COSC 364

Internet Technologies and Engineering Flow Assignment

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Problem Formulation

The objective of this assignment is to balance the load on all transit nodes.

Variable definitions:

i = Index of source node, X = number of source nodes, S_i = source node i

 $k = \text{Index of transit node}, Y = \text{number of transit nodes}, T_k = \text{transit node } k$

j = Index of destination node, Z = number of destination nodes, $D_i = \text{destination node}$

 x_{ikj} = Flow path from S_i to D_i through T_k

 h_{ij} = Demand volume from S_i to D_i

 c_{ik} = Link capacity from S_i to T_k , d_{kj} = Link capacity from T_k to D_i

 u_{ikj} = Binary Variable for path x_{ikj}

Constraints:

1. Each demand volume must be split over exactly 2 different paths.

$$Y \geq 2$$

2. Demand constraint: The sum of all path flows from source node i through transit node k to destination node j must give the total demand volume h.

$$\sum_{k=1}^{Y} x_{ikj} = h_{ij} \text{ for } i \in \{1, \dots, X\}, j \in \{1, \dots, Z\}$$

3. Non-negativity constraints: Each path flow and link capacity must be non-negative, as negative data rates do not make sense.

$$x_{ikj} \ge 0$$
, $c_{ik} \ge 0$, $d_{kj} \ge 0$

- 4. Capacity constraints:
 - a. The link capacity between a source node S_i and a transit node T_k is represented by c_{ik} . The sum of all flows through each link must be less than or equal to the link capacity c_{ik} .

$$\sum_{j=1}^{Z} x_{ikj} \le c_{ik} \text{ for } i \in \{1, ..., X\}, k \in \{1, ..., Y\}$$

b. The link capacity between a transit node T_k and a destination node D_k is represented by d_{kj} . The sum of all flows through each link must be less than or equal to the link capacity d_{kj} .

$$\sum_{i=1}^{X} x_{ikj} \le d_{kj} \text{ for } k \in \{1, ..., Y\}, j \in \{1, ..., Z\}$$

 Binary constraint: For this problem, each demand volume needs to be split over exactly 2 paths. To minimise the load on each transit node, these flows must be equal.

$$\sum\nolimits_{k=1}^{Y} u_{ikj} = 2 \ for \ i \in \{1, \dots, X\}, j \in \{1, \dots, Z\}, u \in \{0, 1\}$$

$$x_{ikj} = u_{ikj} \times \frac{h_{ij}}{2}$$

6. Minimising the load is done by introducing an auxiliary variable *r* used to represent the utilisation of load at each transit node. By minimizing *r*, the demand volume of each transit node becomes as small as possible, balancing loads over all transit nodes.

$$\sum_{i=1}^{X} \sum_{j=1}^{Z} x_{ikj} \le r \ for \ k \in \{1, \dots, Y\}$$

These constraints form the minimisation problem below:

Minimize [x, c, d r] r

Subject to

$$\begin{split} \sum_{k=1}^{Y} x_{ikj} &= h_{ij} & for \ i \in \{1, \dots, X\}, j \in \{1, \dots, Z\} \\ \sum_{k=1}^{Y} u_{ikj} &= 2 & for \ i \in \{1, \dots, X\}, j \in \{1, \dots, Z\} \\ x_{ikj} &= u_{ikj} \times \frac{h_{ij}}{2} & for \ i \in \{1, \dots, X\}, k \in \{1, \dots, Y\}, j \in \{1, \dots, Z\} \\ \sum_{j=1}^{Z} x_{ikj} &\leq c_{ik} & for \ i \in \{1, \dots, X\}, k \in \{1, \dots, Y\} \\ \sum_{i=1}^{X} x_{ikj} &\leq d_{kj} & for \ k \in \{1, \dots, Y\}, j \in \{1, \dots, Z\} \\ \sum_{i=1}^{X} \sum_{j=1}^{Z} x_{ikj} &\leq r & for \ k \in \{1, \dots, Y\}, j \in \{1, \dots, Z\} \\ k_{ij} &= i + j & for \ i \in \{1, \dots, X\}, k \in \{1, \dots, Y\}, j \in \{1, \dots, Z\} \\ x_{ikj} &\geq 0 & for \ i \in \{1, \dots, X\}, k \in \{1, \dots, Y\}, j \in \{1, \dots, Z\} \\ c_{ik} &\geq 0 & for \ k \in \{1, \dots, Y\}, j \in \{1, \dots, Z\} \\ r &\geq 0 & for \ k \in \{1, \dots, Y\}, j \in \{1, \dots, Z\} \\ r &\geq 0 & for \ k \in \{1, \dots, Y\}, j \in \{1, \dots, Z\} \\ \end{split}$$

Results

# of T nodes	3	4	5	6	7
Execution	0.494	0.285	0.317	0.306	1.849
time (s)					
N of non-	42	53	64	79	83
zero					
capacities					
Lowest	1, 2 = 130.5	1, 2, 3, 4 = 98	2 = 78	1, 4 = 65	1, 2, 3, 4, 5,
transit load					6, 7 = 56
Highest	3 = 131	1, 2, 3, 4 = 98	1, 3, 4, 5 = 78.5	2, 3, 5, 6=65.5	1, 2, 3, 4, 5,
transit load					6, 7 = 56
Highest	D ₁₇ = 35	D ₃₇ = 35	C ₇₃ = 30	C ₅₅ = 25	C ₅₆ = 25
capacity					
links					

Table 1: CPLEX results for varying Y, with fixed X = Y = 7.

Explanation

The execution time is not what was expected, as the times all seemed very close together until a massive jump at 7 transit nodes, whereas it was expected that the time would steadily increase as more nodes means a more complex calculation. The number of non-zero capacities however did steadily increase with the number of transit nodes, which is expected as with more nodes, the demand is spread out across more links to reduce the load per link. For every number of transit nodes, the transit loads were all within 0.5 of each other, meaning that the load balancing was successful. The overall load average decreases against the number of transit nodes, as more transit nodes means the load is evenly distributed over a larger number. The highest capacity links get values smaller as the number of transit nodes increases because as the number of non-zero capacity links increases, the load again is split over more links giving a lower load on each link.

Appendix

Source Code:

```
#!/usr/bin/env python
# -*- coding: utf-8 -*-
0.00
flow.py
Program to create an LP file of constraints to balance loads equally across
links
    - Each load must be split over exactly 2 paths
Note: This program only runs on Linux systems with CPLEX - check directories
in CPLEX function
.....
# Author: Blake Manson
# Date Created: 02/05/2024
# Date Modified: 29/05/2024
import time
import subprocess
def createLPFileName() -> str:
    Creates the name for an lp file with inputs for X, Y and Z
        Inputted values for X, Y and Z
        The name for the file of form XYZ.lp
    X = int(input("Number of source nodes (X): "))
    Y = int(input("Number of transit nodes (Y): "))
    Z = int(input("Number of destination nodes (Z): "))
    filename = f''\{X\}\{Y\}\{Z\}.lp''
    return X, Y, Z, filename
def writeContraints(X: int, Y: int, Z: int, filename: str):
    Writes all constraints and bounds of minimization formula to XYZ.lp
    f = open(filename, 'w')
    f.write(f"Minimize\n
                           r\nSubject to\n")
    f.write(demandVolume(X, Y, Z))
    f.write(binaryVariable(X, Y, Z))
    f.write(demandFlow(X, Y, Z))
    f.write(sourceTransitCap(X, Y, Z))
    f.write(transitDestinationCap(X, Y, Z))
```

```
f.write(loadBalancing(X, Y, Z))
   f.write("Bounds\n")
   f.write(bounds(X, Y, Z))
   f.write(" r >= 0 \setminus n")
   f.write("Binaries\n")
   f.write(binaries(X, Y, Z))
   f.write("End")
   f.close()
    return
def CPLEX(X: int, Y: int, Z: int, filename: str):
   Runs CPLEX optimisation on the LP file
   Saves STDOUT as a file in of form XYZOut.txt
   # Create output filename for CPLEX
   outputFile = f"{X}{Y}{Z}CPLEX.txt"
   # Paths for CPLEX and the LP file - Change if relevant
   CPLEXPath = "/csse/users/bma206/cplex/cplex/bin/x86-64_linux/cplex"
   filePath = "/media/bma206/8C0D-21E5/COSC364/PlanningAssignment/flow-
planning/"
   # Generate command from file paths and filename
    command = [CPLEXPath, "-c", "read " + filePath + filename, "optimize",
"display solution variables -"]
   # Starts a timer to measure execution time
   startTime = time.time()
   # Run CPLEX as a subprocess and wait for finish, then stop timer
   process = subprocess.Popen(command, stdout=open(outputFile, "wb"))
   process.wait()
   endTime = time.time()
   # Calculate and print execution time to 3dp
   timeTaken = endTime - startTime
   print(f"CPLEX Execution Time: {timeTaken:.3f}s")
   return
def demandVolume(X: int, Y: int, Z: int) -> str:
    """Returns demand volume constraints"""
   output = ""
   for i in range(1, X+1):
        for j in range(1, Z+1):
            output += " "
            for k in range(1, Y+1):
```

```
if k != (Y):
                    output += f''x\{i\}\{k\}\{j\} + "
                    output += f''x\{i\}\{k\}\{j\} = \{i+j\}\n''
    return output
def binaryVariable(X: int, Y: int, Z: int) -> str:
    """Returns binary variable constraints"""
    output = ""
    for i in range(1, X+1):
        for j in range(1, Z+1):
            output += "
            for k in range(1, Y+1):
                if k != (Y):
                    output += f''u\{i\}\{k\}\{j\} + "
                else:
                    output += f"u{i}{k}{j} = 2\n"
    return output
def demandFlow(X: int, Y: int, Z: int) -> str:
    """Returns demand flow constraints"""
    output = ""
    for i in range(1, X+1):
        for j in range(1, Z+1):
            for k in range(1, Y+1):
                output += f" 2 x{i}{k}{j} - {i+j} u{i}{k}{j} = 0 n"
    return output
def sourceTransitCap(X: int, Y: int, Z: int) -> str:
    """Returns source-transit capacity constraints"""
    output = ""
    for i in range (1, X+1):
        for k in range (1, Y+1):
            output += " "
            for j in range(1, Z+1):
                if j != (Z):
                    output += f''x\{i\}\{k\}\{j\} + "
                else:
                    output += f''x\{i\}\{k\}\{j\} - c\{i\}\{k\} <= 0 n''
    return output
def transitDestinationCap(X: int, Y: int, Z: int) -> str:
    """Returns transit-destination capacity constraints"""
    output = ""
    for k in range(1, Y+1):
        for j in range(1, Z+1):
            output += " "
            for i in range(1, X+1):
```

```
if i != (X):
                     output += f''x\{i\}\{k\}\{j\} + "
                     output += f''x\{i\}\{k\}\{j\} - d\{k\}\{j\} <= 0 n''
    return output
def loadBalancing(X: int, Y: int, Z: int) -> str:
    """Returns load balancing constraints"""
    output = ""
    for k in range(1, Y+1):
        output += "
        for j in range(1, Z+1):
            for i in range(1, X+1):
                if i != (X) or j != (Z):
                     output += f''x\{i\}\{k\}\{j\} + "
                else:
                     output += f''x\{i\}\{k\}\{j\} - r <= 0 \n''
    return output
def bounds(X: int, Y: int, Z: int) -> str:
    """Returns the bounds of x, c and d"""
    output = ""
    for i in range(1, X+1):
        for k in range(1, Y+1):
            for j in range(1, Z+1):
                output += f'' x{i}{k}{j} >= 0n''
    for i in range(1, X+1):
        for k in range(1, Y+1):
            output += f'' c\{i\}\{k\} >= 0 n''
    for k in range(1, Y+1):
        for j in range(1, Z+1):
            output += f'' d\{k\}\{j\} >= 0 n''
    return output
def binaries(X: int, Y: int, Z: int) -> str:
    """Returns binary constraints"""
    output = ""
    for i in range(1, X+1):
        for k in range(1, Y+1):
            for j in range(1, Z+1):
                output += f'' u{i}{k}{j}\n''
    return output
def main():
    Main function: Creates file with inputted X, Y, and Z
    Writes constraints formula to XYZ.lp
    Runs CPLEX optimization on file and saves to XYZCPLEX.txt
```

```
X, Y, Z, filename = createLPFileName()
writeContraints(X, Y, Z, filename)
CPLEX(X, Y, Z, filename)

if (__name__ == "__main__"):
    main()
```

LP file (XYZ) = (323):

Minimize

r

Subject to

- x111 + x121 = 2
- x112 + x122 = 3
- x113 + x123 = 4
- x211 + x221 = 3
- x212 + x222 = 4
- x213 + x223 = 5
- x311 + x321 = 4
- x312 + x322 = 5
- x313 + x323 = 6
- u111 + u121 = 2
- u112 + u122 = 2
- u113 + u123 = 2
- u211 + u221 = 2
- u212 + u222 = 2
- u213 + u223 = 2
- u311 + u321 = 2
- u312 + u322 = 2
- u313 + u323 = 2
- 2 x111 2 u111 = 0
- 2 x121 2 u121 = 0
- 2 x112 3 u112 = 0
- 2 x122 3 u122 = 0
- 2 x113 4 u113 = 0
- 2 x123 4 u123 = 0
- 2 x211 3 u211 = 0
- 2 x221 3 u221 = 0

$$2 \times 223 - 5 \times 223 = 0$$

$$x111 + x112 + x113 - c11 \le 0$$

$$x111 + x211 + x311 + x112 + x212 + x312 + x113 + x213 + x313 - r \le 0$$

$$x121 + x221 + x321 + x122 + x222 + x322 + x123 + x223 + x323 - r \le 0$$

Bounds

$$x111 >= 0$$

$$x112 >= 0$$

$$x113 >= 0$$

$$x122 >= 0$$

$$x123 >= 0$$

- x211 >= 0
- x212 >= 0
- x213 >= 0
- x221 >= 0
- x222 >= 0
- x223 >= 0
- x311 >= 0
- x312 >= 0
- x313 >= 0
- x321 >= 0
- x322 >= 0
- x323 >= 0
- c11 >= 0
- c12 >= 0
- c21 >= 0
- c22 >= 0
- c31 >= 0
- c32 >= 0
- d11 >= 0
- d12 >= 0
- d13 >= 0
- d21 >= 0
- d22 >= 0
- d23 >= 0
- r >= 0

Binaries

- u111
- u112
- u113
- u121
- u122

u123

u211

u212

u213

u221

u222

u223

u311

u312

u313

u321

u322

u323

End