

# SEPPi'S TOPOLOGY NOTES

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# Chapter 1

## Manifolds

### 1.1 Topological Manifolds

### 1.2 Smooth Manifolds

### 1.3 Cobordism

### 1.4 Smooth Maps

If  $M$  and  $N$  are topological manifolds, the natural notion of a morphism is  $f : M \rightarrow N$  continuous. Then two topological manifolds  $M, N$ , are equivalent if there exists a homeomorphism  $f : M \rightarrow N$ . Topological manifolds together with continuous maps form a category.

**Definition 1.4.1.** A **category** consists of objects  $C$  and arrows  $A$ . Each arrow goes from some object  $C$  (the source) to another object (the target). These arrows are often called **morphisms**. Furthermore, for each object  $c \in C$  there exists a morphism  $1_c \in A$  such that the source and target of  $1_c$  are both  $c$ . In addition, morphisms can be composed and composition satisfies additivity. For  $x, y \in C$  we write  $\text{Hom}(x, y) \subset A$  as the set of morphisms from  $x$  to  $y$ . Stated this way, composition becomes

$$\circ : \text{Hom}(x, y) \times \text{Hom}(y, z) \rightarrow \text{Hom}(x, z)$$

$$\circ : (f, g) \mapsto g \circ f$$

**Example 1.4.2.** The category of topological manifolds is defined by  $C$  being the class of all topological manifolds with arrows  $A$  being continuous maps between them.

For smooth manifolds, we need the correct notion of a morphism.

**Definition 1.4.3.** A map  $f : M \rightarrow N$ ,  $M, N$  smooth manifolds, is called **smooth** when for each chart  $(U, \varphi)$  for  $M$  and each chart  $(V, \psi)$  for  $N$ , the composition

$$\psi \circ f \circ \varphi^{-1} \in C^\infty(\varphi(U), \mathbb{R}^n).$$

The set of smooth maps from  $M$  to  $N$  is denoted  $C^\infty(M, N)$ . A smooth map with smooth inverse is called a **diffeomorphism**.

**Lemma 1.4.4.** *If  $g : L \rightarrow M$  and  $f : M \rightarrow N$  are smooth maps, then so is  $f \circ g : L \rightarrow N$ .*



## Chapter 2

# Tangent Bundle





## Chapter 3

# Transversality



## Chapter 4

# Vector Fields



## Chapter 5

# Differential Forms