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Latest revision:

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ECO 54448, WI 47903

IRB6660 IRC5

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Type IRB6660-100/3.3 + 130/3.1 + 205/1.9

APPROVED

3HAC029940-001

Status:

2012-12-21

= SP Plant: Location: Sublocation: +

Document no.

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Prepared by, date:

EM 121206 Approved by, date:

JM, 121221

Customer

Robot serial number(s) : IRB6660 IRC5

Drawing number : 3HAC029940-001

Drawing version : DRESS PACK

: 2007-11-07 Manufacture

Type

Type of installation Control cabinet

Mains voltage

Supply

Control voltage

Year of construction

Project start : 2007-10-15

Project manager

Last revision

Designed by : SEMITOT Designed date : 2007-11-07

Number of pages : 12

Latest revision: ECO 54448, WI 47903 Robot type IRB6660-100/3.3 added. Prepared by, date: EM 121206 Approved by, date: JM, 121221



IRB6660 IRC5

TITLE PAGE

Type IRB6660-100/3.3 + 130/3.1 + 205/1.9

2012-12-21 Status: APPROVED

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DP	130	101	CUSTOMER SIGNALS, CANBUS	APPROVED	2007-11-07	semitot
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DP	205	201	CUSTOMER SIGNALS, PARALLEL	APPROVED	2007-11-07	semitot

Latest revision:	ECO 54448, WI 47903 Robot type IRB6660-100/3.3 a	added.		
Prepared by, date:	EM 121206	Approved by, date:	JM, 121221	

Lab/Office:
DOMRO SE
PRMP

IRB6660 IRC5

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Type IRB6660-100/3.3 + 130/3.1 + 205/1.9

Status: 2012-12-21
APPROVED

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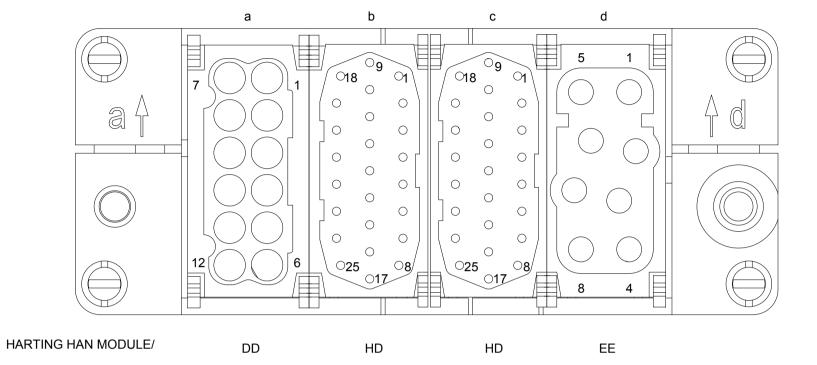
Document no.

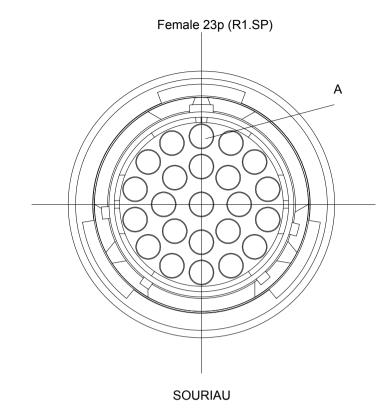
3HAC029940-001 Rev. 0

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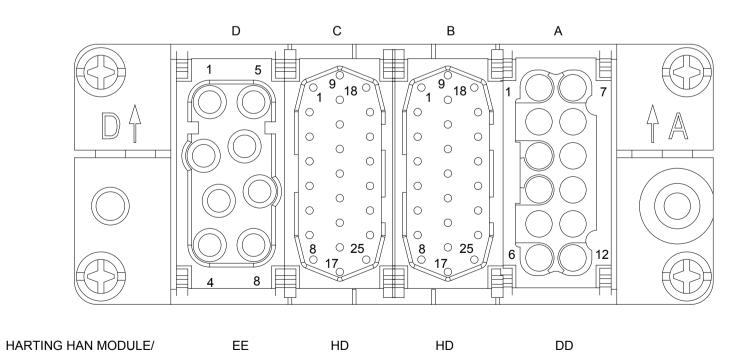


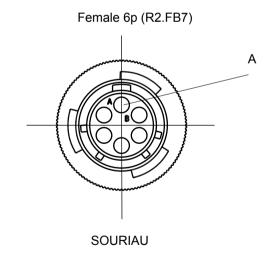
## Male (R1.CP/CS)





## Female (R2.CP/CS)





Latest revision:

ECO 54448, WI 47903
Robot type IRB6660-100/3.3 added.

Prepared by, date:

EM 121206 | Approved by, date: JM, 121221

ABB

Lab/Office: DOMRO SE PRMP

CONNECTOR LAYOUT

Type IRB6660-100/3.3 + 130/3.1 + 205/1.9

Status: 2012-12-21
APPROVED

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