

Time Series Analysis

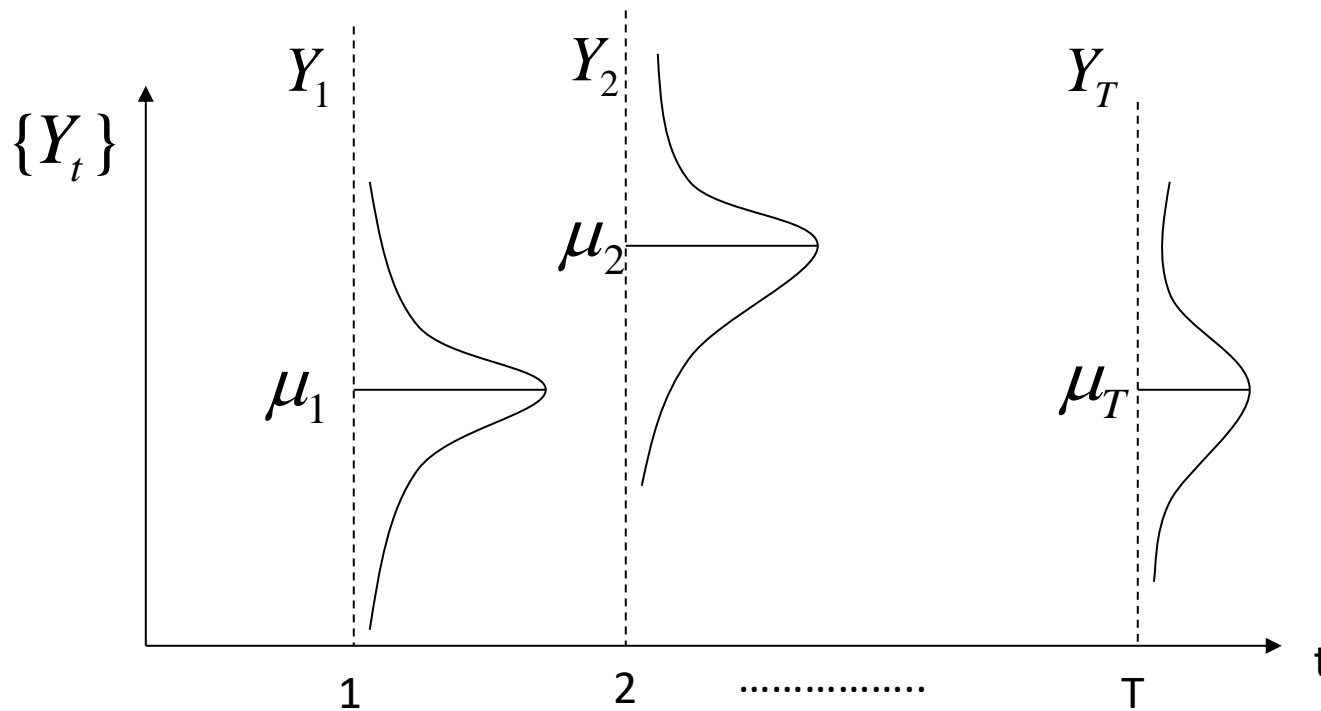
DSSG

8 Aug. 2016

What is a Time Series?

- **Def:** Stochastic Process

$\{Y_t\} = \{Y_1, Y_2, \dots, Y_T\}$ = Collection of random variables.

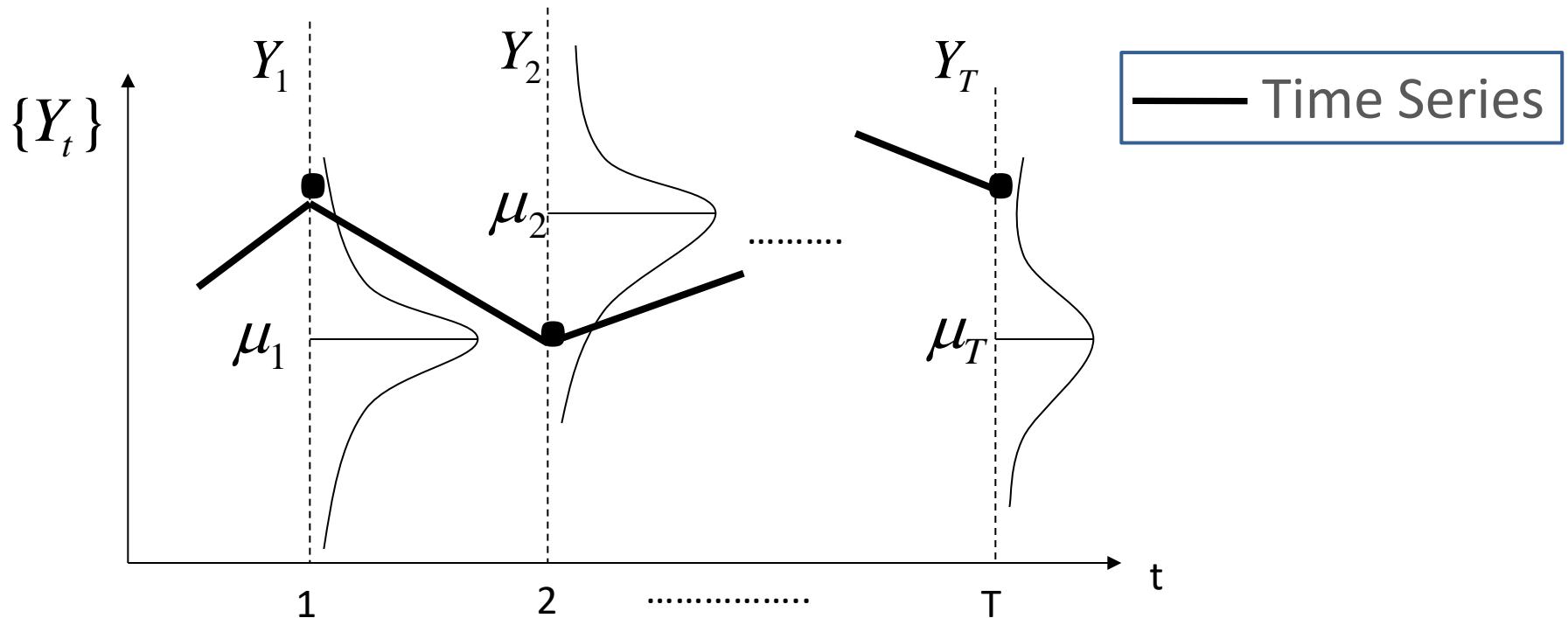


Each R.V can have a different μ , σ , and pdf.

What is a Time Series?

- **Def:** Time Series

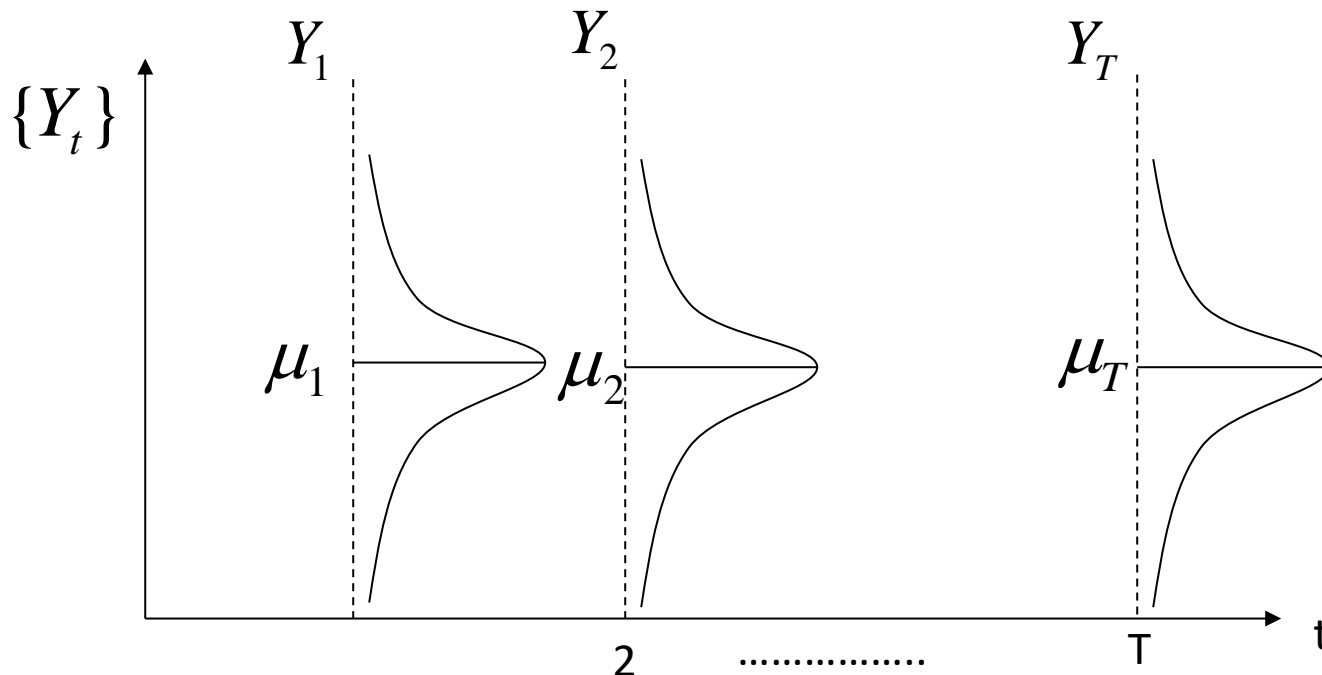
$\{y_t; t=1,2,\dots\} = \{y_1, y_2, \dots, y_T\}$ = Sample realization of a stochastic process.



Stationarity

- **Def:** First Order **Strongly** Stationary

= All R.Vs have the same pdf's (all moments are the same).
 $f_{Y_1}(y) = f_{Y_2}(y) = \dots = f_{Y_T}(y)$

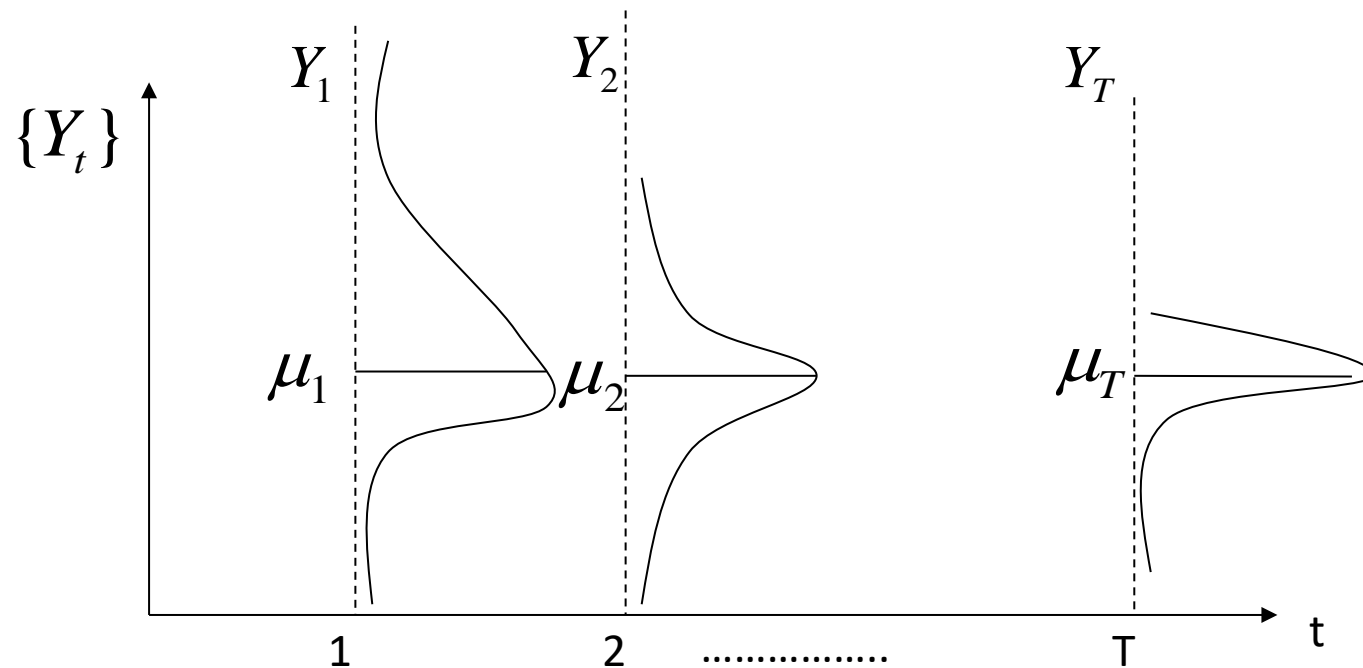


Stationarity

- **Def:** First Order **Weakly** Stationary

= All R.Vs have the same means.

$$\rightarrow \mu_{Y_1} = \mu_{Y_2} = \cdots = \mu_{Y_T}$$




Stationarity

- **Def:** Second Order Weakly Stationary
= *Covariance Stationary*

i. Means: $\mu_{Y_1} = \mu_{Y_2} = \dots = \mu_{Y_T}$

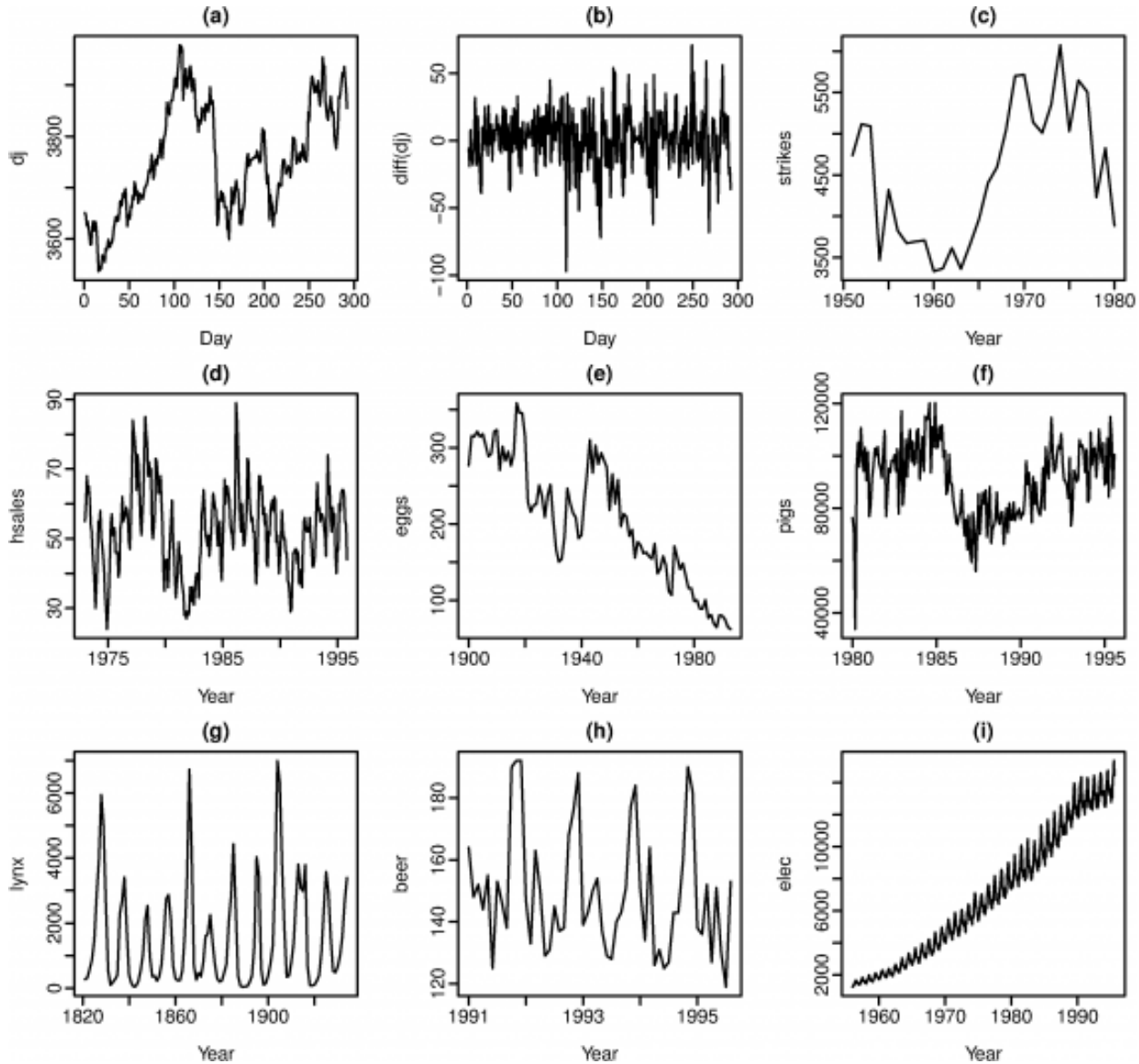
ii. Variances: $\sigma_{Y_1}^2 = \sigma_{Y_2}^2 = \dots = \sigma_{Y_T}^2 = \sigma^2$

iii. Time Independent Covariances: $\rho_{Y_t, Y_{t-k}} = \rho_{|k|}$



The strength of the linear association between the two R.Vs only depends on how many periods (k) apart they are.

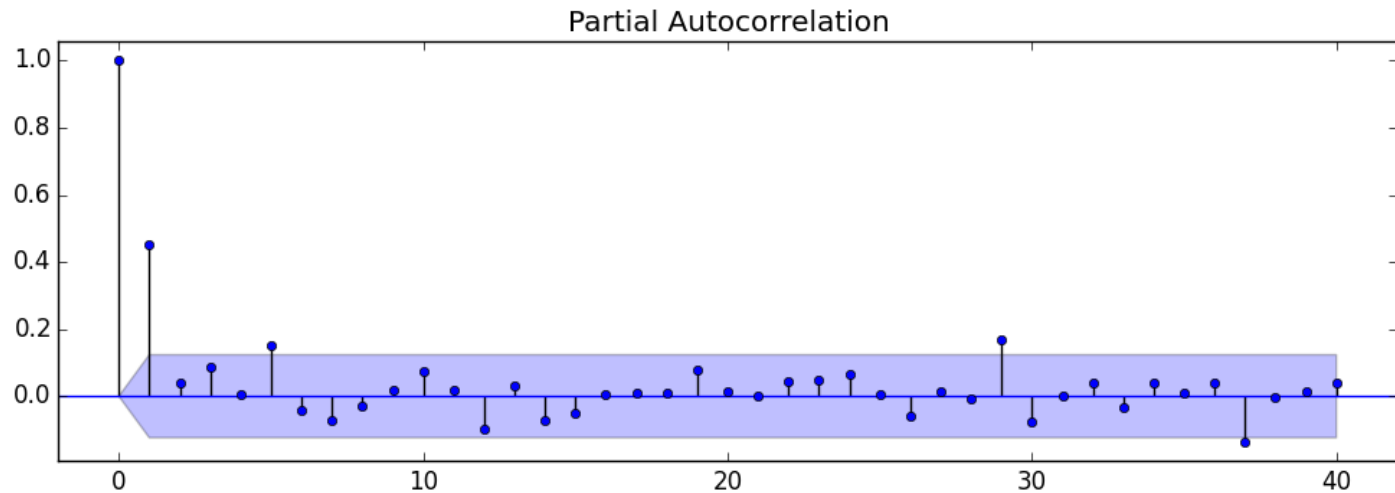
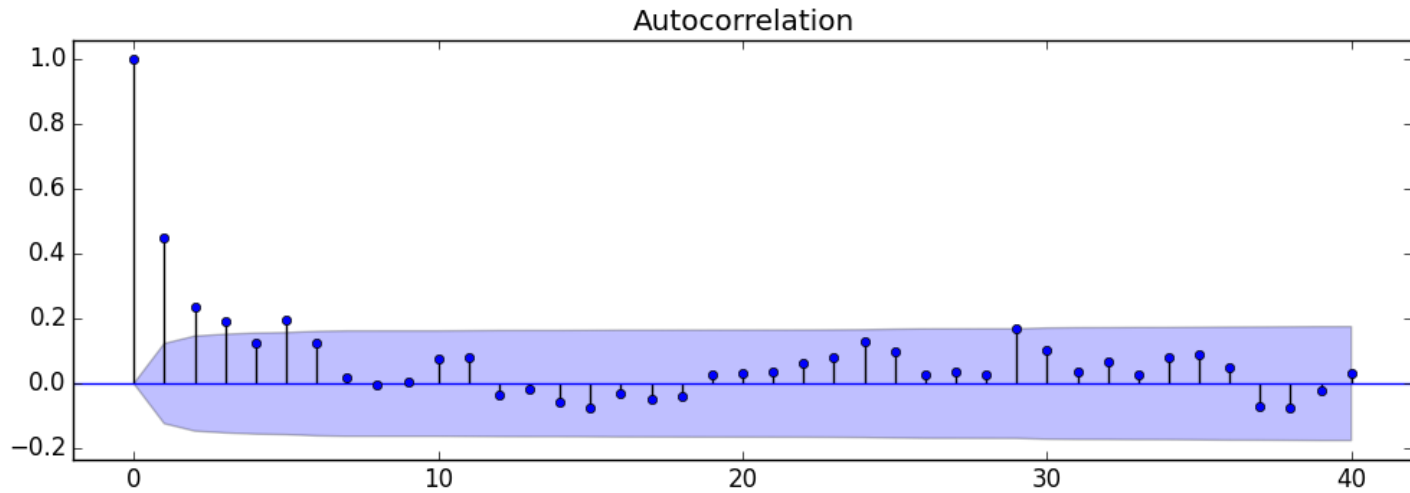
Stationarity



The Autocorrelation Functions

- **Autocovariance Function (ACF)**: Measures correlation between time series and lagged versions of itself
- **Partial Autocorrelation Function (PACF)**: Measures correlation between time series and lagged versions of itself accounting for all lags in between

The Autocorrelation Functions



Moving Average Models

- Def: **MA(q)** = Moving Average process of order $q \geq 0$: $Y_t = \mu + \theta_1 \varepsilon_{t-1} + \theta_2 \varepsilon_{t-2} + \dots + \theta_q \varepsilon_{t-q}$,
- Examples:
 - MA(**1**): $Y_t = \mu + \theta_1 \varepsilon_{t-1} + \varepsilon_t$
 - MA(**5**): $Y_t = \mu + \theta_1 \varepsilon_{t-1} + \theta_5 \varepsilon_{t-5} + \varepsilon_t$
 - MA(**10**): $Y_t = \mu + \theta_{10} \varepsilon_{t-10} + \varepsilon_t$

Wold's Theorem (Part I)

- **Wold's Representation Theorem:** Let $\{y_t\}$ be any zero-mean covariance-stationary process. Then

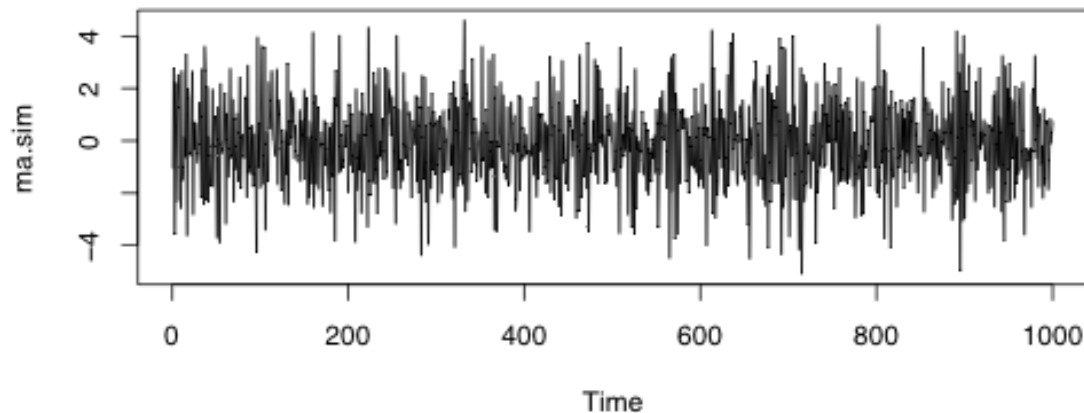
$$y_t = B(L)\varepsilon_t = \sum_{i=0}^{\infty} b_i \varepsilon_{t-i} \quad \varepsilon_t \sim WN(0, \sigma^2)$$

↑
(Innovations)

Moving Average Models

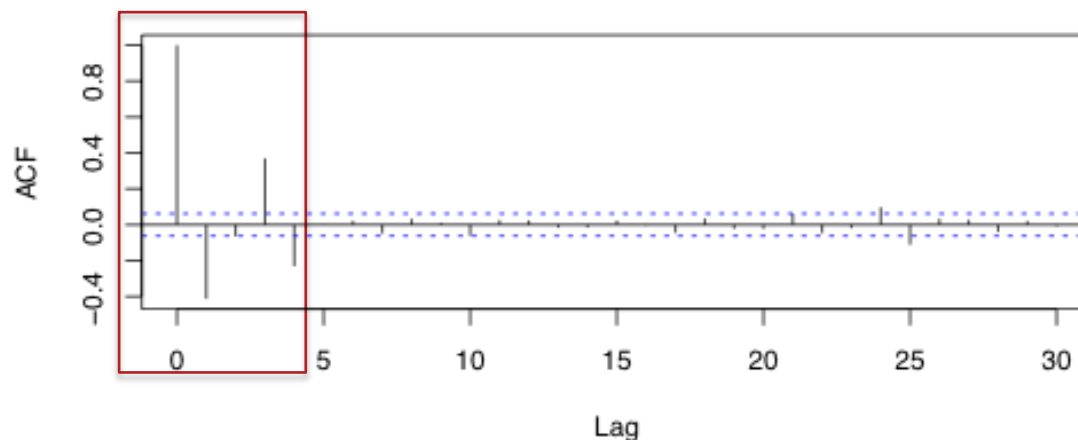
Example: MA(q) Process

What type of a process is this?



Series ma.sim

MA(4) Process

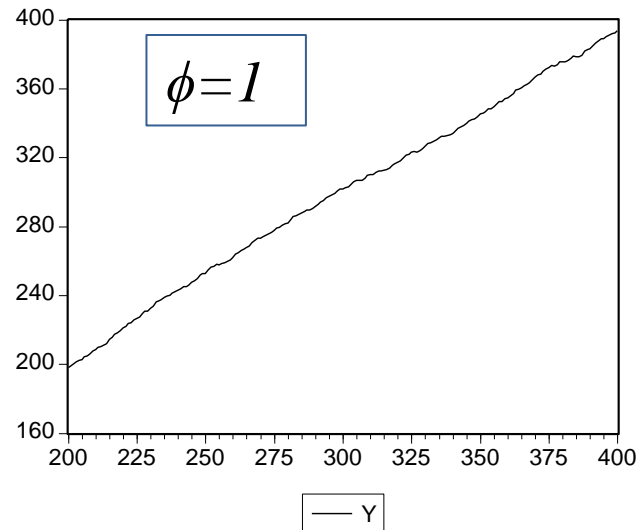
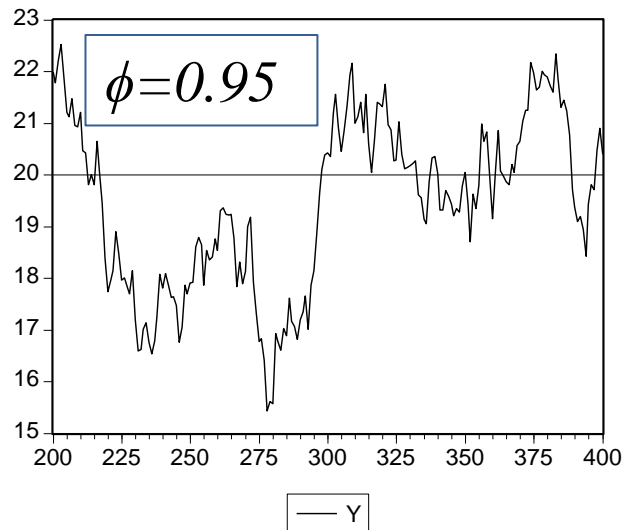
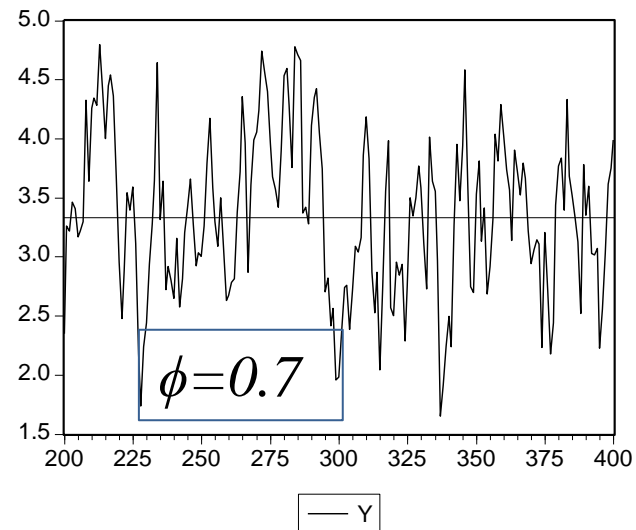
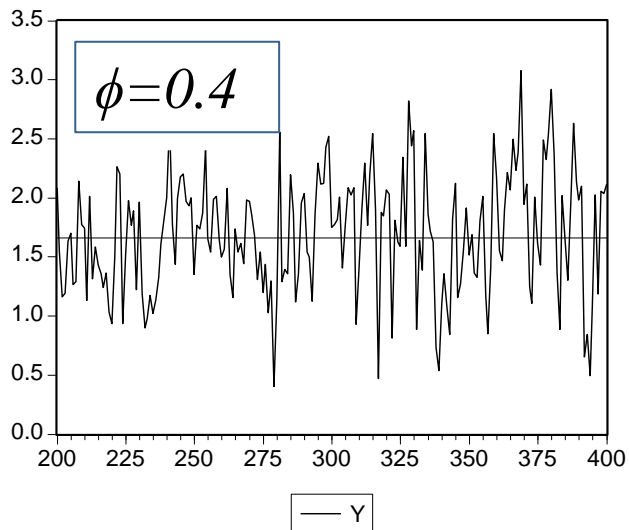


In general, for any MA(q) process, $\rho_k = 0$ for any $k > q$.

Autoregressive Models

- Def: **AR(p)** = Autoregressive process of order $p \geq 0$: $Y_t = c + \phi_1 Y_{t-1} + \phi_2 Y_{t-2} + \dots + \phi_p Y_{t-p} + \varepsilon_t$, where $\varepsilon_t \sim (0, \sigma^2)$, and **ϕ** = persistence parameter.
- Examples:
 - AR(**1**): $Y_t = c + \phi_1 Y_{t-1} + \varepsilon_t$
 - AR(**2**): $Y_t = c + \phi_1 Y_{t-1} + \phi_2 Y_{t-2} + \varepsilon_t$
 - AR(**6**): $Y_t = c + \phi_6 Y_{t-6} + \varepsilon_t$

$$\text{AR}(1): Y_t = c + \phi Y_{t-1} + \varepsilon_t$$



Unit Roots: Estimation and Testing

Unit Root Tests

- Series with unit roots, should be checked for their presence via e.g., a t -statistic

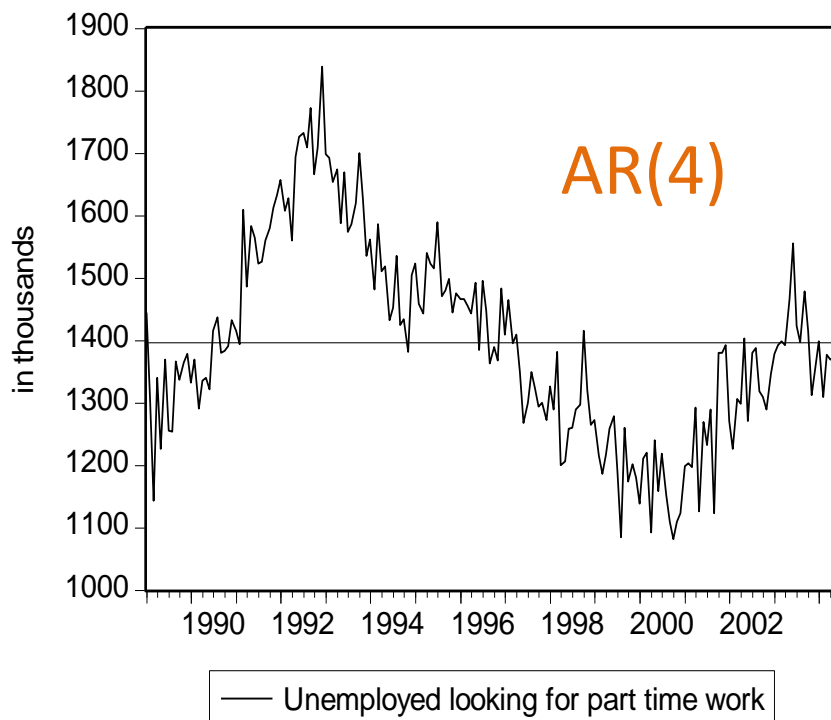
$$\hat{\tau} = \frac{\hat{\varphi} - 1}{s \sqrt{\frac{1}{\sum_{t=2}^T y_{t-1}^2}}} \quad (\text{Dickey-Fuller Statistic})$$

- For the unit root case, $\hat{\tau}$ follows a **Dickey-Fuller Distribution**.
- For the general, nonzero mean case (under the alternative hypothesis), the process is a covariance stationary AR(1) process in deviations from the mean. $\rightarrow y_t = \alpha + \varphi y_{t-1} + \varepsilon_t$, where $\alpha = \mu(1-\varphi)$.
- Note:** The Dickey-Fuller statistic table is for $(\alpha, \varphi)=(0,1)$.

Autoregressive Models

Example: AR(p) Process

Q: What type of a process is this?



Sample: 1989:01 2004:06
Included observations: 186

| Autocorrelation | Partial Correlation | AC | PAC |
|-----------------|---------------------|--------|-------|
| 1 | 0.882 | 0.882 | 0.882 |
| 2 | 0.874 | 0.434 | 0.874 |
| 3 | 0.851 | 0.176 | 0.851 |
| 4 | 0.841 | 0.136 | 0.841 |
| 5 | 0.829 | 0.094 | 0.829 |
| 6 | 0.803 | -0.030 | 0.803 |
| 7 | 0.796 | 0.040 | 0.796 |
| 8 | 0.775 | -0.009 | 0.775 |
| 9 | 0.766 | 0.024 | 0.766 |
| 10 | 0.737 | -0.072 | 0.737 |
| 11 | 0.712 | -0.084 | 0.712 |
| 12 | 0.672 | -0.158 | 0.672 |
| 13 | 0.676 | 0.098 | 0.676 |
| 14 | 0.638 | -0.076 | 0.638 |
| 15 | 0.623 | 0.002 | 0.623 |
| 16 | 0.586 | -0.086 | 0.586 |
| 17 | 0.553 | -0.096 | 0.553 |
| 18 | 0.539 | 0.009 | 0.539 |
| 19 | 0.508 | 0.002 | 0.508 |
| 20 | 0.482 | -0.041 | 0.482 |

In general, for any AR(p) process, $p_k = 0$ for any $k > p$.

Autoregressive Moving Average (ARMA) Models \rightarrow ARMA(p,q) 1 of 2

- The **ARMA(1,1)** Process: $Y_t = \phi Y_{t-1} + \theta \varepsilon_{t-1} + \varepsilon_t$
- The **ARMA(p,q)** Process:

$$Y_t = \phi_1 Y_{t-1} + \cdots + \phi_p Y_{t-p} + \theta_1 \varepsilon_{t-1} + \cdots + \theta_q \varepsilon_{t-q} + \varepsilon_t$$

Mystery Process

