

# Automatic Algorithm Transformation for Efficient Multi-Snapshot

## Analytics on Temporal Graphs (时态图上对多快照分析进行高效算法自动转换)

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数据管理和系统实现



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# Why Multi-snapshot analytics



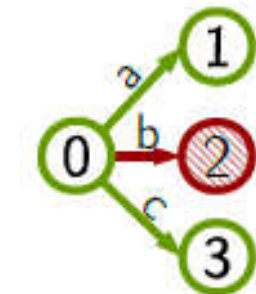
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➤ **What is snapshot**

➤ **What can we do with multi-snapshot**

# basic solution

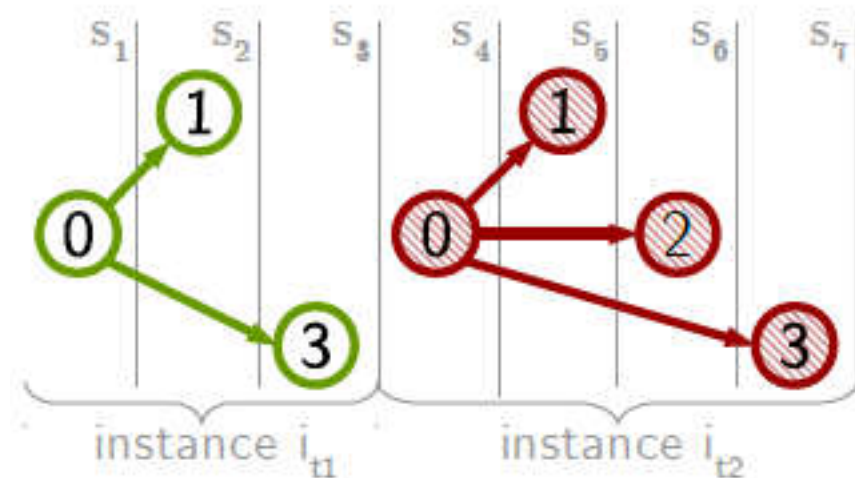
## ➤ Independent Snapshot Execution



○ created at  $t_1$

● created at  $t_2$

(a) Graph  $G^S$

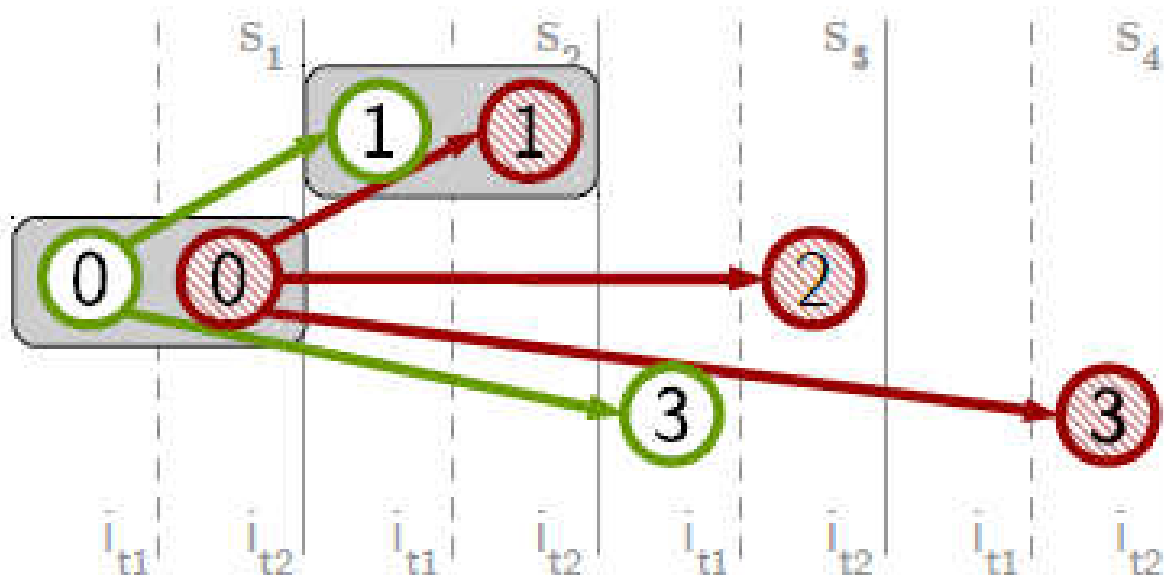


(b) Snapshot-at-a-time

➤ How to facilitate the similarity among snapshots

# Advanced solution

## ➤ Instance Interleaving



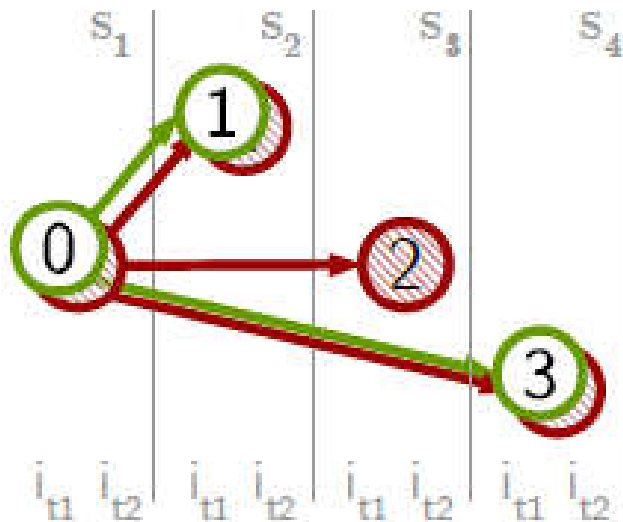
(c) Interleaved

$$i_{t_1} : G^S.neighbors(v_0) = [v_1, v_3]$$

$$i_{t_2} : G^S.neighbors(v_0) = [v_1, v_2, v_3]$$

# Solution author propose

## ➤ Graph-Synchronous Interleaved Execution



(d) SAMS

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Algorithm 1 1-hop neighborhood traversal.

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```
1: visit( $v_0$ )  
2: for  $n \in G^S.\text{neighbors}(v_0)$  do  
3:   visit( $n$ )
```

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Algorithm 2 SAMS variant of Algorithm 1 that allows its concurrent execution for two graph snapshots.

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```
1: visit( $v_0, \{i_{t_1}, i_{t_2}\}$ )  
2: for  $(n, \text{active}_n) \in G^S.\text{neighbors}_*(v_0, \{i_{t_1}, i_{t_2}\})$  do  
3:   visit( $n, \text{active}_n$ )
```

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# Interleaving of Program Instances



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## ➤ Rules for algorithm interleaving

### Rule 1 Function definition

$$\begin{array}{l} \text{sim } (\square) \text{ do} \\ \quad \text{fun } F(\text{args}...) \\ \quad \quad \text{stmt} \end{array} \quad \rangle \quad \begin{array}{l} \text{fun } F_*(S, \text{args}_*...) \\ \quad \mathcal{A}(F_*) := S \\ \quad \text{sim } (\mathcal{A}(F_*)) \text{ do} \\ \quad \quad \text{stmt} \end{array}$$

### Rule 2 Statement sequence

$$\begin{array}{l} \text{sim } (\frac{S}{D}) \text{ do} \\ \quad \text{stmt}_1 \\ \quad \text{stmt}_2 \end{array} \quad \rangle \quad \begin{array}{l} \text{sim } (\frac{S}{D}) \text{ do} \\ \quad \text{stmt}_1 \\ \quad \text{sim } (\frac{S}{D}) \text{ do} \\ \quad \quad \text{stmt}_2 \end{array}$$

### Rule 3 Expression evaluation and assignment

$$\begin{array}{l} \text{sim } (\frac{S}{D}) \text{ do} \\ \quad v := E \end{array} \quad \rangle \quad v_* := \text{eval}_*(E, S \cap D)$$

### Rule 4 Conditional branch statement

$$\begin{array}{l} \text{sim } (\frac{S}{D}) \text{ do} \\ \quad \text{if } E \text{ then} \\ \quad \quad \text{stmt}_t \\ \quad \text{else} \\ \quad \quad \text{stmt}_f \end{array} \quad \rangle \quad \begin{array}{l} e_* := \text{eval}_*(E, S \cap D) \\ T := \{i \mid e_i = \text{true}\} \\ \text{sim } (\frac{T}{D}) \text{ do} \\ \quad \text{stmt}_t \\ \text{sim } (\frac{S \setminus T}{D}) \text{ do} \\ \quad \text{stmt}_f \end{array}$$

### Rule 5 While loop

$$\begin{array}{l} \text{sim } (\frac{S}{D}) \text{ do} \\ \quad \text{while } E \text{ do} \\ \quad \quad \text{stmt} \end{array} \quad \rangle \quad \begin{array}{l} \mathcal{A}(\phi) := S \\ \phi: \text{while } D \cap \mathcal{A}(\phi) \neq \emptyset \text{ do} \\ \quad e_* := \text{eval}_*(E, \mathcal{A}(\phi) \cap D) \\ \quad T := \{i \mid e_i = \text{true}\} \\ \quad \mathcal{A}(\phi) := \mathcal{A}(\phi) \cap T \\ \quad \text{sim } (\frac{T}{D \cap \mathcal{A}(\phi)}) \text{ do} \\ \quad \quad \text{stmt} \end{array}$$

### Rule 6 Loop $\phi$ break statement

$$\begin{array}{l} \text{sim } (\frac{S}{D}) \text{ do} \\ \quad \text{break} \end{array} \quad \rangle \quad \mathcal{A}(\phi) := \mathcal{A}(\phi) \setminus (S \cap D)$$

### Rule 7 For loop

$$\begin{array}{l} \text{sim } (\frac{S}{D}) \text{ do} \\ \quad \text{for } v \in E \text{ do} \\ \quad \quad \text{stmt} \end{array} \quad \rangle \quad \begin{array}{l} \mathcal{A}(\phi) := S \\ \phi: \text{for } v_* \in \text{collect}_*(E, S \cap D) \text{ do} \\ \quad \text{sim } (\frac{S \cap \mathcal{A}(v_*)}{D \cap \mathcal{A}(\phi)}) \text{ do} \\ \quad \quad \text{stmt} \end{array}$$

### Rule 8 Function call

$$\begin{array}{l} \text{sim } (\frac{S}{D}) \text{ do} \\ \quad v := F(x...) \end{array} \quad \rangle \quad v_* := F_*(S \cap D, x_*)$$

### Rule 9 Function $\psi$ return statement

$$\begin{array}{l} \text{sim } (\frac{S}{D}) \text{ do} \\ \quad \text{return } E \end{array} \quad \rangle \quad \begin{array}{l} \text{sim } (\frac{S}{D}) \text{ do} \\ \quad \mathcal{R}(\psi) := E \\ \quad \mathcal{A}(\psi) := \mathcal{A}(\psi) \setminus (S \cap D) \\ \quad \text{if } \mathcal{A}(\psi) = \emptyset \text{ then return } \mathcal{R}(\psi) \end{array}$$

# An example



Rule 7 For loop

$$\begin{array}{l} \text{sim } \left( \begin{smallmatrix} S \\ D \end{smallmatrix} \right) \text{ do} \\ \quad \text{for } v \in E \text{ do} \\ \quad \quad \text{stmt} \end{array} \quad \left. \vphantom{\begin{array}{l} \text{sim } \left( \begin{smallmatrix} S \\ D \end{smallmatrix} \right) \text{ do} \\ \quad \text{for } v \in E \text{ do} \\ \quad \quad \text{stmt} \end{array}} \right\} \begin{array}{l} \mathcal{A}(\phi) := S \\ \phi: \text{for } v_* \in \text{collect}_*(E, S \cap D) \text{ do} \\ \quad \text{sim } \left( \begin{smallmatrix} S \cap \mathcal{A}(v_*) \\ D \cap \mathcal{A}(\phi) \end{smallmatrix} \right) \text{ do} \\ \quad \quad \text{stmt} \end{array}$$

- Sim statement *interleaving marker*
- $S$  scope constraints  $D$  dynamic constraints
- $E$  expression  $v$  variable
- $\mathcal{A}(\phi)$  active set  $\text{collect}_*(\ )$  function
- $\mathcal{A}(v_*)$  active set

# Locality optimized Data Layout



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- **Global property**
  - **Vertex's property in same memory location**
- **Local variables**
  - **Collocate their values in all program instances**



# Experiment Setup

## **6 graph algorithms**

*PageRank Triangle counting BFS DFS closeness centrality  
Tarjan's strongly connected components*

**store graphs in the compressed sparse row (CSR) format**

**Ubuntu Linux 15.10**

**two Intel Xeon E5-2660 v2 CPUs having 20 logical threads  
at 2.2GHz and 256GB of main memory.**

# Datasets



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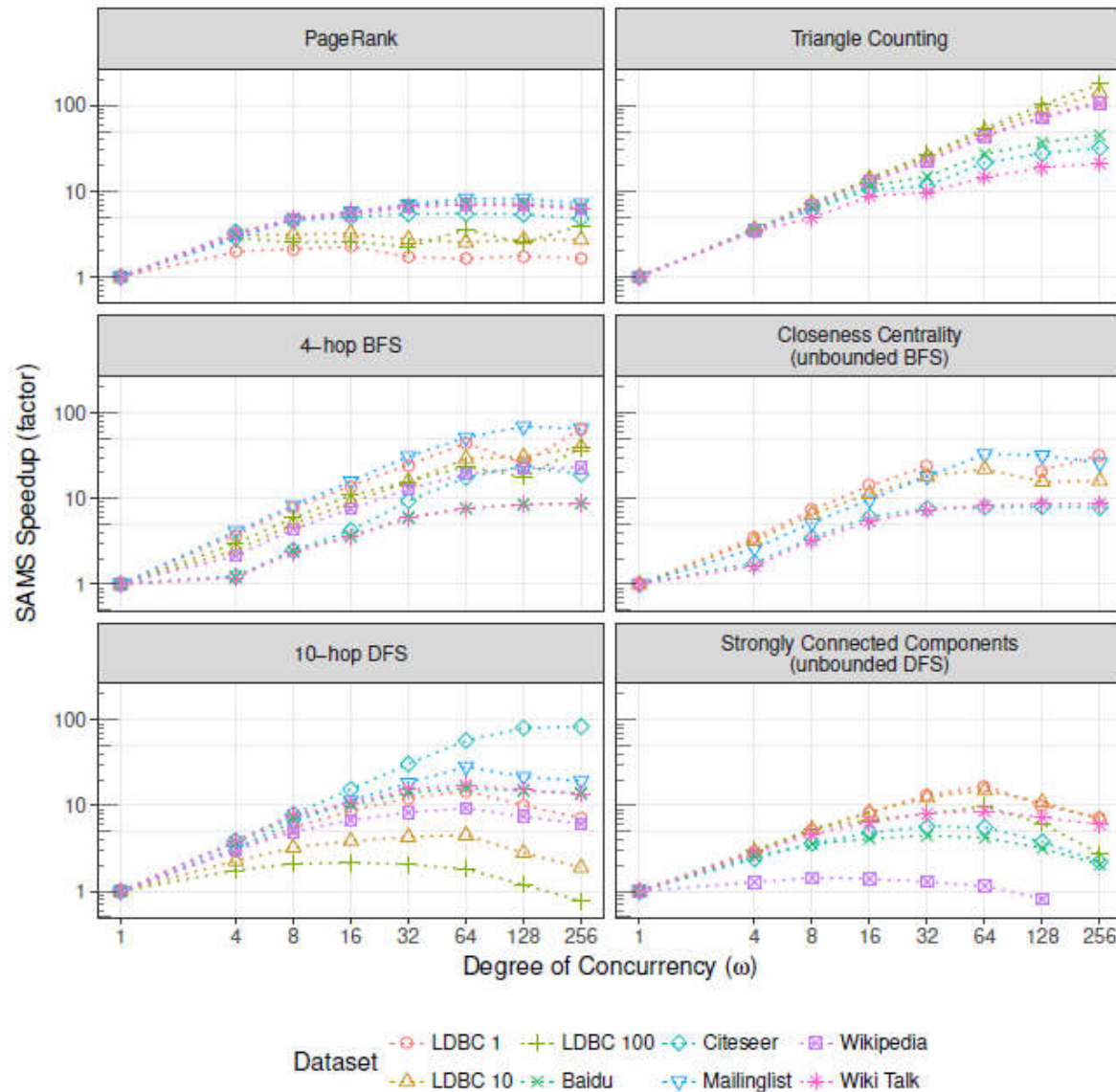
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Table 2: Properties of the evaluated data sets.

Graph	Vertices (k)	Edges (k)	Ø Degree	Diameter	Ø Diameter	Directed	Temporal
LDBC 1	34.4	1,010.6	29.4	5	2.8		X
LDBC 10	226.9	10,141.4	44.7	6	3.0		X
LDBC 100	1,611.9	101,747.9	63.1	6	3.2		X
Baidu	2,753.2	17,643.7	6.4	24	6.6	X	
Citeseer	384.4	1,751.5	4.6	70	18.6	X	
Mailinglist	27.9	1,014.1	36.3	112	7.2	X	X
Wiki Talk	2,502.0	5,021.4	2.0	14	5.0	X	
Wikipedia	1,870.7	39,953.1	21.4	376	4.6	X	X

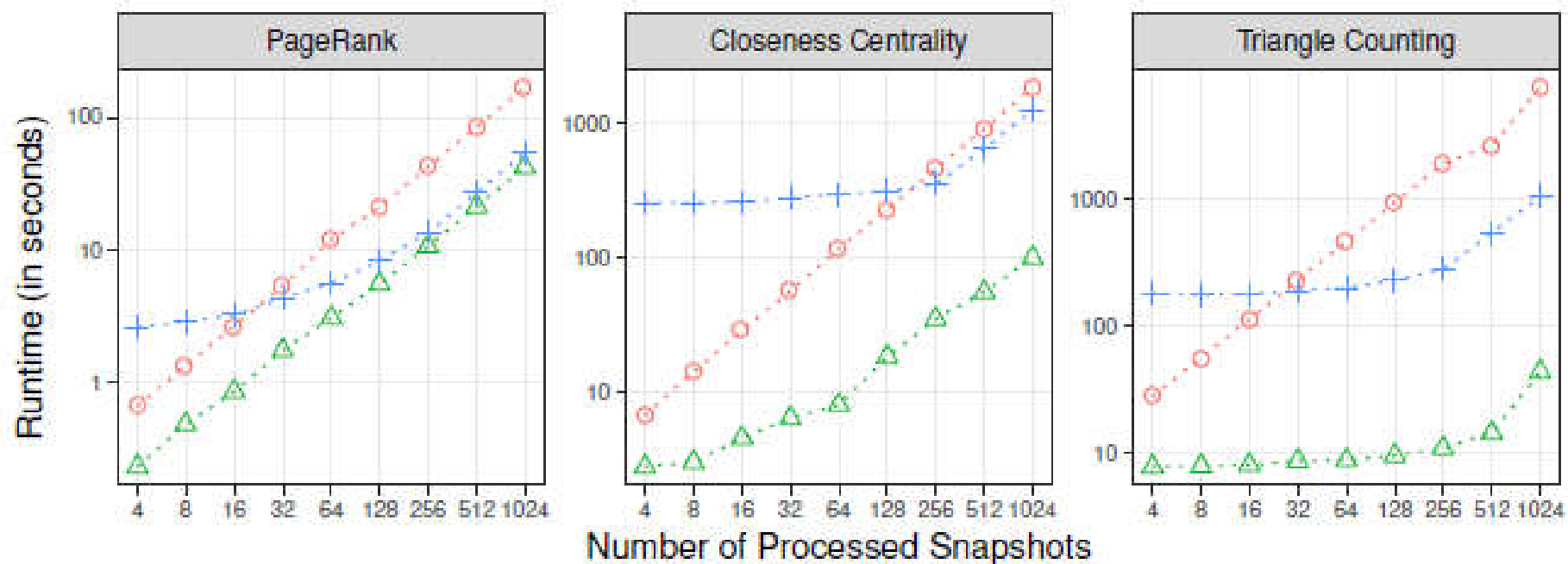
**evaluate all algorithms for 512 distinct graph snapshots, the first comprises 80% of all edges and their incident vertices**

# Speedup



- Speedup of SAMS over snapshot-at-a-time execution for varying degrees of concurrency.

# competitor



Execution -○- Snapshot at a Time -△- Single Algorithm Multiple Snapshots -+- Chronos's strategy

Figure 4: Absolute runtime to process a varying number of snapshots, using the LDBC 100 graph.

# summary



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- Inspiration:
  - Automatically transform
  - sharing common computation
- Deficiency:
  - instable
  - only for concurrency  $\leq 256$
- Further improvement:
  - Out-of-core and distributed processing