

In solving the questions in the assignment, I worked together with my classmate [Shimiao Wang 1004779634]. I confirm that I have written the solutions / code / report in my own words.

Part 1 Q1.1

$$\text{response} = \iint \nabla^2 G(x, y, \delta) \cdot I(x, y) \, dx \, dy$$

Let's assume the black part of the filter is 0, white part of the filter is 1.

$$\text{response} = \iint_r^\infty \nabla^2 G(x, y, \delta) \cdot 1 \, dx \, dy + \iint_r^\infty \nabla^2 G(x, y, \delta) \cdot 0 \, dx \, dy$$

$$= \int_0^{2\pi} \int_r^\infty \nabla^2 G(x, y, \delta) \, r \, dr \, d\theta$$

$$= \int_0^{2\pi} \int_r^\infty \frac{1}{\pi \delta^4} \left(\frac{x^2 + y^2}{2\delta^2} - 1 \right) e^{-\frac{x^2 + y^2}{2\delta^2}} \, r \, dr \, d\theta.$$

$$= \int_0^{2\pi} \int_r^\infty \frac{1}{\pi \delta^4} \left(\frac{r^2}{2\delta^2} - 1 \right) e^{-\frac{r^2}{2\delta^2}} \, r \, dr \, d\theta.$$

$$= \frac{1}{\pi \delta^4} \int_0^{2\pi} \int_r^\infty \left(\frac{r^2}{2\delta^2} - 1 \right) e^{-\frac{r^2}{2\delta^2}} \, r \, dr \, d\theta.$$

$$= \frac{1}{\pi \delta^4} \int_0^{2\pi} \int_r^\infty \frac{r^3}{2\delta^2} e^{-\frac{r^2}{2\delta^2}} - r e^{-\frac{r^2}{2\delta^2}} \, dr \, d\theta.$$

$$= \frac{1}{\pi \delta^4} \int_0^{2\pi} \left[\frac{1}{2} r^2 e^{-\frac{r^2}{2\delta^2}} \right] d\theta$$

$$= \frac{2\pi}{\pi \delta^4} \frac{1}{2} r^2 e^{-\frac{r^2}{2\delta^2}} - 0.$$

$$= \frac{r^2}{\delta^4} e^{-\frac{r^2}{2\delta^2}}$$

Since $D = 2r$. response $= \frac{(\frac{1}{2}D)^2}{\delta^4} e^{-\frac{(\frac{1}{2}D)^2}{2\delta^2}} = \frac{1}{4\delta^4} D^2 e^{-\frac{D^2}{8\delta^2}}$

Differentiate $\frac{d}{\delta} \left(\frac{D^2}{4\sigma^4} e^{-\frac{r^2}{8\sigma^2}} \right)$

$$\begin{aligned}
 &= \frac{D^2}{4\sigma^4} \cdot -\frac{2D^2}{8\sigma^3} e^{-\frac{r^2}{8\sigma^2}} + \frac{4D^2}{4\sigma^5} e^{-\frac{r^2}{8\sigma^2}} \\
 &= \frac{D^2}{\sigma^5} e^{-\frac{D^2}{8\sigma^2}} - \frac{D^4}{16\sigma^7} e^{-\frac{D^2}{8\sigma^2}} \\
 \Rightarrow & \frac{D^2}{\sigma^5} e^{-\frac{D^2}{8\sigma^2}} - \frac{D^4}{16\sigma^7} e^{-\frac{D^2}{8\sigma^2}} = 0 \\
 \Rightarrow & \frac{D^2}{\sigma^5} = \frac{D^4}{16\sigma^7} \\
 \Rightarrow & 16\sigma^2 = D^2 \\
 \sigma &= \frac{1}{4}D
 \end{aligned}$$

Therefore. $\delta = \frac{1}{4}D$ maximise the magnitude of response

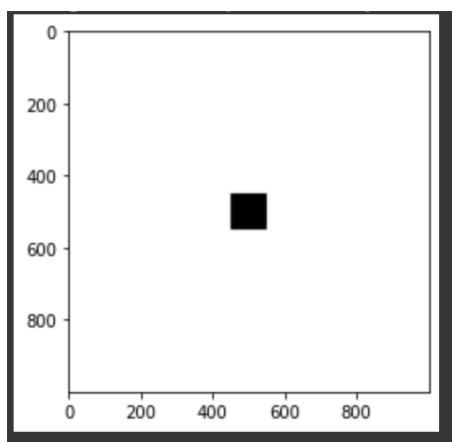
$$Q1.2. \text{ response} = \int_0^{2\pi} \int_0^r r^2 G(x, y, \delta) r dr d\theta$$

$$\begin{aligned}
 &= -\frac{r^2}{D^4} e^{-\frac{r^2}{\sigma^2}} \\
 \Rightarrow & \frac{d}{dr} \left(-\frac{r^2}{D^4} e^{-\frac{r^2}{\sigma^2}} \right) = 0 \\
 \Leftrightarrow & -\frac{d}{dr} \left(\frac{r^2}{D^4} e^{-\frac{r^2}{\sigma^2}} \right) = 0 \\
 \Leftrightarrow & \frac{d}{dr} \left(\frac{r^2}{D^4} e^{-\frac{r^2}{\sigma^2}} \right) = 0
 \end{aligned}$$

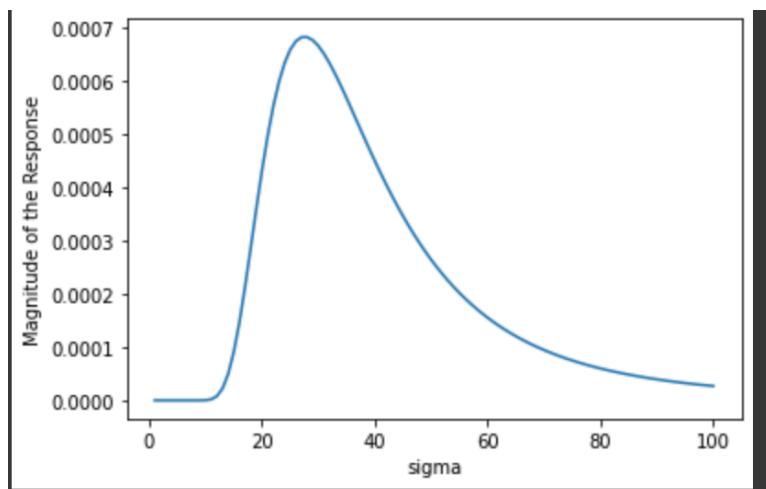
$$\sigma = \frac{1}{4}D$$

Therefore. $\delta = \frac{1}{4}D$ maximise the magnitude of response if we want to detect white circle on a black background.

Q1.3. see CSC420-A3-Q1



The image.



The value of response
correspond to
sigma value .



The maximize sigma value is 28

$$\begin{aligned}
 Q2.1 \quad \det(N - \lambda I) &= \det \begin{pmatrix} I_x^2 - \lambda & I_x I_y \\ I_x I_y & I_y^2 - \lambda \end{pmatrix} \\
 &= (I_x^2 - \lambda)(I_y^2 - \lambda) - I_x I_y I_x I_y \\
 &= I_x^2 I_y^2 - I_x^2 \lambda - I_y^2 \lambda + \lambda^2 - I_x^2 I_y^2 \\
 &= -I_x^2 \lambda - I_y^2 \lambda + \lambda^2 \\
 \Rightarrow \det(N - \lambda I) &= 0 \\
 I_x^2 \lambda + I_y^2 \lambda &= \lambda^2 \\
 \lambda &= (I_x^2 + I_y^2) \lambda \\
 \lambda_1 &= 0, \quad \lambda_2 = I_x^2 + I_y^2
 \end{aligned}$$

Q2.2. if M is positive semi-definite.

Let A be an arbitrary matrix with form $A = (a_1, a_2)$.

WTP: $A^T M A \geq 0$.

$$\begin{aligned}
 A^T M A &= \begin{pmatrix} a_1 \\ a_2 \end{pmatrix} \sum_x \sum_y w(x, y) N(x, y) (a_1, a_2) \\
 &= \sum_x \sum_y w(x, y) \begin{pmatrix} a_1 \\ a_2 \end{pmatrix} N(a_1, a_2)
 \end{aligned}$$

$$\text{Since } \lambda_1, \lambda_2 \geq 0, \quad \begin{pmatrix} a_1 \\ a_2 \end{pmatrix} N(a_1, a_2) \geq 0.$$

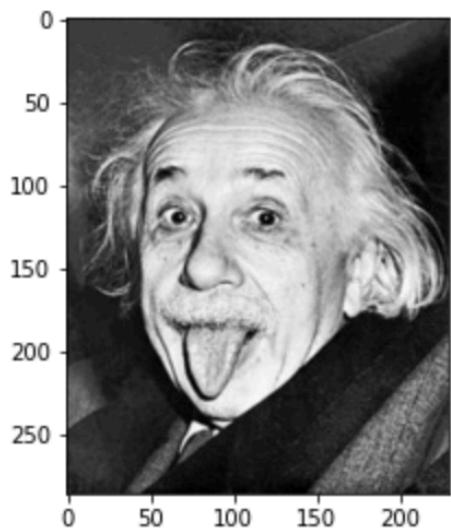
Since $w(x, y) \geq 0$.

$$w(x, y) \begin{pmatrix} a_1 \\ a_2 \end{pmatrix} N(a_1, a_2) \geq 0.$$

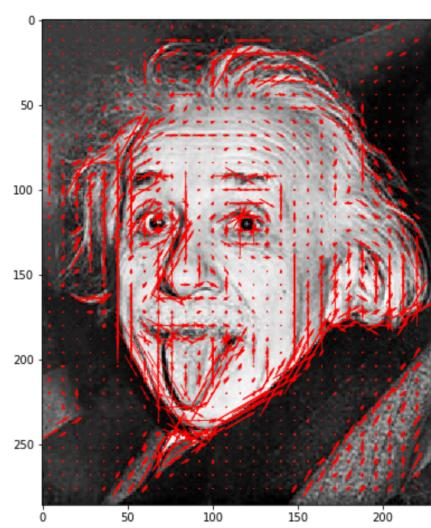
$$A^T M A \geq 0.$$

Therefore M is positive semi-definite.

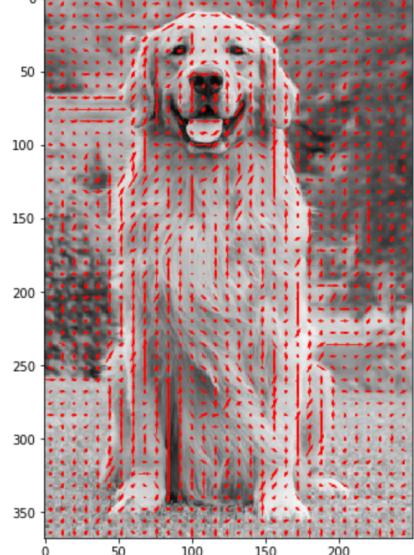
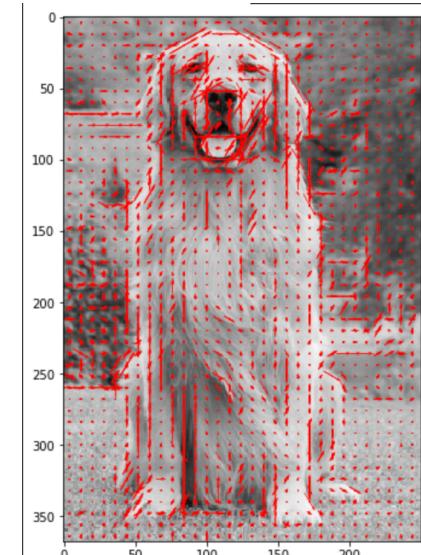
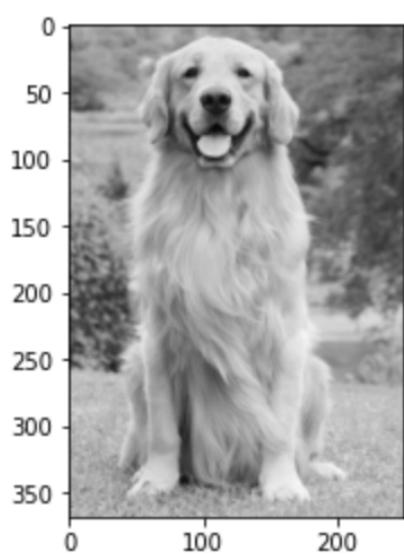
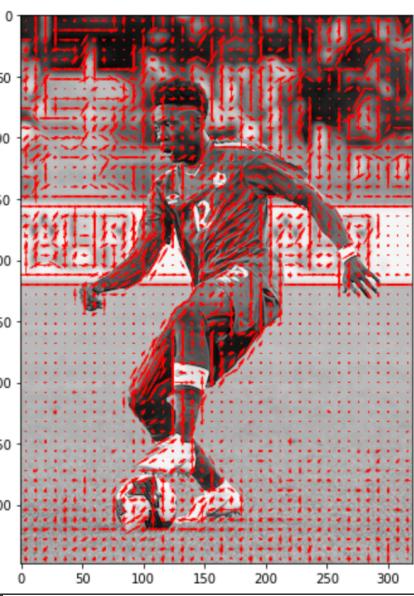
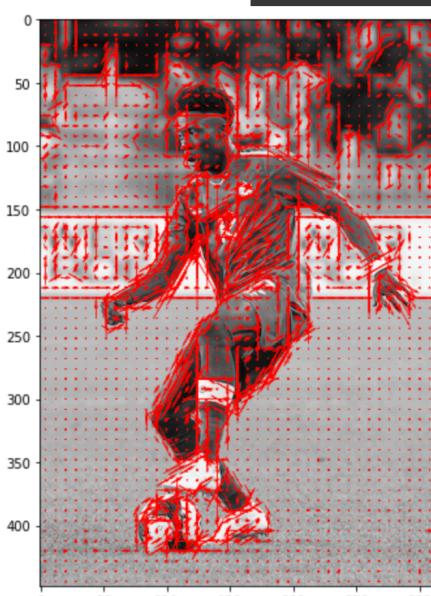
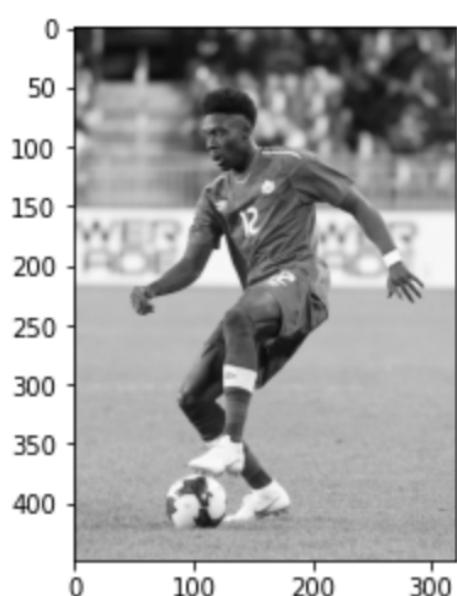
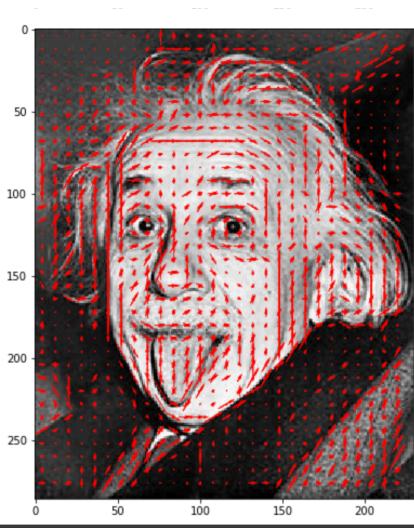
Q3.3 original



accumulated gradient



of occurrence



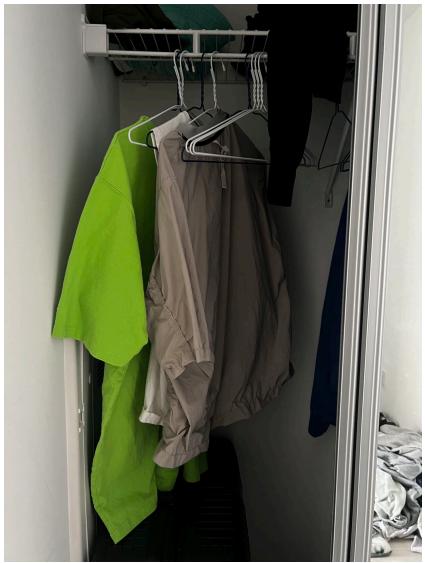
Threshold : $0.03 \times \text{Max C gradient magnitude}$

Cell size : 8

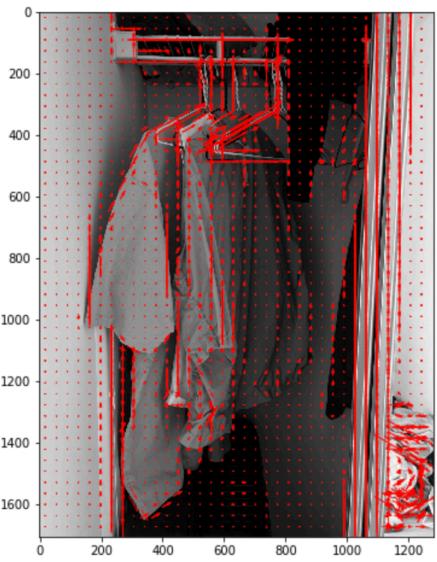
From the above images, we can see that the accumulation method has normally larger vector magnitude compared to the image using occurrence method. Which also interpret that for those more clearly edges (greater gradient difference). The graph will make those edges more noticeable. While for the accumulation method, any edge (no matter how sharp and clear) will possess equal effect on the histogram.

Q3.4.

Image without flashlight



Standard HOG



Normalized HOG.

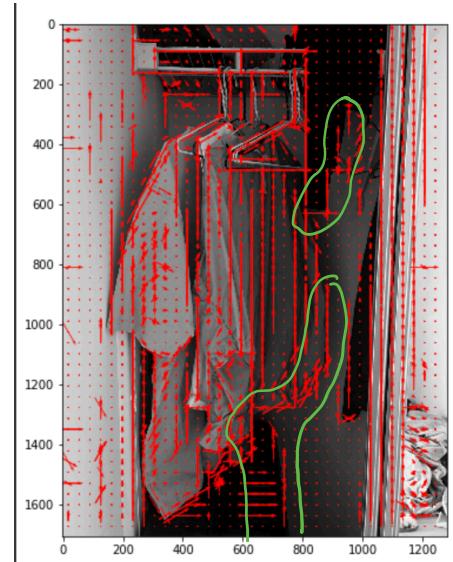
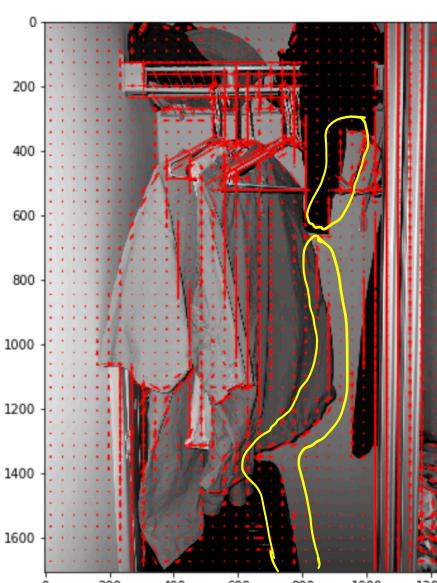


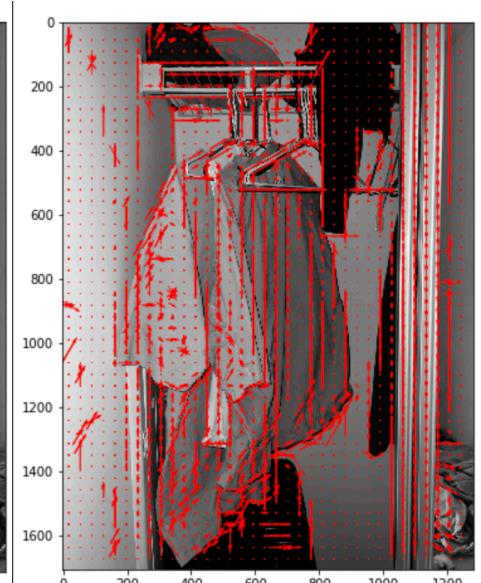
Image with flashlight.



Standard HOG



Normalized HOG.



For normalized HOG . I used the # of occurrence approach.

(since I don't want the extent of difference or edge affect my result).

Threshold : $0.03 \times \text{Max C gradient magnitude}$

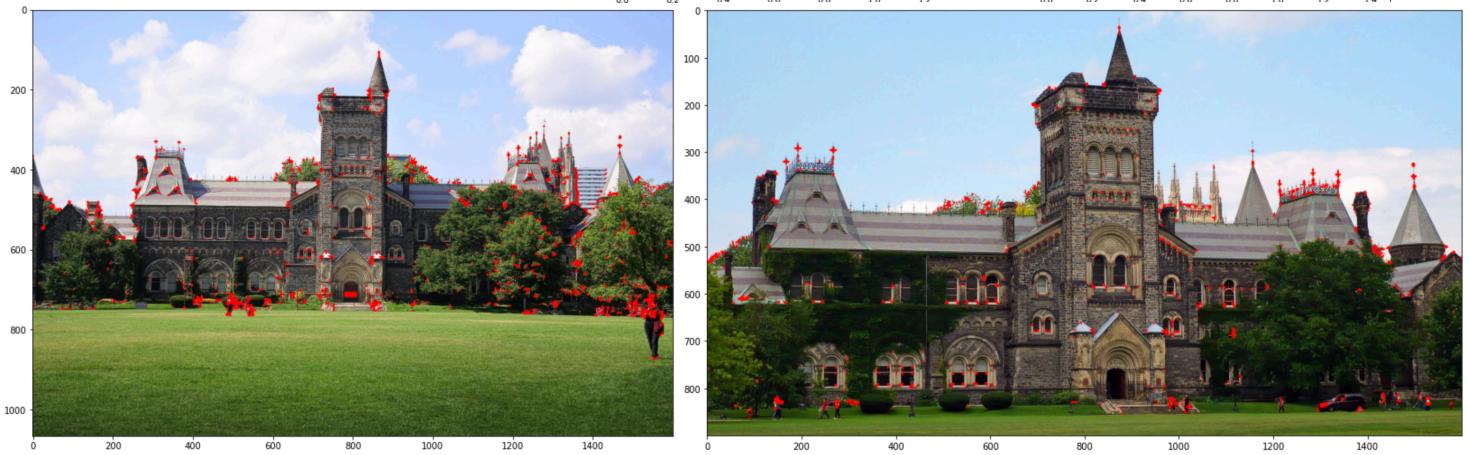
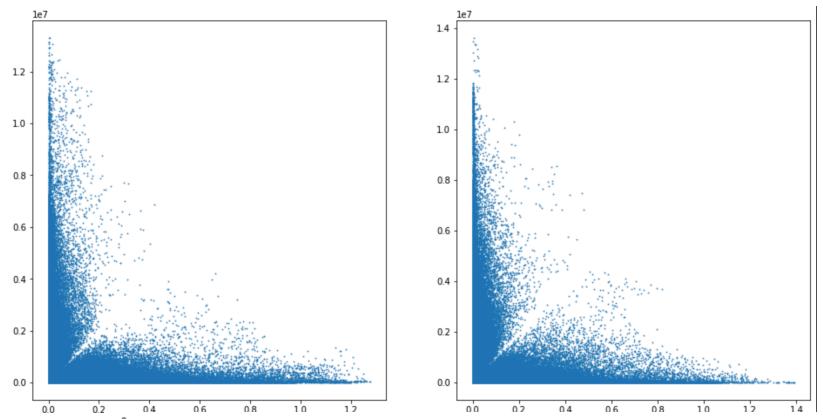
Cell size : 36

By comparing flash / without flash images. Look at the yellow circles that I highlighted, Under the flashlight. the edge of object under a shadow environment will be easily detected due to the light increase the proportion of gradient magnitude on edge.

Now let's compare the normalized hog of the image without flashlight, By looking at green area highlighted. The edges we under shadow environment that we cannot detect before are now noticeable. Therefore normalization is a great approach, it can detect more details of edges even under insufficient light environment than the standard HOG.

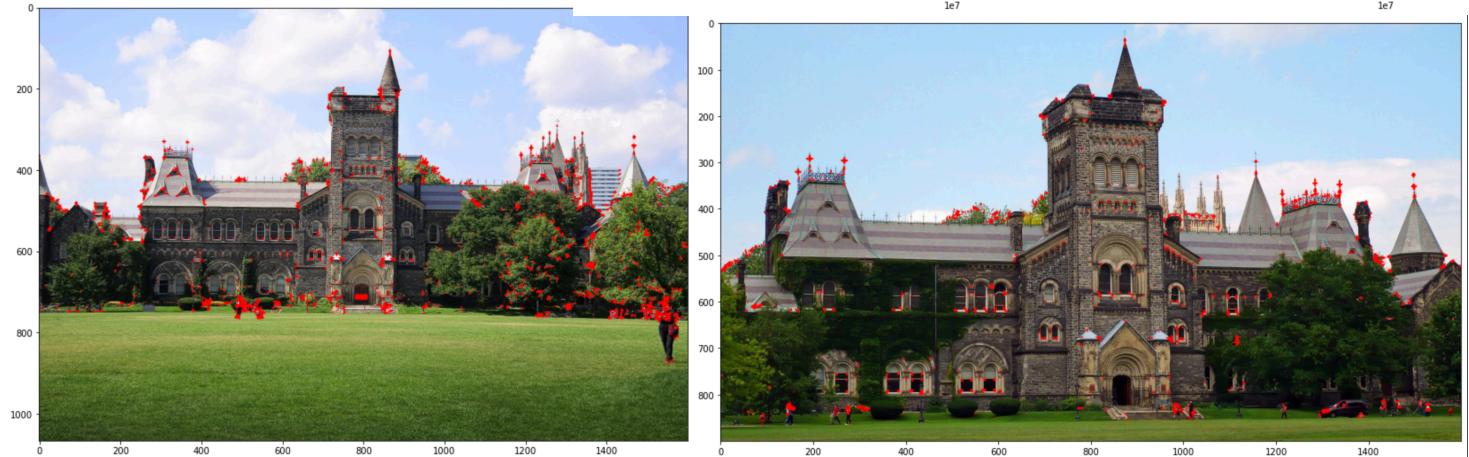
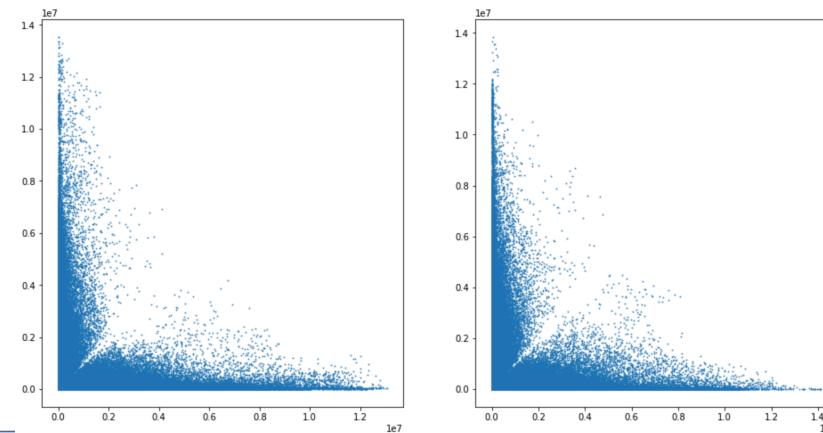
Q4. 1.2.3.

Scatter plot $\sigma = 6$



Q4.4.

Scatter plot. $\sigma = 60$



The $\sigma=60$ compared with $\sigma=6$ we can see that there are more corner details are detected. Since larger σ means larger size of the blur filter, and make the eigen values scattered more isolated.