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Sweden

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ABB

Lab/Office: PAW

ROBOT CARRIER RTT 1400/2400

TITLE PAGE

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Total 13

Prepared by, date: PR, 091222

Approved by, date: AL,100115

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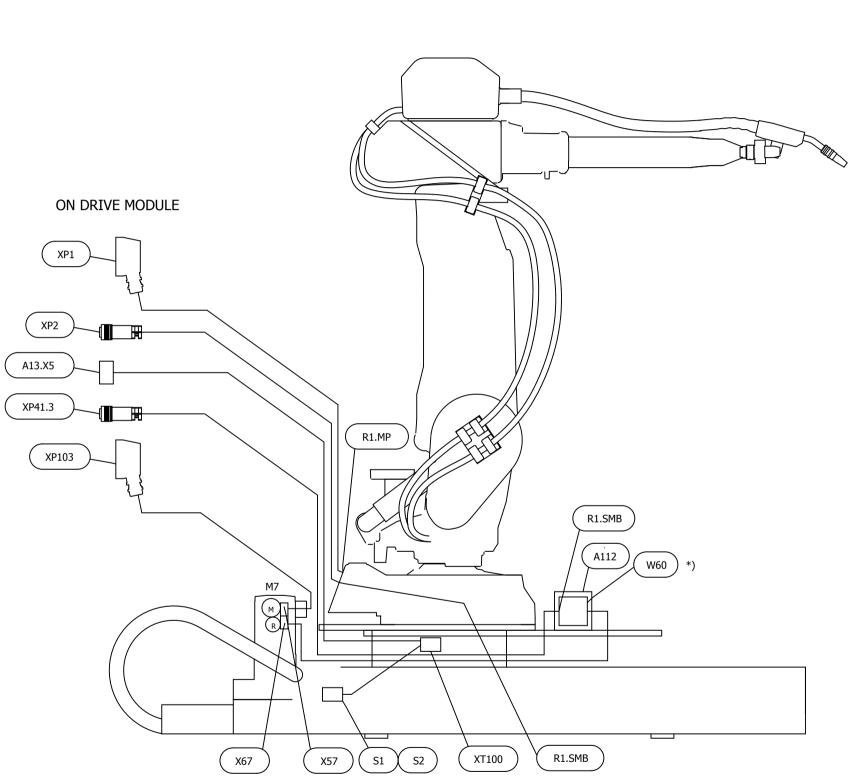
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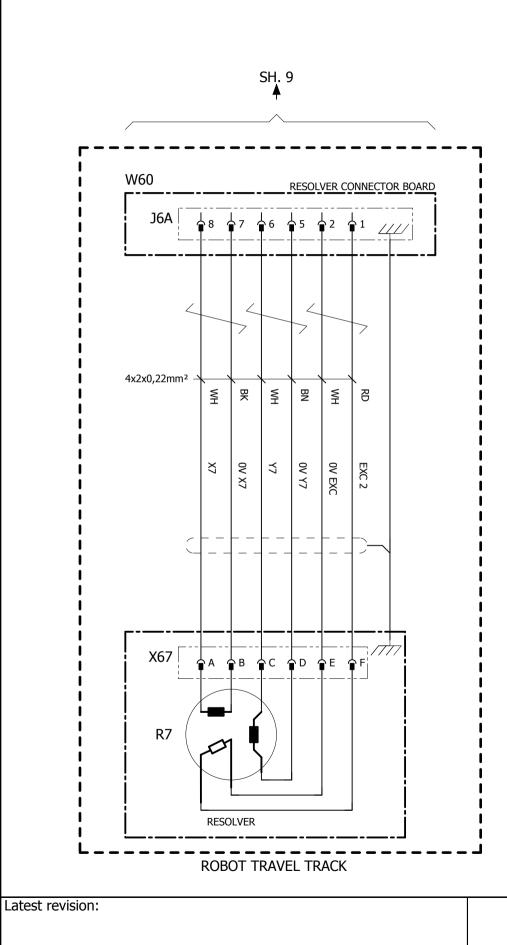
*) SYSTEM CONFIGURATION

MOTOR No	SMB NODE No	UNIT
M7	7	ROBOT TRAVEL TRACK

		1 1120/0	Office	Chatana	Disaste
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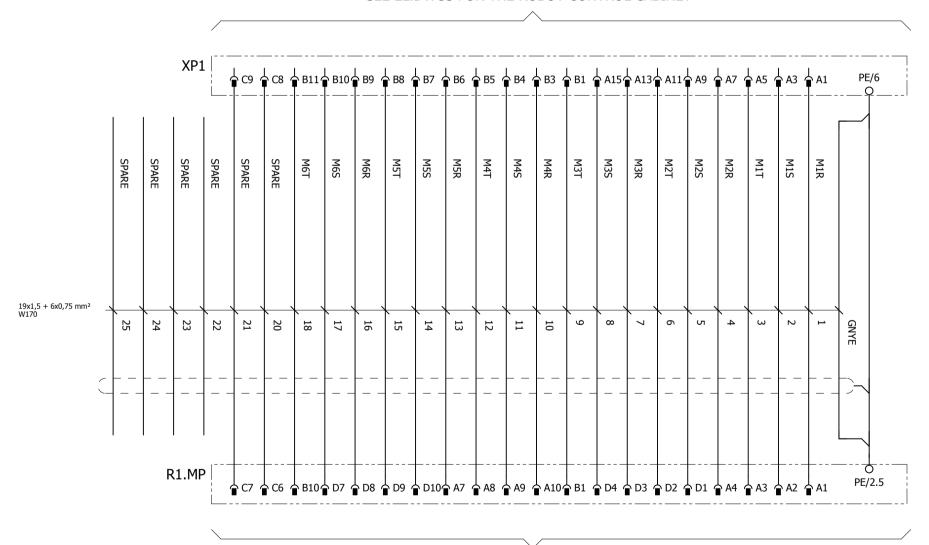
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RESOLVER

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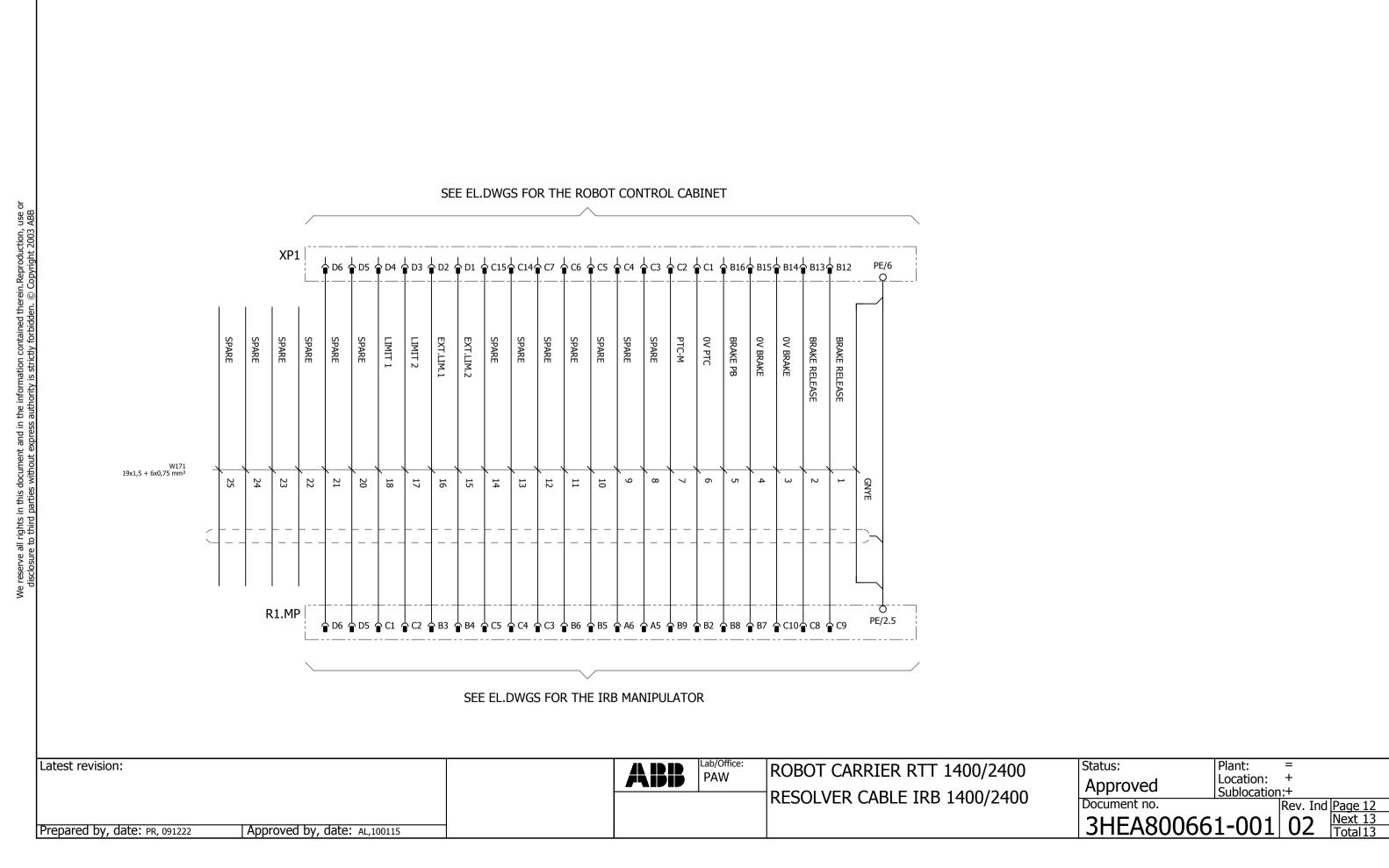




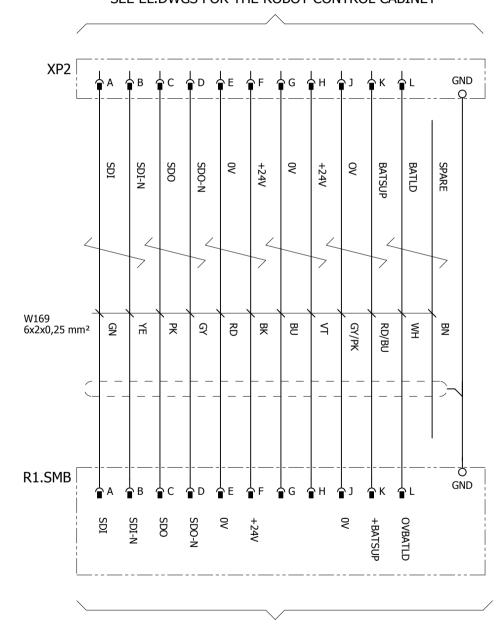
SEE EL.DWGS FOR THE IRB MANIPULATOR

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