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ABB AB

SE-721 68 Västerås Sweden

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Prepared by, date: EM 110322



Lab/Office: DMRO SE

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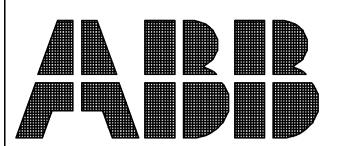
Plant: = IRB260 Location: + Manipulator Sublocation:+

Document no.

3HAC025611-001

Rev. Ind

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Customer

Robot serial number(s):

Drawing number : Manipulator

Drawing version

: 2011-03-25 Manufacture

Type

Type of installation

Control cabinet

Mains voltage

Supply Control voltage

Year of construction

Project start 2005-09-02

Project manager

Last revision

Designed by SEERMES Designed date 2011-03-25

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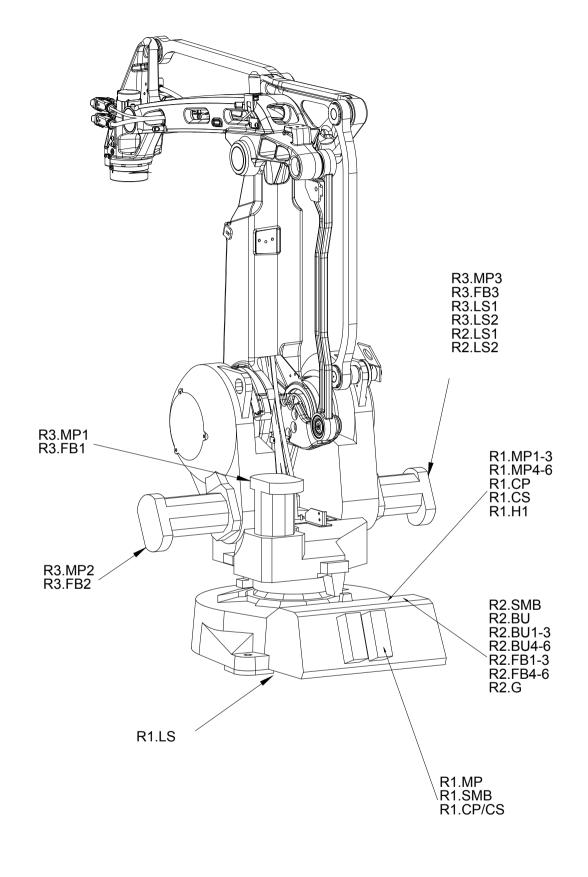
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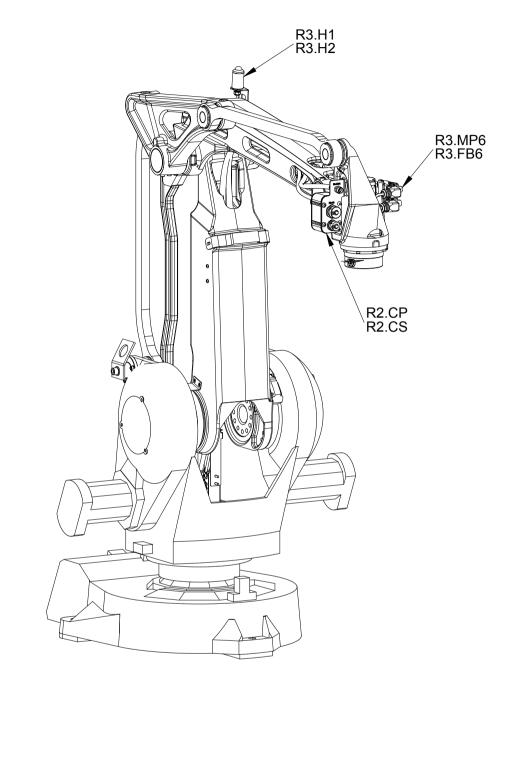
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Manipulator Connection Points

Status: 2011-03-24

Plant: = IRB260
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