# Lecture 12: Clustering and EM

#### wbg231

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## 1 unsupervised learning

- the goal is to discover unknown structure in the data
- we try to estimate densities with some latent variable  $\theta$

$$P(x|\theta)$$

#### k means

- dataset  $\mathcal{D} = (x_1 \cdots x_n) \subset X$  where  $X \in \mathbb{R}^d$
- the goal is to partition D into k disjoint subsets  $C_1 \cdots C_k$
- let  $c_i \in \{1 \cdots k\}$  be the cluster assignment of data point  $x_i$
- the centroid of the data  $C_i$  is defined as

$$\mu_i = argmin_{\mu \in X} |||x - \mu||^2$$

so that is each centroid is the mean of it's cluster

• the objective is

$$j(c,\mu) = \sum_{i=1}^{n} ||x_i \mu_c||^2$$

- the k means algorithm is described here
  - **1** Initialize: Randomly choose initial centroids  $\mu_1, \ldots, \mu_k \in \mathbb{R}^d$ .
  - 2 Repeat until convergence (i.e.  $c_i$  doesn't change anymore):
    - For all i, set

$$c_i \leftarrow \mathop{\arg\min}_j \|x_i - \mu_j\|^2. \qquad \qquad \text{Minimize $J$ w.r.t. $c$ while fixing $\mu$}$$

For all j, set

$$\mu_j \leftarrow \frac{1}{|C_j|} \sum_{x \in C_j} x.$$
 Minimze  $J$  w.r.t.  $\mu$  while fixing  $c$ .

• Recall the objective:  $J(c, \mu) = \sum_{i=1}^{n} ||x_i - \mu_{c_i}||^2$ .

- so there is an alternative behavior of picking the best cluster for each data point, and picking the best centroid for each cluster
- the objective of k means is non convex, so it can get stuck in bad local minima pretty easily
- can re run it multiple times to try to avoid this

### gaussian mixture models

- a generative model for X, done with MLE
- assume there are k sets up and we have the probability distribution of each
- the generative story of a GMM is as follows
  - 1. chose a cluster  $z \sim catagorical(\pi_1 \cdots \pi_k)$
  - 2. chose a conditional distribution for that cluster  $x|z \sim \mathcal{N}(\mu_z, \Sigma_z)$
- $\bullet$  then we can get the marginal likelihood of our dataset by marginalizing over the latent variable z

$$P(x) = \sum_{z} P(x, y) = \sum_{z} p(x|z)P(z) = \sum_{k} \pi_k \mathcal{N}(\mu_k, \Sigma_k)$$

- note that in GMMs the label of the cluster is not important
- how do we learn the parameters  $\mu_k, \pi_k, \Sigma_K$
- we can do mle

$$L(\theta) = \sum_{i=1}^{n} log P(x_i | \theta) = \sum_{i=1}^{n} log(\sum_{z} P(x, z | \theta))$$

note that our class label and data points are connected so we can not just push log into the sum

- there is no closed form solution for GMM
- so gradient descent is kind of involved
- if we had cluster assignments mle would be easy
- we observe x and want to know z.

$$P(z = j | x_i) = \frac{P(x, z = j)}{p(x)} = \frac{P(x | z = j)P(z = j)}{\sum_k P(x | z = k)P(z = k)} = \frac{\pi_i \mathcal{N}(x_i | \mu_j, \Sigma_j)}{\sum_k \pi_k \mathcal{N}(x_i | \mu_k, \Sigma_k)}$$

- think of P(z|x) as a soft class assignment
- if we knew  $\mu, \Sigma, \pi$  that would be easy to compute

### expectation max for GMM

Let's compute the cluster assignments and the parameters iteratively.

The expectation-minimization (EM) algorithm:

- 1 Initialize parameters  $\mu$ ,  $\Sigma$ ,  $\pi$  randomly.
- 2 Run until convergence:
  - E-step: fill in latent variables by inference.
    - compute soft assignments  $p(z | x_i)$  for all i.
  - **9** M-step: standard MLE for  $\mu$ ,  $\Sigma$ ,  $\pi$  given "observed" variables.
    - Equivalent to MLE in the observable case on data weighted by  $p(z | x_i)$ .

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- so we estimate using expectation maximization in this method we first intilize the parameters  $\mu, \Sigma, \pi$  randomly
- then alternate between teh E and M step until convergence
- where the E step i gill in latent variables by inference (compute the soft class assignments  $P(z|x_i)\forall i$ )
- M step: standard MLE for  $\mu, \Sigma, \pi$  given our soft assignments. this is equivalent to mle in observable case on data weighed by  $P(z|x_i)$

#### M step

• let P(Z|x) be the soft assigned

π assignments:

$$\gamma_i^j = \frac{\pi_j^{\text{old}} \mathcal{N}\left(x_i \mid \mu_j^{\text{old}}, \Sigma_j^{\text{old}}\right)}{\sum_{c=1}^k \pi_c^{\text{old}} \mathcal{N}\left(x_i \mid \mu_c^{\text{old}}, \Sigma_c^{\text{old}}\right)}.$$

$$\begin{array}{lcl} n_z & = & \displaystyle \sum_{i=1}^n \gamma_i^z \\ \mu_z^{\text{new}} & = & \displaystyle \frac{1}{n_z} \displaystyle \sum_{i=1}^n \gamma_i^z x_i \\ \\ \Sigma_z^{\text{new}} & = & \displaystyle \frac{1}{n_z} \displaystyle \sum_{i=1}^n \gamma_i^z \left( x_i - \mu_z^{\text{new}} \right) \left( x_i - \mu_z^{\text{new}} \right)^T \\ \\ \pi_z^{\text{new}} & = & \displaystyle \frac{n_z}{n}. \end{array}$$

#### em for GMM summary

- em is a genearl algorithm for leanring latent vairble mdoels
- key dea is that if the data was fully observable MLE would be easy
- E step fill in latent vaibles by comuting  $P(z|x,\theta)$
- M step standard MLE given fully observable data
- this si simpler and more efficient than graidnt methods
- k means is a special case of EM for GMM wil hard assignments

#### latent variable models

#### generative latent vairble models

- two sets of random variables Z, X
- z is hidden unobserved variables
- x is observed variables

• joint probability model is parametrized by  $\theta \in \Theta$ 

$$P(x, z|\theta)$$

- a latent variable model is a probability model for which certain varibles are never observed
- x alone is incomplete data
- $\bullet$  (x,z) is complete data

## objectives

• learning probelm given incomplete data find the mle

$$\hat{\theta} = argmax_{\theta} P(x|\theta)$$

• the inference problem is

$$P(z|x,\theta)$$

• there are cases where learning and inference are both hard

## EM algorithm

• at slide 88