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Customer	
Drawing number	
Drawing number	
Drawing version	
Manufacture	:
Type	
Type of installation	
Control cabinet	
Mains voltage	
Supply	
Control voltage	
Year of construction	
Project start	•
Project manager	
Last revision	
Designed by	
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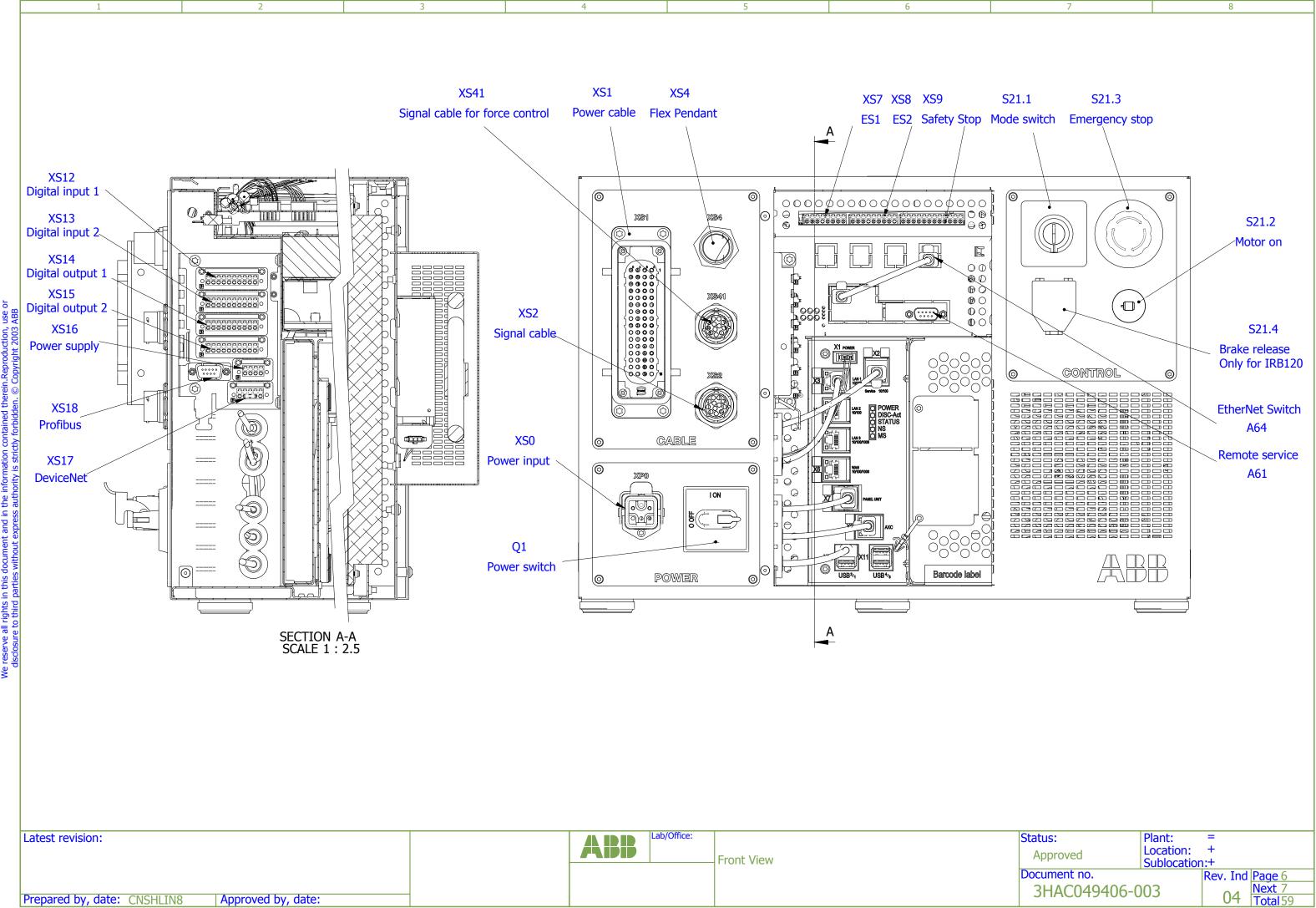
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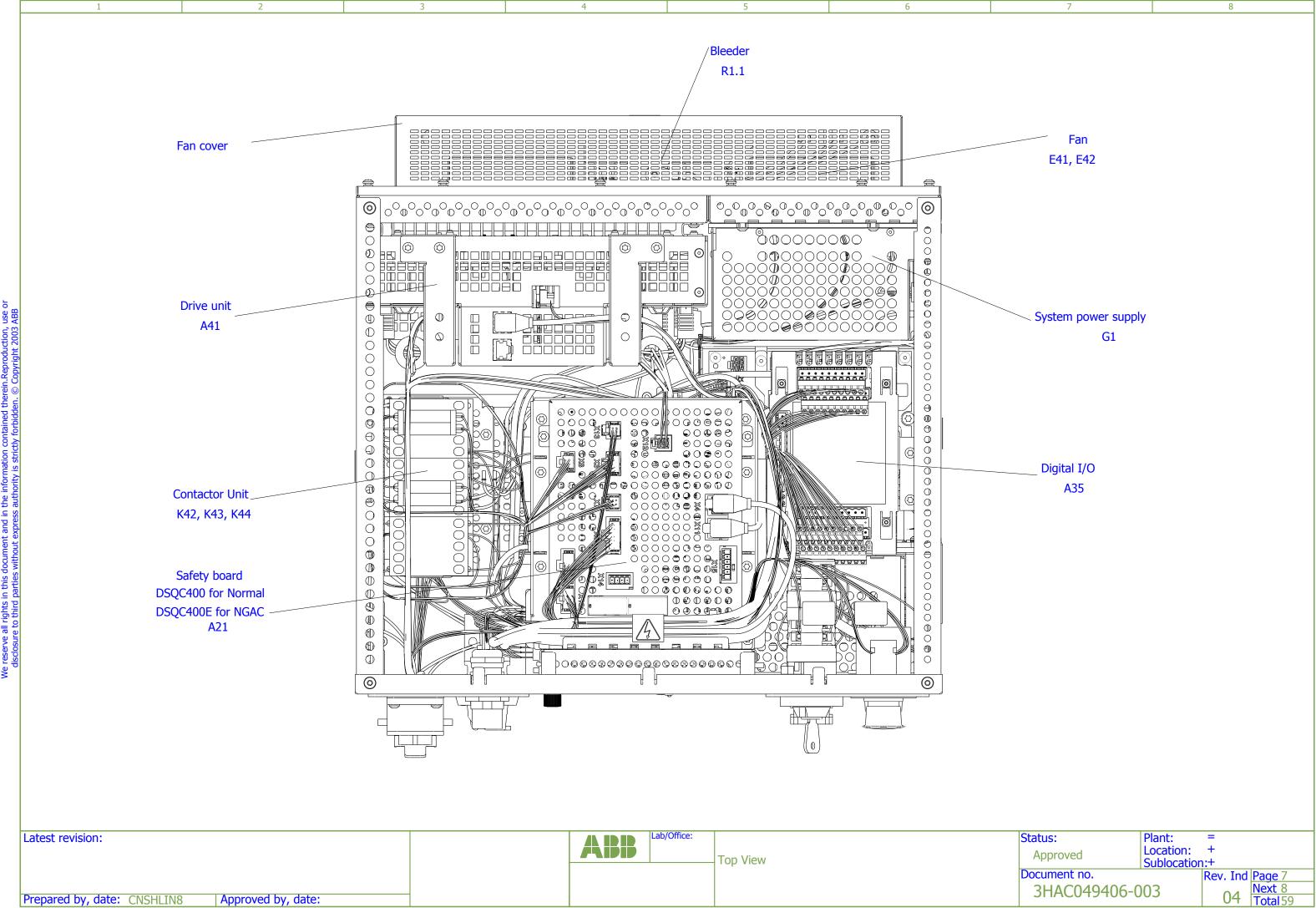
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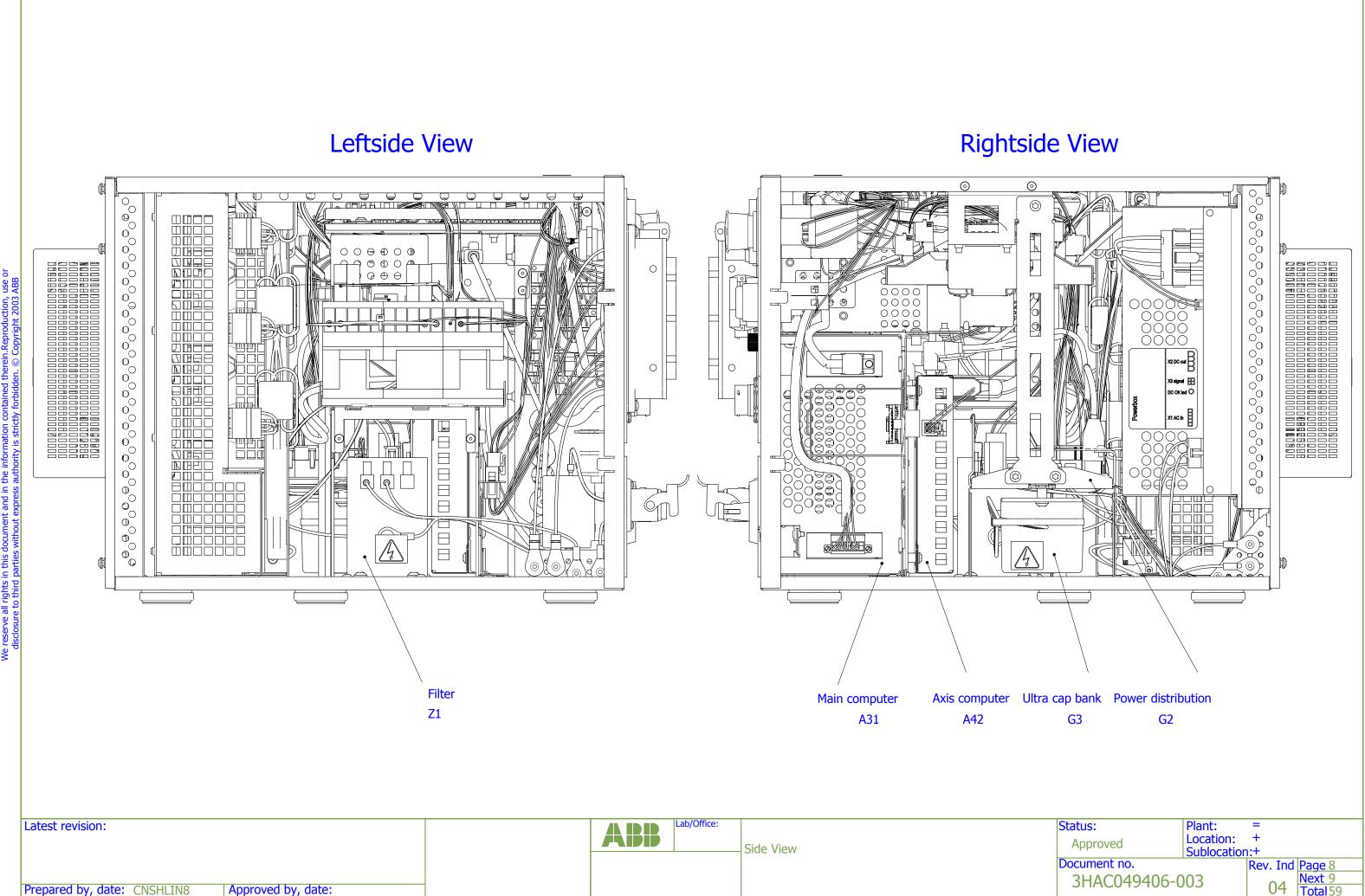
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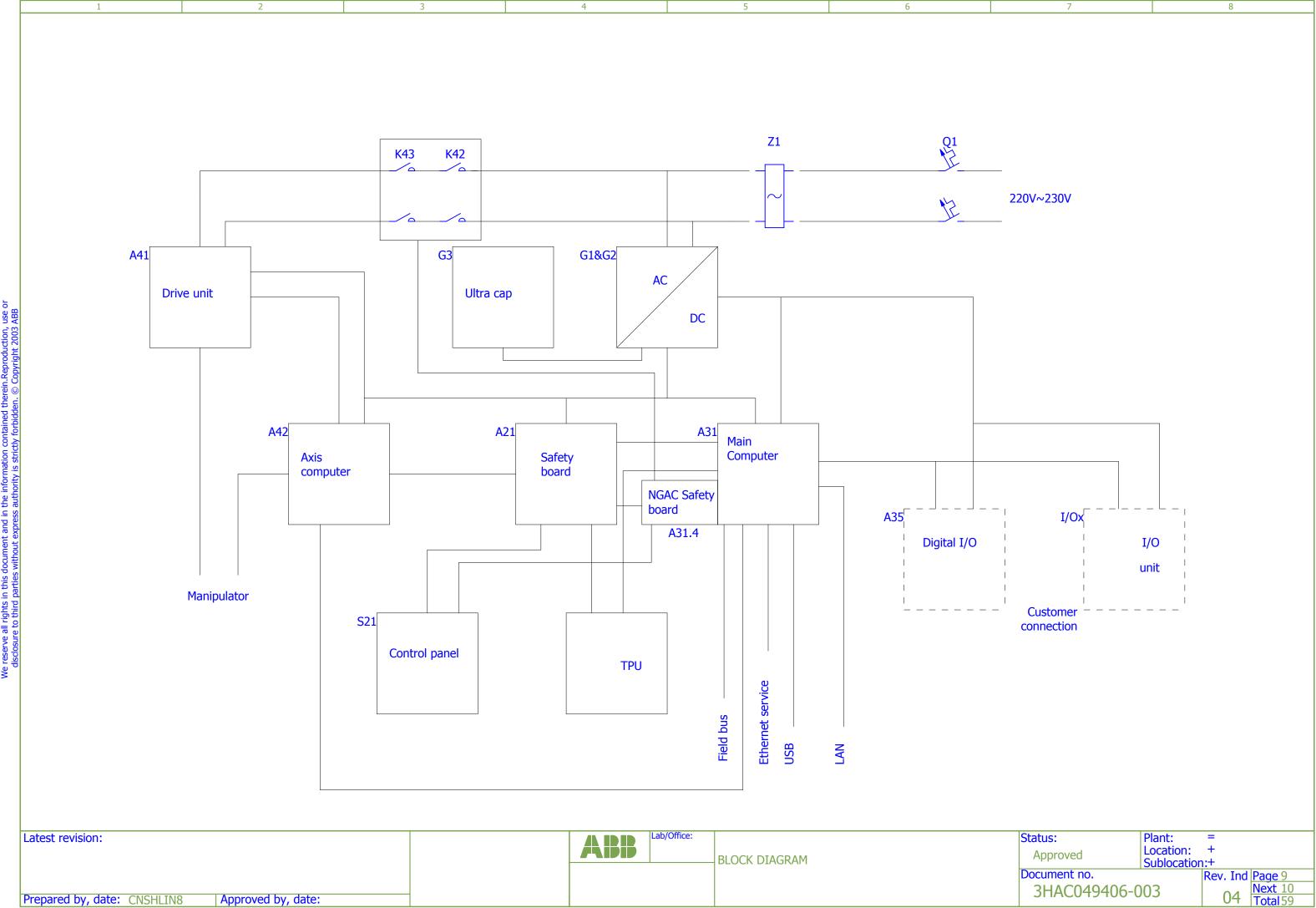
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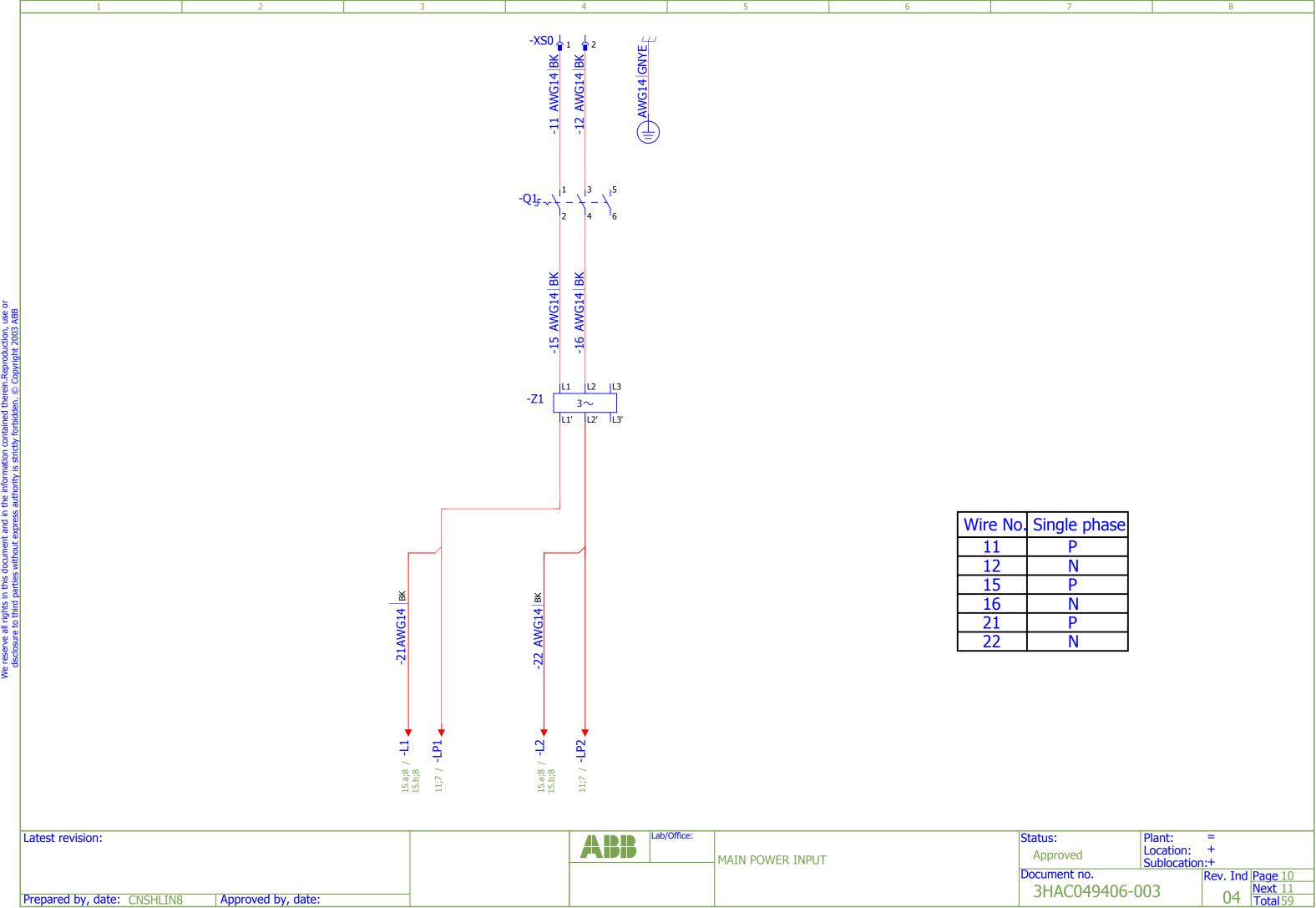
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- Remove output terminals of DSQC652 and mark two wires : input 24VDC and 0V
- Update Main computer from DSQC1018 to DSQC1024
Rev 04 2017 03 - Add CP/CS for IRB910 IRB1410 - Add floor cable for IRB910 Plant: = Location: + Sublocation:+ Lab/Office: Latest revision: Status: ABB Approved REVISION INFORMATION Document no. Rev. Ind Page 5 Next 6 Total 59 3HAC049406-003 Prepared by, date: CNSHLIN8 Approved by, date:

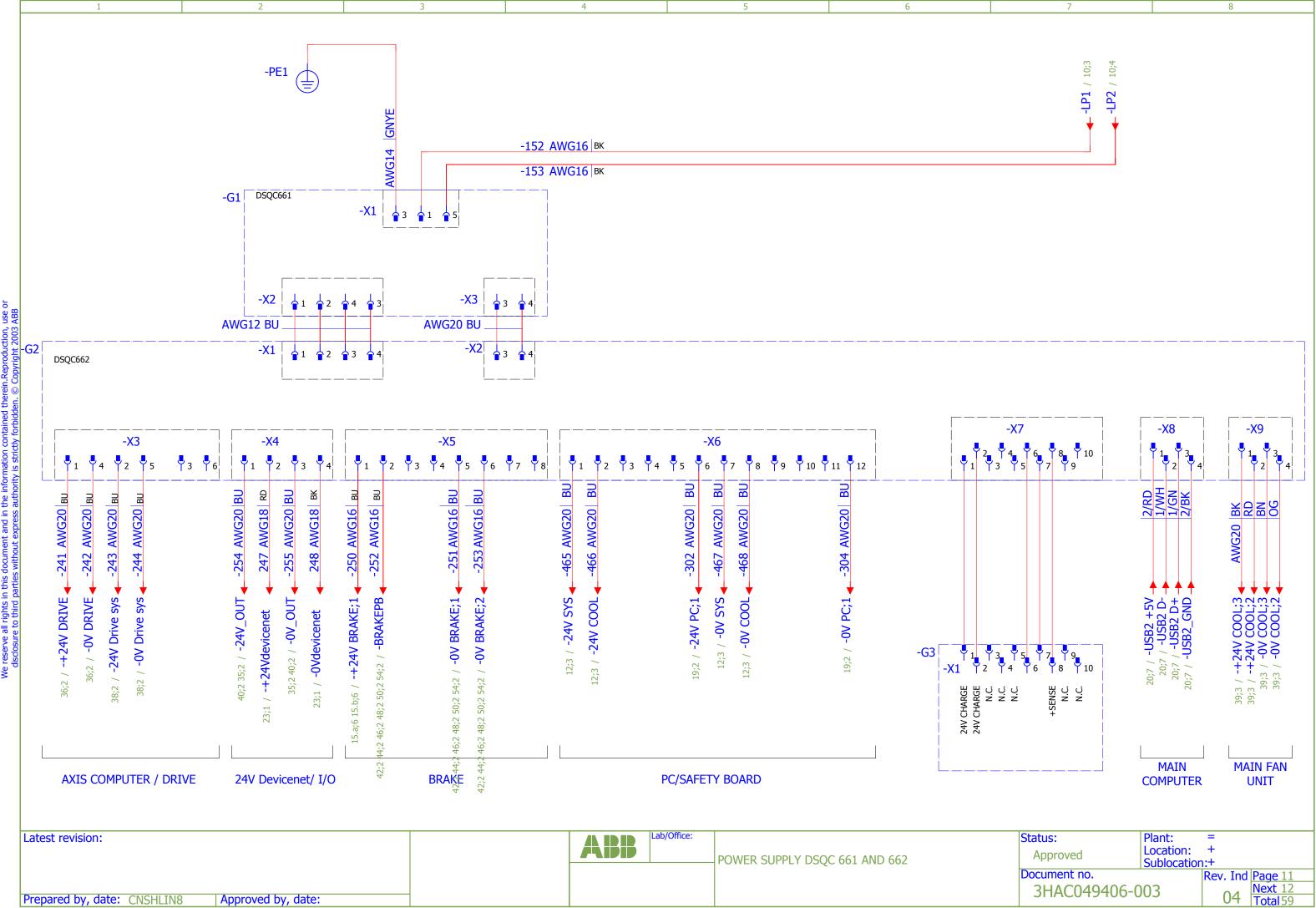


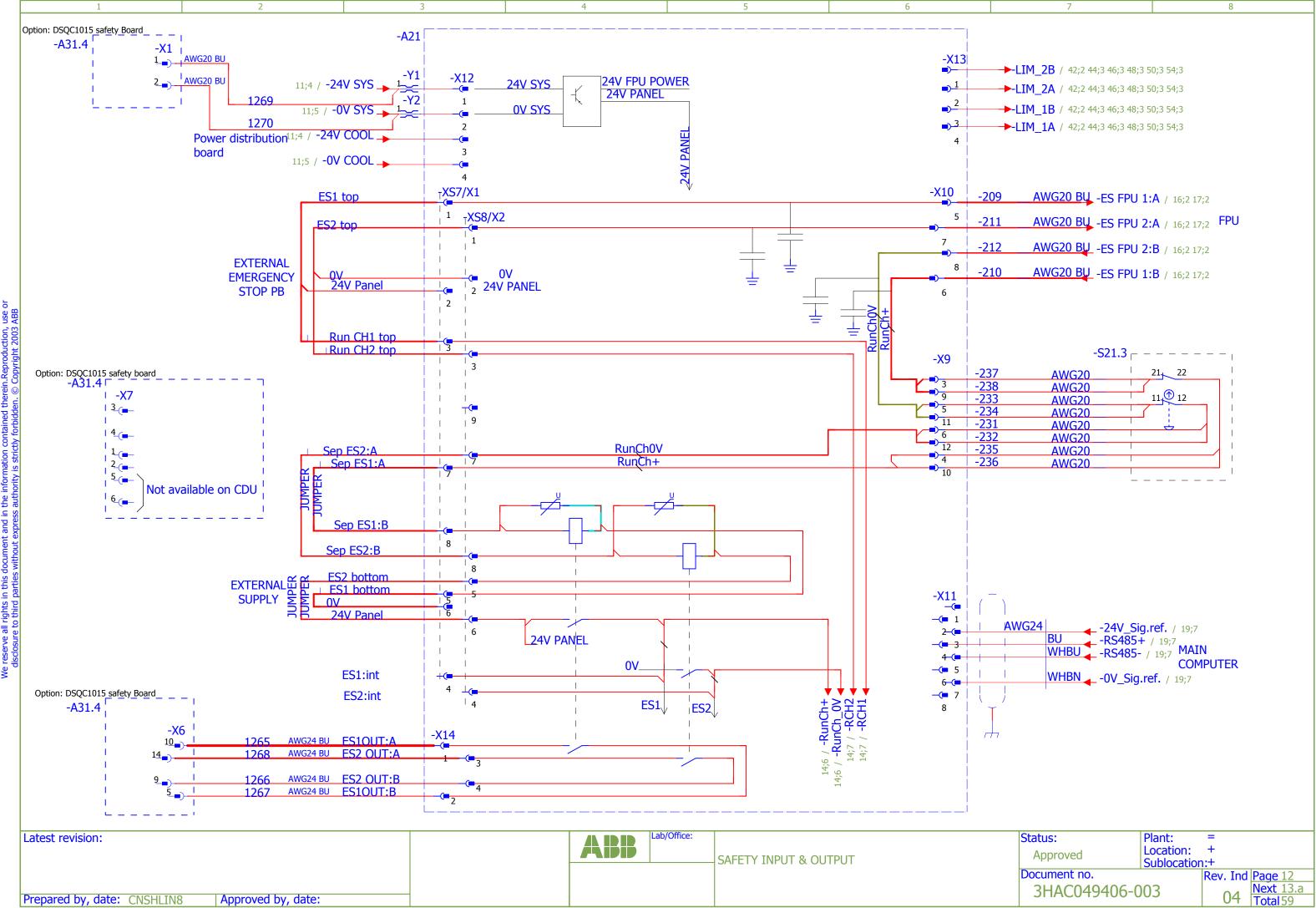


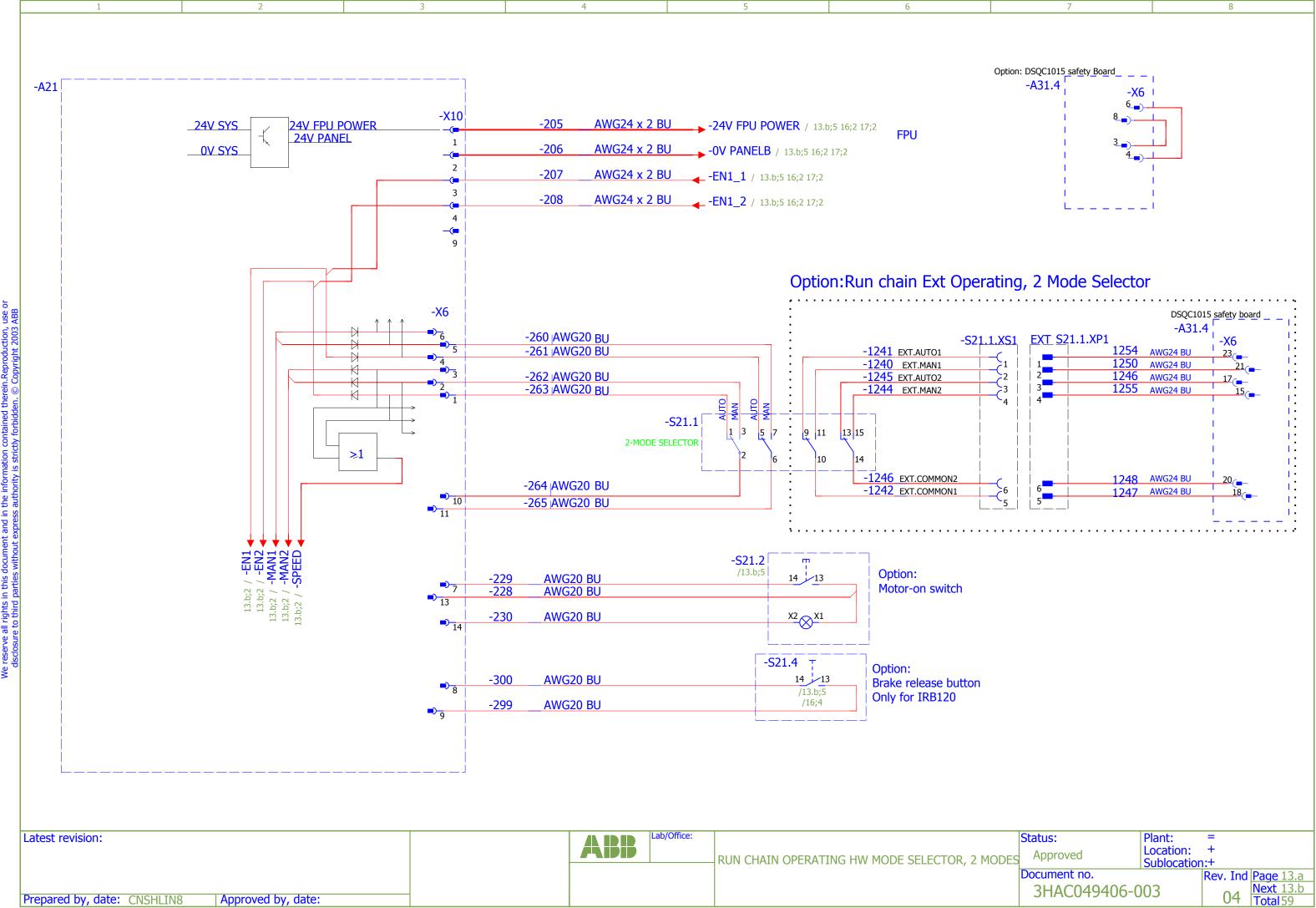


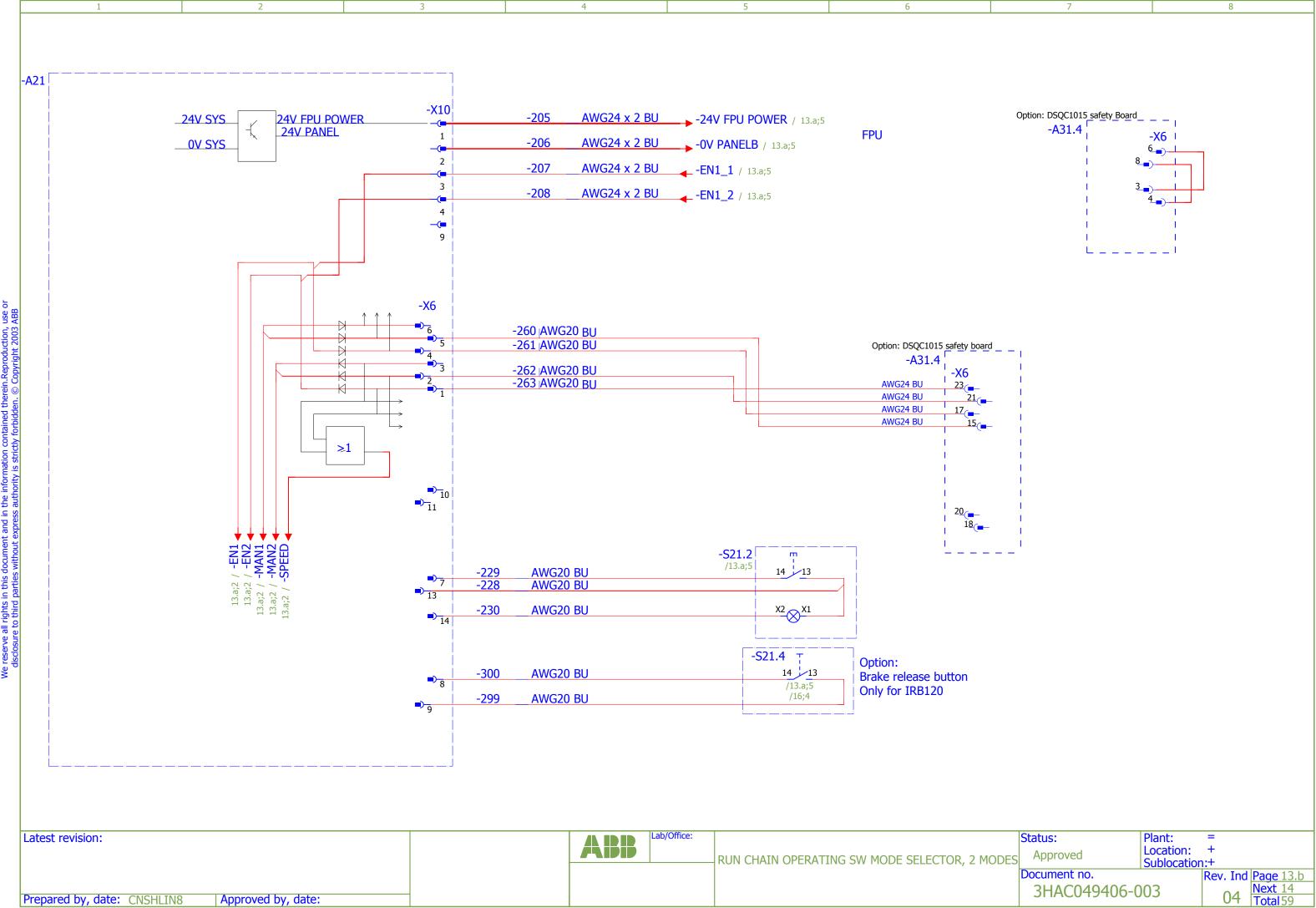


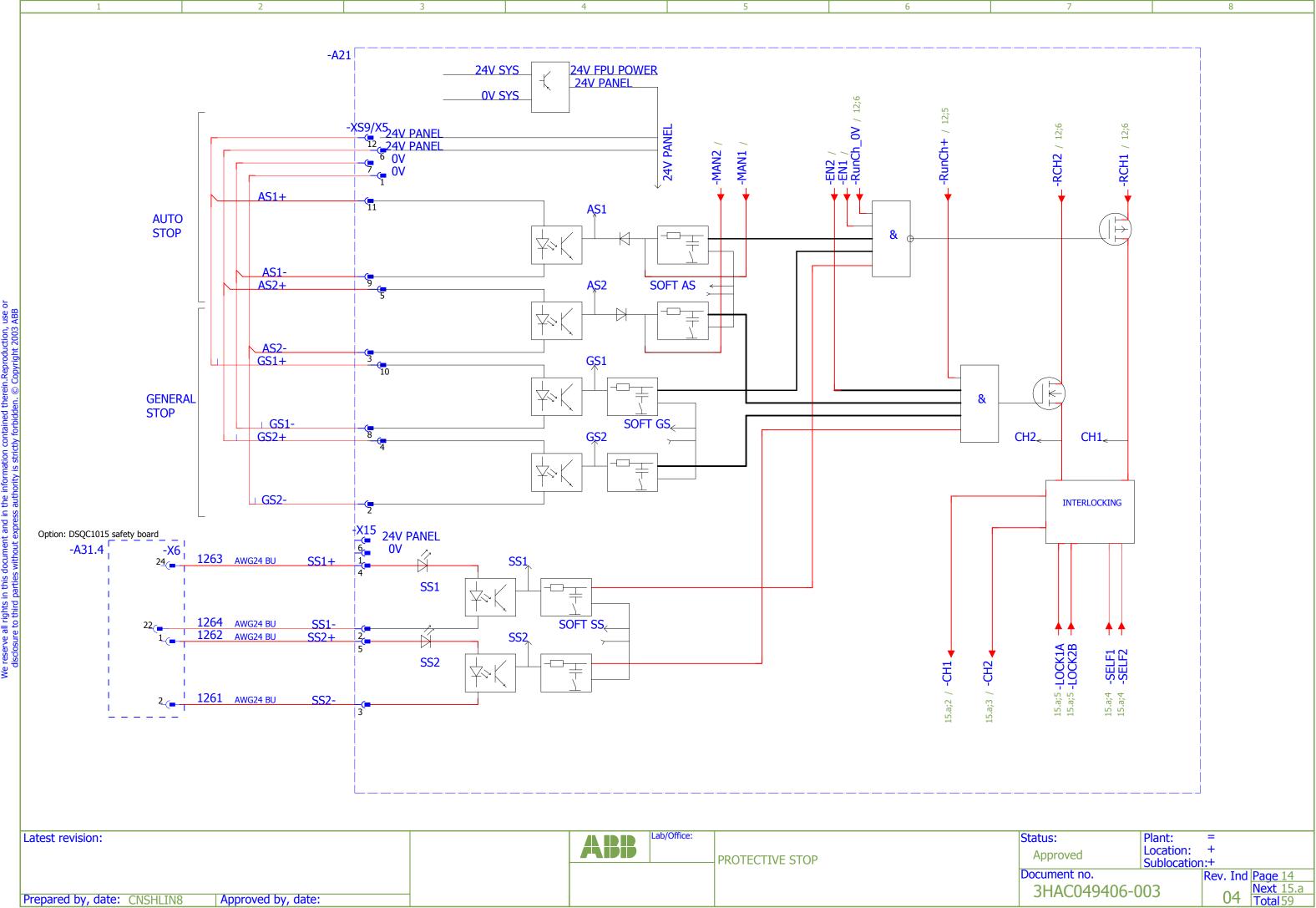


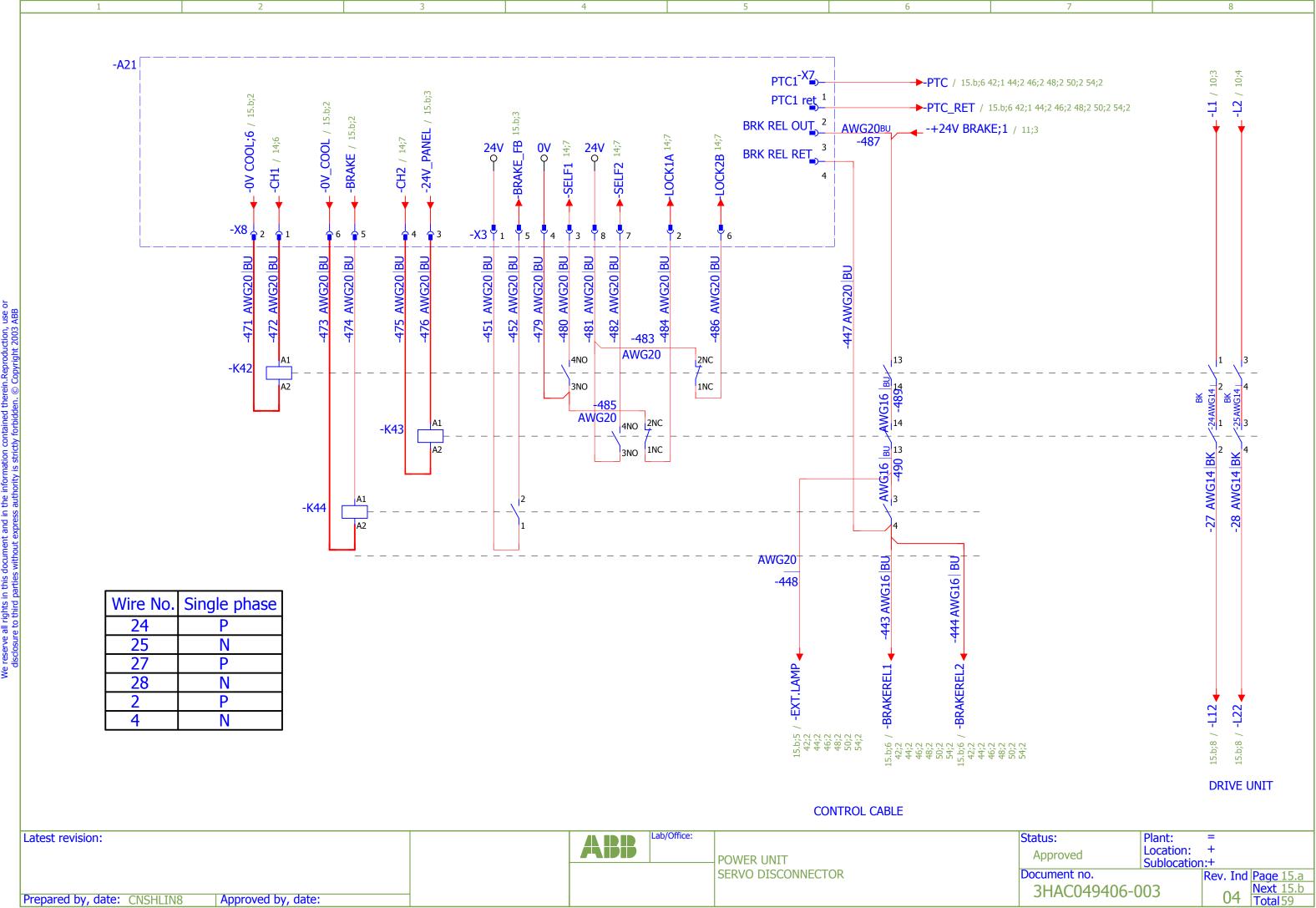


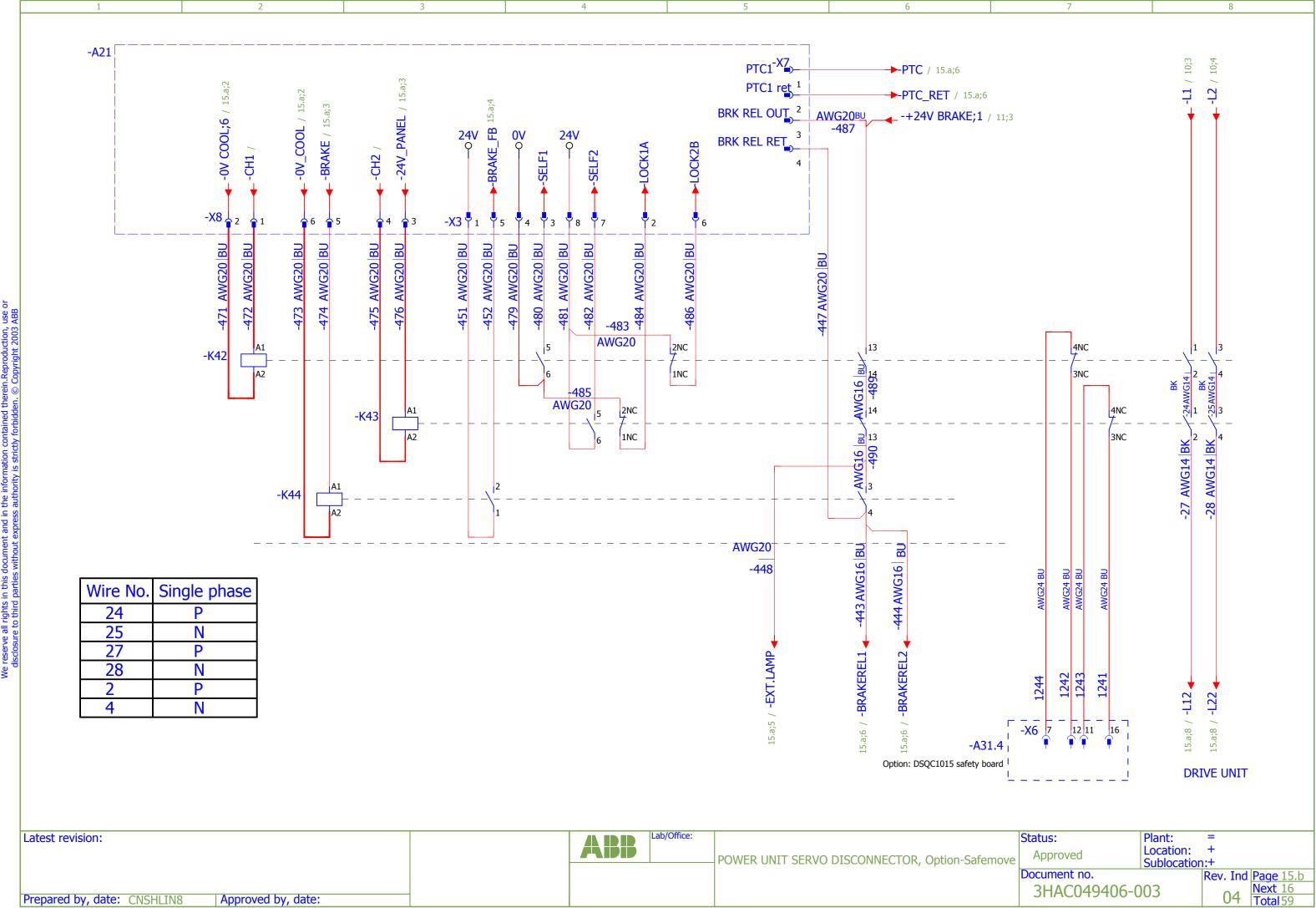


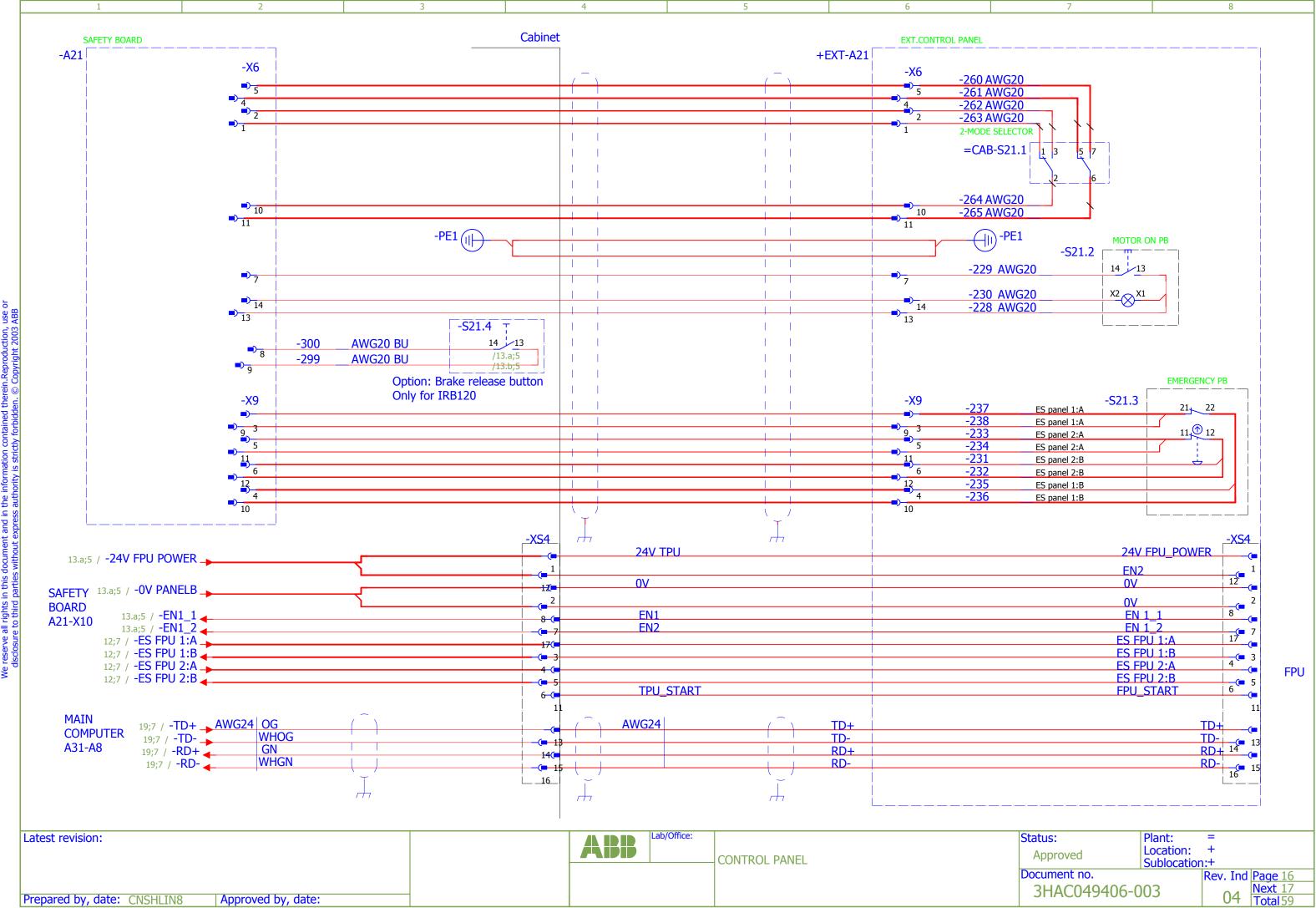


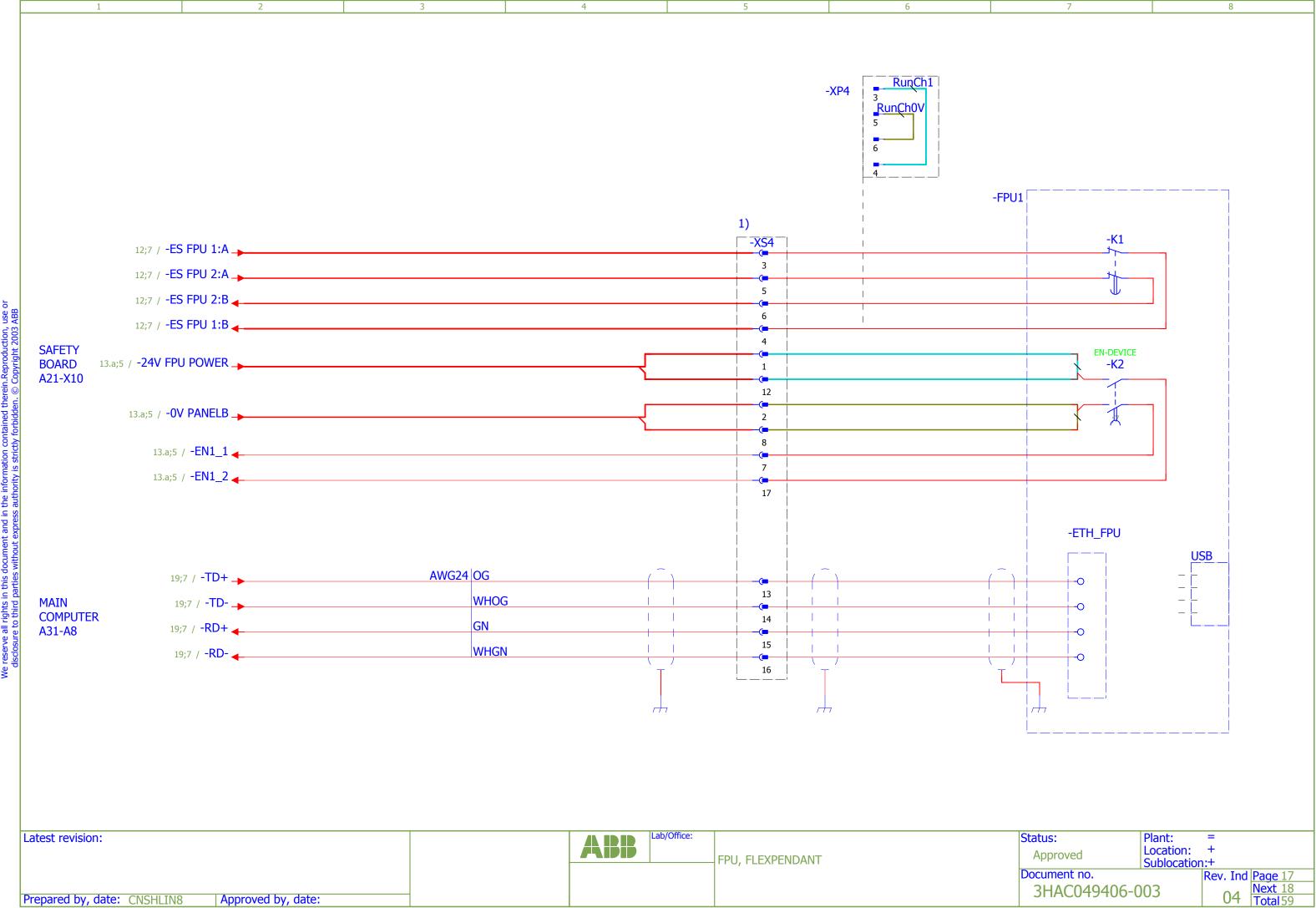




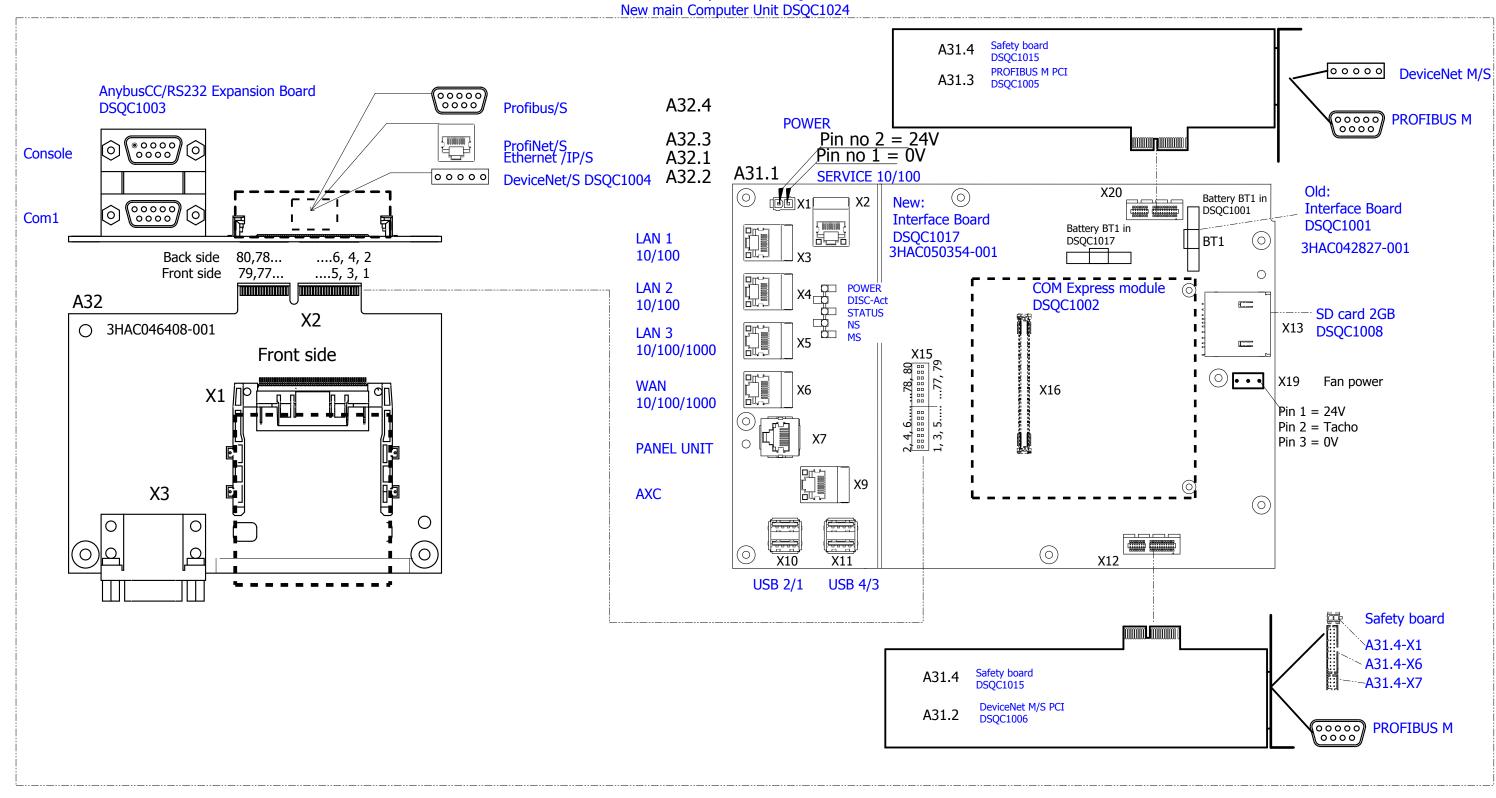




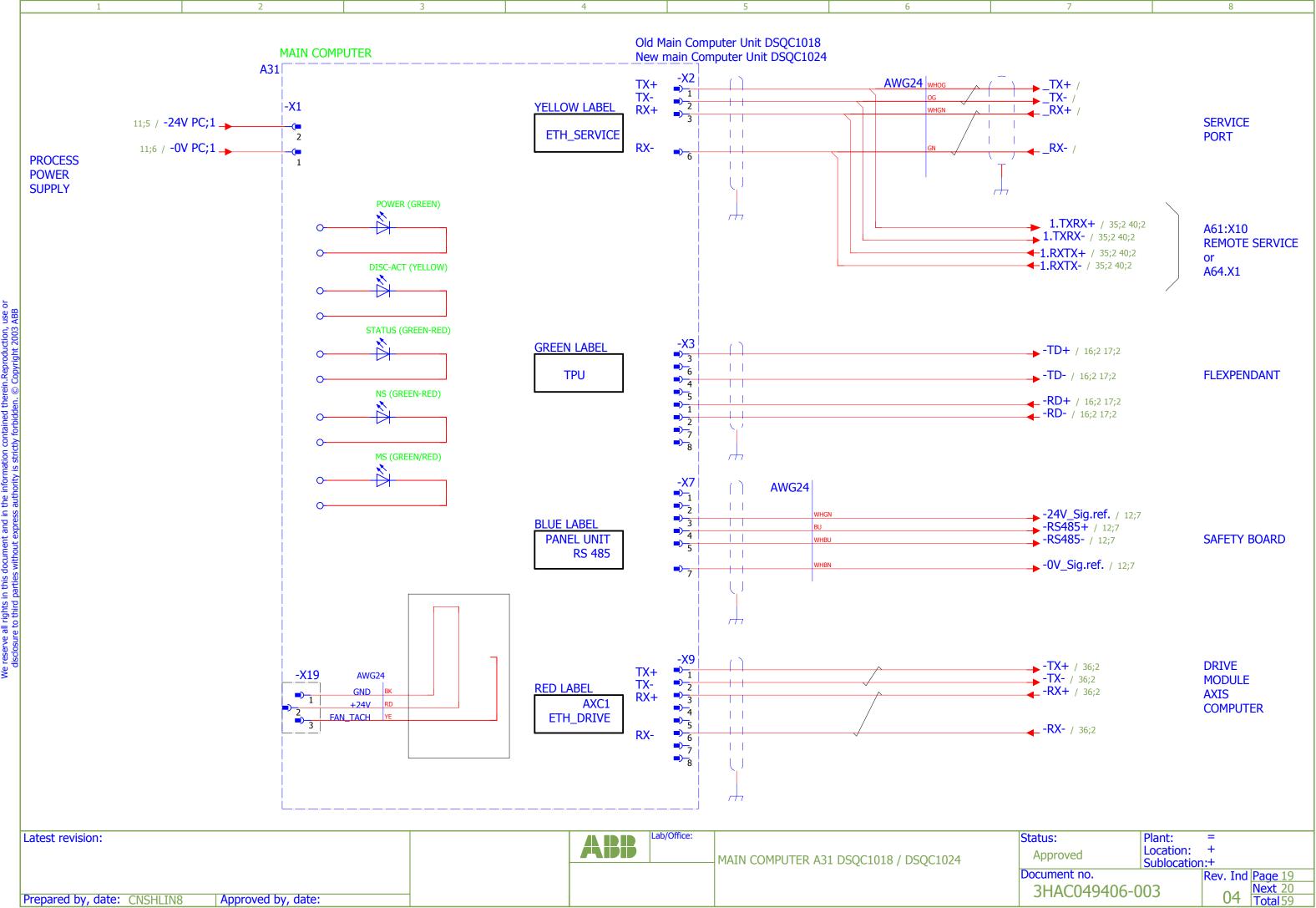


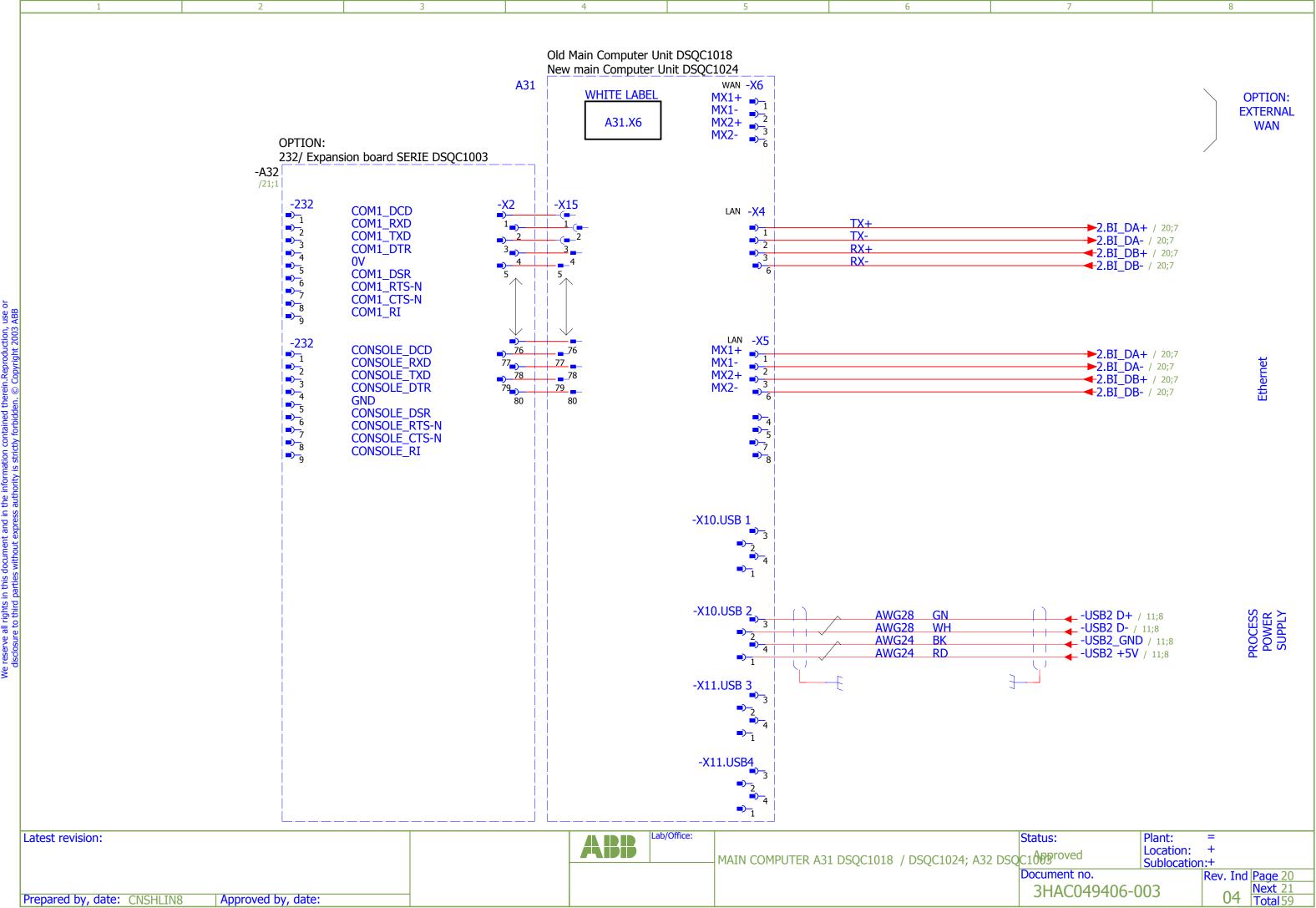


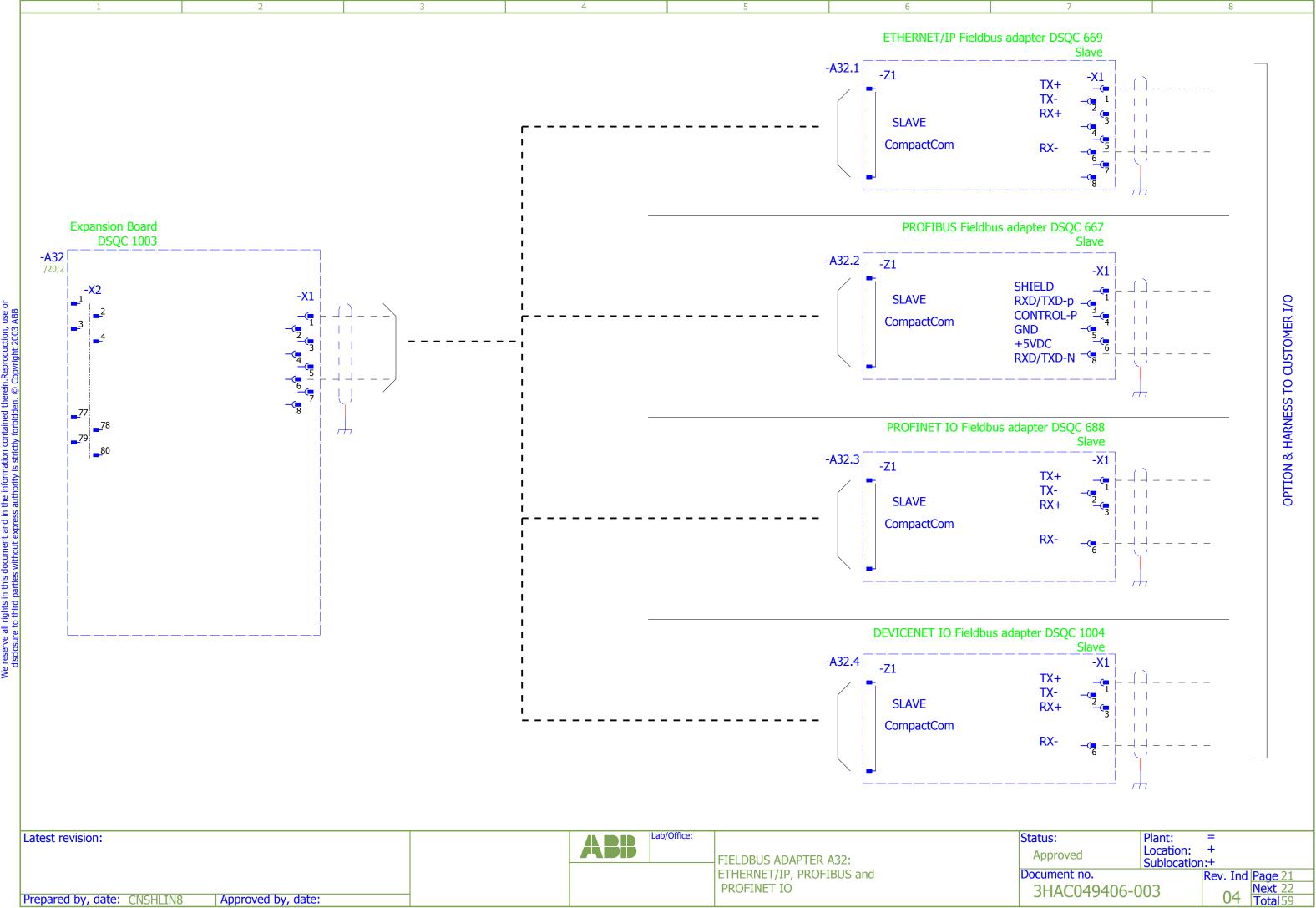
A31
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New main Computer Unit DSOC1024

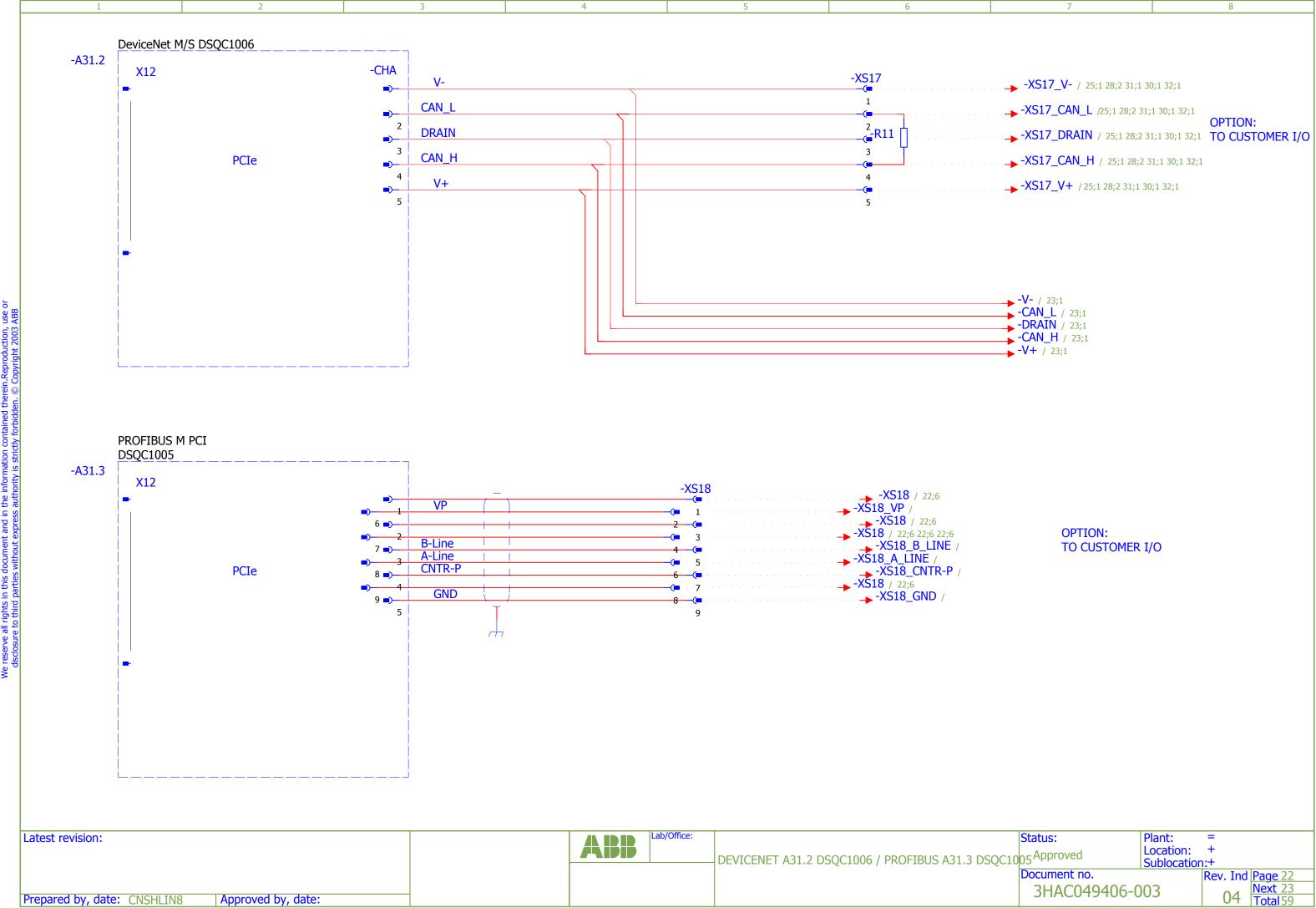


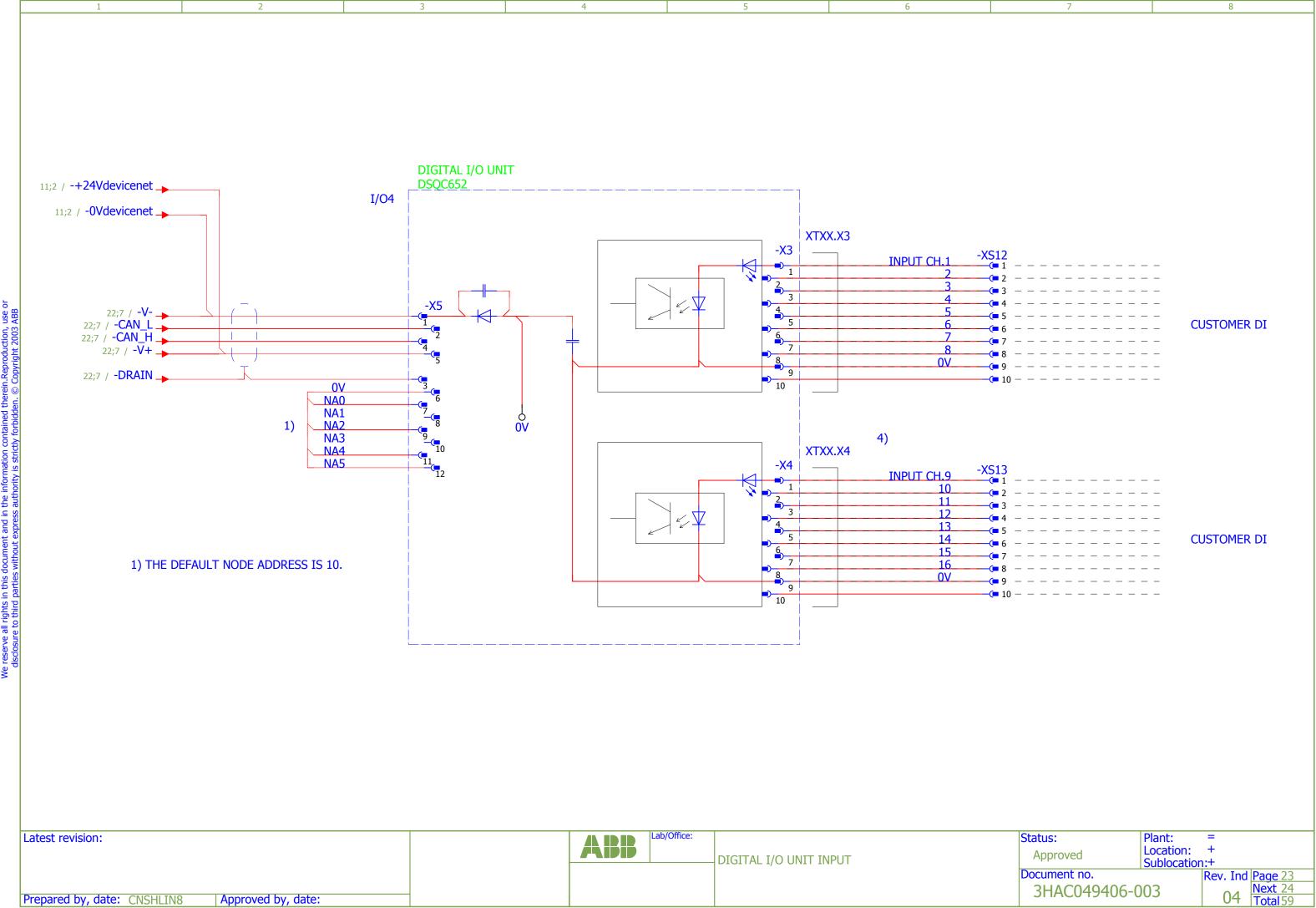


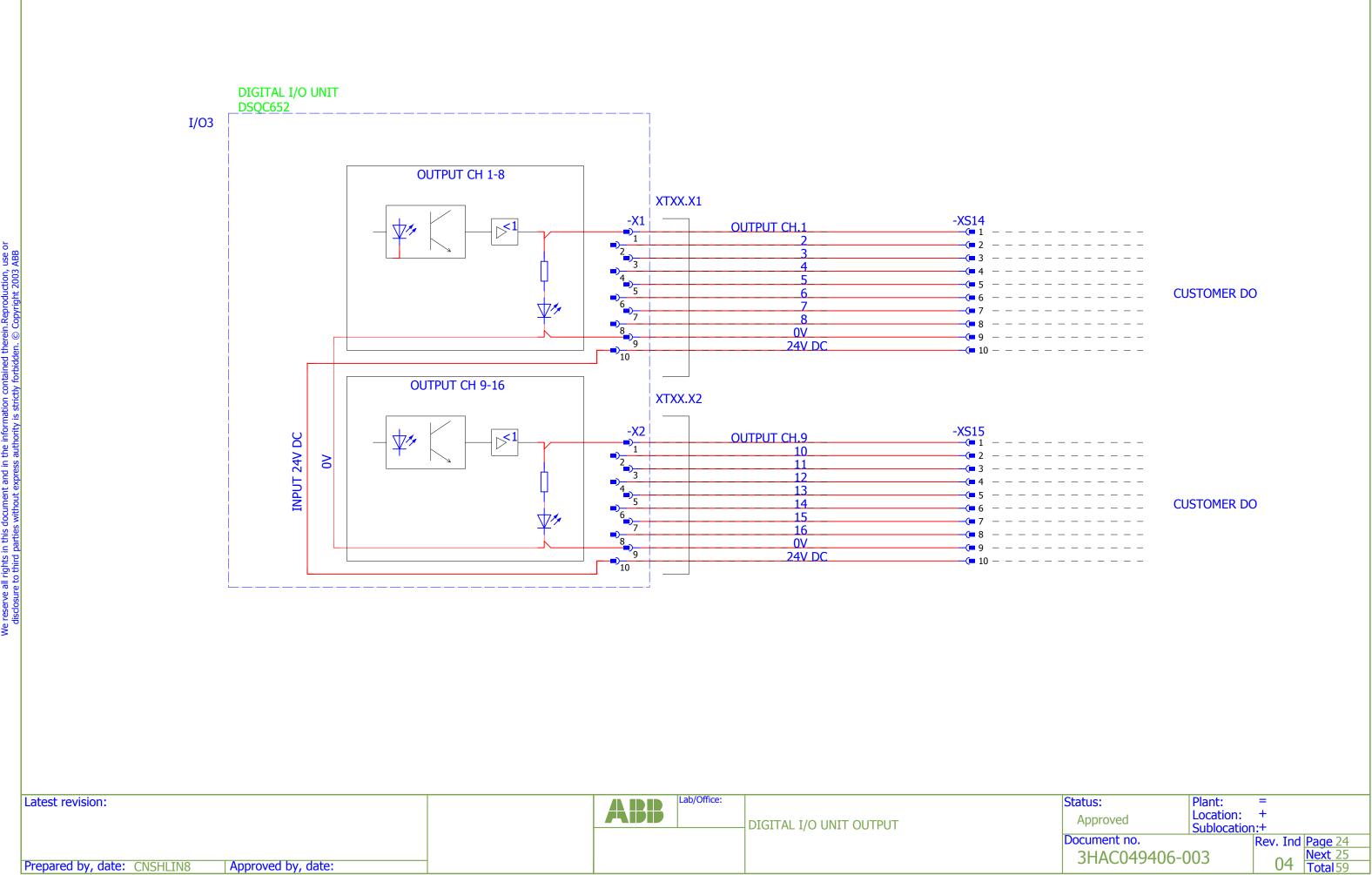












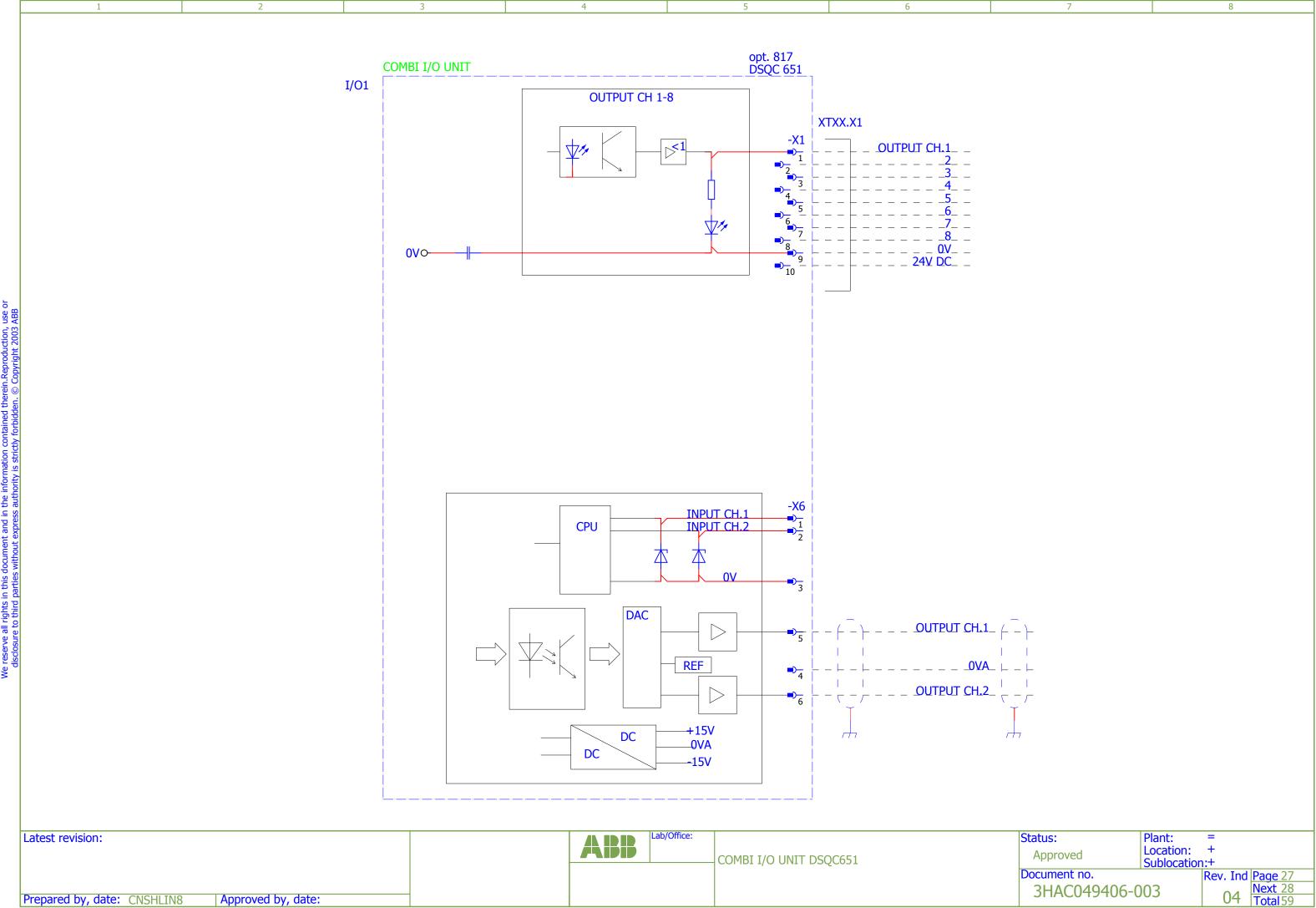
-I/Ox4 XTXX.X3 -X3 3) 22;7 / -XS17_V-22;7 / -XS17_CAN_L 22;7 / -XS17_CAN_H 22;7 / -XS17_V+ 22;7 / **-XS17_DRAIN** 10 0V NA0 OR PREVIOUS I/O UNIT NA1 0V 1) NA2 NA3 NA4 NA5 11 XTXX.X4 1) JUMPERS PLACED ACCORDING TO THE ACTUAL NODE ADDRESS. 2) RESISTANS 120 OHM SHALL ALWAYS BE CONNECTED IN THE FIRST AND THE LAST CONNECTOR IN THE CAN-BUS CIRCUIT. 3) CONNECTED IN THE LAST CONNECTOR IN THE CAN-BUS CIRCUIT. 4) ONLY FOR DIGITAL I/O DSQC 652. Lab/Office: Plant: Latest revision: ABB Status: Location: +
Sublocation:+ Approved DIGITAL PART OF COMBI I/O AND Rev. Ind Page 25 Next 26 Total 59 DIGITAL I/O UNIT DSQC651&652 Document no. 3HAC049406-003 Prepared by, date: CNSHLIN8 Approved by, date:

DIG. PART OF COMBI I/O AND DIG. I/O UNIT

opt. 816 opt. 817 DSQC 651& 652

opt. 816 DSQC 652 I/O1 OUTPUT CH 1-8 XTXX.X1 24V DC_ _ OUTPUT CH 9-16 XTXX.X2 INPUT 24V DC 9 Plant: = Location: + Sublocation:+ Lab/Office: Status: Latest revision: ABB Approved DIGITAL I/O UNIT DSQC652 Document no. Rev. Ind Page 26 Next 27 Total 59 3HAC049406-003 Prepared by, date: CNSHLIN8 Approved by, date:

DIGITAL I/O UNIT

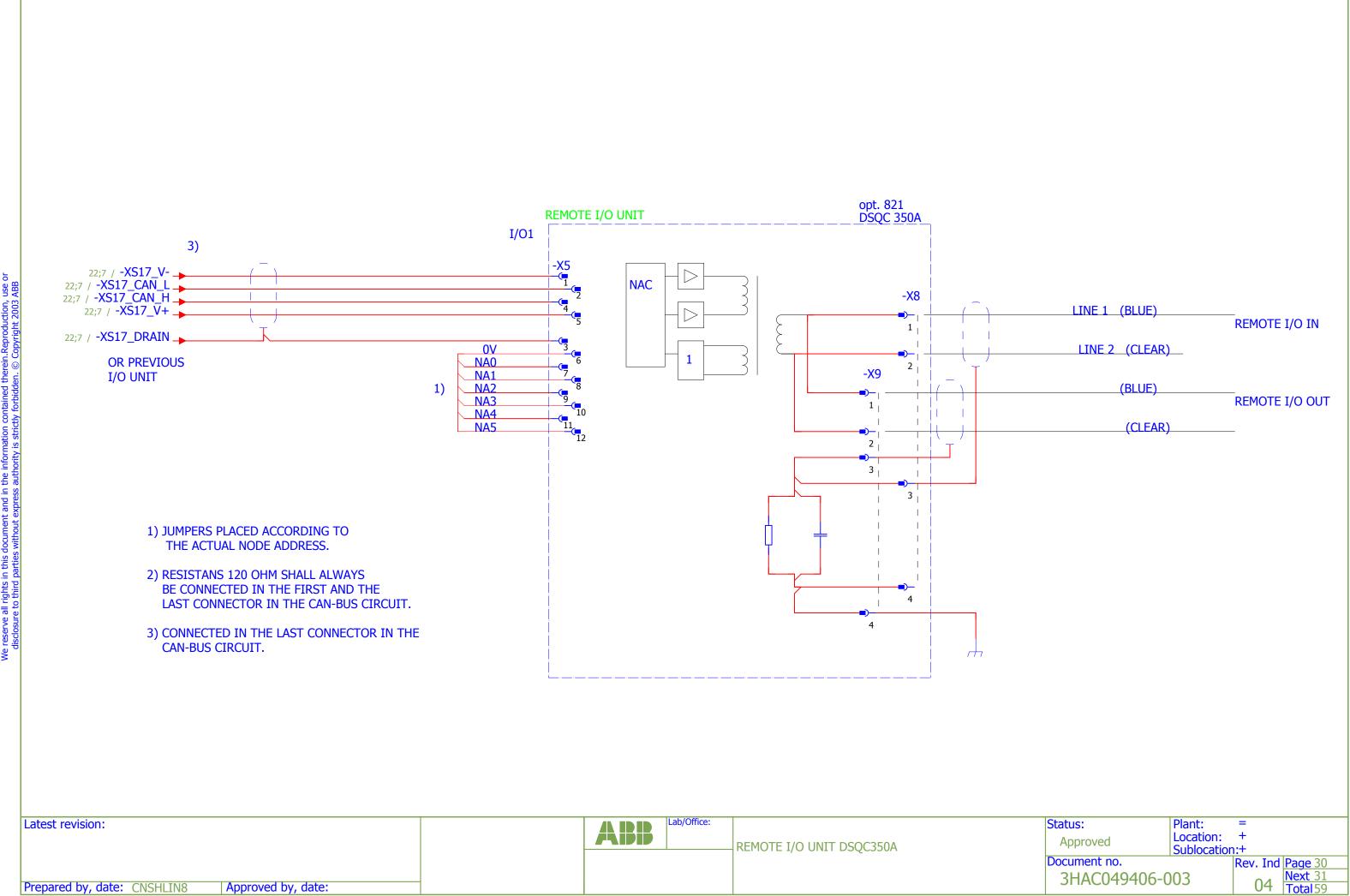


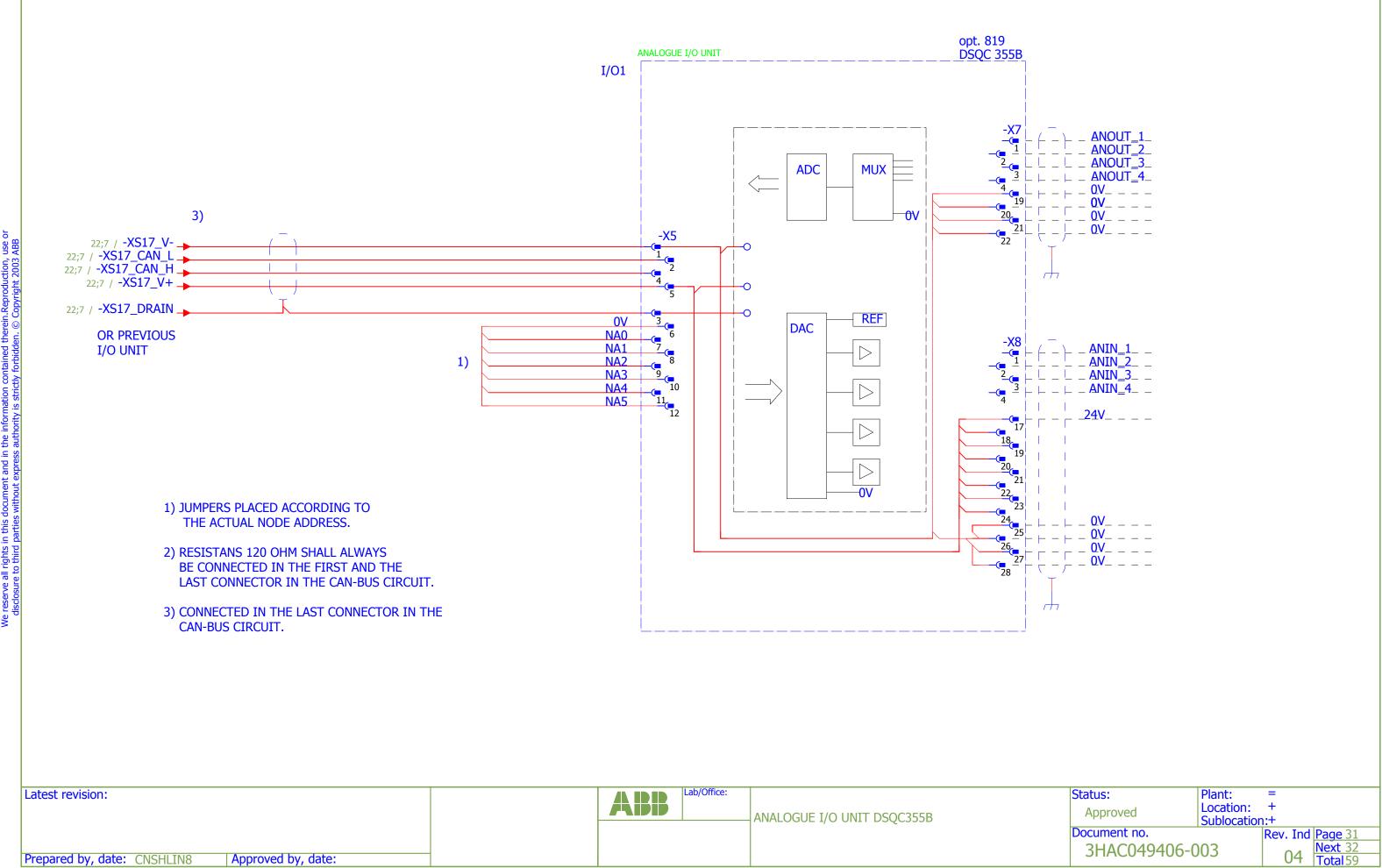
I/O1 XTXX.X3 INPUT CH.1_ 3) 22;7 / -XS17_V-22;7 / -XS17_CAN_L 22;7 / -XS17_CAN_H 22;7 / -XS17_V+ 22;7 / **-XS17_DRAIN** 0V NA0 **OR PREVIOUS 0V** I/O UNIT NA1 1) NA2 NA3 11 12 NA4 NA5 1) JUMPERS PLACED ACCORDING TO THE ACTUAL NODE ADDRESS. 2) RESISTANS 120 OHM SHALL ALWAYS BE CONNECTED IN THE FIRST AND THE LAST CONNECTOR IN THE CAN-BUS CIRCUIT. 3) CONNECTED IN THE LAST CONNECTOR IN THE CAN-BUS CIRCUIT. Lab/Office: Plant: Latest revision: ABB Status: Location: + Sublocation:+ Approved RELAY I/O UNIT DSQC653 Rev. Ind Page 28 Next 29 Total 59 Document no. 3HAC049406-003 Prepared by, date: CNSHLIN8 Approved by, date:

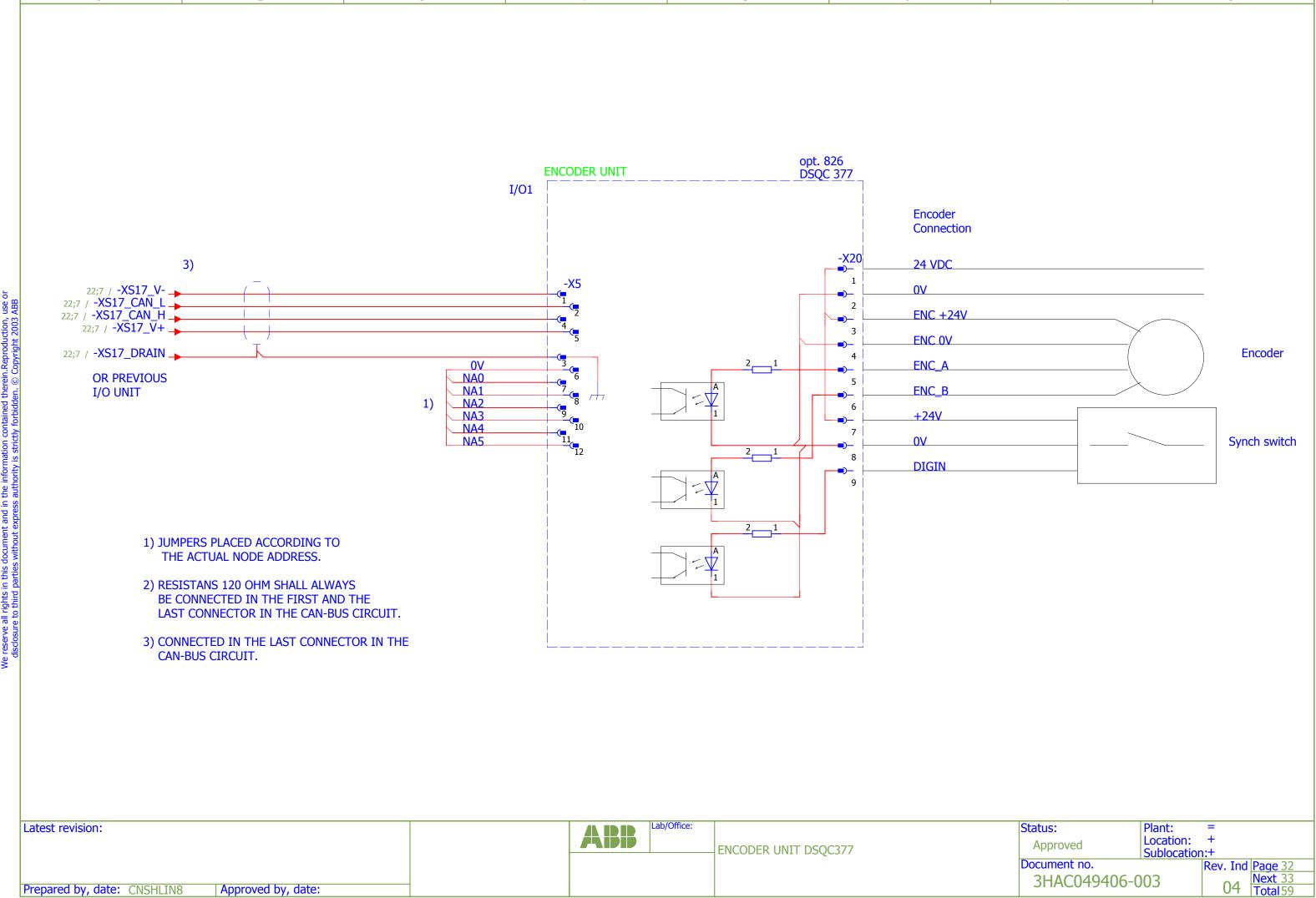
DIG. PART OF RELAY I/O UNIT

opt. 818 DSQC 653

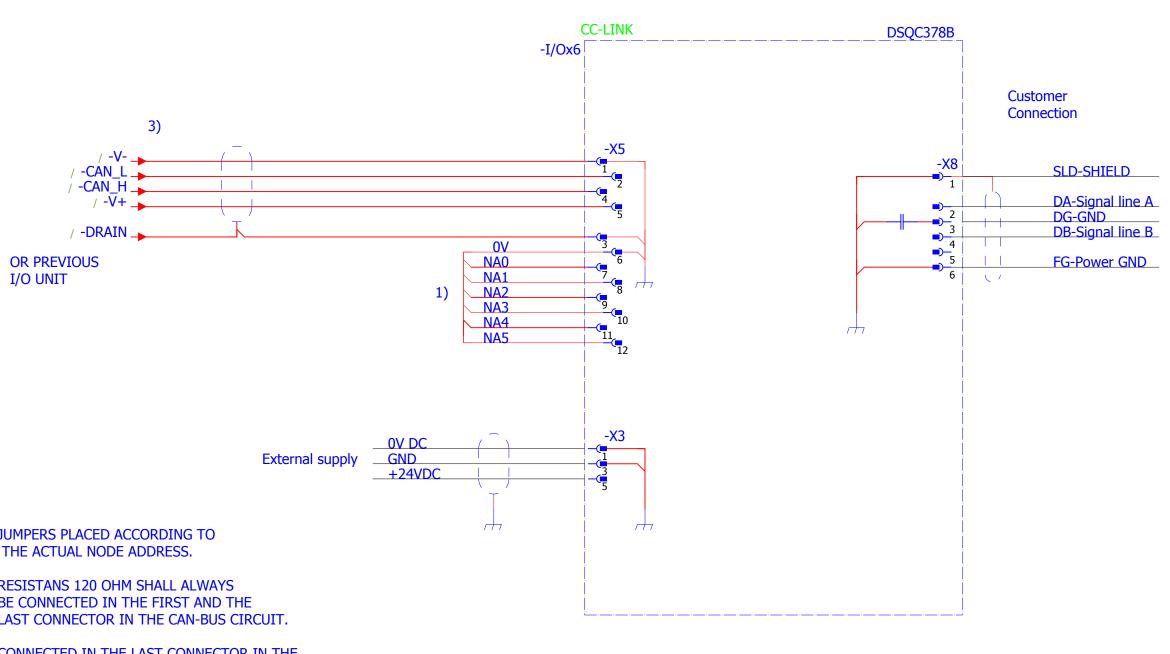






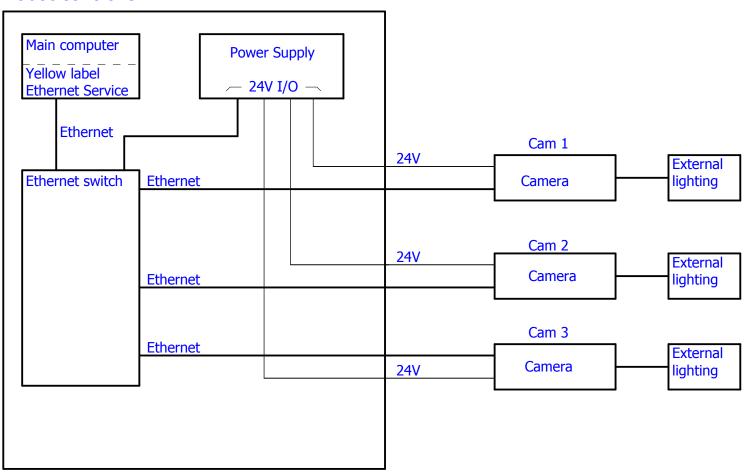


-X3 0V DC External supply __GND +24VDC 1) JUMPERS PLACED ACCORDING TO THE ACTUAL NODE ADDRESS. 2) RESISTANS 120 OHM SHALL ALWAYS BE CONNECTED IN THE FIRST AND THE LAST CONNECTOR IN THE CAN-BUS CIRCUIT. 3) CONNECTED IN THE LAST CONNECTOR IN THE CAN-BUS CIRCUIT. Lab/Office: Plant: Latest revision: ABB Status: Location: + Sublocation:+ Approved CC-LINK Rev. Ind Page 33 Next 34 Total 59 Document no. 3HAC049406-003 Prepared by, date: CNSHLIN8 Approved by, date:

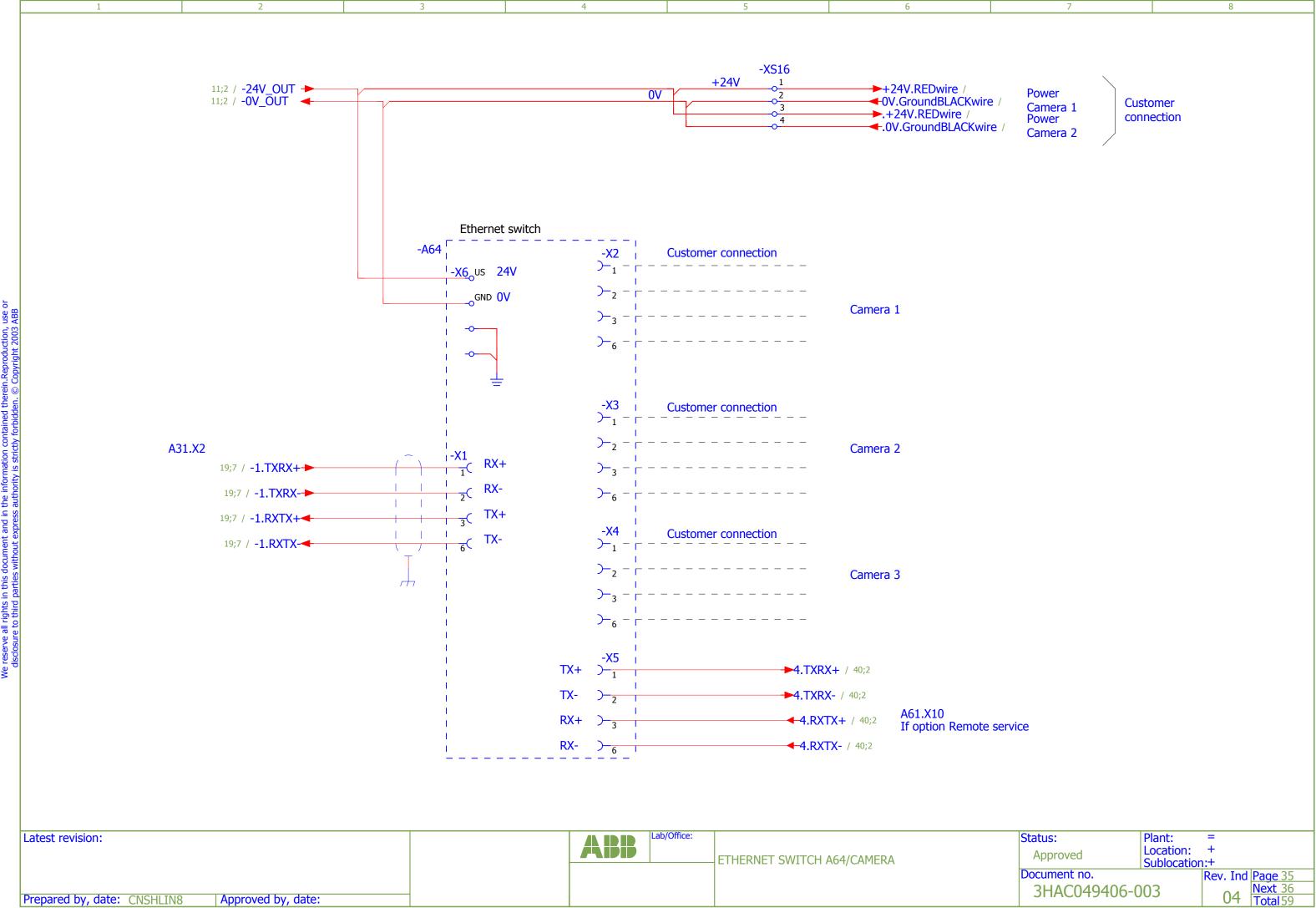


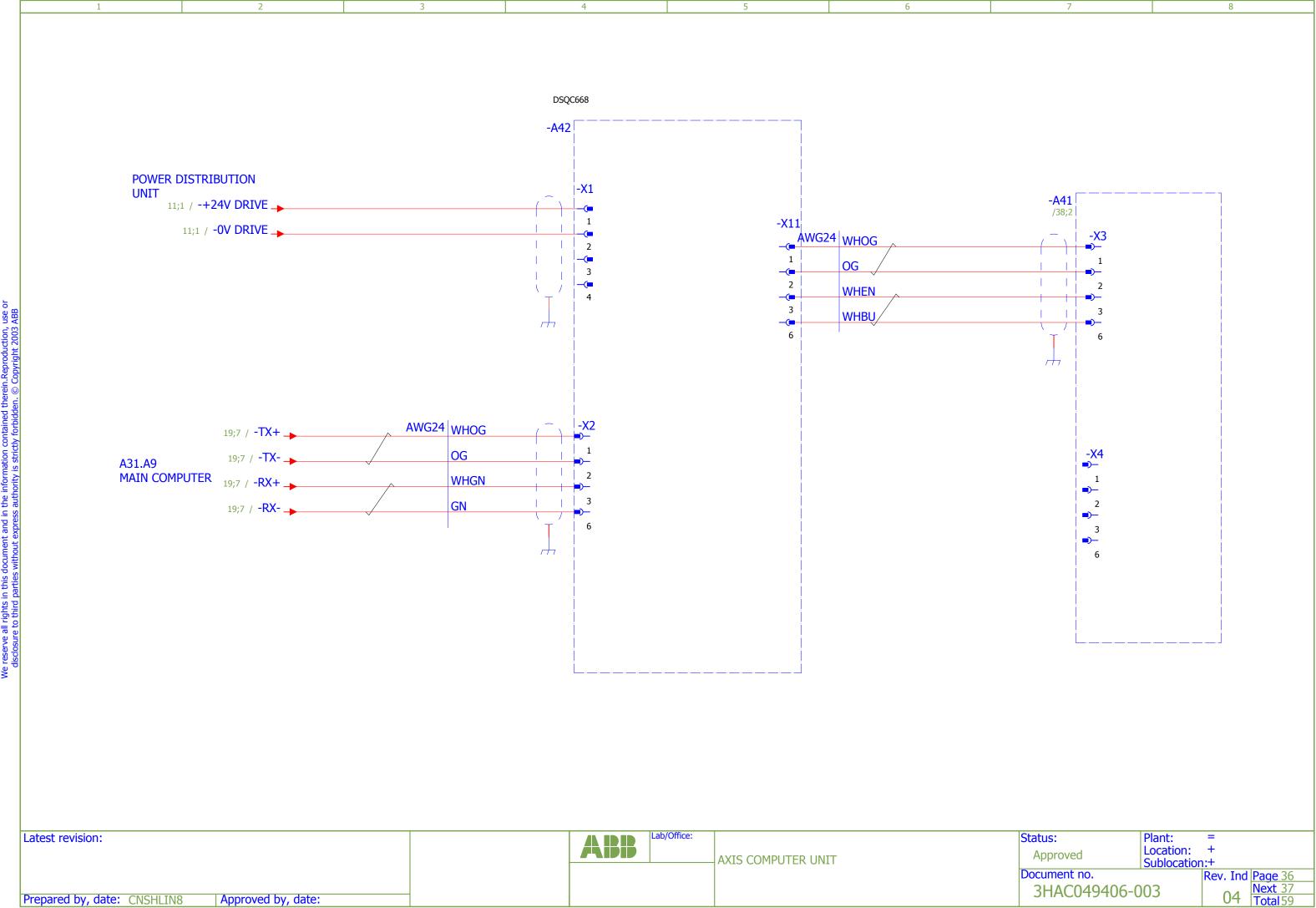
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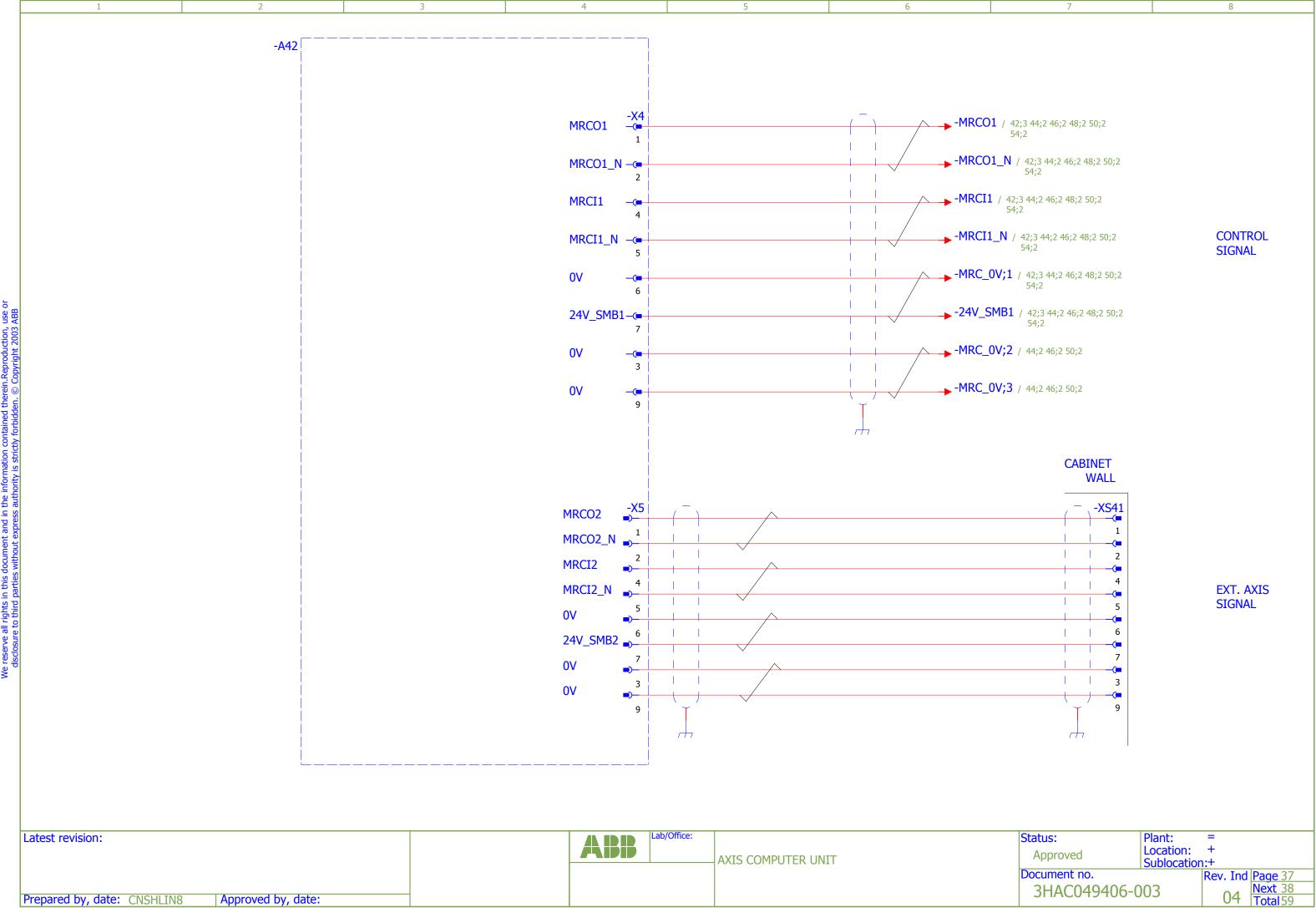
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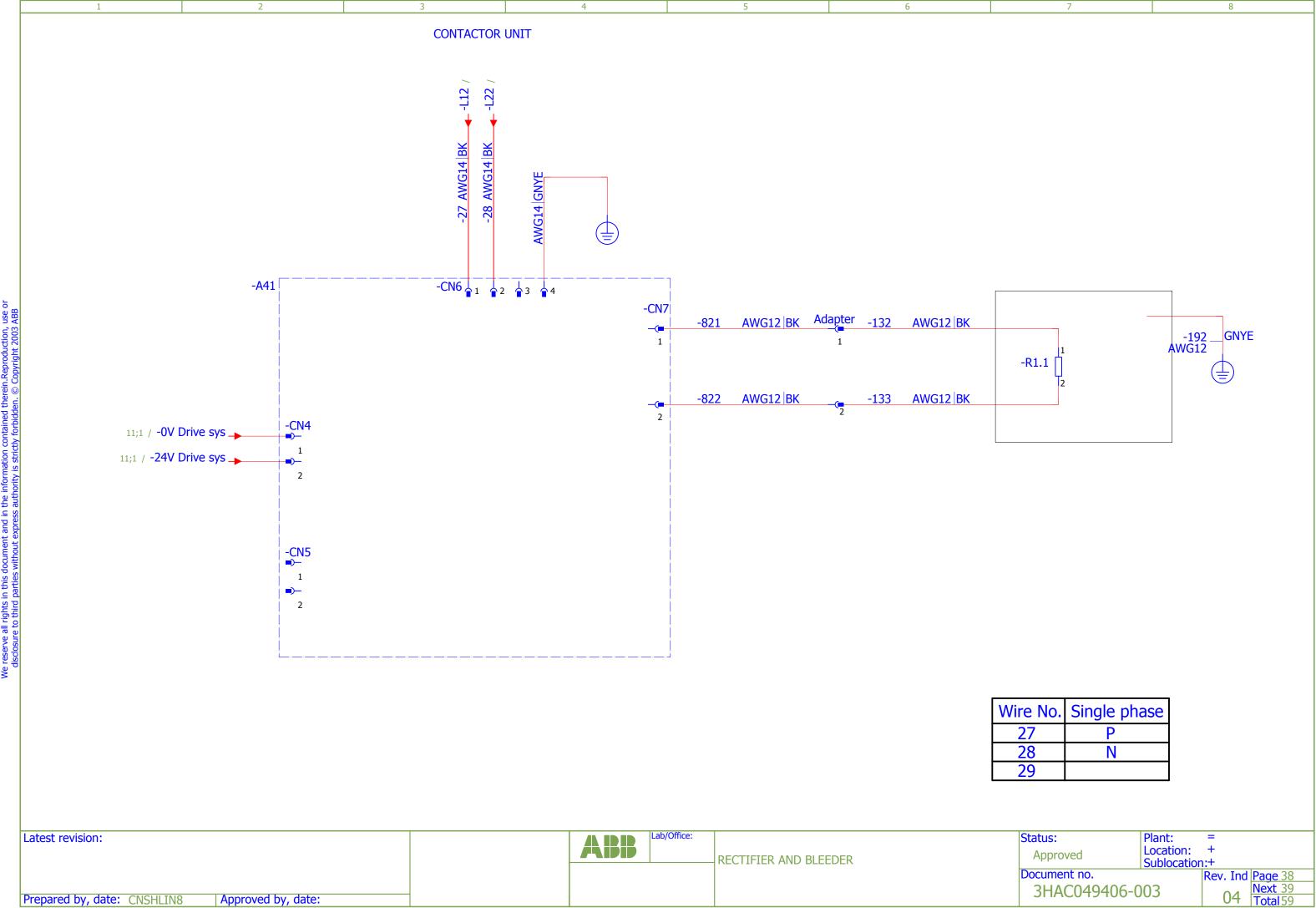


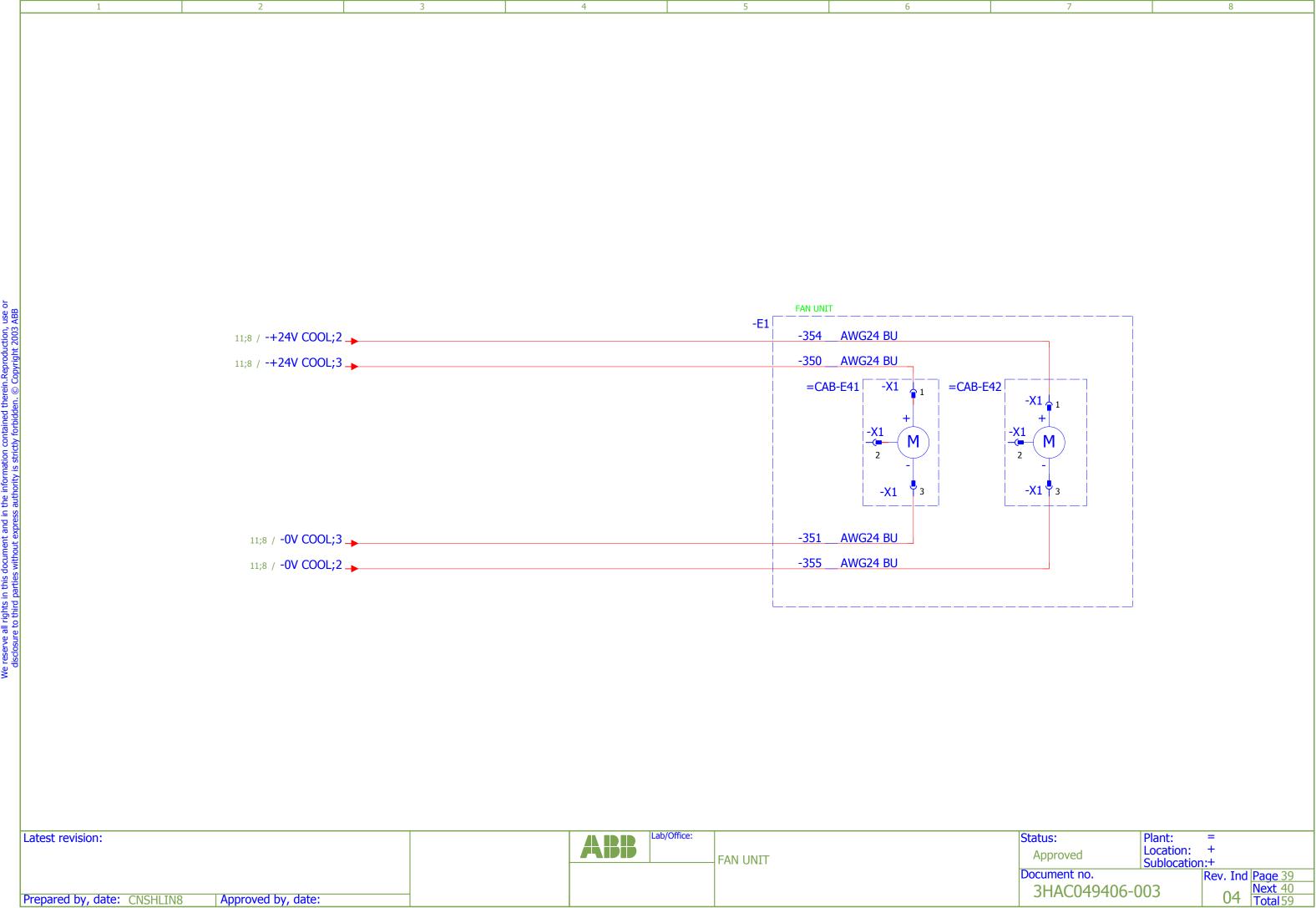


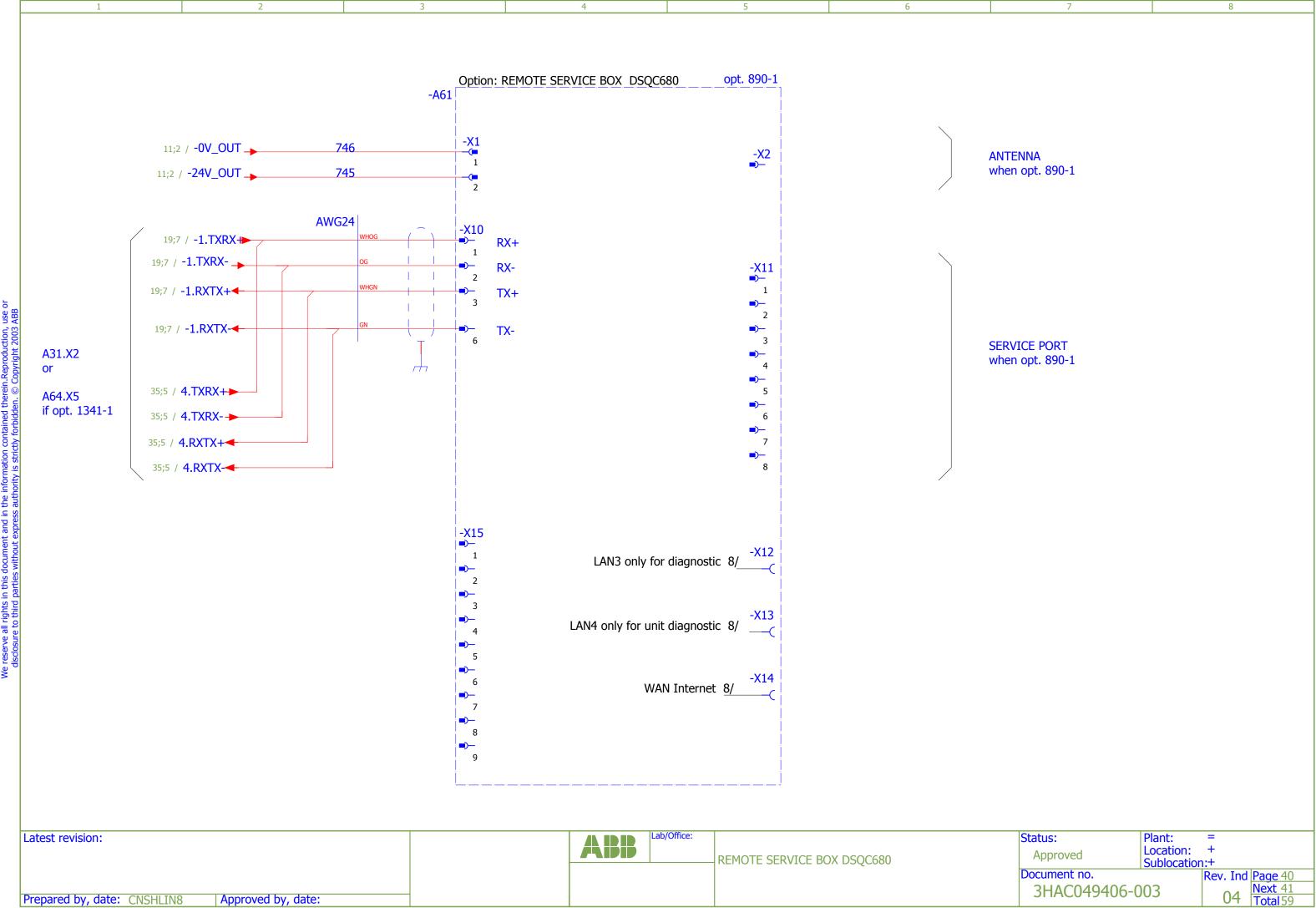




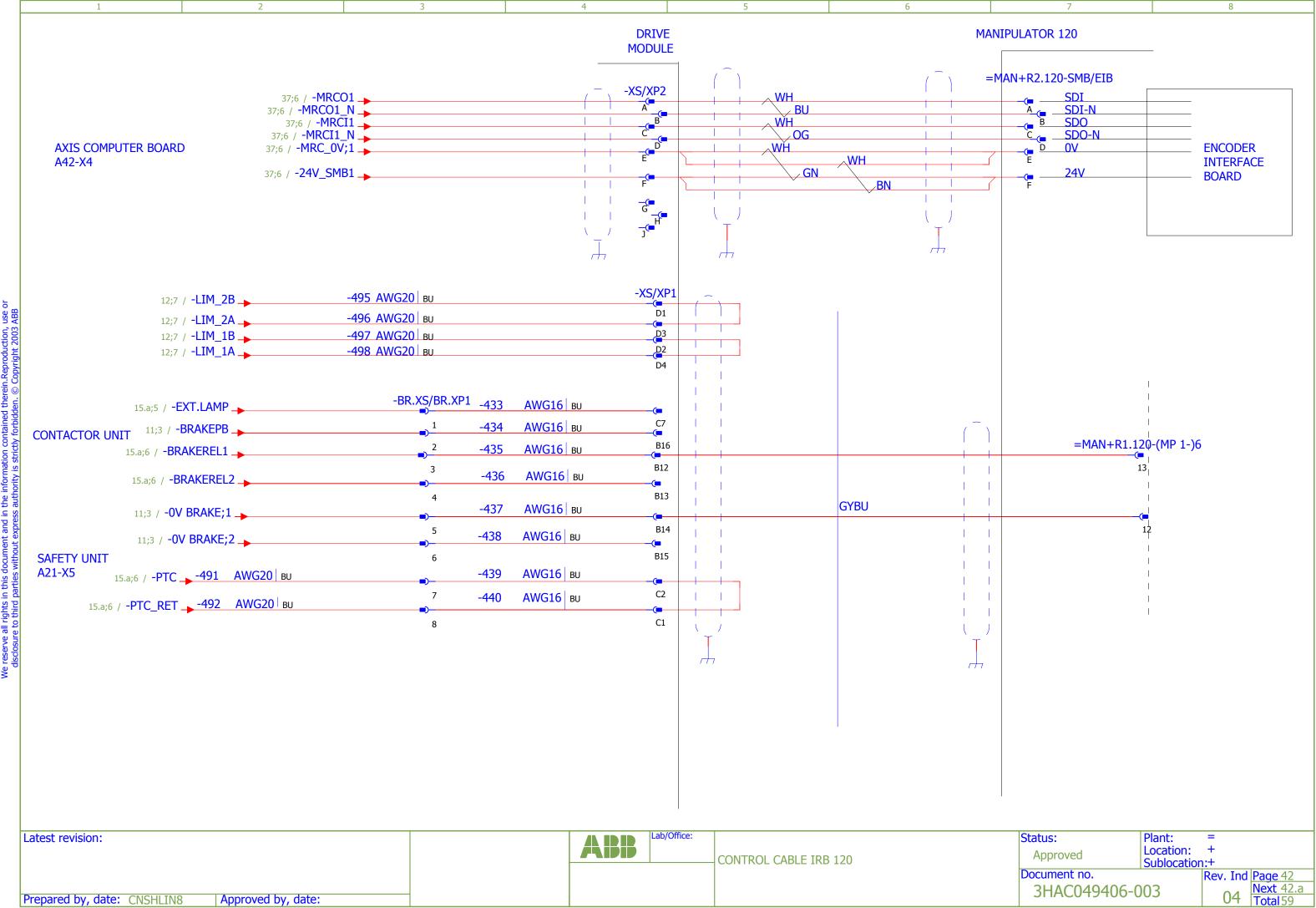


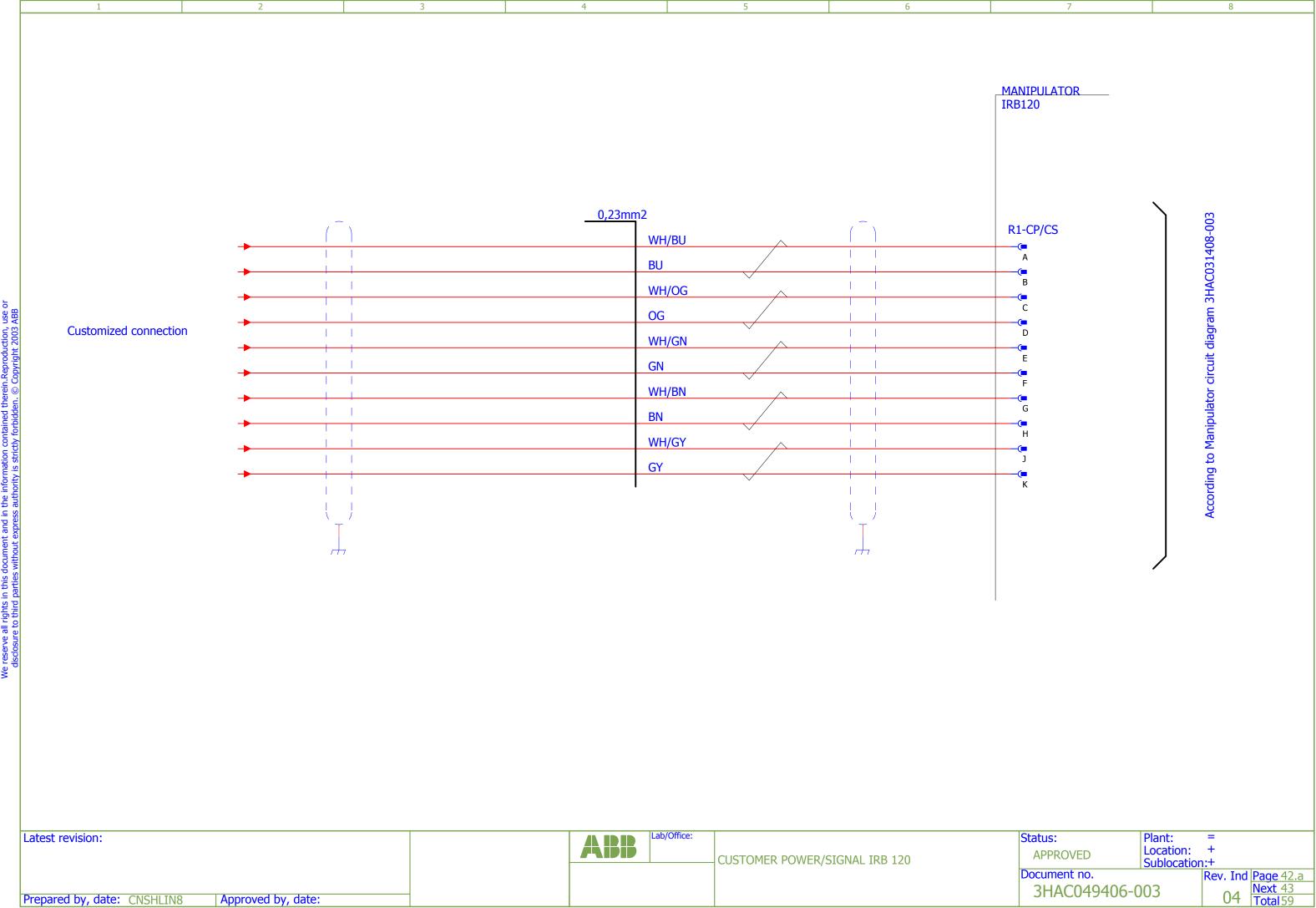






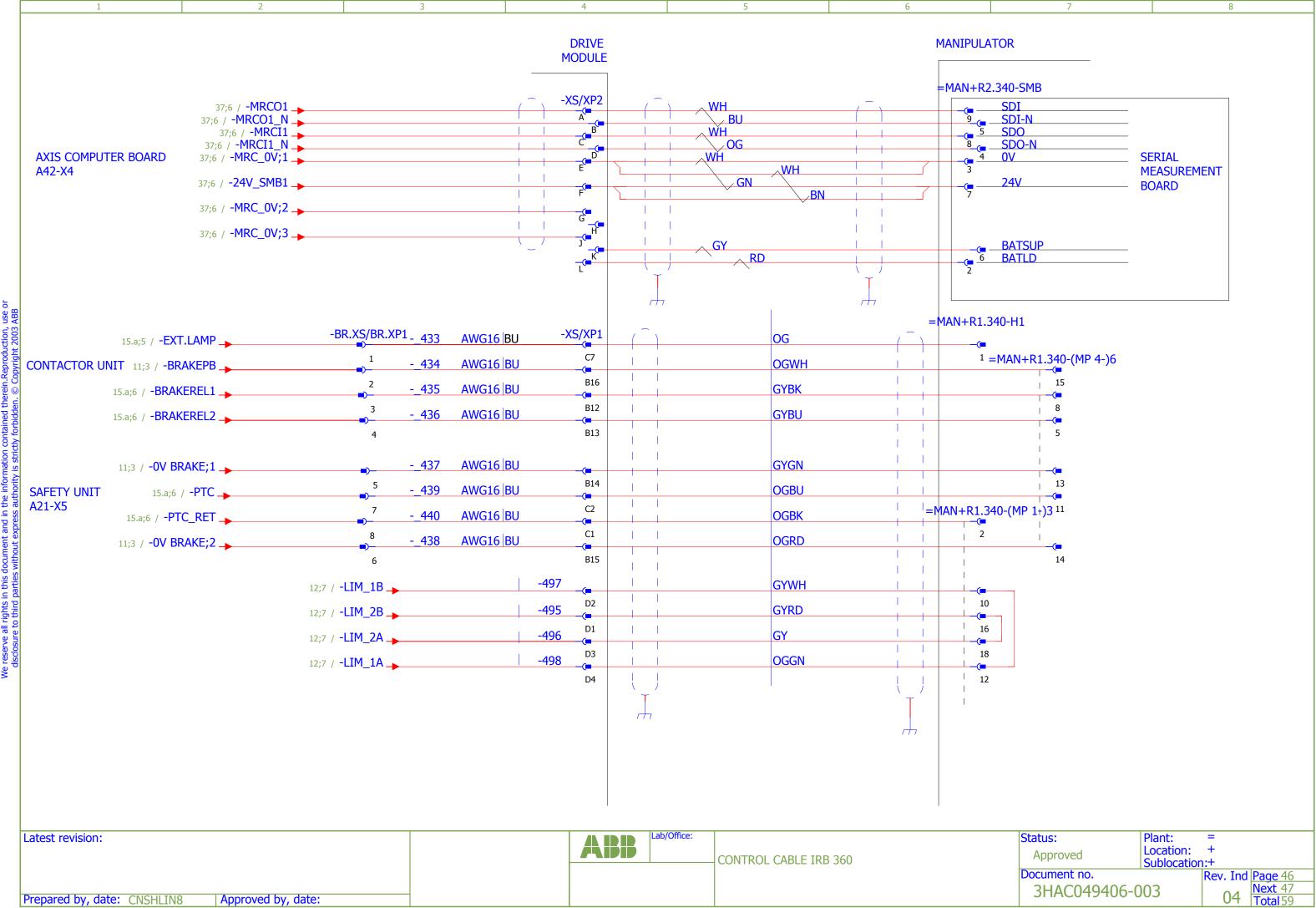
IRB 120 cabinet module AWG14 BK AWG14 BK AWG14 BK AWG14 BK AWG14 BK AWG14 BK -XS/XP1 ☆ B9 ☆ B10 ☆ B11 A1 A3 A5 🔓 B6 🔓 B7 🔓 B8 A7 A9 A11 A13 A15 B1 ↑ B3 ↑ B4 ↑ B5 **CABINET MANIPULATOR 120** 15 16 19 =MAN+R1.120-(MP 1-)6 Plant: Latest revision: Status: ABB Location: + Sublocation:+ **Approved** SERVO DRIVE SYSTEM IRB 120 Document no. Rev. Ind Page 41 Next 42 Total 59 3HAC049406-003 Prepared by, date: CNSHLIN8 Approved by, date:





IRB 140 cabinet module MAIN SERVO DRIVE UNIT -A41 $-\text{CN}100 \downarrow_1 \downarrow_3 \downarrow_2 -\text{CN}200 \downarrow_1 \downarrow_3 \downarrow_2 -\text{CN}300 \downarrow_1 \downarrow_3 \downarrow_2$ $-\mathsf{CN400} \, \, \, \, \big|_{1} \, \, \, \, \, \big|_{3} \, \, \, \, \big|_{2} \, \, \, -\mathsf{CN500} \, \, \big|_{1} \, \, \, \, \big|_{3} \, \, \, \big|_{2} \, \, -\mathsf{CN600} \, \, \big|_{1} \, \, \, \big|_{3} \, \, \big|_{2}$ AWG14 BK -420 AWG10 GNYE AWG10 GNYE -XS/XP1 ★ A1 ★ A3 ★ A5 ↑ A7 ↑ A9 ↑ A11 A13 A15 B1 **DRIVE MODULE** 🔓 B3 🔓 B4 🔓 B5 🔓 B6 🔓 B7 🔓 B8 🔓 B9 🔓 B10🔓 B11 3NGN BNBK M2R **MANIPULATOR** =MAN+R1.140-(MP 1-)3 Plant: Latest revision: Status: ABB Location: + Sublocation:+ Approved SERVO DRIVE SYSTEM IRB 140 Document no. Rev. Ind Page 43 Next 44 Total 59 3HAC049406-003 Prepared by, date: CNSHLIN8 Approved by, date:

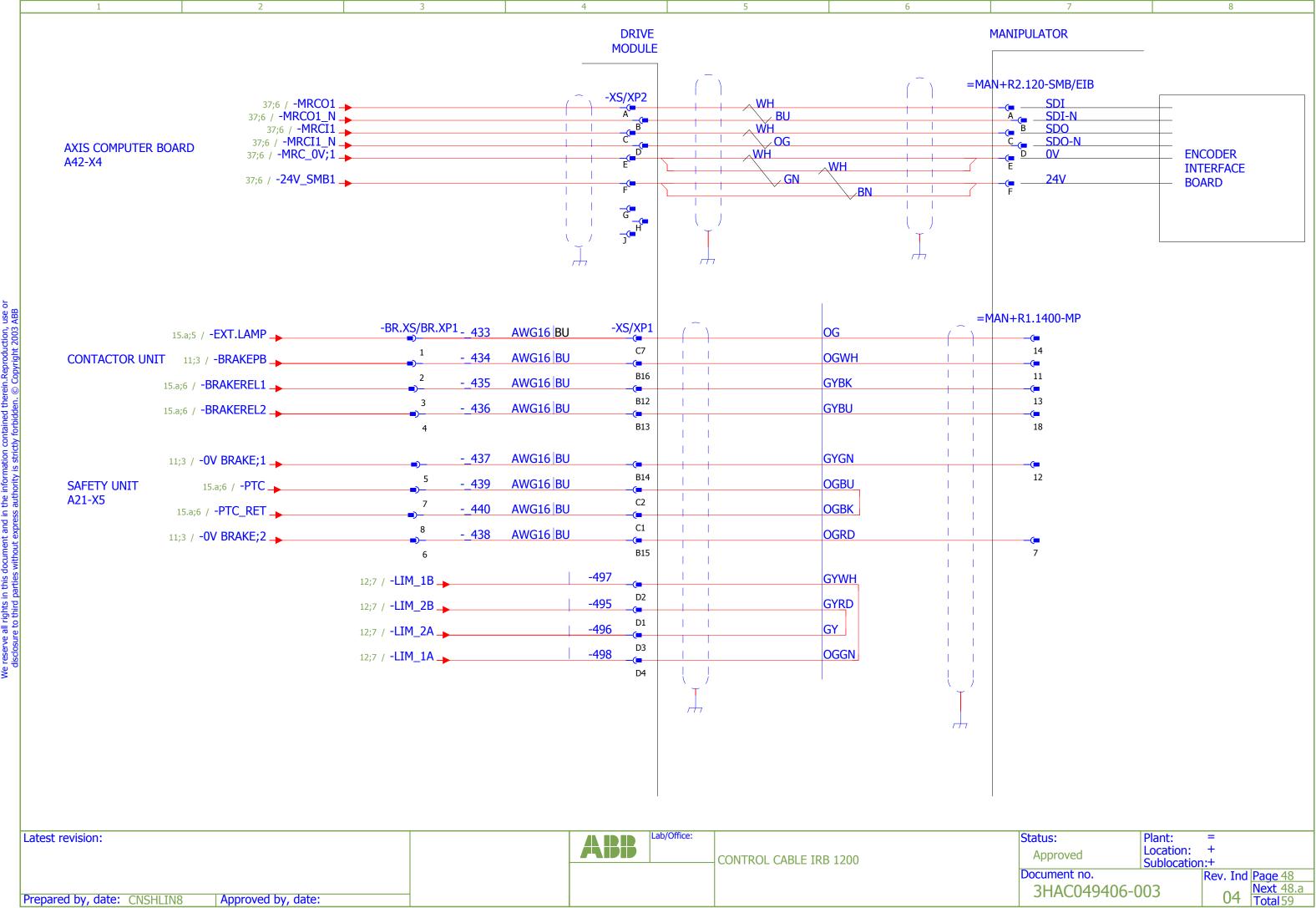


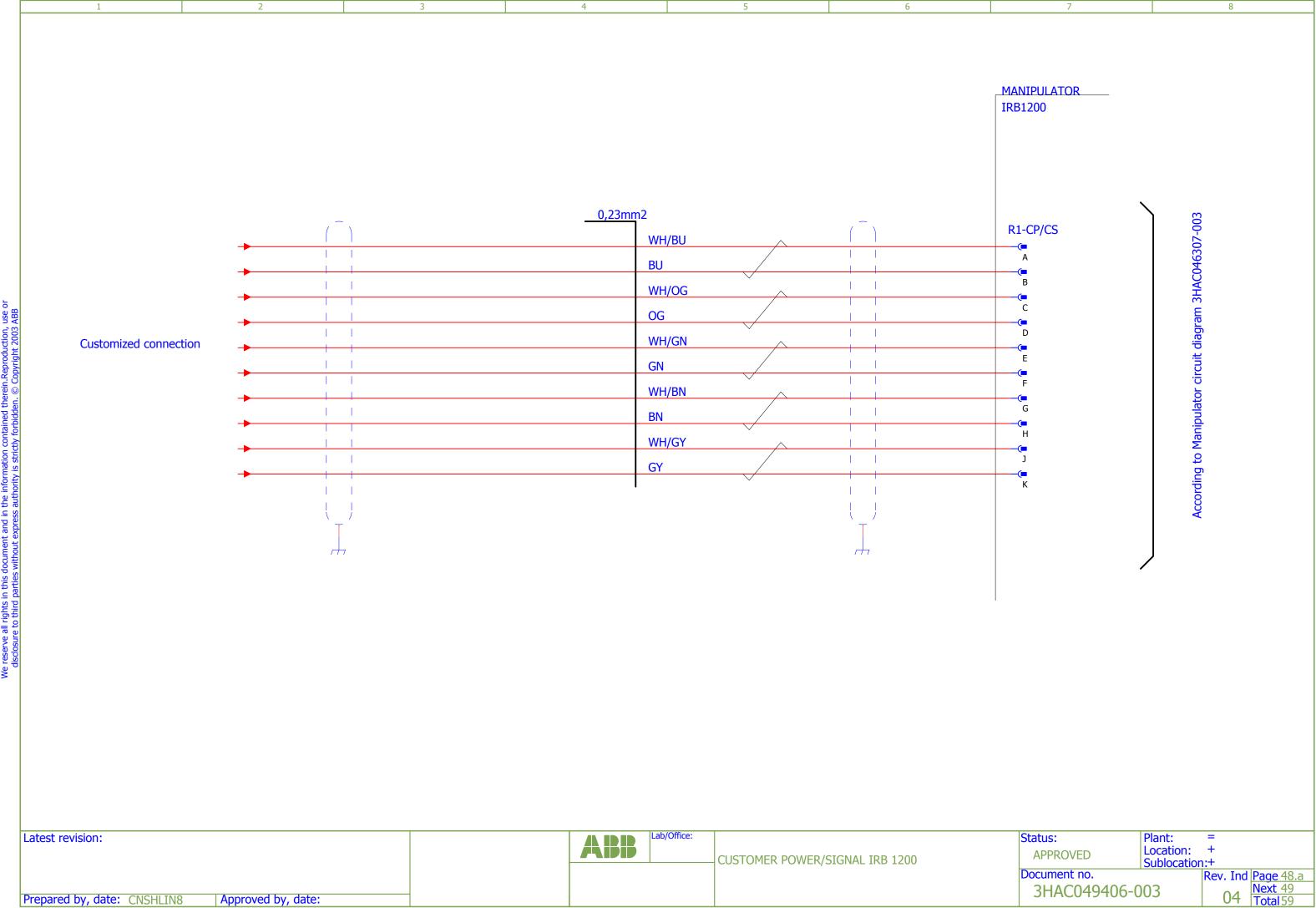


-CN300 \ 1 \ 1 3 \ 2 AWG14 BK -430 -XS/XP1 ♠ A1 ♠ A3 ♠ A5 **☆** B6 **☆** B7 **☆** B8 🛉 A7 🔓 A9 🔓 A11 A13 A15 B1 ♣ B3 ♣ B4 ♣ B5 ♣ B9 ♣ B10 ♣ B11 GNRD BKBU BKGN BURD M2R 20 23 24 🛉 15 🔓 16 🔓 19 =MAN+R1.1400-MP Latest revision: ABB SERVO DRIVE SYSTEM IRB 1200 Prepared by, date: CNSHLIN8 Approved by, date:

IRB 1200 cabinet module MAIN SERVO DRIVE UNIT -A41 AWG10 GNYE AWG10 GNYE **DRIVE MODULE MANIPULATOR** Plant: Status: Location: + Sublocation:+ Approved Document no. Rev. Ind Page 47 Next 48 Total 59

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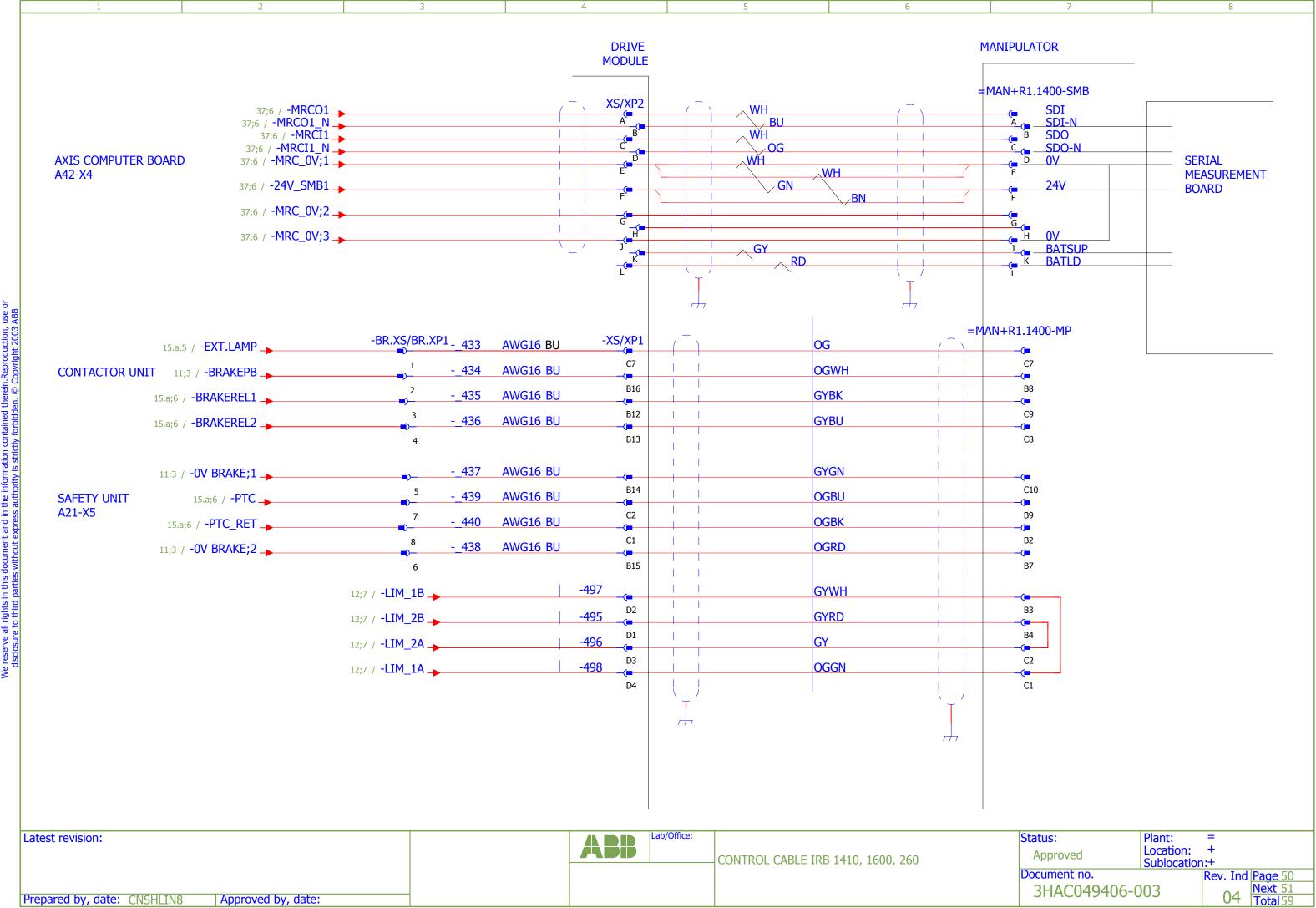


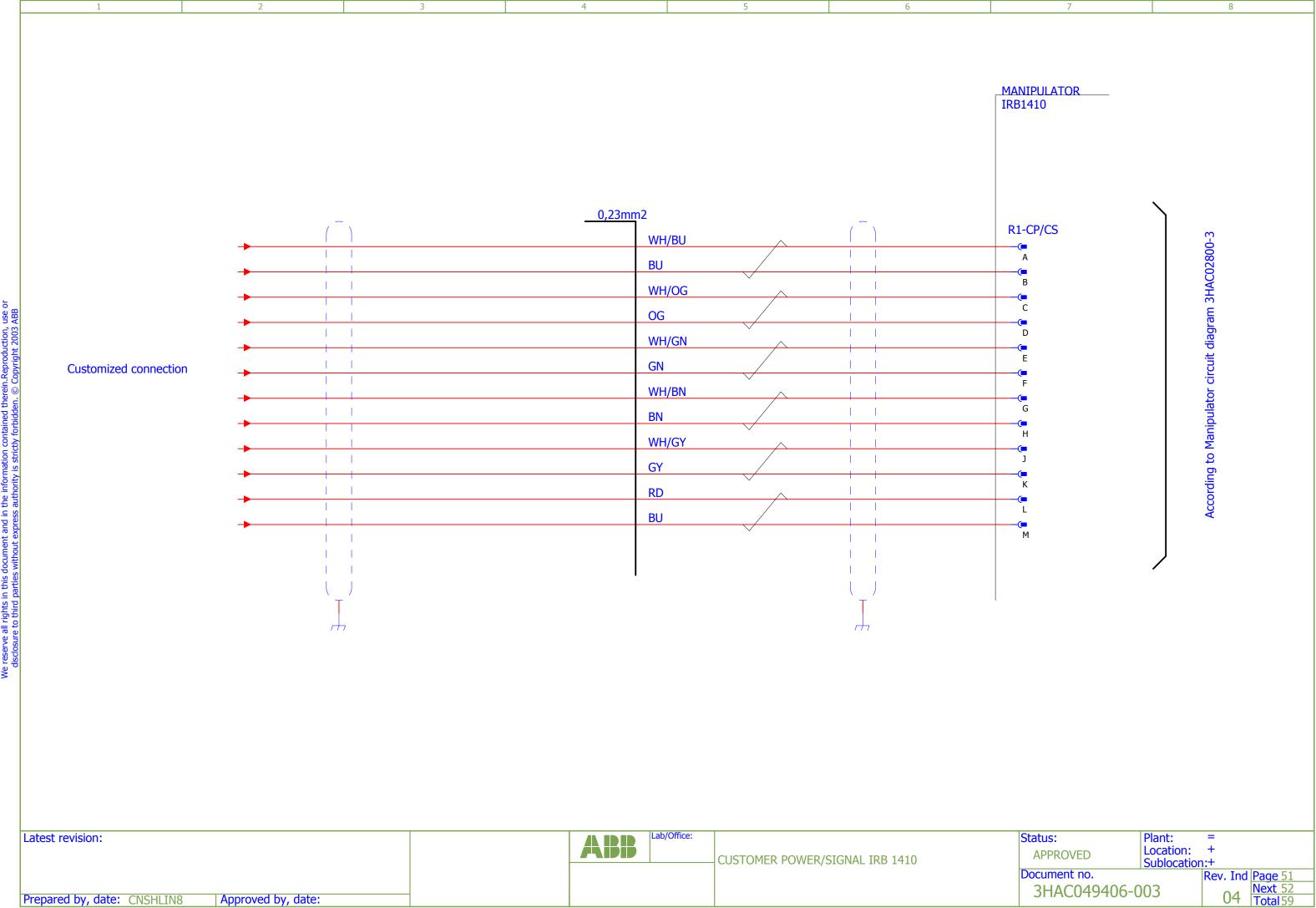


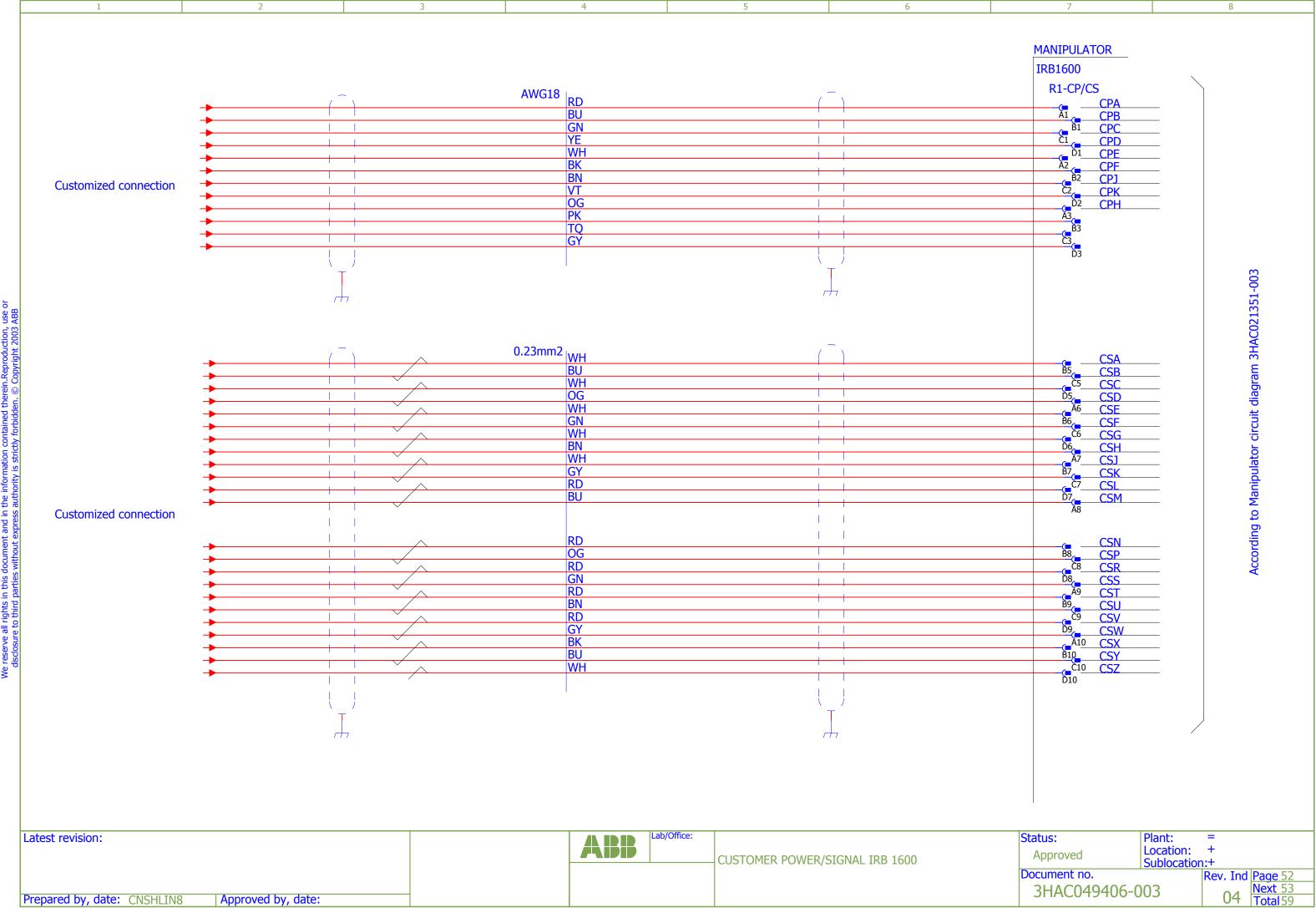
IRB 1410, 1600, 260 cabinet module MAIN SERVO DRIVE UNIT -A41 -CN600 \(\frac{1}{1} \) \(\frac{1}{3} \) \(\frac{1}{2} \) 2 -CN300 ¼ 1 ¼ 3 ¼ 2 -CN400 1 1 3 2 AWG14 BK AWG10 GNYE AWG10 GNYE -XS/XP1 & A1 & A3 & A5 🔓 A7 🔓 A9 🔓 A11 A13 A15 B1 🔓 B3 🔓 B4 🔓 B5 ☆ B6 ☆ B7 ☆ B8 📥 B9 🔓 B10 🔓 B11 **DRIVE MODULE MANIPULATOR** 📥 D8 📥 D7 📥 B10 ↑ A10↑ A9 ↑ A8 🛉 D3 🔓 D4 🔓 B1 =MAN+R1.1400-MP Plant: Latest revision: ABB Status: Location: Approved SERVO DRIVE SYSTEM IRB 1410, 1600, 260 Document no. Rev. Ind Page 49 3HAC049406-003

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MAIN SERVO DRIVE UNIT -A41 -CN300 \ 1 \ 1 3 \ 2 AWG14 BK AWG14 BK AWG14 BK AWG16 GNYE AWG16 GNYE -XS/XP1 A1 A3 A5 ↑ A7 ↑ A9 ↑ A11 A13 A15 B1 ☆ B9 ☆ B10☆ B11 **DRIVE MODULE** 쑮 **MANIPULATOR** 12 13 14 =MAN+R1.910-MP Plant: Latest revision: Status: ABB Location: + Sublocation:+ **Approved** SERVO DRIVE SYSTEM IRB 910 Document no. Rev. Ind Page 53 Next 54 Total 59 3HAC049406-003 Prepared by, date: CNSHLIN8 Approved by, date:

IRB 910 cabinet module

