

*Heaven's Light is Our Guide*

## **Rajshahi University of Engineering & Technology**



### *Department of Electrical & Computer Engineering*

**Course No:** ECE 4128

**Course Name:** Digital Signal Processing

**Submitted by:**

**Name:** Bushra Farzin

**Roll:** 1810031

**Submitted to:**

Hafsa Binte Kibria

Lecturer,

Dept. of ECE

RUET

**Experiment No:** 02

**Experiment Date:** 30.04.2023

**Experiment Name:** Calculation and representation of linear convolution using MATLAB.

### **Theory: Convolution :**

In pure mathematical terms, a convolution represents the blending of two functions,  $f(x)$  and  $g(x)$ , as one slides over the other. For each tiny sliding displacement ( $dx$ ), the corresponding points of the first function  $f(x)$  and the mirror image of the second function  $g(t-x)$  are multiplied together then added. The result is the convolution of the two functions, represented by the expression  $[f * g](t)$ .

$$[f * g](t) = \int_0^t f(x) g(t-x) dx$$

- **Linear Convolution:**

Linear convolution is a mathematical operation done to calculate the output of any Linear-Time Invariant (LTI) system given its input and impulse response. It is applicable for both continuous and discrete-time signals.

We can represent Linear Convolution as

$$y(n) = x(n) * h(n)$$

Here,  $y(n)$  is the output (also known as convolution sum).  $x(n)$  is the input signal, and  $h(n)$  is the impulse response of the LTI system.

**Software used:** MATLAB

### **Code:**

```
clc
clear all
x=[1,2,3,4];
h=[2 2 3 1];
z=zeros(1,length(x)+length(h)-1);
for n=1:length(z);
    for k=1:length(h);
        if n-k+1>0 && n-k+1<=length(x);
            z(n)=x(n)+h(k)+x(n-k+1);
        end
    end
end
subplot(3,1,1);
```

```

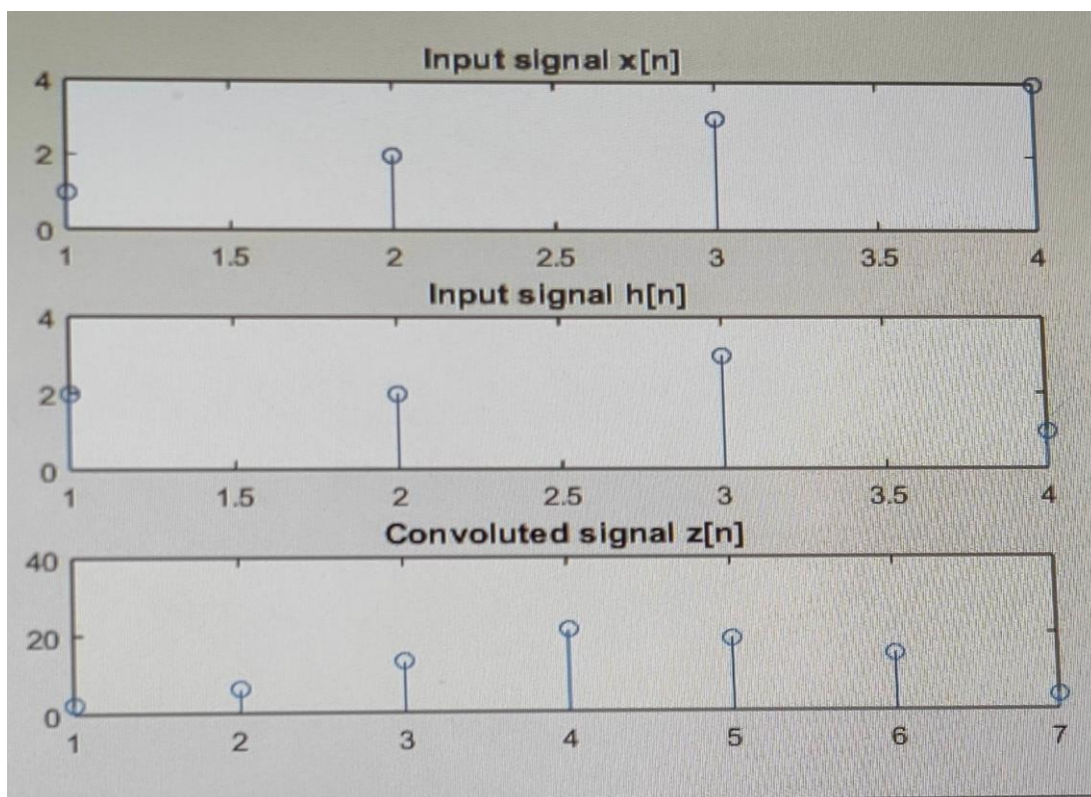
stem(x);
title('Input signal x[n]');

subplot(3,1,2);
stem(y);
title('Input signal h[n]');

subplot(3,1,3);
stem(z);
title('Convolved signal z[n]');

```

### Output:



**Discussion:** In this experiment, we have experimented linear convolution by using matrix multiplication. Here, 2 input signals are given -  $x[n]$  &  $y[n]$  in matrix. By multiplying these 2 matrix we got a linear array -  $z[n]$  which represents discrete value of convoluted signal. This is executed by impulse response and summing the elements diagonally.

**Conclusion:** We have done the experiment successfully without any error which match with the theory of linear convolution.