The information in this document is subject to change without notice and should not be construed as a commitment by ABB. ABB assumes no responsibility for any errors that may appear in this document.

Except as may be expressly stated anywhere in this document, nothing herein shall be construed as any kind of guarantee or warranty by ABB for losses, damages to persons or property, fitness for a specific purpose or the like.

In no event shall ABB be liable for incidental or consequential damages arising from use of this document.

This document and parts thereof must not be reproduced or copied without ABB's written permission, and contents therof must not be imparted to a third party nor be used for any unauthorized purpose. Contravention will be prosecuted.

Additional copies of this document may be obtained from ABB at its then current charge.

© Copyright 2004 ABB ALL right reserved.

ABB Automation Technologies AB
Robotics
SE-721 68 Västerås
Sweden

Latest revision:

SMB, 2 axis

ABB COPYRIGHT

SMB, 2 axis

APPROVED

APPROVED

Status:

APPROVED

Sublocation: +

Sublocation:

Description : SMB, 2 axis

: 3HEA801153-002 Drawing number

Drawing version : 02

2009-02-03 Date

Customer

Year of construction 2009

Drawn by : PAW/JS

Number of pages

Latest revision: 2010

Prepared by, date:

Approved by, date:

ABB

Lab/Office: PAW

SMB, 2 axis

TITLE PAGE

Status: **APPROVED** 

Plant: Location: +
Sublocation:+

Document no.

Rev. Ind Page 2
Next 3
Total 7

3HEA801153-002 02

## We reserve all rights in this document and in the information contained therein.Reproduction, use or disclosure to third parties without express authority is strictly forbidden. © Copyright 2003 ABB

## TABLE OF CONTENTS

PAGE	PAGE DESCRIPTION	Date	Edited by	
1	ABB COPYRIGHT	2009-02-06	PAW/JS	
2	TITLE PAGE	2009-02-06	PAW/JS	
3	TABLE OF CONTENTS	2009-02-06	PAW/JS	
4	SIGNAL & RESOLVER CABLE, M7 &M8	2009-02-17	PAW/JS	02
5	POWER CABLE, M7	2009-02-17	PAW/JS	02
6	POWER CABLE, M8	2009-02-17	PAW/JS	02
7	BRAKE, PTC, LURB, LIMIT SW: M7&M8	2009-02-17	PAW/JS	02
				-
				-
				+
				_
				_
				_
				_

Latest revision:		
Prepared by, date:	Approved by, date:	

Lab/Office: PAW ABB

SMB, 2 axis TABLE OF CONTENTS

Document no.

 Status:
 Plant:
 =

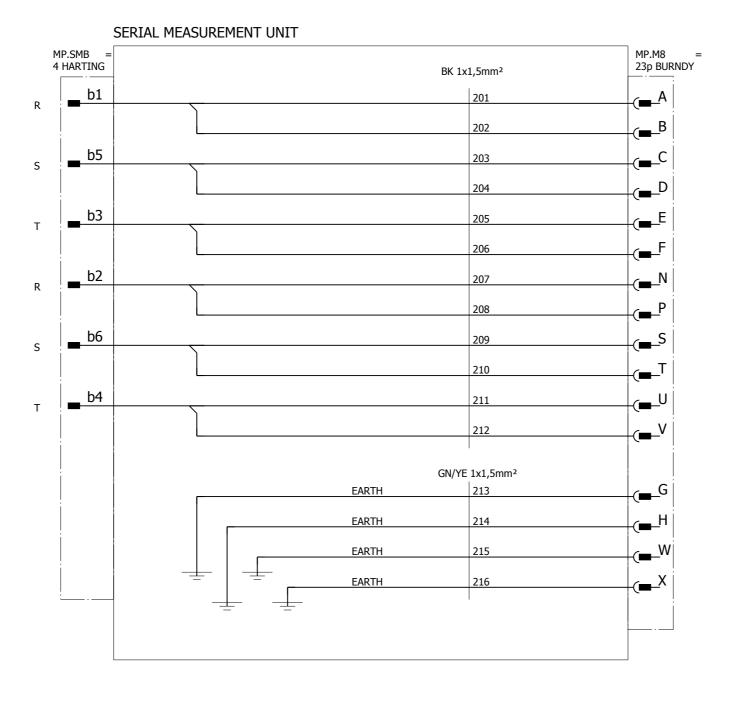
 APPROVED
 Location:
 +

 Sublocation:+
 Sublocation:+
 Rev. Ind Page 3

 Next 4
 Total7

SERIAL MEASUREMENT UNIT MP.M7 = 23p BURNDY MP.SMB 4 HARTING BK 1x1,5mm<sup>2</sup> \_\_a1 \_\_a5 S <u>D</u> \_\_a3 \_\_a2 We reserve all rights in this document and in the information contained therein.Reproduction, use or disclosure to third parties without express authority is strictly forbidden. © Copyright 2003 ABB **a**6 S **\_**a4 GN/YE 1x6mm<sup>2</sup> GN/YE 1x1,5mm<sup>2</sup> EARTH EARTH EARTH Plant: = Location: + Sublocation:+ Rev. Ind Page 5 Next 6 Total 7 Lab/Office: PAW SMB, 2 axis Latest revision: Status: **APPROVED** Rev. 02:Wire type changed(3-5) POWER CABLE, M7 Document no. 3HEA801153-002 Prepared by, date: Approved by, date:

We reserve all rights in this document and in the information contained therein.Reproduction, use or disclosure to third parties without express authority is strictly forbidden. © Copyright 2003 ABB



Latest revision:
Rev. 02:Wire type changed(4-5)

Prepared by, date:

SMB, 2 axis

Plant: =
Location: +
Sublocation:+
Sublocation:+
Document no.
3HEA801153-002

Rev. Ind Page 6
Next 7
Total 7

