IK200
ARSITEKTUR DAN ORGANISASI KOMPUTER

Yudi Ahmad Hambali, M.T.
yudi.a.hambali@upi.edu

System Interconnection dan Sistem Bus

Program Concept

- Hardwired systems are inflexible
- General purpose hardware can do different tasks, given correct control signals
- Instead of re-wiring, supply a new set of control signals

What is a program?

A sequence of steps

For each step, an arithmetic or logical operation is done

For each operation, a different set of control signals is needed

Function of Control Unit

For each operation a unique code is provided

e.g. ADD, MOVE

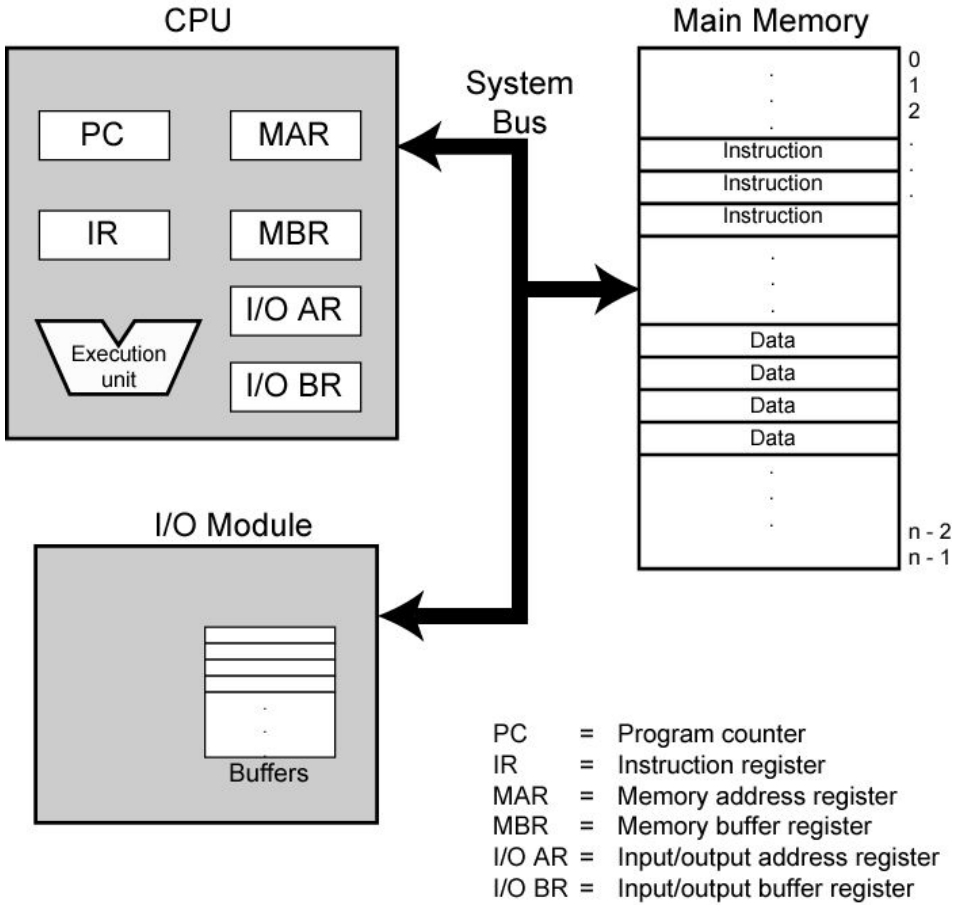
A hardware segment accepts the code and issues the control signals

We have a COMPUTER!

Components

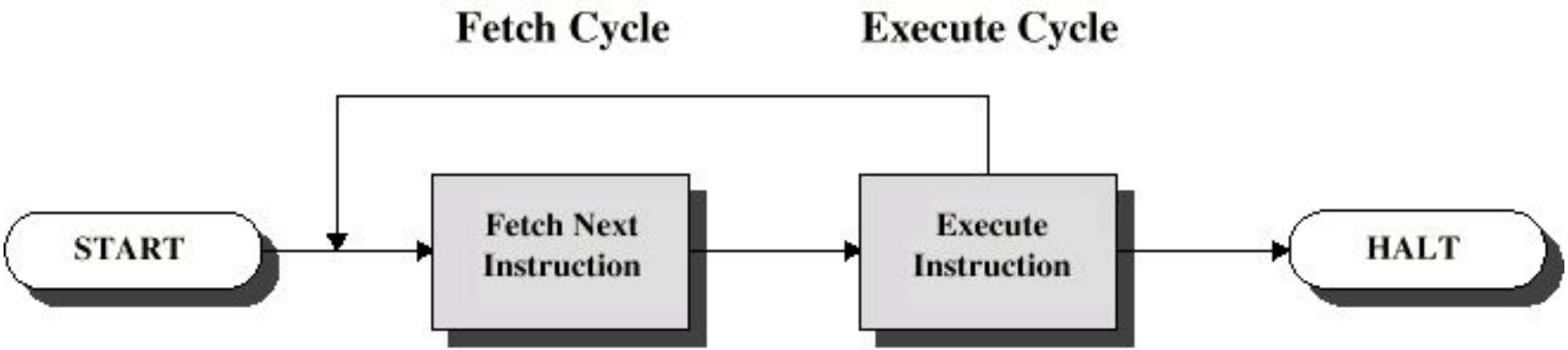
- The Control Unit and the Arithmetic and Logic Unit constitute the Central Processing Unit
- Data and instructions need to get into the system and results out
  - Input/output
- Temporary storage of code and results is needed
  - Main memory

Computer Components: Top Level View



Instruction Cycle (Siklus Instruksi)

- Two steps:
  - Fetch
  - Execute



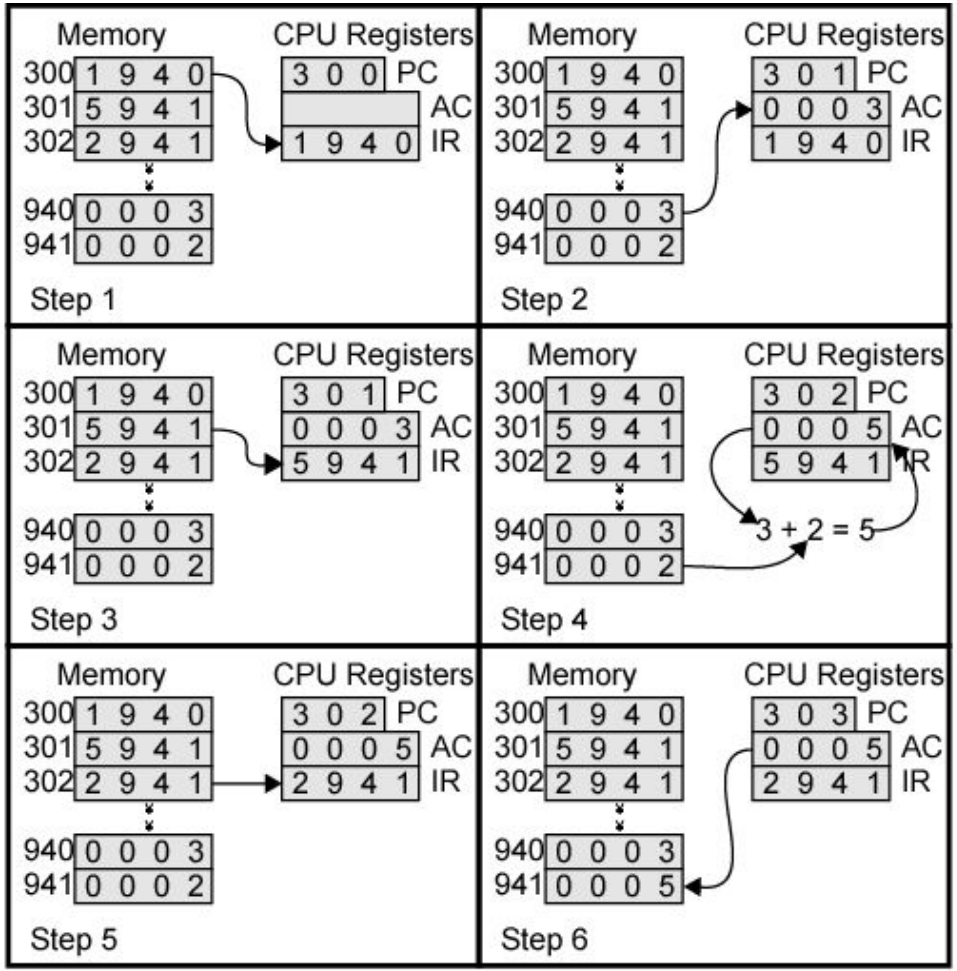
Fetch Cycle

- Program Counter (PC) holds address of next instruction to fetch
- Processor fetches instruction from memory location pointed to by PC
- Increment PC
  - Unless told otherwise
- Instruksi dimuat ke Instruction Register (IR)
- Prosesor menafsirkan (interprets) instruksi dan melakukan tindakan yang diperlukan

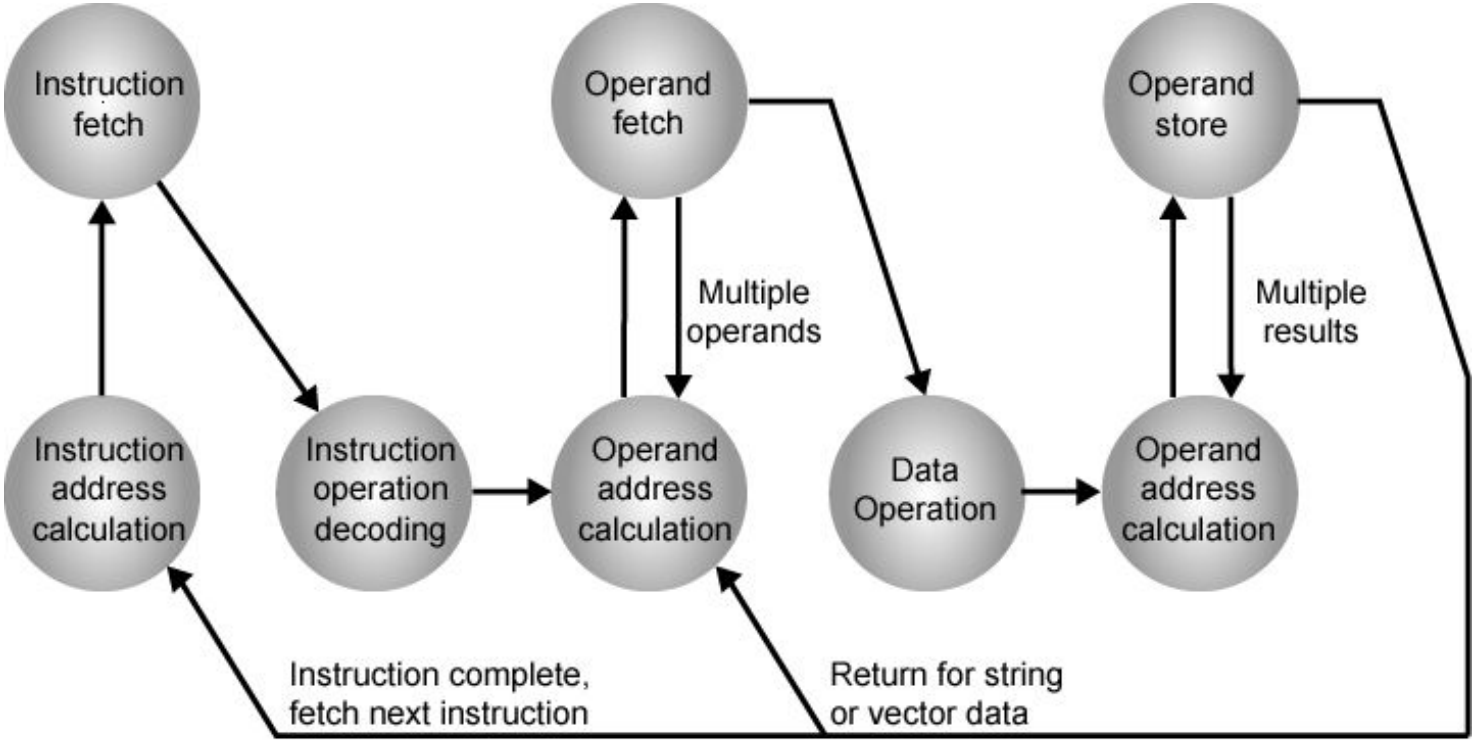
Execute Cycle

- Processor-memory
  - Data transfer between CPU and main memory
- Processor I/O
  - Data transfer between CPU and I/O module
- Data processing
  - Some arithmetic or logical operation on data
- Control
  - Alteration of sequence of operations (perubahan urutan operasi)
  - e.g. jump
- Combination of above

Example of Program Execution



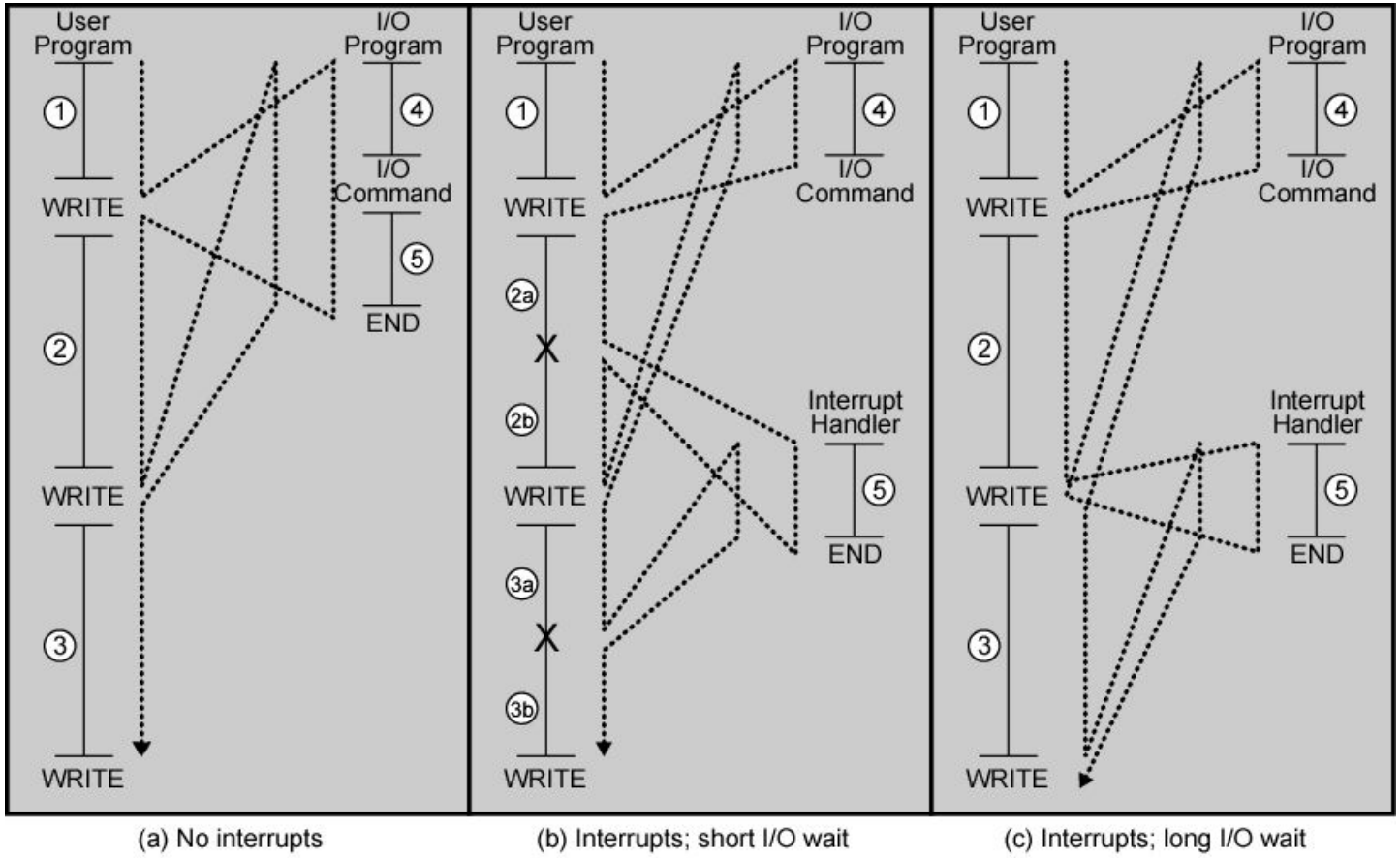
Instruction Cycle State Diagram



Interrupts

- Mechanism by which other modules (e.g. I/O) may interrupt normal sequence of processing
- Program
  - e.g. overflow, division by zero
- Timer
  - Generated by internal processor timer
  - Used in pre-emptive multitasking
- I/O
  - from I/O controller
- Hardware failure
  - e.g. memory parity error

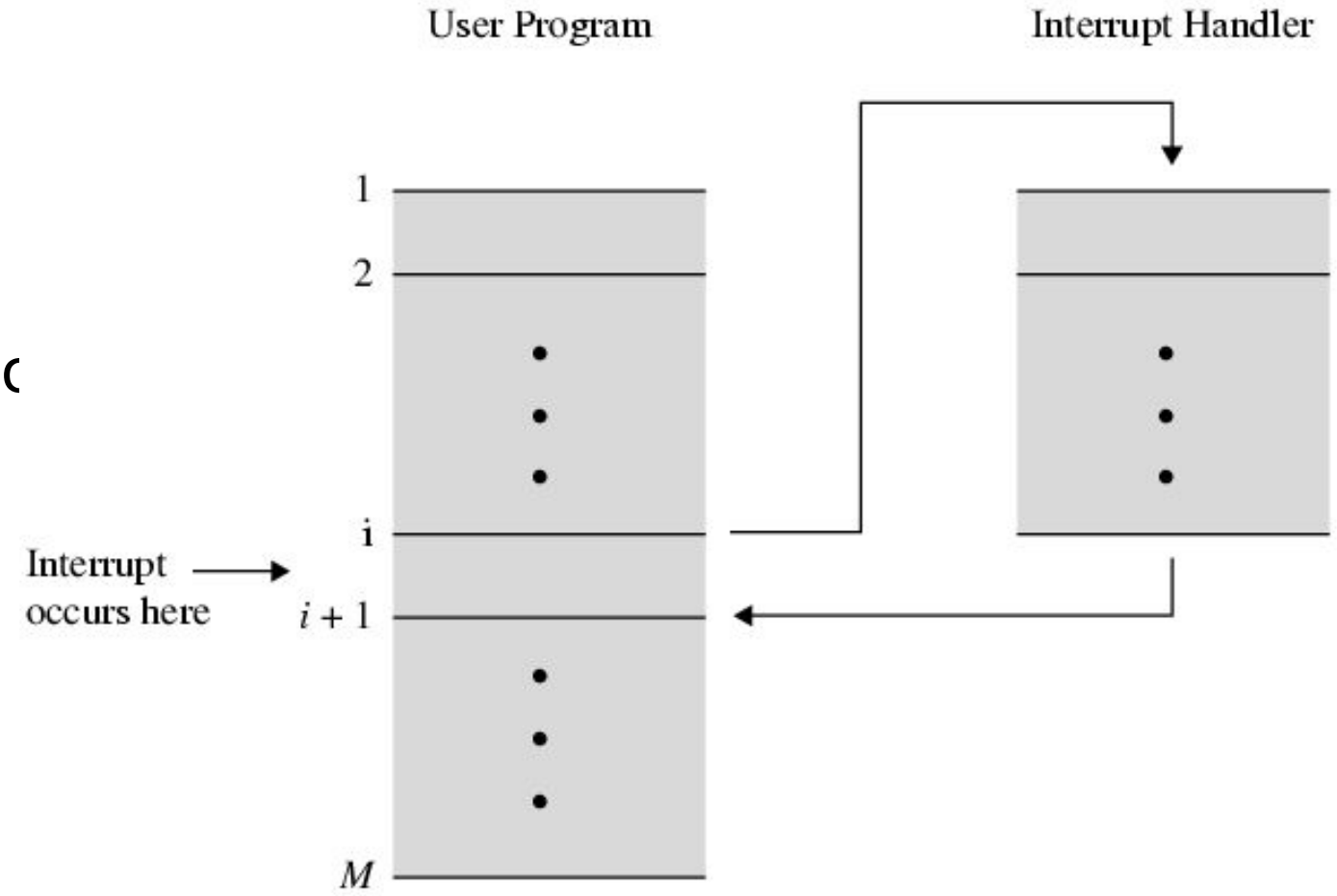
Program Flow Control



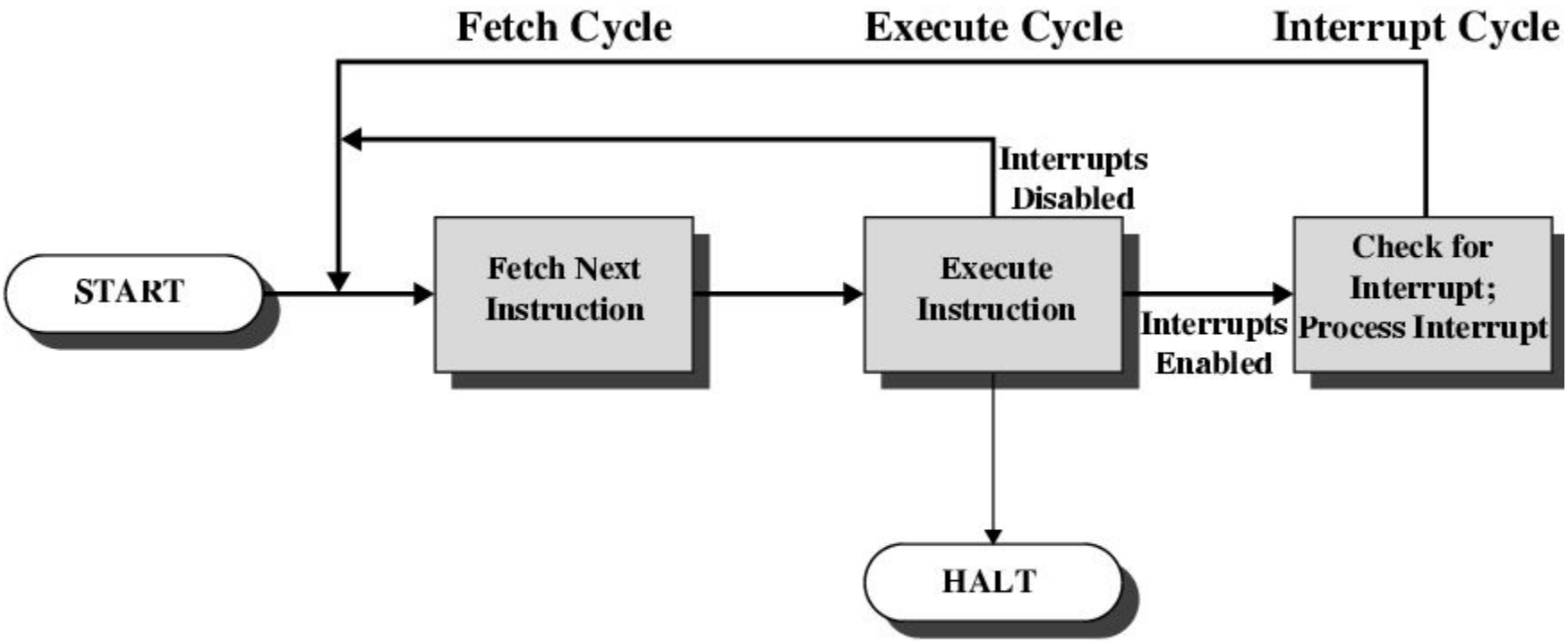
Interrupt Cycle

- Added to instruction cycle
- Processor checks for interrupt
  - Indicated by an interrupt signal
- If no interrupt, fetch next instruction
- If interrupt pending:
  - Suspend execution of current program
  - Save context
  - Set PC to start address of interrupt handler routine
  - Process interrupt
  - Restore context and continue interrupted program

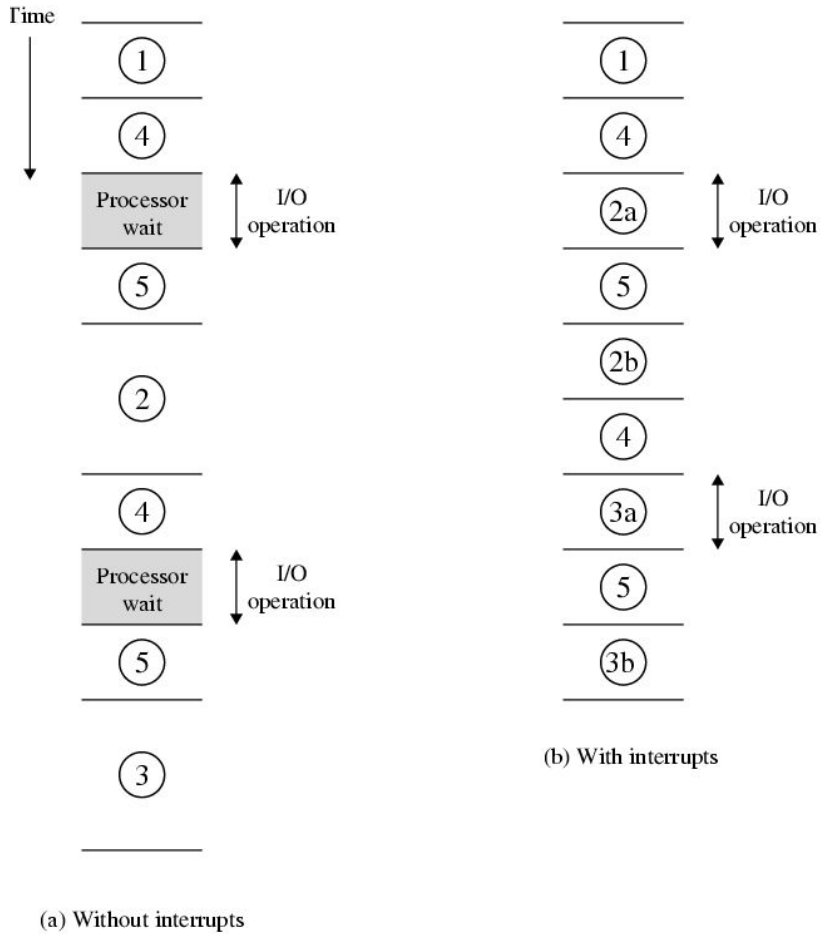
Transfer of Cc via Interrupts



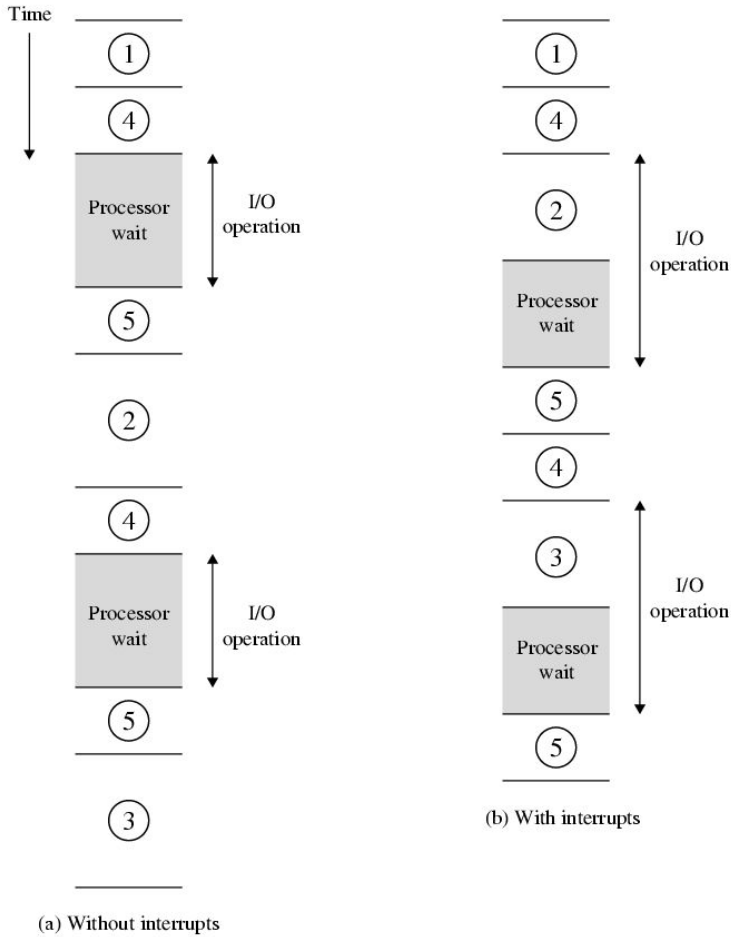
Instruction Cycle with Interrupts



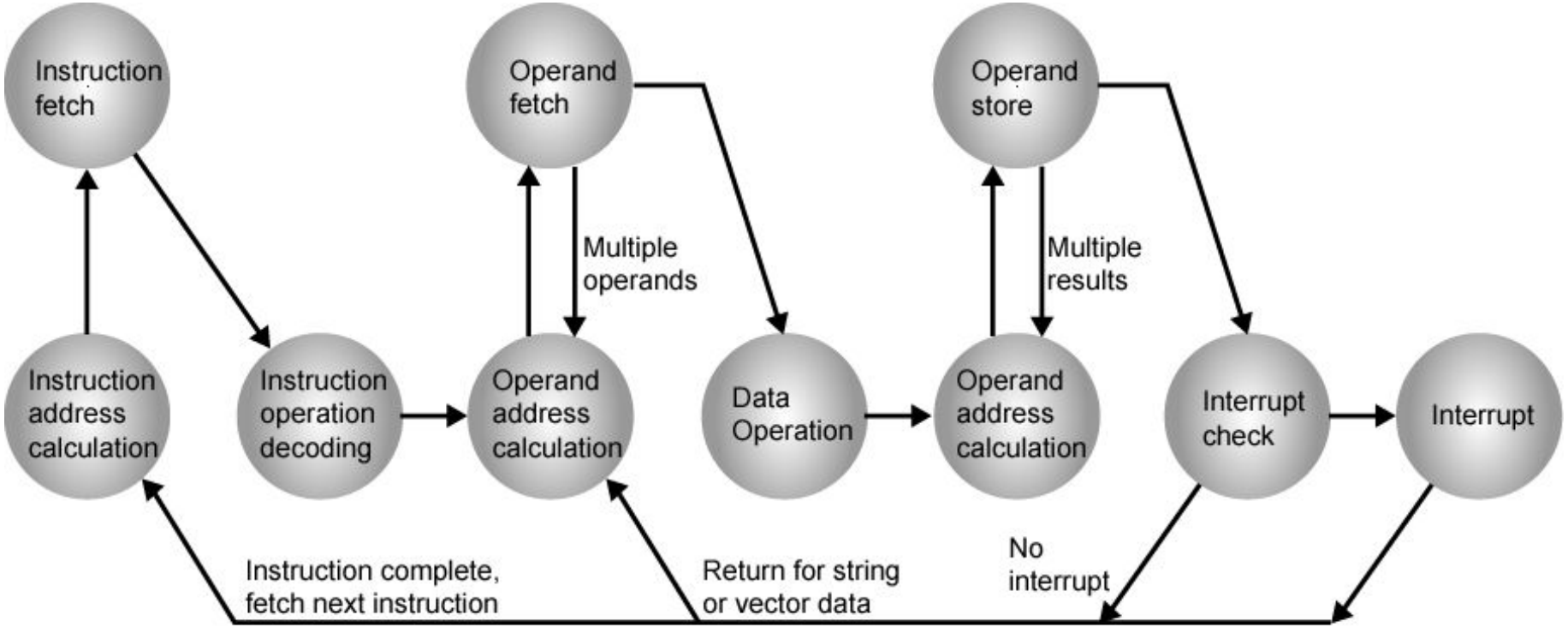
Program Timing
Short I/O Wait



Program Timing
Long I/O Wait



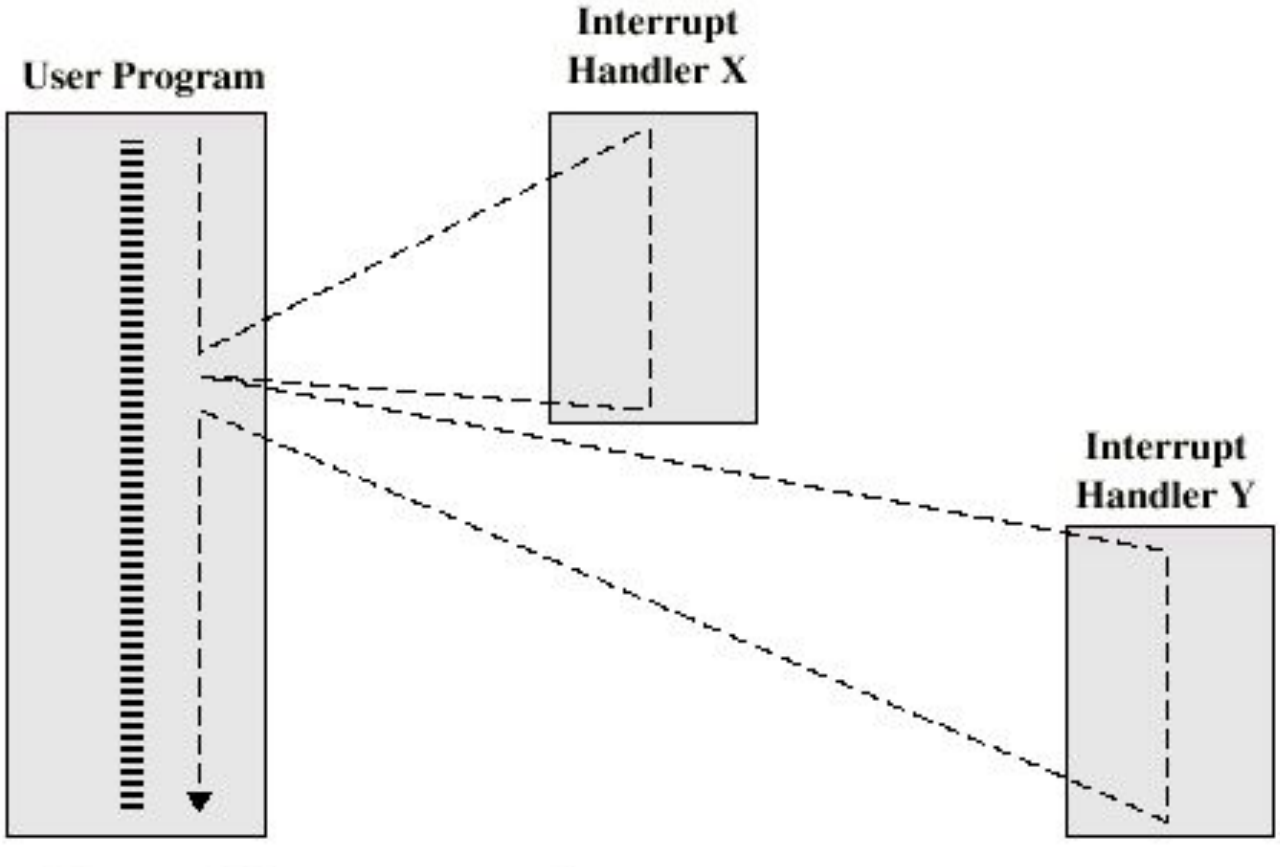
Instruction Cycle (with Interrupts) - State Diagram



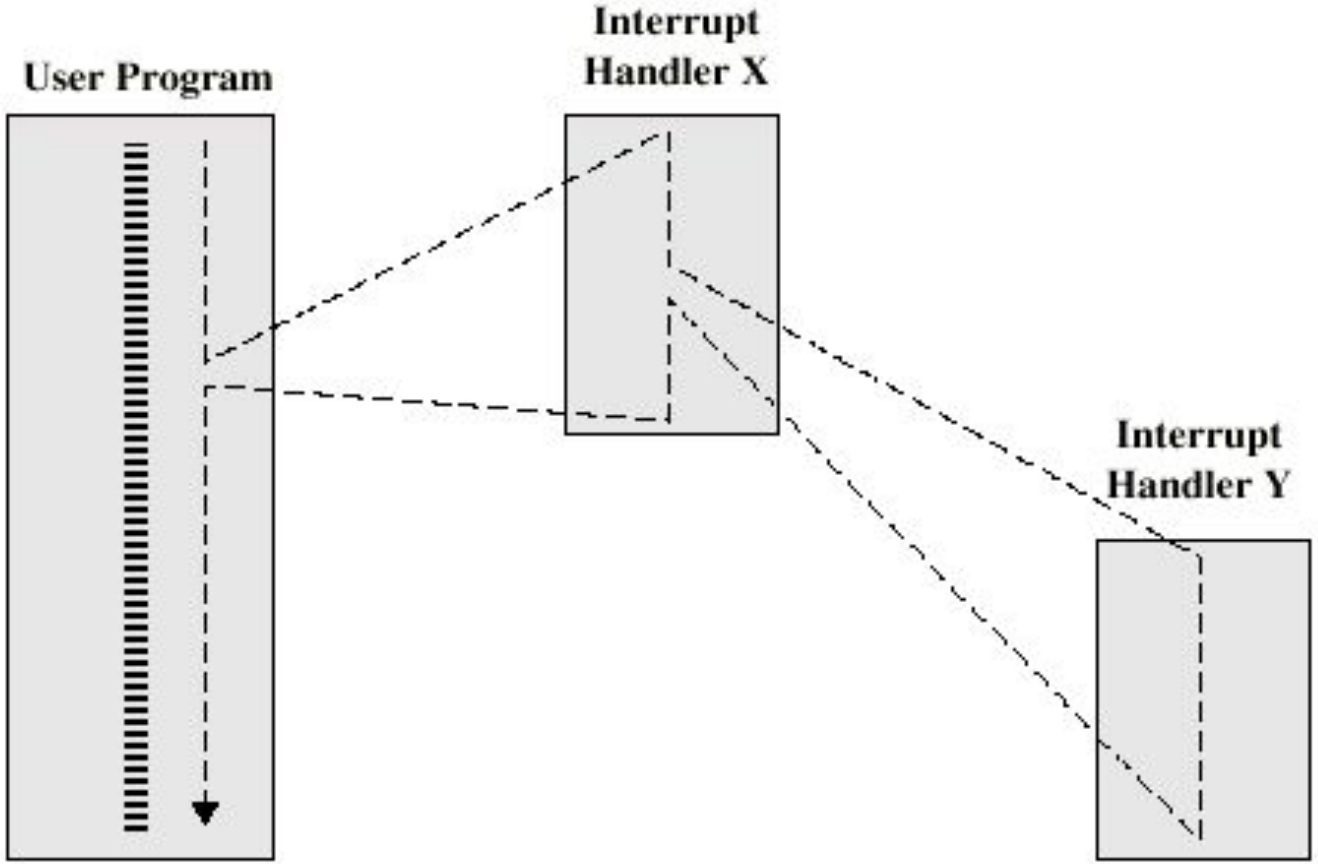
Multiple Interrupts

- Disable interrupts
  - Processor will ignore further interrupts whilst processing one interrupt
  - Interrupts remain pending and are checked after first interrupt has been processed
  - Interrupts handled in sequence as they occur
- Define priorities
  - Low priority interrupts can be interrupted by higher priority interrupts
  - When higher priority interrupt has been processed, processor returns to previous interrupt

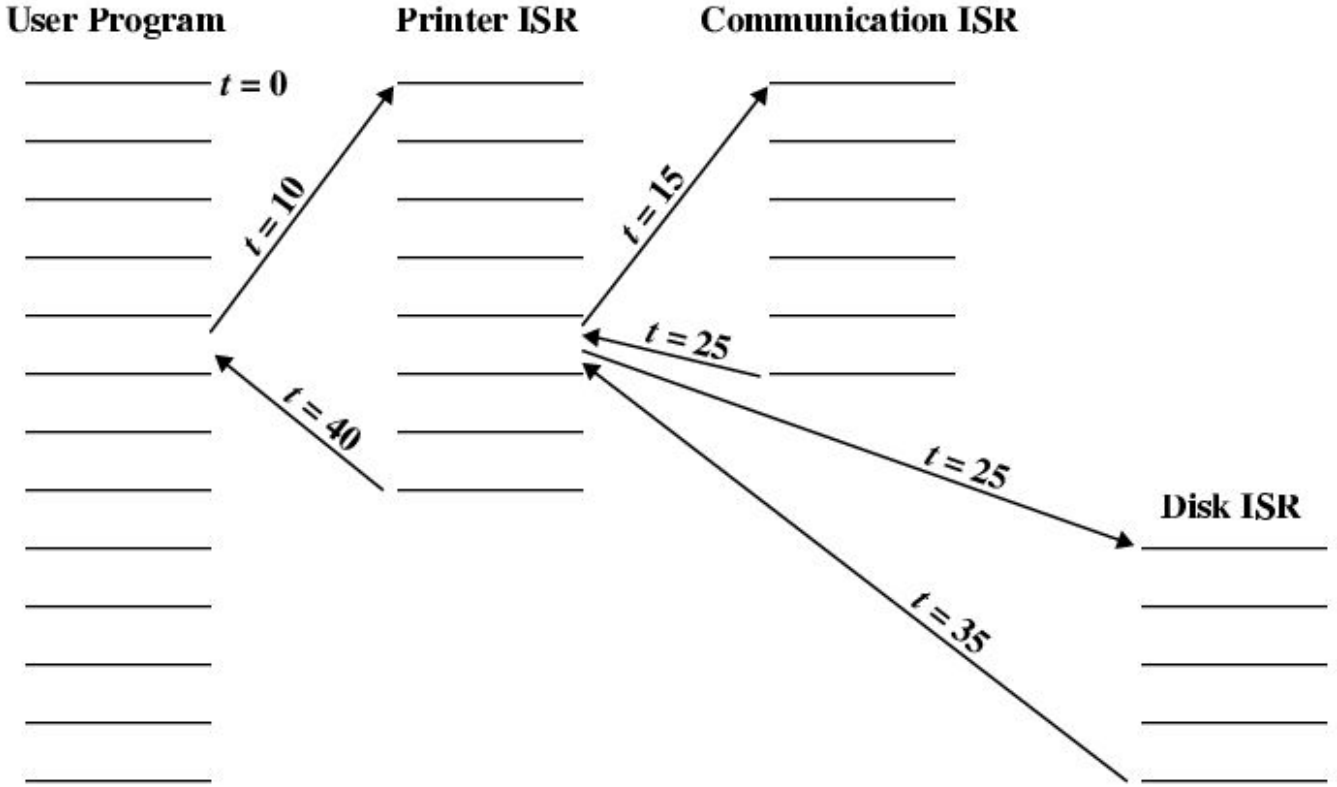
Multiple Interrupts - Sequential



Multiple Interrupts – Nested



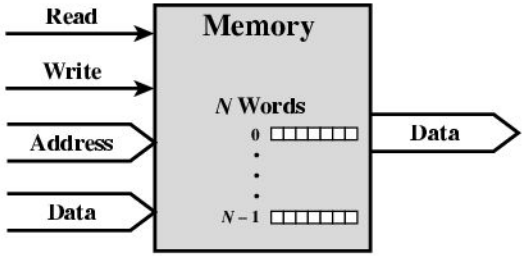
Time Sequence of Multiple Interrupts

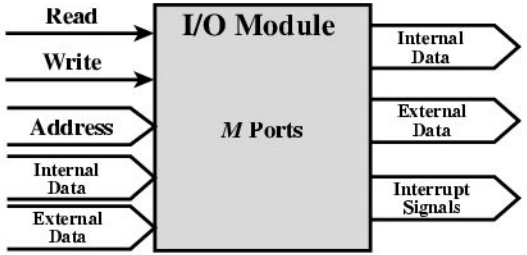


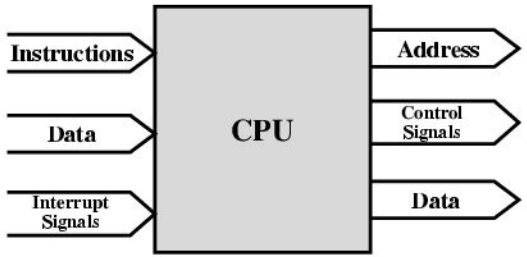
Connecting

- All the units must be connected
- Different type of connection for different type of unit
  - Memory
  - Input/Output
  - CPU

Computer Modules







Memory Connection

- Receives and sends data
- Receives addresses (of locations)
- Receives control signals
  - Read
  - Write
  - Timing

Input/Output Connection

- Similar to memory from computer's viewpoint
- Output
  - Receive data from computer
  - Send data to peripheral
- Input
  - Receive data from peripheral
  - Send data to computer

Input/Output Connection (2)

- Receive control signals from computer
- Send control signals to peripherals
  - e.g. spin disk
- Receive addresses from computer
  - e.g. port number to identify peripheral
- Send interrupt signals (control)

CPU Connection

- Reads instruction and data
- Writes out data (after processing)
- Sends control signals to other units
- Receives (& acts on) interrupts

Buses

- There are a number of possible interconnection systems
- Single and multiple BUS structures are most common
- e.g. Control/Address/Data bus (PC)
- e.g. Unibus (DEC-PDP)

What is a Bus?

- A communication pathway connecting two or more devices
- Usually broadcast
- Often grouped
  - A number of channels in one bus
  - e.g. 32 bit data bus is 32 separate single bit channels
- Power lines may not be shown

Data Bus

- Carries data
  - Remember that there is no difference between “data” and “instruction” at this level
- Width is a key determinant of performance
  - 8, 16, 32, 64 bit

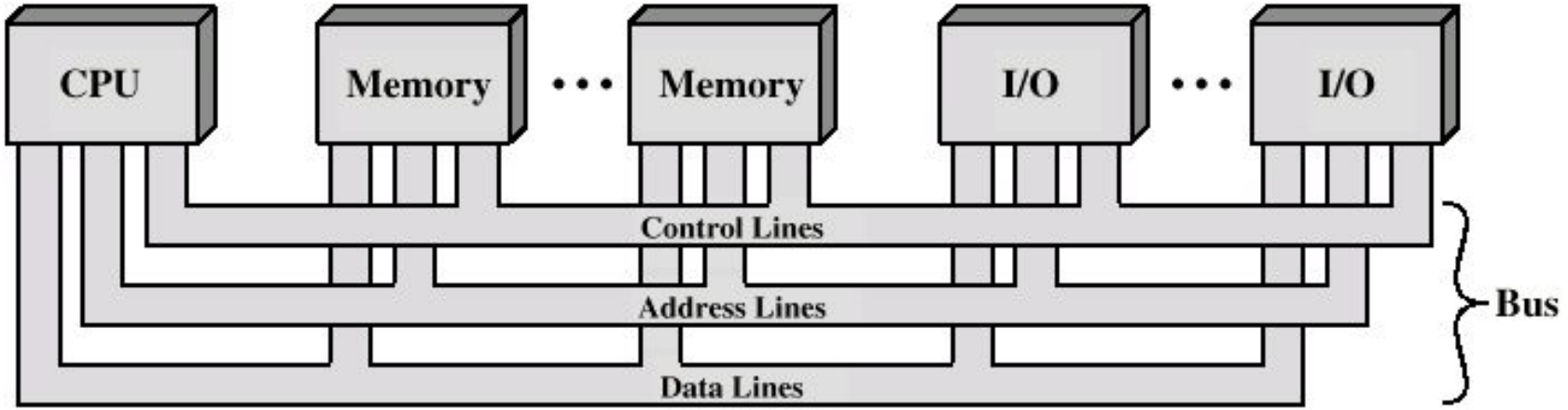
Address Bus

- Identify the source or destination of data
- e.g. CPU needs to read an instruction (data) from a given location in memory
- Bus width determines maximum memory capacity of system
  - e.g. 8080 has 16 bit address bus giving 64k address space

Control Bus

- Control and timing information
  - Memory read/write signal
  - Interrupt request
  - Clock signals

Bus Interconnection Scheme



Reference

Stallings William, Computer Organization and Architecture 7th Edition.

Stallings William, Computer Organization and Architecture 11th Edition.

Randal E. Bryant, Computer System: A Programmer’s Perspective.