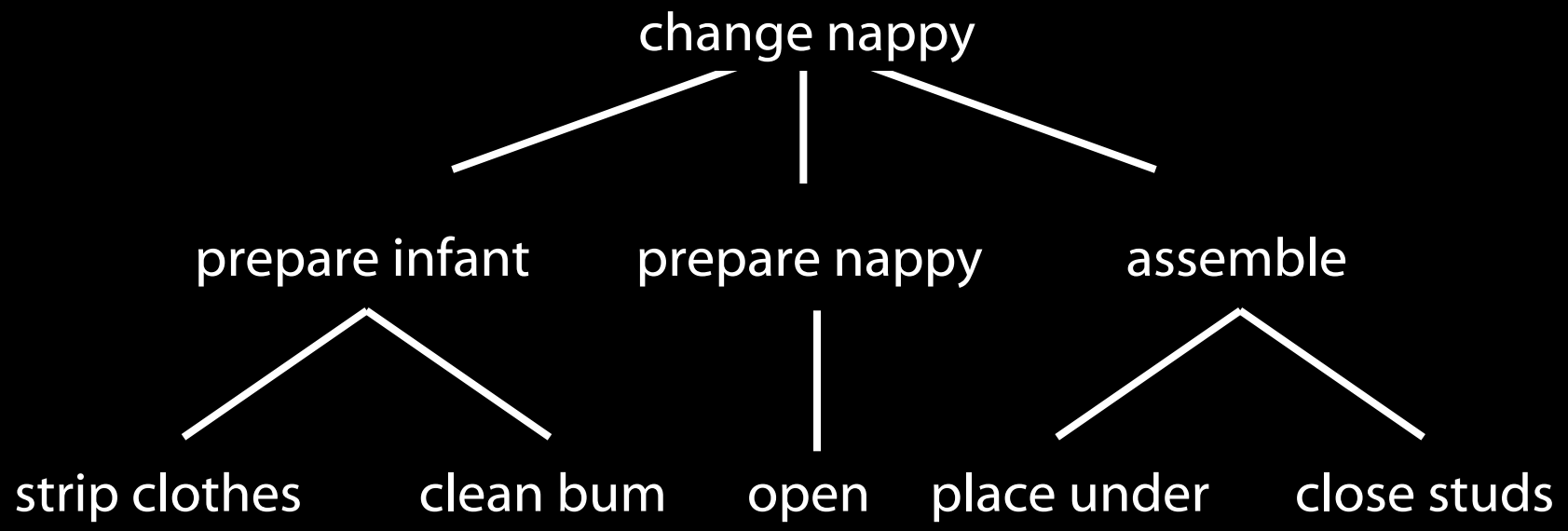
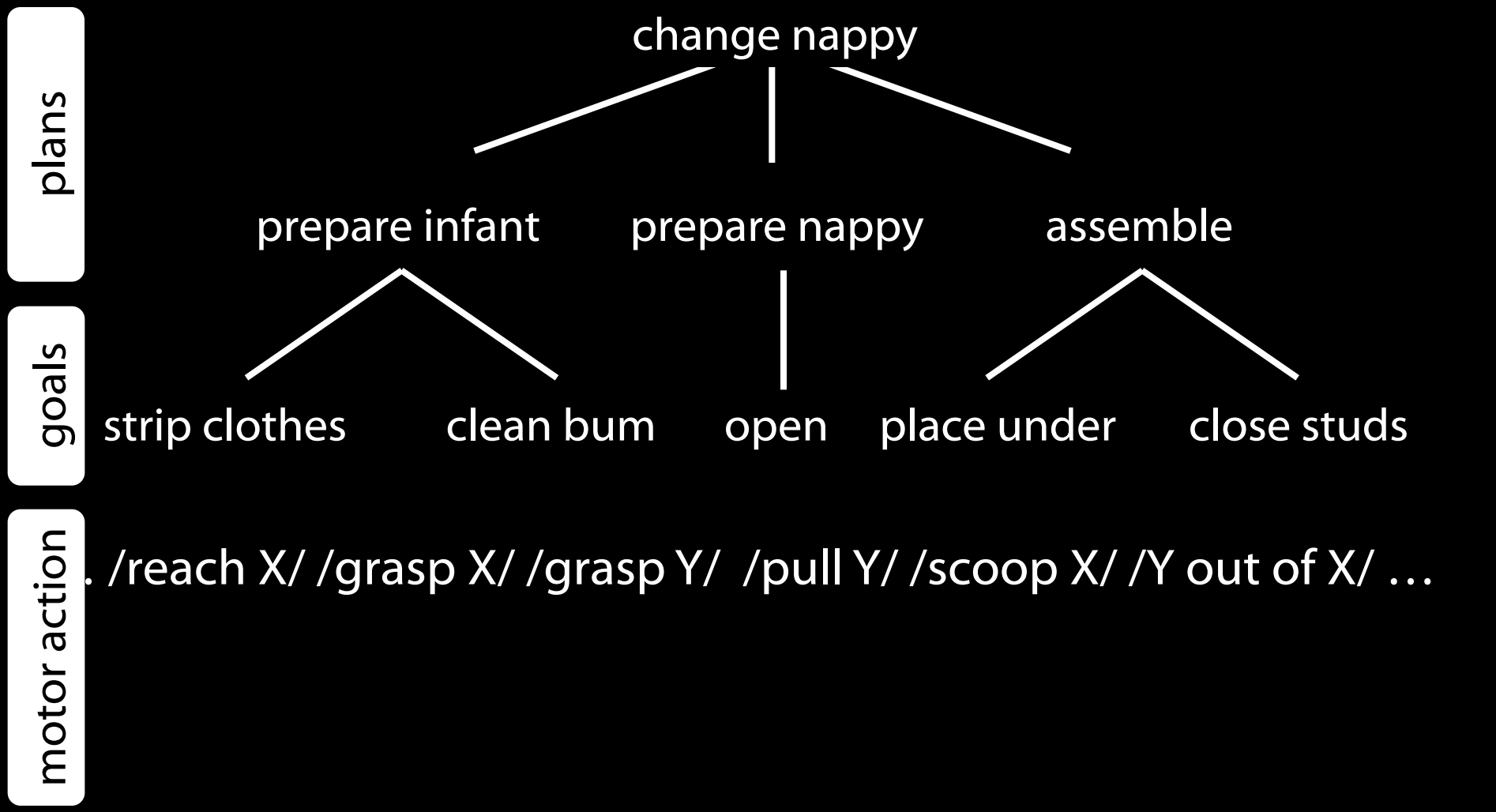
change nappy

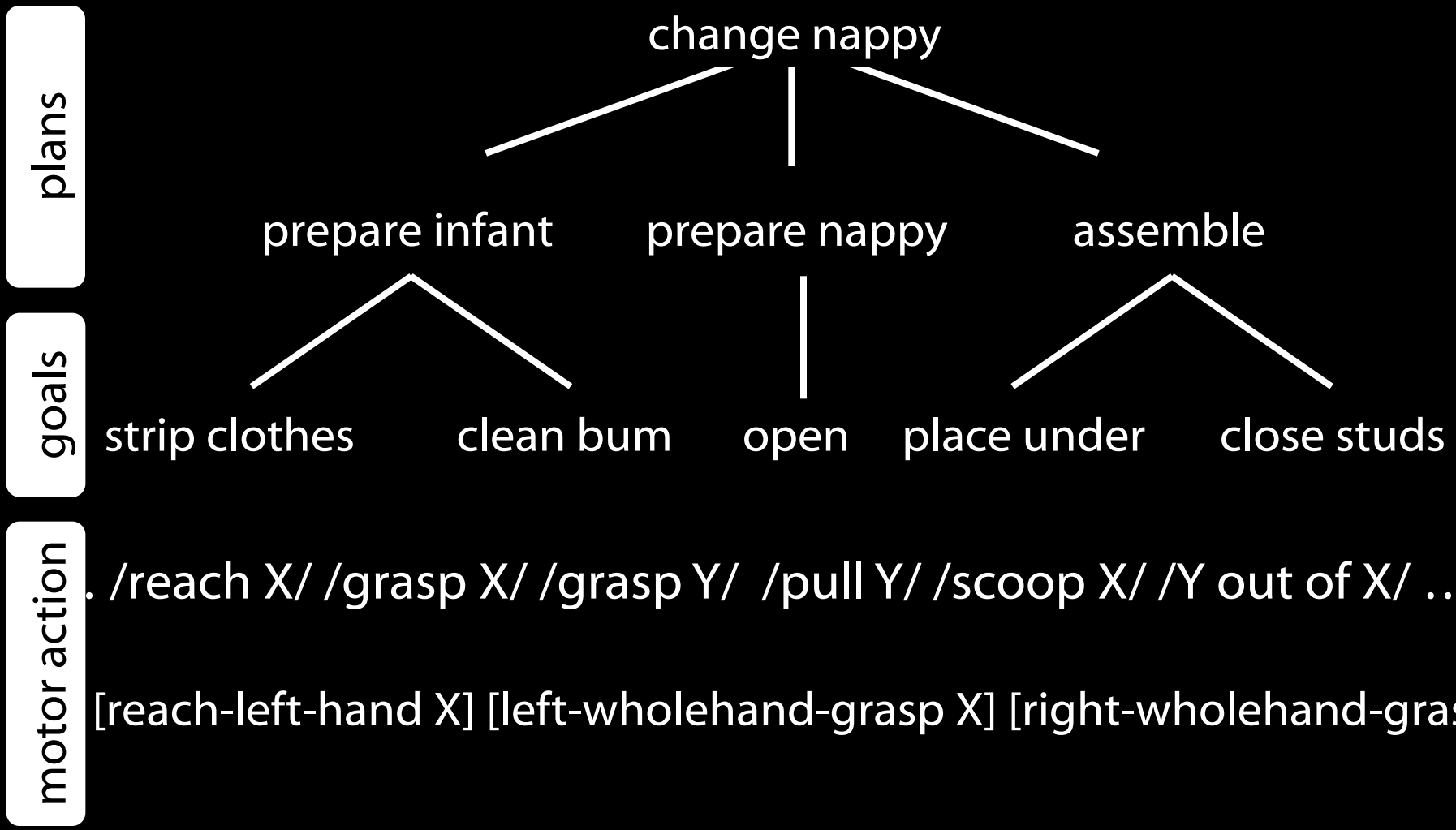
plans

plans

goals


change nappy
prepare infant
prepare nappy
assemble
strip clothes
clean bum
open
place under
close studs


plans
goals
motor action
change nappy
prepare infant
prepare nappy
assemble
strip clothes
clean bum
open
place under
close studs
. /reach X/ /grasp X/ /grasp Y/ /pull Y/ /scoop X/ /Y out of X/ …


plans
goals
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[reach-left-hand X] [left-wholehand-grasp X] [right-wholehand-grasp …

plans

goals

motor action

motion

change nappy

prepare infant

prepare nappy

assemble

strip clothes

clean bum

open

place under

close studs

. /reach X/ /grasp X/ /grasp Y/ /pull Y/ /scoop X/ /Y out of X/ …

[reach-left-hand X] [left-wholehand-grasp X] [right-wholehand-grasp …

Image adapted from: Rizzolatti, Giacomo, and Giuseppe Luppino. 2001. The Cortical Motor System. *Neuron* 31, no. 6 (September 27): 889-901. doi:10.1016/S0896-6273(01)00423-8.

plans

goals

motor action

motion

change nappy

prepare infant

prepare nappy

assemble

strip clothes

clean bum

open

place under

close studs

. /reach X/ /grasp X/ /grasp Y/ /pull Y/ /scoop X/ /Y out of X/ …

[reach-left-hand X] [left-wholehand-grasp X] [right-wholehand-grasp …

motor emulation

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plans

goals

motor action

motion

change nappy

prepare infant

prepare nappy

assemble

strip clothes

clean bum

open

place under

close studs

sequential probabilities

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motor emulation

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plans

goals

motor action

motion

change nappy

prepare infant

prepare nappy

assemble

hierarchical patterns

strip clothes

clean bum

open

place under

close studs

sequential probabilities

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[reach-left-hand X] [left-wholehand-grasp X] [right-wholehand-grasp …

motor emulation

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plans

goals

motor actio

motion

change nappy

prepare infant

prepare nappy

assemble

strip clothes

clean bum

open

place under

close studs

object-directed actions

. /reach X/ /grasp X/ /grasp Y/ /pull Y/ /scoop X/ /Y out of X/ …

[reach-left-hand X] [left-wholehand-grasp X] [right-wholehand-grasp …

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plans

goals

motor action

motion

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prepare infant

prepare nappy

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clean bum

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Your *field* = a set of objects related to you by proximity, orientation, lighting and other factors

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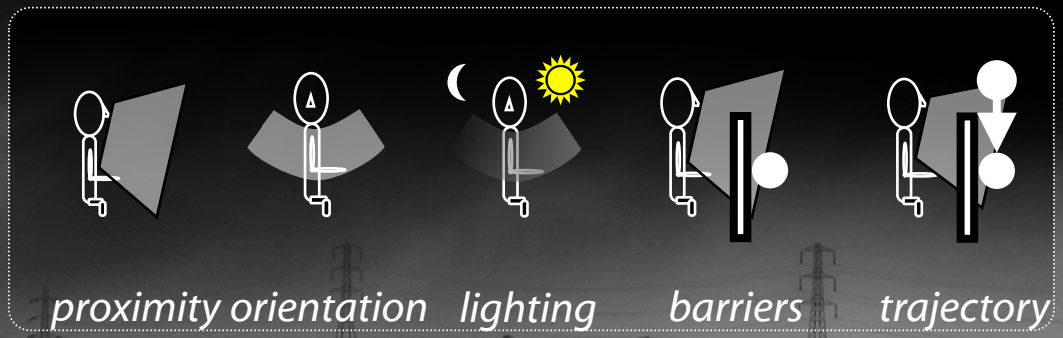

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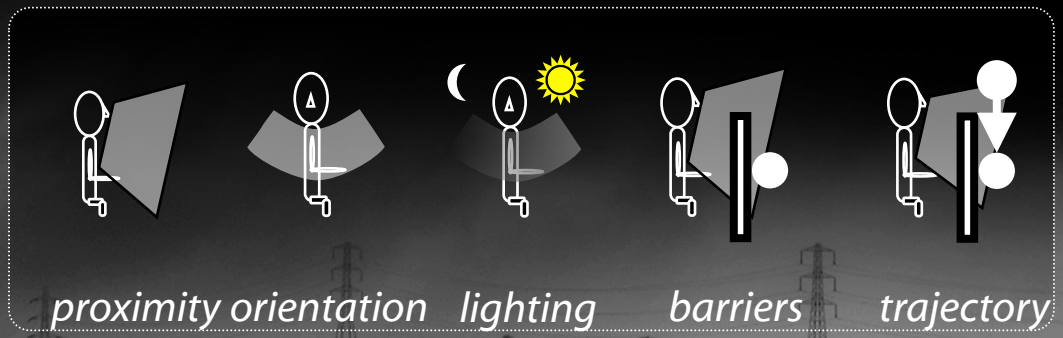

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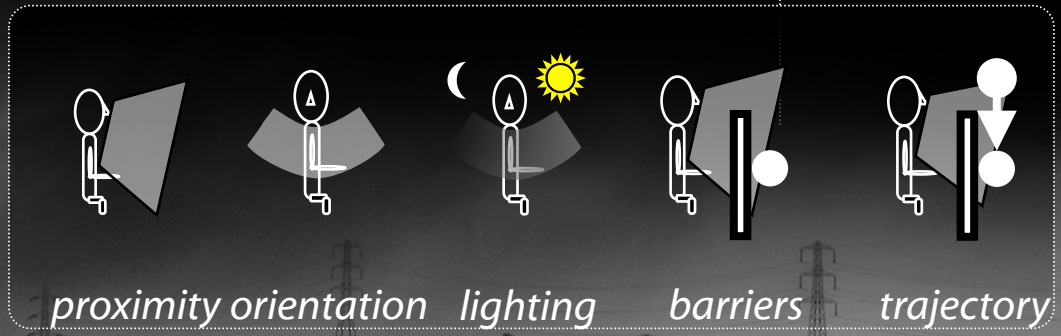

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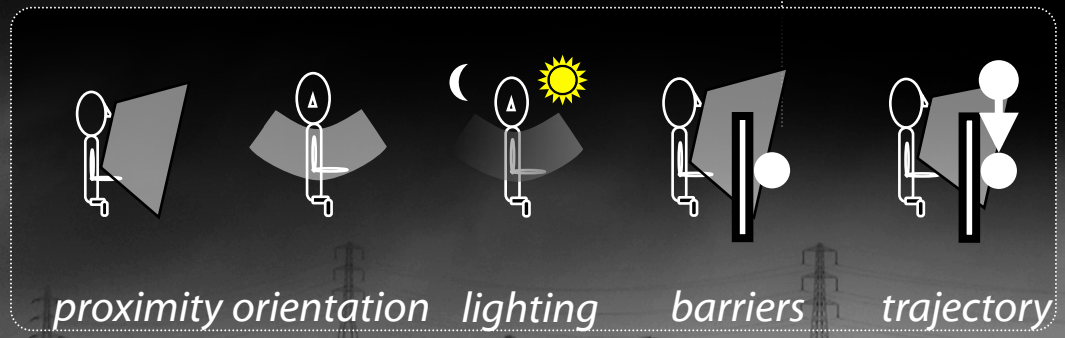

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xperimenter

ubject

Your *field* = a set of objects related to you by proximity, orientation, lighting and other factors

"children could … think about what the other person saw rather than what they saw"

(Flavell, Shipstead & Croft 1978: 1210)

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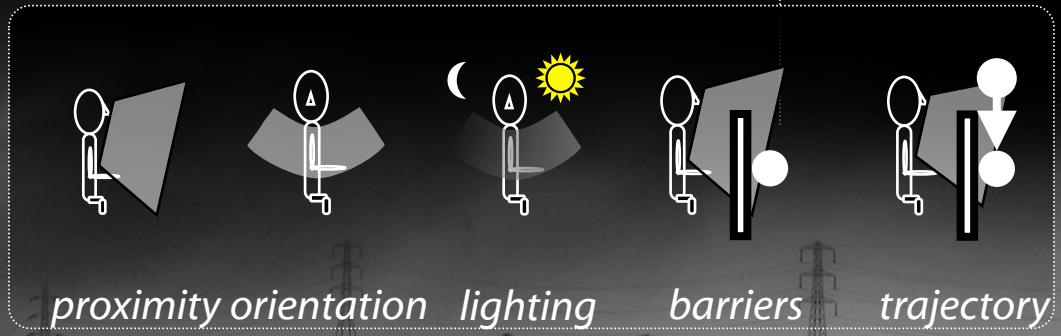
E xperimenter

S ubject



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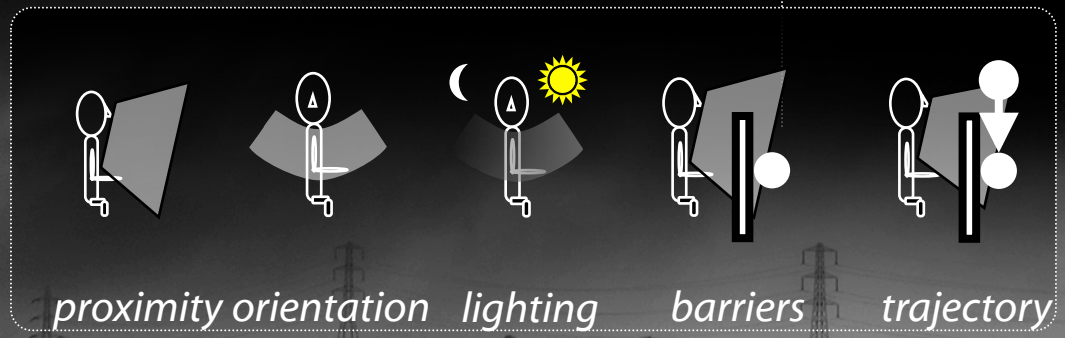

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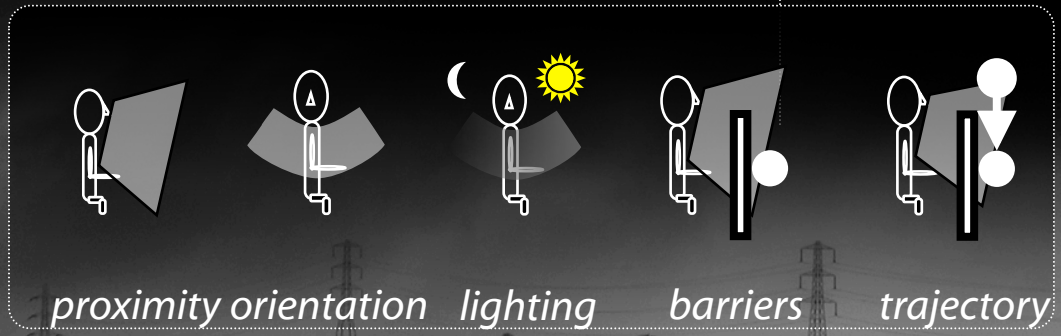

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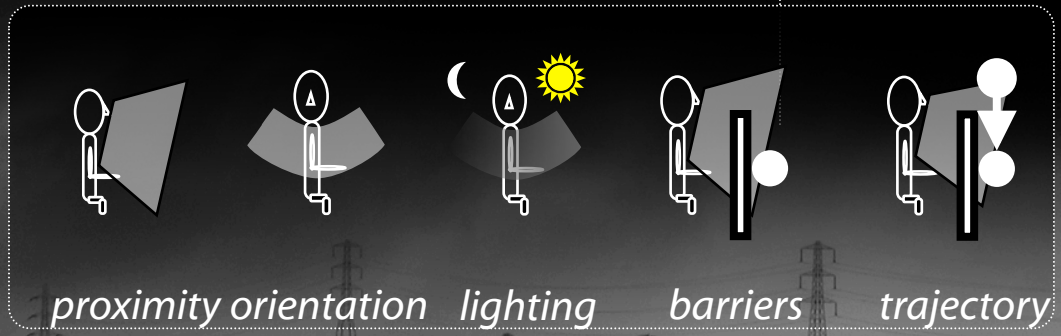

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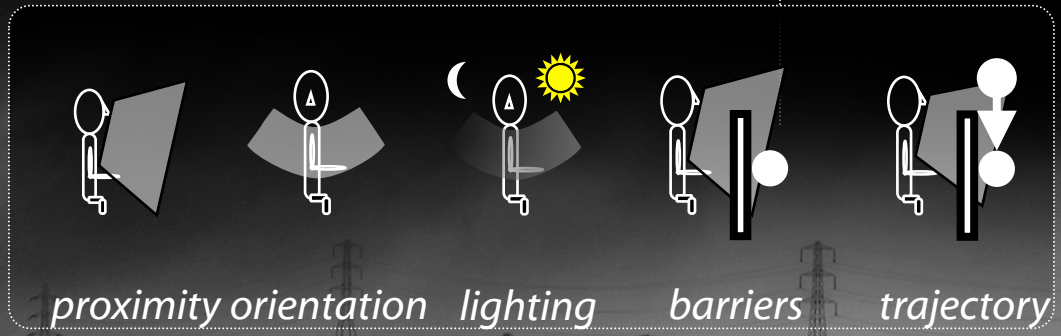
Principle 4: correct registration is a condition of *successful* action.



source: Liszkowski et al (2008)

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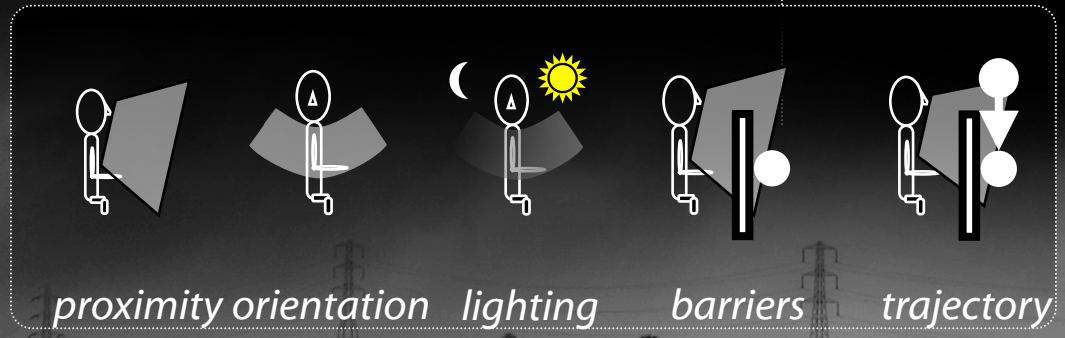

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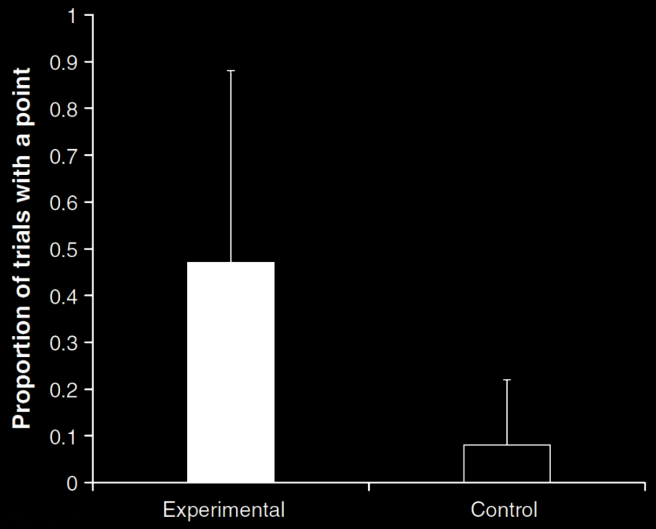

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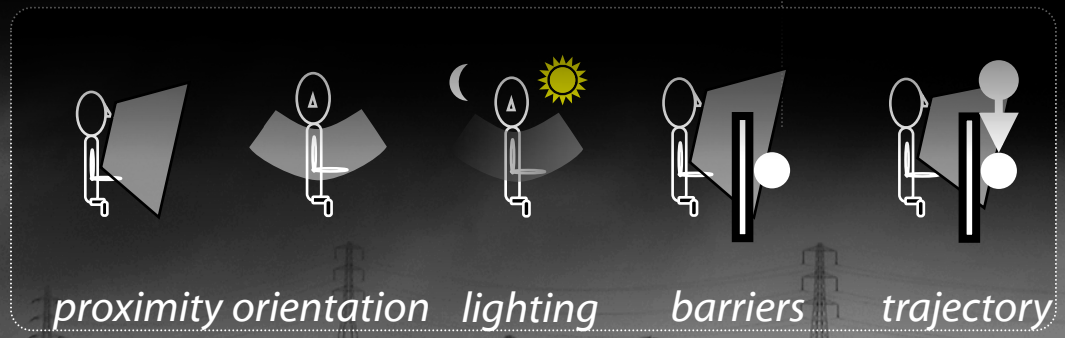
"Helping by informing inextricably involves … an understanding of others' goals and … of others' ignorance."
(Liszkowski, Carpenter & Tomasello 2008: 738-9)



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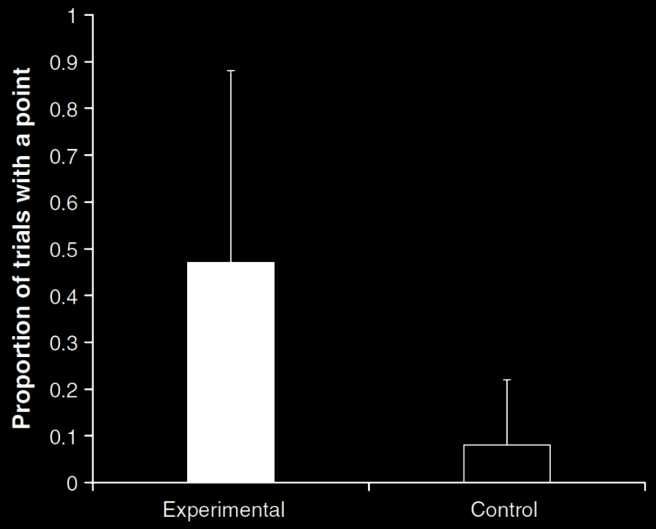

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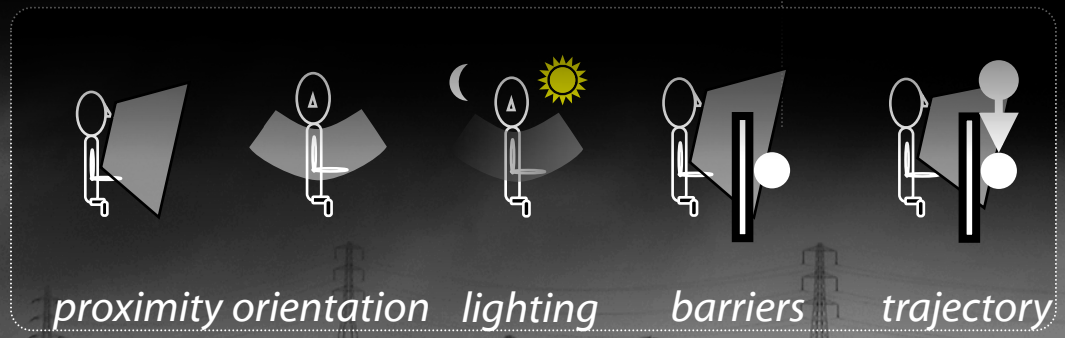

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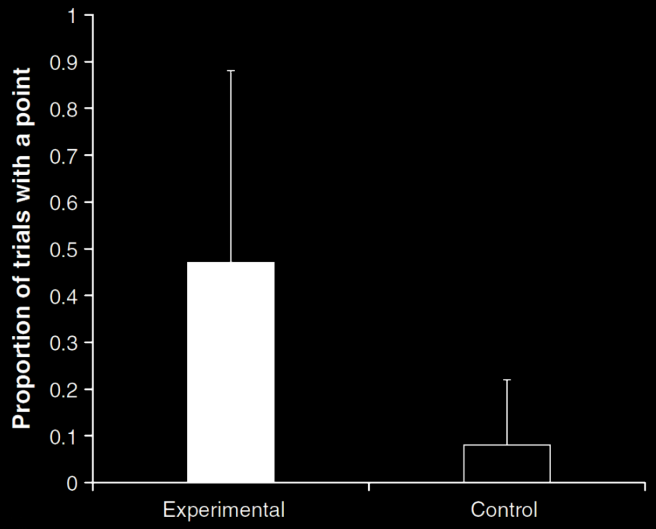

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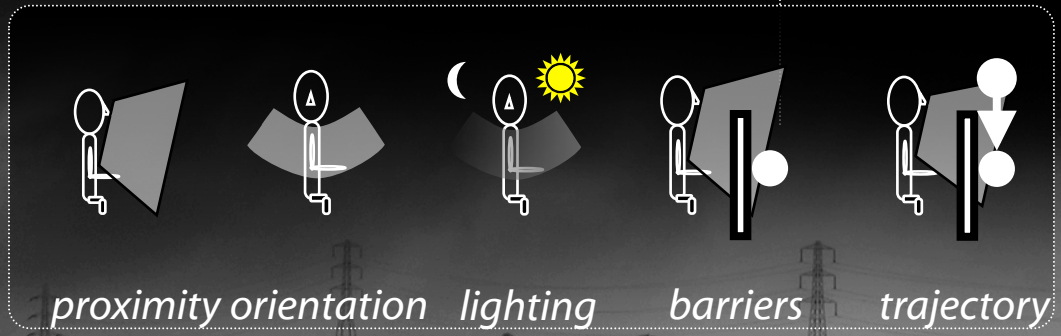

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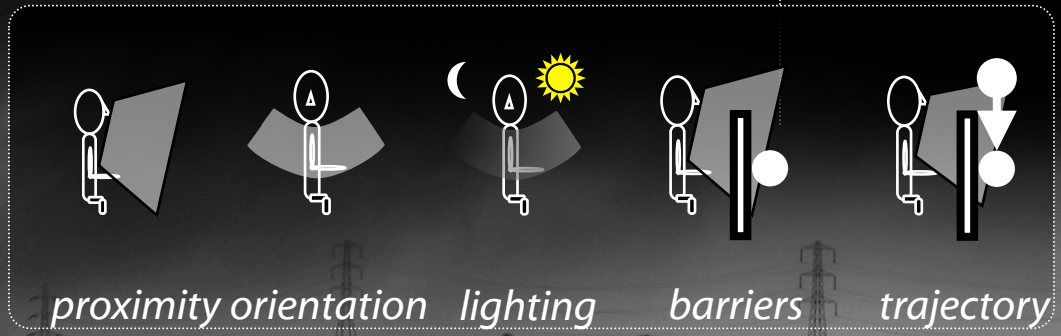
Principle 5



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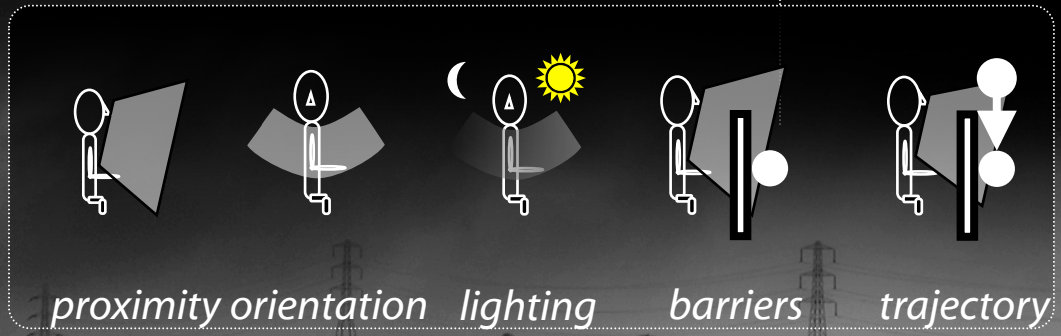

source Träuble, Marinovic, & Pauen (2010)

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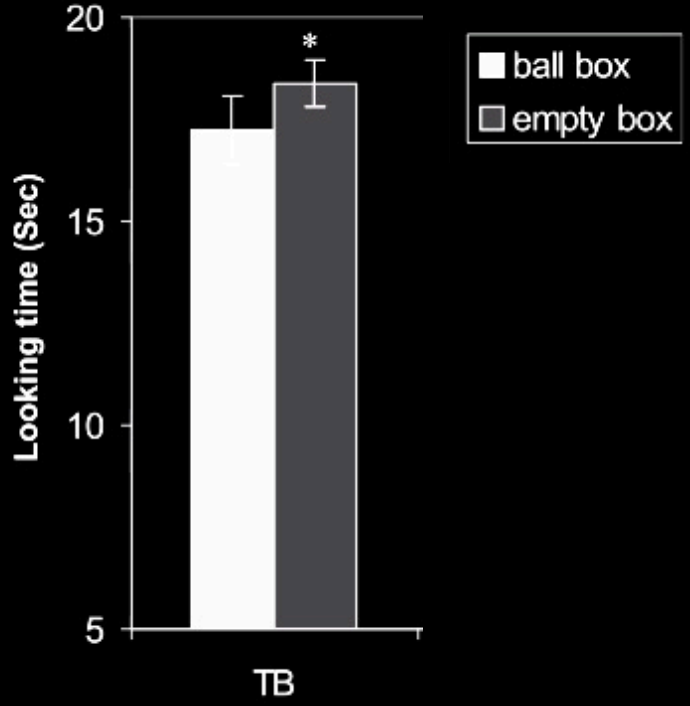

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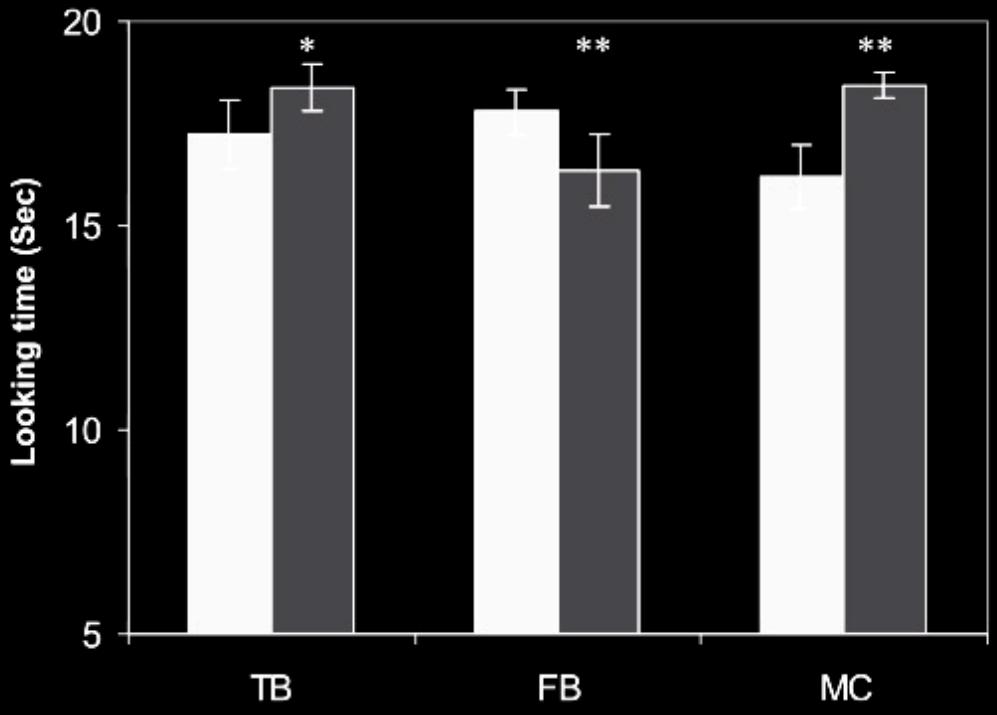

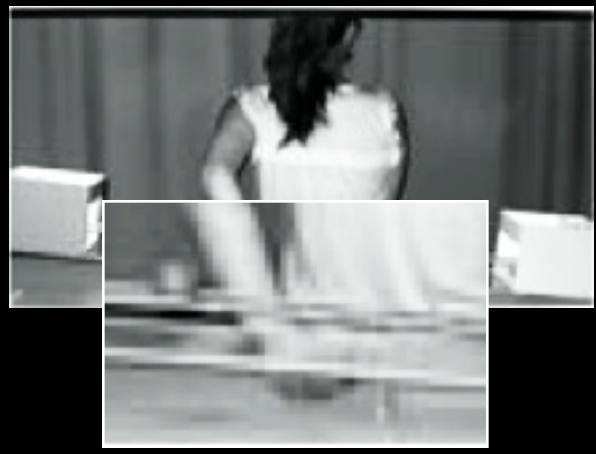

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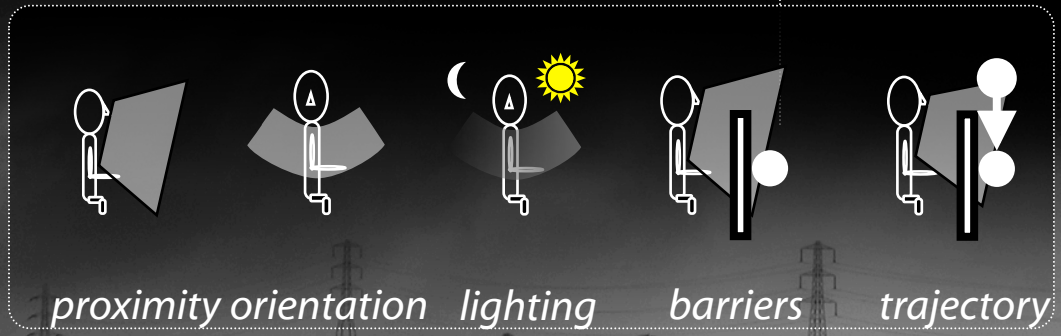

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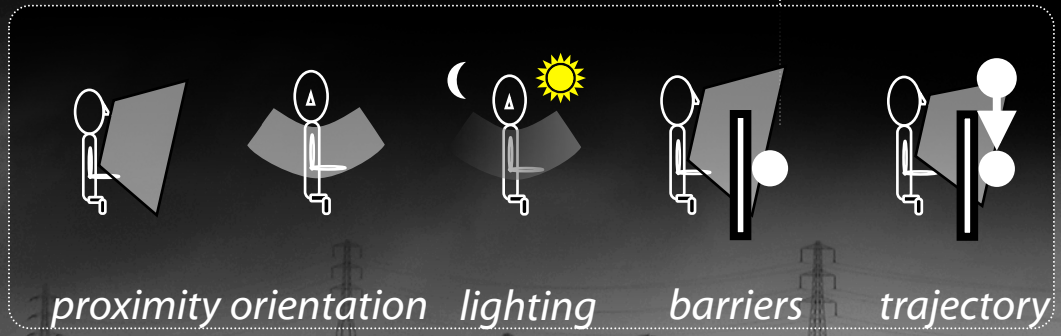

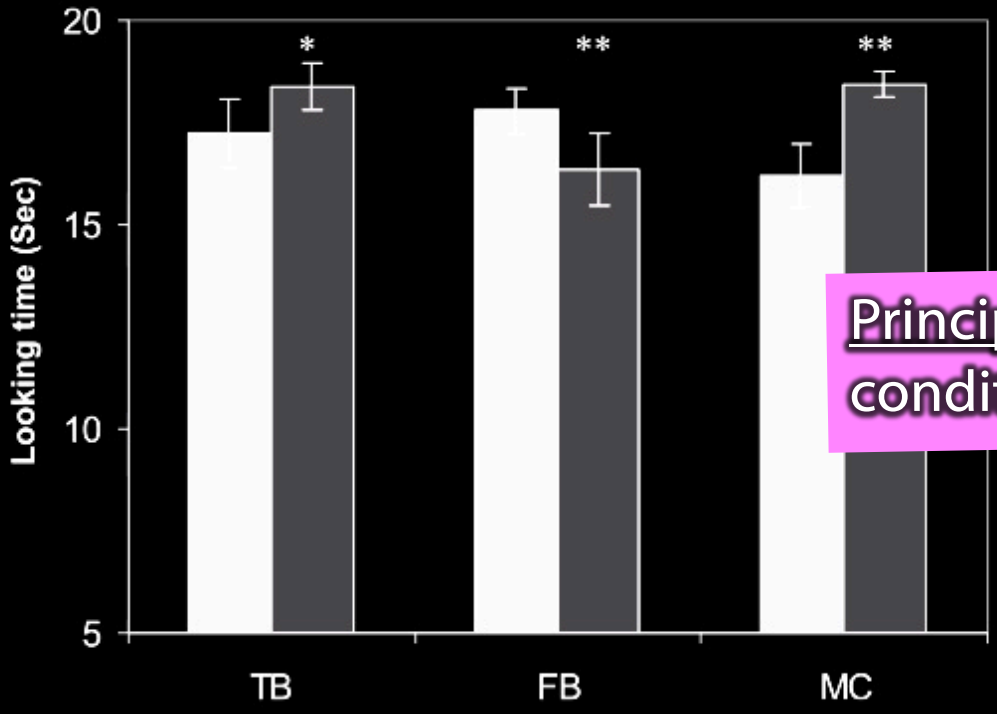

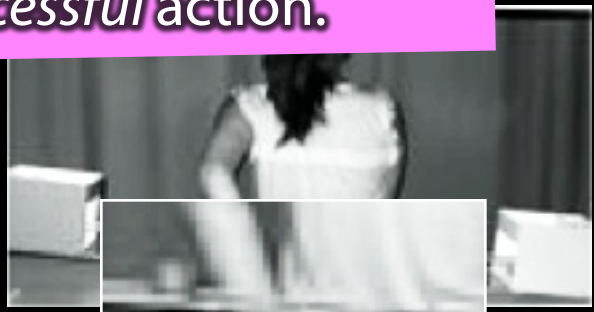

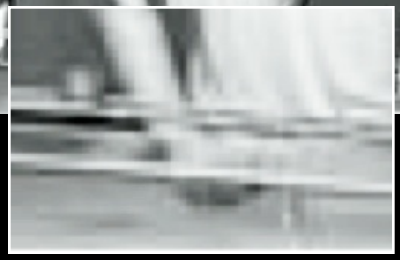

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