{\alpha\beta} = E[(\alpha - m_\alpha)^* (\beta - m_\beta)]$$

$$\Rightarrow E[(\alpha^* - m_\alpha^*) (\beta - m_\beta)]$$

$$\Rightarrow E[\alpha^* \beta - \alpha^* m_\beta - m_\alpha^* \beta + m_\alpha^* m_\beta]$$

$$\Rightarrow E[\alpha^* \beta] - m_\beta E[\alpha^*] - m_\alpha^* E[\beta] + m_\alpha^* m_\beta$$

$$\Rightarrow E[\alpha^* \beta] - m_\beta m_\alpha^* - \cancel{m_\alpha^* m_\beta} + \cancel{m_\alpha^* m_\beta}$$

$$\Rightarrow E[\alpha^* \beta] - m_\beta m_\alpha^*$$

$\therefore \text{Covariance} = E[(\alpha - m_\alpha)^* (\beta - m_\beta)]$

$$= E[\alpha^* \beta] - m_\alpha^* m_\beta$$

$$\rightarrow E[z_0^* z_1] - E[z_1] E[z_0^*] - a \left( E[z_0^2] - E[z_0] E[z_0^*] \right) = 0$$

$$\gamma_{z_0 z_1}$$

$$a \sigma_{z_0}^2$$

$\therefore \gamma_{z_0 z_1} = \sigma_{z_0}^2 \quad \text{if } z_0 = z_1$

$$\therefore \gamma_{z_0 z_1} - a \sigma_{z_0}^2 = 0$$

$$\Rightarrow a = \frac{\gamma_{z_0 z_1}}{\sigma_{z_0}^2}$$

optimal

$$b = m_{z_1} - m_{z_0} \frac{\gamma_{z_0 z_1}}{\sigma_{z_0}^2}$$

predictor