# ENAE441 Group Project

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#### 1 Overview

The goal of this project was to tie together many different topics from the course into once large project. Data acquired online about varying GNSS satellites was to be analyzed using trilateration, coordinate transformation, Lambert solvers, and TLEs.

In doing this, we discovered **Things maybe**.

### 2 Work Done

- 2.1 Trilateration
- 2.2 Postition
- 2.3 Position Vectors
- 2.4 Solving the Lambert Problem
- 2.5 Pseudoranges
- 3 Conclusion
- 3.1 Results
- 3.2 Sources of Error
- 3.3 Limitations

#### A Code

### A.1 Main Analysis Code

```
% Load data
  % clear all
  % clc
  % close all
  run set_data.m
  % run set_parameters.m
  % Trilateration
  rho_t1_sat1 = Trilateration(rho_obsv_t1_sat1, ref_matrix, 1e-4,
      rho_njtr_t1_sat1)
  rho_t2_sat1 = Trilateration(rho_obsv_t2_sat1, ref_matrix, 1e-4,
      rho_njtr_t2_sat1)
  rho_t1_sat2 = Trilateration(rho_obsv_t1_sat2, ref_matrix, 1e-4,
      rho_njtr_t1_sat2)
  rho_t2_sat2 = Trilateration(rho_obsv_t2_sat2, ref_matrix, 1e-4,
      rho_njtr_t2_sat2)
13
  % Frame Conversion
14
  gst_t1_sat1 = GST(T1, t1);
  gst_t2_sat1 = GST(T2, t2_sat1);
  gst_t2_sat2 = GST(T2, t2_sat2);
```

### A.2 Parameter Setting

```
1 % Script to initialize global parameters/formatting for ENAE 404
2 % Inludes things like fundamental constants, planetary radii, etc.
  % Author: Blaire Weinberg
  % Formatting
  format long g
   clear all
  % Fundamental Constants
  c = 3e5; % km/s
11
12
  % Gravitational Parameters
13
   mu_earth = 3.986e5; % km<sup>3</sup> / s<sup>2</sup>
14
  mu_mars = 4.305 e4; \% km^3/s^2
   mu\_saturn = 3.7931187e7; \% km^3/s^2
16
  mu_moon = 0.00490e6; % km^3/s^2 (nssdc.gsfc.nasa.gov/planetary/factsheet/
      moonfact.html)
   mu_jupiter = 126.687e6; % km^2/s^2 (nssdc.gsfc.nasa.gov/planetary/factsheet/
      jupiterfact.html)
  mu_mercury = 0.022032e6; % km<sup>2</sup>/s<sup>2</sup> (https://nssdc.gsfc.nasa.gov/planetary/
      factsheet/mercuryfact.html)
  mu\_sun = 132712e6; % km^2/s^2 (https://nssdc.gsfc.nasa.gov/planetary/factsheet
      /sunfact.html)
  % Radii
22
  r_{earth} = 6378; \% \text{ km}
  r_moon = 1738.1; % km (nssdc.gsfc.nasa.gov/planetary/factsheet/moonfact.html)
   r_jupiter = 71492; % km (nssdc.gsfc.nasa.gov/planetary/factsheet/jupiterfact.
      html)
  r_mercury = 2439.7; % km (https://nssdc.gsfc.nasa.gov/planetary/factsheet/
26
      mercuryfact.html)
   r_mars = 3396.2; % km (https://nssdc.gsfc.nasa.gov/planetary/factsheet/
      marsfact.html)
   r_{-}geo = 42164; \% \text{ km}
28
29
  % Semi-major axes
30
  a_mercury = 57.91e6; % km (https://nssdc.gsfc.nasa.gov/planetary/factsheet/
      mercuryfact.html)
   a_earth = 149.6e6; % km (https://nssdc.gsfc.nasa.gov/planetary/factsheet/
      earthfact.html)
   a_jupiter = 778.57e6; % km (nssdc.gsfc.nasa.gov/planetary/factsheet/
33
      jupiterfact.html)
34
35
   m_mercury = 0.33011e24; % kg (https://nssdc.gsfc.nasa.gov/planetary/factsheet/
      mercuryfact.html)
   m_jupiter = 1898.19e24; % kg (nssdc.gsfc.nasa.gov/planetary/factsheet/
37
      jupiterfact.html)
   m_sun = 1988500e24; % kg (nssdc.gsfc.nasa.gov/planetary/factsheet/sunfact.html
38
  % Gravitational Parameters
   g_earth = 9.798e-3; % km/s (https://nssdc.gsfc.nasa.gov/planetary/factsheet/
```

#### A.3 Data Setting

```
% This script contains all of the data pulled from online for the project
     % Author: Blaire Weinberg
     % G32
      t_sat1 = [datetime(2019, 09, 29, 20, 0, 0);
                            datetime (2019, 09, 30, 3, 12, 30)]; % YY-MM-DD hh:mm: ss
     % [GODE: LYCO: NJTR]
      rho_obsv_t1_sat1 = [25051697.711; 25250311.013; 25300673.18]; % m
      rho\_obsv\_t2\_sat1 = [24885268.756; 25027333.239; 24905662.38]; \% m
11
      rho_gode_t1_sat1 = [-16495.751222; -20282.441992; -4990.466293]; \% m
      rho_gode_t2_sat1 = [20213.786583; -14550.961176; -8980.879524]; \% m
13
14
      rho_1 y co_1 t 1_s at 1 = [-16495.751222; -20282.441992; -4990.466293]; \% m
15
      rho_1 y co_1 t 2_1 s a t 1 = [20213.786583; -14550.961176; -8980.879524]; \% m
16
17
      rho_njtr_t1_sat1 = [-16495.751222; -20282.441992; -4990.466293]; \% m
18
      rho_njtr_t2_sat1 = [20213.786583; -14550.961176; -8980.879524]; \% m
19
     %% G10
21
      t_{sat2} = [datetime(2019, 09, 29, 20, 0, 0);
22
                            datetime (2019, 09, 30, 1, 22, 30); % YY-MM-DD hh:mm: ss
23
24
     % [GODE; LYCO; NJTR]
25
      rho_obsv_t1_sat2 = [23211963.276; 23183895.657; 23332124.46]; \% m
26
      rho_{-}obsv_{-}t2_{-}sat2 = [24741064.469; 24965346.244; 24859334.14]; \% m
28
      {\tt rho\_gode\_t1\_sat2} \ = \ [-16660.548228; \ -11669.484643; \ 17253.892228]; \ \% \ {\tt matching} \ + \ (-16660.548228; \ -11669.484643; \ 17253.892228]; \ \% \ {\tt matching} \ + \ (-16660.548228; \ -11669.484643; \ 17253.892228]; \ \% \ {\tt matching} \ + \ (-16660.548228; \ -11669.484643; \ 17253.892228]; \ \% \ {\tt matching} \ + \ (-16660.548228; \ -11669.484643; \ 17253.892228]; \ \% \ {\tt matching} \ + \ (-16660.548228; \ -11669.484643; \ 17253.892228]; \ \% \ {\tt matching} \ + \ (-16660.548228; \ -11669.484643; \ 17253.892228]; \ \% \ {\tt matching} \ + \ (-16660.548228; \ -11669.484643; \ -11669.484643; \ -11669.484643; \ -11669.484643; \ -11669.484643; \ -11669.484643; \ -11669.484643; \ -11669.484643; \ -11669.484643; \ -11669.484643; \ -11669.484643; \ -11669.484643; \ -11669.484643; \ -11669.484643; \ -11669.484643; \ -11669.484643; \ -11669.484643; \ -11669.484643; \ -11669.484643; \ -11669.484643; \ -11669.484643; \ -11669.484643; \ -11669.484643; \ -11669.484643; \ -11669.484643; \ -11669.484643; \ -11669.484643; \ -11669.484643; \ -11669.484643; \ -11669.484643; \ -11669.484643; \ -11669.484643; \ -11669.484643; \ -11669.484643; \ -11669.484643; \ -11669.484643; \ -11669.484643; \ -11669.484643; \ -11669.484643; \ -11669.484643; \ -11669.484643; \ -11669.484643; \ -11669.484643; \ -11669.484643; \ -11669.484643; \ -11669.484643; \ -11669.484643; \ -11669.484643; \ -11669.484643; \ -11669.484643; \ -11669.484643; \ -11669.484643; \ -11669.484643; \ -11669.484643; \ -11669.484643; \ -11669.484643; \ -11669.484643; \ -11669.484643; \ -11669.484643; \ -11669.484643; \ -11669.484643; \ -11669.484643; \ -11669.484643; \ -11669.484643; \ -11669.484643; \ -11669.484643; \ -11669.484643; \ -11669.484643; \ -11669.484643; \ -11669.484643; \ -11669.484643; \ -11669.484643; \ -11669.484643; \ -11669.484643; \ -11669.484643; \ -11669.484643; \ -11669.484643; \ -11669.484643; \ -11669.484643; \ -11669.484643; \ -11669.4846443; \ -11669.4846443; \ -11669.4846443; \ -11669.48464445; \ -11669.4846445; \ -11669.4846455; \ -1166
      rho_gode_t2_sat2 = [11443.232098; -19758.768196; -13321.664005]; \% m
30
      \label{eq:rho_lyco_t1_sat2} $$rho_lyco_t1_sat2 = [-16660.548228; -11669.484643; 17253.892228]; \% m$$
32
      rho_1 y co_1 t 2_s at 2 = [11443.232098; -19758.768196; -13321.664005]; \% m
33
34
      rho_njtr_t1_sat2 = [-16660.548228; -11669.484643; 17253.892228]; \% m
      rho_nitr_t2_sat2 = [11443.232098; -19758.768196; -13321.664005]; \% m
36
37
     % Ground Stations
     % ECEF XYZ
     GODE = [1130774.439; -4831255.071; 3994200.558]; \% m
     LYCO = [1080274.057; -4680045.229; 4182682.6660]; \% m
     NJTR = [1278261.278; -4703708.0040; 4099884.5550]; \% m
42
43
      ref_matrix = [GODE'; LYCO'; NJTR'];
45
     % Times
      t1 = 20 * 3600; \% s
47
      t2\_sat1 = (3 * 3600) + (12 * 60) + 30; \% s
      t2\_sat2 = 3600 + (22 * 60) + 30; \% s
49
```

```
^{51} T1 = (7181 + 29 + 0.5) / 32525;
^{52} T2 = (7181 + 30 + 0.5) / 32525;
```

#### A.4 Trilateration

```
function [r] = Trilateration (rho_obsv, ref, tolerance, r_guess)
  % Determines the location of a satellite given reference information
  % Inputs:
       % rho_obsv: vector containing observed ranges
       % ref: matrix containing all of the [X Y Z] information for the
       % reference locations for the observations
       % r_guess: guess [X Y Z] vector for where the satellite should be located
  % Outputs:
       % r: [X Y Z] vector containing the iterated solution for where the
10
       % satellite is
11
12
  % Author: Blaire Weinberg
13
14
  r = r_g uess;
15
16
   rho_pred = sqrt((ref(:, 1)-r(1,1)).^2+(ref(:, 2)-r(2,1)).^2+(ref(:, 3)-r(3,1))
17
      . ^ 2 );
   e = (rho\_obsv-rho\_pred);
   while (norm(e)>tolerance)
19
       A = [(r(1,1)-ref(1,1))/rho\_pred(1), (r(2,1)-ref(1,2))/rho\_pred(1), (r(3,1))]
20
           -\text{ref}(1, 3))/\text{rho}_{pred}(1);
             (r(1,1)-ref(2,1))/rho_pred(2), (r(2,1)-ref(2,2))/rho_pred(2), (r(3,1))
21
                -\text{ref}(2, 3))/\text{rho-pred}(2);
             (r(1,1)-ref(3,1))/rho\_pred(3), (r(2,1)-ref(3,2))/rho\_pred(3), (r(3,1))
22
                -ref(3, 3))/rho_pred(3);
       rho\_pred = sqrt((ref(:, 1)-r(1,1)).^2+(ref(:, 2)-r(2,1)).^2+(ref(:, 3)-r)
23
           (3,1)).^2);
       e = (rho\_obsv-rho\_pred);
24
       r = r + (A \setminus e);
       disp(e);
26
  end
```

- A.5 Piece of Code 4
- A.6 Piece of Code 5
- **B** Group Work Distribution
- B.1 Tyler Chotoo

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B.2 Abubakr Hamid

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B.3 Richard Quarles

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## B.4 Blaire Weinberg

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