# **Fully connected networks**

In the previous notebook, you implemented a simple two-layer neural network class. However, this class is not modular. If you wanted to change the number of layers, you would need to write a new loss and gradient function. If you wanted to optimize the network with different optimizers, you'd need to write new training functions. If you wanted to incorporate regularizations, you'd have to modify the loss and gradient function.

Instead of having to modify functions each time, for the rest of the class, we'll work in a more modular framework where we define forward and backward layers that calculate losses and gradients respectively. Since the forward and backward layers share intermediate values that are useful for calculating both the loss and the gradient, we'll also have these function return "caches" which store useful intermediate values.

The goal is that through this modular design, we can build different sized neural networks for various applications.

In this HW #3, we'll define the basic architecture, and in HW #4, we'll build on this framework to implement different optimizers and regularizations (like BatchNorm and Dropout).

CS231n has built a solid API for building these modular frameworks and training them, and we will use their very well implemented framework as opposed to "reinventing the wheel." This includes using their Solver, various utility functions, and their layer structure. This also includes nndl.fc\_net, nndl.layers, and nndl.layer\_utils. As in prior assignments, we thank Serena Yeung & Justin Johnson for permission to use code written for the CS 231n class (cs231n.stanford.edu).

## **Modular layers**

This notebook will build modular layers in the following manner. First, there will be a forward pass for a given layer with inputs (x) and return the output of that layer (out) as well as cached variables (cache) that will be used to calculate the gradient in the backward pass.

```
def layer_forward(x, w):
    """ Receive inputs x and weights w """
    # Do some computations ...
    z = # ... some intermediate value
    # Do some more computations ...
    out = # the output

cache = (x, w, z, out) # Values we need to compute gradients
    return out, cache
```

The backward pass will receive upstream derivatives and the cache object, and will return gradients with respect to the inputs and weights, like this:

```
def layer_backward(dout, cache):
    """
    Receive derivative of loss with respect to outputs and cache,
    and compute derivative with respect to inputs.
    """
    # Unpack cache values
    x, w, z, out = cache

# Use values in cache to compute derivatives
    dx = # Derivative of loss with respect to x
    dw = # Derivative of loss with respect to w
return dx, dw
```

```
In [107]: ## Import and setups
           import time
           import numpy as np
           import matplotlib.pyplot as plt
           from nndl.fc net import *
           from cs231n.data utils import get CIFAR10 data
           from cs231n.gradient check import eval numerical gradient, eval numer
           ical gradient array
           from cs231n.solver import Solver
           %matplotlib inline
           plt.rcParams['figure.figsize'] = (10.0, 8.0) # set default size of pl
           plt.rcParams['image.interpolation'] = 'nearest'
           plt.rcParams['image.cmap'] = 'gray'
           # for auto-reloading external modules
           # see http://stackoverflow.com/questions/1907993/autoreload-of-module
           s-in-ipvthon
           %load ext autoreload
           %autoreload 2
           def rel error(x, y):
             """ returns relative error """
             return np.max(np.abs(x - y) / (np.maximum(1e-8, np.abs(x) + y)) / (np.maximum(1e-8, np.abs(x) + y))
           np.abs(y)))
          The autoreload extension is already loaded. To reload it, use:
            %reload ext autoreload
In [108]: # Load the (preprocessed) CIFAR10 data.
           data = get CIFAR10 data()
           for k in data.kevs():
             print('{}: {} '.format(k, data[k].shape))
          X val: (1000, 3, 32, 32)
          X_train: (49000, 3, 32, 32)
          X test: (1000, 3, 32, 32)
          y val: (1000,)
          y train: (49000,)
```

## **Linear layers**

In this section, we'll implement the forward and backward pass for the linear layers.

The linear layer forward pass is the function affine\_forward in nndl/layers.py and the backward pass is affine backward.

After you have implemented these, test your implementation by running the cell below.

y test: (1000,)

## **Affine layer forward pass**

Implement affine forward and then test your code by running the following cell.

```
In [109]: # Test the affine forward function
           num inputs = 2
           input shape = (4, 5, 6)
           output dim = 3
           input size = num inputs * np.prod(input shape)
           weight size = output dim * np.prod(input shape)
           x = np.linspace(-0.1, 0.5, num=input size).reshape(num inputs, *input
           \overline{w} = \text{np.linspace}(-0.2, 0.3, \text{num=weight size}).\text{reshape}(\text{np.prod}(\text{input sha}))
           pe), output dim)
           b = np.linspace(-0.3, 0.1, num=output dim)
           out, = affine forward(x, w, b)
           correct_out = np.array([[ 1.49834967,  1.70660132,  1.91485297],
                                     [ 3.25553199, 3.5141327,
                                                                   3.77273342]])
           # Compare your output with ours. The error should be around 1e-9.
           print('Testing affine forward function:')
           print('difference: {}'.format(rel error(out, correct out)))
```

Testing affine\_forward function: difference: 9.76984946819e-10

## Affine layer backward pass

Implement affine\_backward and then test your code by running the following cell.

```
In [110]: # Test the affine backward function
          x = np.random.randn(10, 2, 3)
          w = np.random.randn(6, 5)
          b = np.random.randn(5)
          dout = np.random.randn(10, 5)
          dx num = eval numerical gradient array(lambda x: affine forward(x, w,
           b)[0], x, dout)
          dw num = eval numerical gradient array(lambda w: affine forward(x, w,
           b)[0], w, dout)
          db num = eval numerical gradient array(lambda b: affine forward(x, w,
           b)[0], b, dout)
           _, cache = affine_forward(x, w, b)
          \overline{dx}, dw, db = affine_backward(dout, cache)
          # The error should be around 1e-10
          print('Testing affine backward function:')
          print('dx error: {}'.format(rel error(dx num, dx)))
          print('dw error: {}'.format(rel error(dw num, dw)))
          print('db error: {}'.format(rel error(db num, db)))
          Testing affine backward function:
          dx error: 8.60871575069e-11
```

0X error: 8.008/15/5009e-11

dw error: 5.16849626491e-11 db error: 6.21942801469e-11

## **Activation layers**

In this section you'll implement the ReLU activation.

## **ReLU forward pass**

Implement the relu\_forward function in nndl/layers.py and then test your code by running the following cell.

```
In [111]: # Test the relu forward function
          x = np.linspace(-0.5, 0.5, num=12).reshape(3, 4)
          out, = relu forward(x)
          correct_out = np.array([[ 0.,
                                                 0.,
                                                               0.,
                                                                            0.,
                                   [ 0.,
                                                 0.,
                                                               0.04545455.
                                                                            0.13
          636364,],
                                   [ 0.22727273, 0.31818182, 0.40909091,
                                                                            0.5,
                 ]])
          # Compare your output with ours. The error should be around 1e-8
          print('Testing relu forward function:')
          print('difference: {}'.format(rel error(out, correct out)))
          Testing relu forward function:
```

# ReLU backward pass

Implement the relu\_backward function in nndl/layers.py and then test your code by running the following cell.

Testing relu\_backward function: dx error: 3.27561396362e-12

difference: 4.9999979802e-08

# Combining the affine and ReLU layers

Often times, an affine layer will be followed by a ReLU layer. So let's make one that puts them together. Layers that are combined are stored in nndl/layer utils.py.

## **Affine-ReLU layers**

We've implemented affine\_relu\_forward() and affine\_relu\_backward in nndl/layer\_utils.py. Take a look at them to make sure you understand what's going on. Then run the following cell to ensure its implemented correctly.

```
In [113]: from nndl.layer utils import affine relu forward, affine relu backwar
          x = np.random.randn(2, 3, 4)
          w = np.random.randn(12, 10)
          b = np.random.randn(10)
          dout = np.random.randn(2, 10)
          out, cache = affine relu forward(x, w, b)
          dx, dw, db = affine relu backward(dout, cache)
          dx num = eval numerical gradient array(lambda x:
          affine relu forward(x, w, b)[0], x, dout)
          dw num = eval numerical gradient array(lambda w:
          affine relu forward(x, w, b)[0], w, dout)
          db num = eval numerical gradient array(lambda b:
          affine relu forward(x, w, b)[0], b, dout)
          print('Testing affine relu forward and affine relu backward:')
          print('dx error: {}'.format(rel_error(dx_num, dx)))
          print('dw error: {}'.format(rel error(dw num, dw)))
          print('db error: {}'.format(rel error(db num, db)))
          Testing affine relu forward and affine relu backward:
          dx error: 1.47423906121e-08
          dw error: 9.4703746119e-10
          db error: 1.35072953084e-11
```

## **Softmax and SVM losses**

You've already implemented these, so we have written these in layers.py. The following code will ensure they are working correctly.

```
num_classes, num_inputs = 10, 50
In [114]:
          x = 0.001 * np.random.randn(num inputs, num_classes)
          y = np.random.randint(num classes, size=num inputs)
          dx num = eval numerical gradient(lambda x: svm loss(x, y)[0], x, verb
          ose=False)
          loss, dx = svm loss(x, y)
          # Test svm loss function. Loss should be around 9 and dx error should
           be 1e-9
          print('Testing svm loss:')
          print('loss: {}'.format(loss))
          print('dx error: {}'.format(rel error(dx num, dx)))
          dx num = eval numerical gradient(lambda \times softmax loss(x, y)[0], x,
          verbose=False)
          loss, dx = softmax loss(x, y)
          # Test softmax loss function. Loss should be 2.3 and dx error should
           be 1e-8
          print('\nTesting softmax loss:')
          print('loss: {}'.format(loss))
          print('dx error: {}'.format(rel error(dx num, dx)))
          Testing svm loss:
          loss: 9.00013162042
          dx error: 3.0387355051e-09
          Testing softmax loss:
          loss: 2.30259872626
```

Implementation of a two-layer NN

dx error: 1.0323036143e-08

In nndl/fc\_net.py, implement the class TwoLayerNet which uses the layers you made here. When you have finished, the following cell will test your implementation.

```
In [115]: N, D, H, C = 3, 5, 50, 7
    X = np.random.randint(C, size=N)

std = le-2
    model = TwoLayerNet(input_dim=D, hidden_dims=H, num_classes=C, weight _scale=std)

print('Testing initialization ... ')
    W1_std = abs(model.params['W1'].std() - std)
    b1 = model.params['b1']
    W2_std = abs(model.params['W2'].std() - std)
    b2 = model.params['b2']
    assert W1_std < std / 10, 'First layer weights do not seem right'
    assert mp.all(b1 == 0), 'First layer biases do not seem right'
    assert W2_std < std / 10, 'Second layer weights do not seem right'
    assert np.all(b2 == 0), 'Second layer biases do not seem right'
</pre>
```

```
print('Testing test-time forward pass ... ')
model.params['W1'] = np.linspace(-0.7, 0.3, num=D*H).reshape(D, H)
model.params['b1'] = np.linspace(-0.1, 0.9, num=H)
model.params['W2'] = np.linspace(-0.3, 0.4, num=H*C).reshape(H, C)
model.params['b2'] = np.linspace(-0.9, 0.1, num=C)
X = np.linspace(-5.5, 4.5, num=N*D).reshape(D, N).T
scores = model.loss(X)
correct scores = np.asarray(
  [[11.53165108, 12.2917344,
                                13.05181771, 13.81190102,
                                                            14.571984
34, 15.33206765, 16.09215096],
   [12.05769098, 12.74614105, 13.43459113, 14.1230412,
                                                             14.811491
28, 15.49994135, 16.18839143],
   [12.58373087, 13.20054771, 13.81736455, 14.43418138,
                                                            15.050998
22, 15.66781506, 16.2846319 ]])
scores diff = np.abs(scores - correct scores).sum()
assert scores diff < 1e-6, 'Problem with test-time forward pass'</pre>
print('Testing training loss (no regularization)')
y = np.asarray([0, 5, 1])
loss, grads = model.loss(X, y)
correct loss = 3.4702243556
assert abs(loss - correct loss) < 1e-10, 'Problem with training-time</pre>
 loss'
model.reg = 1.0
loss, grads = model.loss(X, y)
correct loss = 26.5948426952
assert abs(loss - correct loss) < 1e-10, 'Problem with regularization
 loss'
for reg in [0.0, 0.7]:
  print('Running numeric gradient check with reg = {}'.format(reg))
  model.reg = reg
  loss, grads = model.loss(X, y)
  for name in sorted(grads):
    f = lambda : model.loss(X, y)[0]
    grad num = eval numerical gradient(f, model.params[name],
verbose=False)
    print('{} relative error: {}'.format(name, rel error(grad num, gr
ads[name])))
Testing initialization ...
Testing test-time forward pass ...
Testing training loss (no regularization)
Running numeric gradient check with reg = 0.0
W1 relative error: 1.83365627867e-08
W2 relative error: 3.11807423476e-10
b1 relative error: 9.82831520464e-09
b2 relative error: 4.32913495457e-10
Running numeric gradient check with reg = 0.7
W1 relative error: 2.52791523102e-07
W2 relative error: 7.97665280616e-08
b1 relative error: 1.34676189626e-08
b2 relative error: 7.75909428384e-10
```

## **Solver**

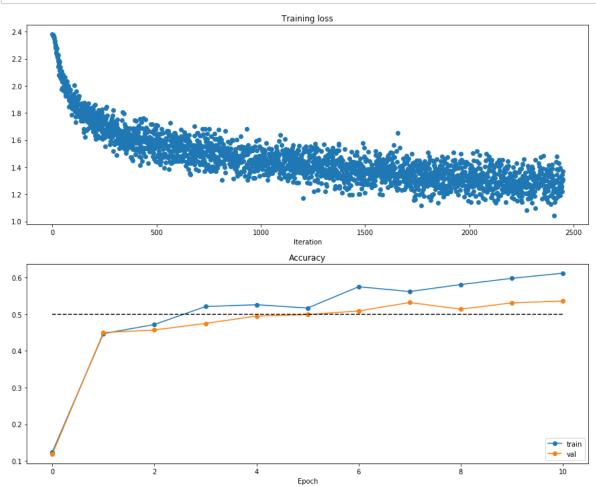
We will now use the cs231n Solver class to train these networks. Familiarize yourself with the API in cs231n/solver.py. After you have done so, declare an instance of a TwoLayerNet with 200 units and then train it with the Solver. Choose parameters so that your validation accuracy is at least 50%.

```
In [117]:
          model = TwoLayerNet()
          solver = None
          # YOUR CODE HERE:
              Declare an instance of a TwoLayerNet and then train
              it with the Solver. Choose hyperparameters so that your validatio
          n
          #
              accuracy is at least 40%. We won't have you optimize this furthe
          r
              since you did it in the previous notebook.
          model = TwoLayerNet(hidden dims=200, reg=.25)
          solver = Solver(model, data, print every=490,
                         batch size=200,
                         lr decay=.95,
                         optim_config = {
                              'learning rate' : 1e-3,
                         })
          solver.train()
          # END YOUR CODE HERE
          (Iteration 1 / 2450) loss: 2.381478
          (Epoch 0 / 10) train acc: 0.124000; val_acc: 0.118000
          (Epoch 1 / 10) train acc: 0.447000; val_acc: 0.450000
          (Epoch 2 / 10) train acc: 0.472000; val acc: 0.457000
          (Iteration 491 / 2450) loss: 1.457798
          (Epoch 3 / 10) train acc: 0.521000; val acc: 0.475000
          (Epoch 4 / 10) train acc: 0.526000; val acc: 0.495000
          (Iteration 981 / 2450) loss: 1.523241
          (Epoch 5 / 10) train acc: 0.517000; val acc: 0.499000
          (Epoch 6 / 10) train acc: 0.575000; val acc: 0.509000
          (Iteration 1471 / 2450) loss: 1.432054
          (Epoch 7 / 10) train acc: 0.562000; val acc: 0.532000
          (Epoch 8 / 10) train acc: 0.581000; val acc: 0.514000
          (Iteration 1961 / 2450) loss: 1.343220
          (Epoch 9 / 10) train acc: 0.598000; val acc: 0.531000
          (Epoch 10 / 10) train acc: 0.612000; val acc: 0.536000
```

In [118]: # Run this cell to visualize training loss and train / val accuracy

plt.subplot(2, 1, 1)
plt.title('Training loss')
plt.plot(solver.loss\_history, 'o')
plt.xlabel('Iteration')

plt.subplot(2, 1, 2)
plt.title('Accuracy')
plt.plot(solver.train\_acc\_history, '-o', label='train')
plt.plot(solver.val\_acc\_history, '-o', label='val')
plt.plot([0.5] \* len(solver.val\_acc\_history), 'k--')
plt.xlabel('Epoch')
plt.legend(loc='lower right')
plt.gcf().set\_size\_inches(15, 12)
plt.show()



## **Multilayer Neural Network**

Now, we implement a multi-layer neural network.

Read through the FullyConnectedNet class in the file nndl/fc\_net.py.

Implement the initialization, the forward pass, and the backward pass. There will be lines for batchnorm and dropout layers and caches; ignore these all for now. That'll be in assignment #4.

```
In [148]:
          N, D, H1, H2, C = 2, 15, 20, 30, 10
          X = np.random.randn(N, D)
          y = np.random.randint(C, size=(N,))
          for reg in [0, 3.14]:
            print('Running check with reg = {}'.format(reg))
            model = FullyConnectedNet([H1, H2], input dim=D, num classes=C,
                                       reg=reg, weight scale=5e-2, dtype=np.floa
          t64)
            loss, grads = model.loss(X, y)
            print('Initial loss: {}'.format(loss))
            for name in sorted(grads):
              f = lambda : model.loss(X, y)[0]
              grad num = eval numerical gradient(f, model.params[name],
          verbose=False, h=1e-5)
              print('{} relative error: {}'.format(name, rel error(grad num, gr
          ads[name])))
```

```
Running check with reg = 0
Initial loss: 2.3013653843
W1 relative error: 1.35064716142e-06
W2 relative error: 4.01073941783e-07
W3 relative error: 1.04377988289e-07
b1 relative error: 8.39454578961e-08
b2 relative error: 7.1797379996e-09
b3 relative error: 8.52298577931e-11
Running check with reg = 3.14
Initial loss: 7.31589155688
W1 relative error: 6.28609875144e-09
W2 relative error: 1.44438461983e-08
W3 relative error: 1.28177508603e-08
b1 relative error: 2.11059960475e-07
b2 relative error: 5.58921132425e-09
b3 relative error: 1.99575793561e-10
```

In [163]: # Use the three layer neural network to overfit a small dataset. num train = 50small data = { 'X train': data['X train'][:num train], 'y train': data['y train'][:num train], 'X\_val': data['X\_val'], 'y\_val': data['y\_val'], #### !!!!!! # Play around with the weight scale and learning rate so that you can overfit a small dataset. # Your training accuracy should be 1.0 to receive full credit on this part. weight scale = 1e-2learning rate = 1e-3model = FullyConnectedNet([100, 100], weight scale=weight scale, dtype=np.float64) solver = Solver(model, small data, print every=400, num epochs=200, batch size=25, update rule='sgd', optim config={ 'learning rate': learning rate, ) solver.train() plt.plot(solver.loss\_history, 'o') plt.title('Training loss history') plt.xlabel('Iteration') plt.ylabel('Training loss') plt.show()

```
(Iteration 1 / 400) loss: 2.340599
(Epoch 0 / 200) train acc: 0.100000; val acc: 0.102000
(Epoch 1 / 200) train acc: 0.120000; val acc: 0.100000
(Epoch 2 / 200) train acc: 0.140000; val acc: 0.107000
(Epoch 3 / 200) train acc: 0.180000; val acc: 0.116000
(Epoch 4 / 200) train acc: 0.160000; val acc: 0.115000
(Epoch 5 / 200) train acc: 0.200000; val acc: 0.119000
(Epoch 6 / 200) train acc: 0.240000; val acc: 0.125000
(Epoch 7 / 200) train acc: 0.280000; val acc: 0.128000
(Epoch 8 / 200) train acc: 0.380000; val acc: 0.128000
(Epoch 9 / 200) train acc: 0.360000; val acc: 0.127000
(Epoch 10 / 200) train acc: 0.480000; val acc: 0.131000
(Epoch 11 / 200) train acc: 0.440000; val acc: 0.126000
(Epoch 12 / 200) train acc: 0.420000; val acc: 0.130000
(Epoch 13 / 200) train acc: 0.460000; val acc: 0.136000
(Epoch 14 / 200) train acc: 0.500000; val acc: 0.147000
(Epoch 15 / 200) train acc: 0.520000; val acc: 0.159000
(Epoch 16 / 200) train acc: 0.520000; val acc: 0.158000
(Epoch 17 / 200) train acc: 0.540000; val acc: 0.165000
(Epoch 18 / 200) train acc: 0.560000; val acc: 0.157000
(Epoch 19 / 200) train acc: 0.540000; val acc: 0.161000
(Epoch 20 / 200) train acc: 0.540000; val acc: 0.162000
(Epoch 21 / 200) train acc: 0.560000; val acc: 0.164000
(Epoch 22 / 200) train acc: 0.560000; val acc: 0.161000
(Epoch 23 / 200) train acc: 0.560000; val acc: 0.166000
(Epoch 24 / 200) train acc: 0.580000; val_acc: 0.163000
(Epoch 25 / 200) train acc: 0.600000; val acc: 0.177000
(Epoch 26 / 200) train acc: 0.600000; val acc: 0.175000
(Epoch 27 / 200) train acc: 0.600000; val acc: 0.173000
(Epoch 28 / 200) train acc: 0.580000; val acc: 0.169000
(Epoch 29 / 200) train acc: 0.580000; val acc: 0.169000
(Epoch 30 / 200) train acc: 0.580000; val acc: 0.165000
(Epoch 31 / 200) train acc: 0.620000; val acc: 0.176000
(Epoch 32 / 200) train acc: 0.600000; val acc: 0.183000
(Epoch 33 / 200) train acc: 0.620000; val acc: 0.184000
(Epoch 34 / 200) train acc: 0.620000; val acc: 0.176000
(Epoch 35 / 200) train acc: 0.620000; val acc: 0.178000
(Epoch 36 / 200) train acc: 0.620000; val acc: 0.175000
(Epoch 37 / 200) train acc: 0.620000; val acc: 0.174000
(Epoch 38 / 200) train acc: 0.700000; val acc: 0.188000
(Epoch 39 / 200) train acc: 0.680000; val acc: 0.172000
(Epoch 40 / 200) train acc: 0.700000; val acc: 0.176000
(Epoch 41 / 200) train acc: 0.700000; val acc: 0.175000
(Epoch 42 / 200) train acc: 0.700000; val acc: 0.173000
(Epoch 43 / 200) train acc: 0.700000; val acc: 0.167000
(Epoch 44 / 200) train acc: 0.740000; val acc: 0.175000
(Epoch 45 / 200) train acc: 0.740000; val acc: 0.176000
(Epoch 46 / 200) train acc: 0.700000; val acc: 0.178000
(Epoch 47 / 200) train acc: 0.760000; val acc: 0.183000
(Epoch 48 / 200) train acc: 0.760000; val acc: 0.178000
(Epoch 49 / 200) train acc: 0.780000; val acc: 0.192000
(Epoch 50 / 200) train acc: 0.800000; val acc: 0.193000
(Epoch 51 / 200) train acc: 0.800000; val acc: 0.190000
(Epoch 52 / 200) train acc: 0.820000; val acc: 0.193000
(Epoch 53 / 200) train acc: 0.820000; val_acc: 0.190000
(Epoch 54 / 200) train acc: 0.800000; val acc: 0.189000
(Epoch 55 / 200) train acc: 0.820000; val acc: 0.197000
```

```
(Epoch 56 / 200) train acc: 0.840000; val acc: 0.191000
(Epoch 57 / 200) train acc: 0.840000; val_acc: 0.196000
(Epoch 58 / 200) train acc: 0.840000; val acc: 0.188000
(Epoch 59 / 200) train acc: 0.860000; val acc: 0.187000
(Epoch 60 / 200) train acc: 0.840000; val acc: 0.184000
(Epoch 61 / 200) train acc: 0.820000; val acc: 0.183000
(Epoch 62 / 200) train acc: 0.860000; val acc: 0.189000
(Epoch 63 / 200) train acc: 0.860000; val acc: 0.189000
(Epoch 64 / 200) train acc: 0.860000; val acc: 0.195000
(Epoch 65 / 200) train acc: 0.840000; val acc: 0.199000
(Epoch 66 / 200) train acc: 0.840000; val acc: 0.195000
(Epoch 67 / 200) train acc: 0.860000; val acc: 0.191000
(Epoch 68 / 200) train acc: 0.880000; val acc: 0.190000
(Epoch 69 / 200) train acc: 0.880000; val acc: 0.188000
(Epoch 70 / 200) train acc: 0.880000; val acc: 0.192000
(Epoch 71 / 200) train acc: 0.880000; val acc: 0.182000
(Epoch 72 / 200) train acc: 0.880000; val acc: 0.179000
(Epoch 73 / 200) train acc: 0.880000; val acc: 0.191000
(Epoch 74 / 200) train acc: 0.880000; val acc: 0.196000
(Epoch 75 / 200) train acc: 0.880000; val acc: 0.186000
(Epoch 76 / 200) train acc: 0.880000; val acc: 0.193000
(Epoch 77 / 200) train acc: 0.880000; val acc: 0.189000
(Epoch 78 / 200) train acc: 0.880000; val acc: 0.186000
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(Epoch 106 / 200) train acc: 0.980000; val acc: 0.190000
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(Epoch 109 / 200) train acc: 0.980000; val acc: 0.183000
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(Epoch 111 / 200) train acc: 0.980000; val acc: 0.187000
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(Epoch 122 / 200) train acc: 0.980000; val acc: 0.191000
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