

PA4 REPORT

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In the solution, I firstly created a struct for node called “**myNode**”. In this node I have:

- ID, size, index and next (which shows the next node).
- Constructor for the myNode.

Then I defined the class “**HeapManager**”, which the name was given in the test cases. This class has the followings in its public part:

- Constructor
- myAlloc
- myFree
- print
- initHeap

In its private part, it has the head node, which keeps the linked list. I also defined the mutex here.

Here is the implementation of the rest of the functions in allocator.cpp as a pseudocode:

Define **HeapManager** constructor (makes the head NULL and initializes the mutex)

Define **initHeap**(int size)

Mutex lock (even though in the test cases we don't need a mutex for initHeap, I put it there just for it may be needed)

Creating the node with the given size, ID = -1, index=0 and next=NULL.

Mutex unlock

Define **myMalloc**(int ID, int size)

Mutex lock

Initialize “search” node as the “head” node

Initialize “prev” node as NULL

WHILE search != NULL

IF search's ID != -1 or search's size < size:

Assign search node to prev

Assign search->next to search

ELSE

Break

IF search is NULL:

Print allocating error message

Print linked list

Mutex unlock

Return -1

ELSE

IF size == search->size:

```
Assign search->ID to ID given as parameter
Print allocation message and linked list
Unlock mutex
Return search->index
```

ELSE

```
Define a new myNode with the given parameters ID, size, search -
>index and "search" as next node.
```

```
IF prev is NULL:
```

```
    Assign newNode to head
```

```
ELSE:
```

```
    Assign newNode to prev->next
```

```
Increment search->index with size
```

```
Decrement search->size with size
```

```
Print allocation message and linked list
```

```
Mutex unlock
```

```
Return newNode->index
```

Define **myFree**(int ID, int index)

```
    Mutex lock
```

```
    Initialize "search" node as the "head" node
```

```
    Initialize "prev" node as NULL
```

```
    WHILE search != NULL:
```

```
        IF search->ID equal to ID and search->index equal to index:
```

```
            Make search->ID = -1
```

```
        IF prev != NULL and prev->ID == -1:
```

```
            Add search->size to prev->size
```

```
            Make prev's next equal to search->next
```

```
            delete "search"
```

```
            Assign prev to search
```

```
        IF search->next != NULL and search->next->ID == -1:
```

```
            Add search->next->size to search->size
```

```
            Define a new node "newNode" and assign it to search->next
```

```
            Make search's next equal to nextNode's next
```

```
            Delete nextNode
```

```
Print freeing message and linked list
```

```
Unlock mutex
```

```
Return 1
```

ELSE

```
Update prev as search
```

```
Update search as search->next
```

```
Print freeing error message and print linked list
Unlock mutex
Return -1
```

Define **print()**

```
Create printPtr equal to the head node
WHILE printPtr is not equal to NULL:
    Print node's ID, size, index
    IF printPtr's next is not NULL:
        Print "---"
    Update printPtr as printPtr->next
Print new line
```

For the locking mechanism, I used mutex. I initialized it in the class constructor and used the lock in the critical sections (such as myFree and myAlloc, so that their operations are not interrupted). I did not use it in the print function, since that function is used inside the other functions, and their atomicity were guaranteed with the mutex lock. The mutex is released at the end of these critical sections.

The atomicity is guaranteed by locking the sections in which shared data (such as linked list) were updated. By doing that, race conditions are prevented.