

Linear systems

Many mathematical problems reduce to $\vec{A}\vec{x} = \vec{b}$
(possibly, with a bit of manipulation).

matrix \vec{A} unknowns \vec{x} solutions \vec{b}

For example:

$$17x + 3y - 9z + 2 = 0$$

$$-9x + 2y + 4z - 9 = 0$$

$$\frac{1}{2}x - 7y + z + 1 = 0$$

becomes

$$\underbrace{\begin{pmatrix} 17 & 3 & 9 \\ -9 & 2 & 4 \\ \frac{1}{2} & -7 & 1 \end{pmatrix}}_{\vec{A}} \underbrace{\begin{pmatrix} x \\ y \\ z \end{pmatrix}}_{\vec{x}} = \underbrace{\begin{pmatrix} -2 \\ 9 \\ 1 \end{pmatrix}}_{\vec{b}}$$

$N=3$ eqns, 3 unk.
straightforward,
but the algebra
gets tedious
as N grows

How to make this easier to solve?

* Convert this system to be an upper-triangular matrix by Gaussian elimination, which can then be solved by substitution *

→ this is what you do when you solve sets of equations by hand by substitution!

$$\underbrace{A^{(n-1)}}_{\text{upper triangular}} x = \underbrace{b^{(n-1)}}_{\text{transformed RHS}}$$

$$\begin{pmatrix} A_{11}^{(n-1)} & \cdots & A_{1n}^{(n-1)} \\ \vdots & \ddots & \vdots \\ \text{\textcircled{0}} & \cdots & A_{nn} \end{pmatrix} \begin{pmatrix} x_1 \\ \vdots \\ x_N \end{pmatrix} = \begin{pmatrix} b_1^{(n-1)} \\ \vdots \\ b_N^{(n-1)} \end{pmatrix}$$

solve the last row:
(N^{th} row)

$$x_n = b_N / A_{nn}$$

[note: dropped (n)
superscripts for clarity
in this slide]

then the $N-1^{\text{st}}$ row:

$$A_{N-1, N-1} x_{N-1} + A_{N, N-1} x_N = b_{N-1}$$

$$\text{so, } x_{N-1} = \frac{b_{N-1} - A_{N, N-1} x_N}{A_{N-1, N-1}}$$

etc.

with the general form

$$x_i = \frac{1}{A_{i,i}^{(n-1)}} \left[b_i - \sum_{j=i+1}^N A_{ij} x_j \right]$$

for $i = N-1, N-2, \dots, 1$