

# "Linear regression" (or Just Least Squares...)

①

Let

$$x_i \in \mathbb{R}^n, \quad i = 1, \dots, m$$

$$y_i \in \mathbb{R}, \quad i = 1, \dots, m$$

$$\bar{X} := \begin{pmatrix} - & x_1 & - \\ & \vdots & \\ - & x_m & - \end{pmatrix} \in \mathbb{R}^{m \times n}, \quad y = \begin{pmatrix} y_1 \\ \vdots \\ y_m \end{pmatrix} \in \mathbb{R}^m$$

Want to solve

$$\bar{X} \hat{w} = y \quad (*)$$

Case I  $m < n$ .

- $\bar{X}$  is fat
- few eqns, many unknowns
- $N(\bar{X}) \neq \{0\}$

Observe we to see this, what if  $\bar{X} = e_i^T$ .

To make life easier, assume for now that  $\text{rank}(\bar{X}) = m$ . Then  $\dim \text{col } \bar{X} = m$ .  
So  $\bar{X}$  is surjective &  $y \in \text{col } \bar{X}$ . Since  $N(\bar{X}) \neq \{0\}$ ,  $\exists$  many solutions to (\*).

~~Also  $\dim \text{col } \bar{X} = \dim \text{row } \bar{X}$  follows from rank-nullity. By construction, we have  $m$  lin. indep. rows.~~

How can we narrow down Solns?  
Options:

- Pick  $\hat{w}$  w/ small  $\|\hat{w}\|_2$ 
  - ↳ gives w/ notion of regularization & "low complexity" solution
  - ↳ also, can work w/  $\|\hat{w}\|_2^2$ , and use properties of Hilbert spaces, which should make analysis really simple.
- pick "Sparsiest"  $w$ . Small  $\|\hat{w}\|_0$  norm.  $\hookrightarrow$  compressed sensing. Reconstruct sometimes.

(2)

We will go w/ option 1 for now.

If  $\hat{w}, w$  both solve (\*), then  $\hat{w} - w \in N(X)$ .

If  $\hat{w}$  lies in the row space of  $X$ , then  $\hat{w} \perp (\hat{w} - w)$ ,

Since  $\text{row}(X) \perp N(X)$ . <sup>Suppose  $w \neq \hat{w}$</sup>  In that case,

$$\begin{aligned}\|\hat{w}\|^2 &= \langle w + (\hat{w} - w), w + (\hat{w} - w) \rangle \\ &= \|w\|^2 + \underbrace{\|\hat{w} - w\|^2}_{>0} > \|w\|^2.\end{aligned}$$

Hence, If  $\exists$  a soln in the row space, it has minimum norm and is unique.

To find such a solution, we need a map that brings  $\text{col } X$  back to  $\text{row } X$ . In general,  $X$  is bijective from  $\text{row } X$  to  $\text{col } X$  & the pseudo inverse provides the reverse mapping. For now, we'll cheat a little rather than use the general pseudo inverse.

claim

$$\text{rank } X = \text{rank } X^T X = \text{rank } X X^T$$

pf

1. claim  $\text{rank } X = \text{rank } X^T$ . don't want to show.
2. Use rank-nullity. (i.e. show  $X$  &  $X^T X$  have same nullspace.)
  - Suppose  $Xw = 0$ . Then  $X^T Xw = 0$ . So,  $N(X) \subset N(X^T X)$ .
  - Suppose  $X^T Xw = 0$ . Then  $w^T X^T Xw = 0 \Rightarrow |Xw|^2 = 0 \Rightarrow Xw = 0 \Rightarrow N(X^T X) \subset N(X)$ .

Claim follows by rank-nullity.

$$\mathbf{X} : m \times n$$

(3)

Since we assumed  $\text{rank } \mathbf{X} = m$  ( $\mathbf{X}$  fat, linearly ind. rows), we get  $\text{rank } \mathbf{X} \mathbf{X}^T = m \Leftrightarrow (\mathbf{X} \mathbf{X}^T)^{-1}$  exists.

want to solve

$$\mathbf{X} \hat{\mathbf{w}} = \mathbf{y}$$

Anything we can set  $\hat{\mathbf{w}}$  to to make this work?

$$\text{let } \hat{\mathbf{w}} = \mathbf{X}^T (\mathbf{X} \mathbf{X}^T)^{-1} \mathbf{y}$$

$$\mathbf{X} \hat{\mathbf{w}} = \mathbf{X} \mathbf{X}^T (\mathbf{X} \mathbf{X}^T)^{-1} \mathbf{y} = \mathbf{y}.$$

Note that  $\hat{\mathbf{w}} = \underbrace{\mathbf{X}^T (\mathbf{X} \mathbf{X}^T)^{-1}}_{=: \mathbf{Z}} \mathbf{y}$ . This means  $\hat{\mathbf{w}} \in \text{row}(\mathbf{X}^T)$ .

Hence,  $\hat{\mathbf{w}}$  is our Unique Soln.

Note:

- $\mathbf{X}^+ := \mathbf{X}^T (\mathbf{X} \mathbf{X}^T)^{-1}$  is pseudo-inverse when rows are lin. indep.
- If  $\mathbf{X}$  were rank deficient, what would it mean? Most importantly,  $\dim \text{col } \mathbf{X} < m$ . (Since  $\dim \text{row } \mathbf{X} = \dim \text{col } \mathbf{X} = \text{rank } \mathbf{X}$ )  
 $\Rightarrow \mathbf{X} \mathbf{X}^T$  is not invertible.
- Analysis would go through if we restricted to  $\mathbf{y} \in \text{col}(\mathbf{X})$  and had a more general pseudo-inv. taking  $\text{col } \mathbf{X}$  back to  $\text{row } \mathbf{X}$ .

Case II:  $m = n$

• don't care right now since we're looking at full row/col rank matrices to isolate effects of each asymmetry.  
Separately, first. why?

Case III  $m > n$

- $X$  is tall
- ~~linearly indep. cols~~
- $\dim \text{col } X \leq n < m$ 
  - ↳ so,  $X$  not surjective
- What about  $N(X)$ ?
  - ↳ may or may not be empty
- If we assume  $\text{rank } X = n$ , then
  - $X$  has lin indep cols
  - $\dim \text{col } X = n$
  - $N(X) = \{0\}$ 
    - ↳ rank-nullity:

$$\text{rank-nullity:}$$
$$A \in \mathbb{R}^{m \times n}$$

$$\text{rank } A + \dim N(A) = n$$
$$(\begin{smallmatrix} \text{rank } A \\ = \dim \text{col } A \\ = \dim \text{row } A \end{smallmatrix})$$

Assume  $\text{rank } X = n$

• Says you:  $N(X) = \{0\}$ .

Suppose  $\hat{y} \in \text{col } X$ . claim:  $\exists$  a unique  $\hat{w}$  solves  $X\hat{w} = \hat{y}$  (\*\*)

pf  $\text{rank } X^T X = n \Rightarrow (X^T X)^{-1}$  exists. Also, since  $\hat{y} \in \text{col } X$ , a  $\hat{w}$  solves (\*\*)  $\exists$ . observe

$$X\hat{w} = \hat{y} \Leftrightarrow (X^T X)^{-1} X^T X \hat{w} = (X^T X)^{-1} X^T y$$
$$\Leftrightarrow \hat{w} = (X^T X)^{-1} X^T y$$

(5)

Also,  $(X^T X)^+ X^T$  has nullspace =  $\{0\}$ .

↳ why? TODO.

This proves claim.

II

Suppose if possible, outside  $\text{col } X$ , want  $\hat{w}$  s.t.

$$\hat{w} \in \arg\min_w \|Xw - y\|_2$$

But we're in a Hilbert space, so solution to this is just projection.

$$\text{i.e., } \|\hat{y} - y\|_2^2 \leq \|y' - y\|_2^2 \quad \forall y' \in \text{col } X$$

for  $\hat{y} \in \text{col } X$  if  $\hat{y}$  is the unique vector such that

$$(\hat{y} - y) \perp \text{col } X.$$

ToDo: Formally, recall Hilbert proj theorem.

Hence, the optimal  $\hat{w}$  satisfies

$$(X\hat{w} - y) \perp \text{each col of } X$$

$$\Downarrow$$

$$(X\hat{w} - y)^T X = \vec{0}$$

$$\Leftrightarrow \hat{w}^T X^T X = y^T X \quad \Leftrightarrow \quad \boxed{X^T X \hat{w} = X^T y.}$$

know  $(X^T X)^+$  exists.

$$\hat{w} = (X^T X)^+ X^T y$$

Observations

- $\bar{X}^+ := (\bar{X}^T \bar{X})^+ \bar{X}^T$  is pseudo-inv. when cols are lin ind-p.
- If  $\bar{X}$  were rank deficient, what would it mean?  $N(\bar{X}) \neq 0$ . So, many  $\hat{w}$  satisfy  $\bar{X} \hat{w} = \hat{y}$  where  $\hat{y} = \text{Proj}_{\text{col}(\bar{X})}(y)$ . So, many least squares solns. Which to pick?

Computational

consideration:

Have to invert  $(\bar{X}^T \bar{X}) \in \mathbb{R}^{n \times n}$ .

What if  $n$  (dim of feature space) is big?

Can solve optimization problem directly.

$$\min_w \underbrace{\|\bar{X}w - y\|^2}_{=: J(w)}$$

$$\nabla J(w) = (\bar{X}w - y)^T \bar{X}$$

double check. can confirm by computing  $\frac{\partial J}{\partial w_i}$  and seeing that this is  $i$ -th component of  $(\bar{X}w - y)^T \bar{X}$ .

Use GD:

$$w_{t+1} = w_t - (\bar{X}w_t - y)^T \bar{X}$$

omissions / take on faith so far

- GD:  $O(mn)$  flops per iteration
- Normal eq. / pseudo-inverse:  $\approx O(n^3)$
- If  $m \ll n$ , GD seems probably better.

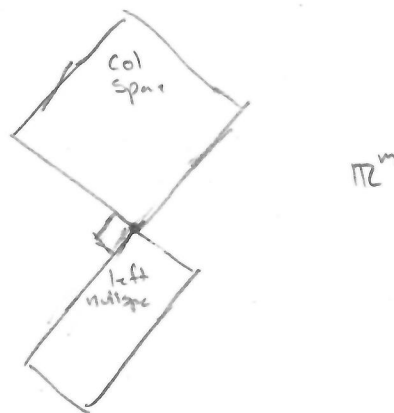
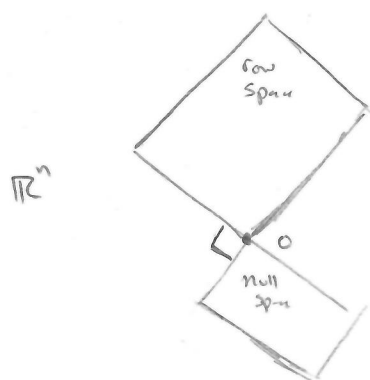
- rank  $A = \text{rank } A^T$
- rank-nullity thm
- Hilbert proj. thm.
- form of  $\nabla J$

# SVD

⑦

Diagonalization makes life incredibly easy, when possible. Life is particularly easy, when eigenvectors are orthogonal. The SVD provides a <sup>an orthonormal</sup> diagonal decomposition for arbitrary (non-square) matrices. The catch: The basis vectors used for domain / range can be different. So, SVD not necessarily suitable for applications w/ powers of matrices. Since you don't get  $A^2 = S \Lambda S^T S \Lambda S^T = S \Lambda^2 S^T$ . But useful when this doesn't matter.

$$A \in \mathbb{R}^{m \times n}$$



Let  $r = \text{rank } A$

We want an orthonormal basis  $v_1, \dots, v_r$  &  $u_1, \dots, u_r$  for col space s.t.

$$A v_i = \sigma_i u_i$$

What's a good candidate for  $(v_i)_{i=1}^r$ ? How about eigenvectors of

$$\underbrace{A^T A \in \mathbb{R}^{n \times n}}_{\text{basis for row space}} \quad A A^T \in \mathbb{R}^{m \times m}$$

Note:  $A^T A$  &  $A A^T$  are positive semi-def. why?

$$\text{Lb/c } x^T A^T A x = \|A x\|^2 \geq 0 \quad \forall x.$$

$$\text{Have, } A^T A v_i = \sigma_i^2 v_i \Rightarrow v_i^T A^T A v_i = \sigma_i^2 v_i^T v_i \Rightarrow \|A v_i\| = \sigma_i$$

$$\text{Let } u_i = A v_i$$

Let  $\hat{u}_i = Av_i$ . Lets see what happens.

Have

$$A^T Av_i = \sigma_i^2 v_i \Leftrightarrow A A^T Av_i = \sigma_i^2 Av_i$$

$\Leftrightarrow A A^T \hat{u}_i = \sigma_i^2 \hat{u}_i$  so,  $u_i := \frac{1}{\sigma_i} Av_i$  is a unit eigenvector of  $A A^T$

Have

- $(u_i)_{i=1}^r$  <sup>orthonormal</sup> basis for col space
- $(v_i)_{i=1}^r$  <sup>orthonormal</sup> basis for row space

•  $Av_i = \sigma_i u_i$

•  $\sigma_i > 0$ ,  $\sigma_i = \sqrt{\lambda_i}$ , where  $\lambda_i \in \sigma(A^T A) \setminus \{0\}$

Complete each basis w/ orthonormal basis for nullspace / left nullspace to get  $(v_1, \dots, v_r, \dots, v_n)$ ,  $\dots$ ,  $(u_1, \dots, u_r, \dots, u_m)$

- $V$  is  $n \times n$  matrix w/ cols  $(v_i)$
- $U$  is  $m \times m$  w/ cols  $(u_i)$
- $\Sigma$  is  $\begin{pmatrix} \sigma_1 & & \\ & \ddots & \\ & & \sigma_r \end{pmatrix}$  w/ diagonal entries  $\sigma_i$   
 $\hat{\Sigma} \begin{matrix} n \times n \\ = \dim A \end{matrix}$  see  $\searrow$

$Av_i = \sigma_i u_i \Leftrightarrow$

$AV = U\Sigma \Leftrightarrow \boxed{A = \underbrace{U\Sigma V^T}_{SVD}}$



## Pseudo-inverse

We know  $A$  is an injective map from row space to col. space.

Want to construct an inverse that will bring any  $y \in \text{col}(A)$  back to unique  $x$  s.t.  $Ax = y$ . This is what pseudo-inv. does.

This all becomes easy if we can map  $\sigma_i u_i$  back to  $v_i$ .

i.e., want  $A^+$  s.t.

$$A^+(\sigma_i u_i) = v_i$$

$$\Downarrow$$

$$A^+ u_i = \frac{1}{\sigma_i} v_i$$

$$\Downarrow$$

$$A^+ u = V \Sigma^+, \text{ where } \Sigma^+ \text{ is same as } \Sigma \text{ but w/}$$

$1/\sigma_i$  on diag, where  $\sigma_i \neq 0$

holds by def.

of  $\sigma_i$ , since cols

defined upto  $i = \text{rank}(A)$

$$\Downarrow$$

$$\boxed{A^+ := V \Sigma^+ U^T}$$

As a sanity check, say  $Ax = y$  w/  $x \in \text{row}(A)$ ,  $x = \sum_{i=1}^r \alpha_i v_i$ .

$$y = \sum_{i=1}^r \alpha_i \sigma_i u_i \Rightarrow A^+ y = \sum_{i=1}^r \alpha_i A^+ \sigma_i u_i = \sum_{i=1}^r \alpha_i v_i = x.$$

So,

$$\bullet A^+ A x = x, \text{ for } x \in \text{row}(A).$$

other implications:

more generally,

• If  $x \in \mathbb{R}^n$ ,  $A^T A x = \text{proj}_{\text{row}(A)}(x)$

• If  $y \in \mathbb{R}^m$ ,  $A^T y = A^T (\hat{y} + z)$  for  $\hat{y} = \text{proj}_{\text{col}(A)}(y)$ ,

and any  $z \in N(A^T)$ . Continuing,

$$A^T y = \hat{x}$$

$$A \hat{x} = \hat{y}$$

where  $\hat{x}$  is unique element of  $\text{row}(A)$  solving  $A \hat{x} = \hat{y}$ ,  
w/  $\hat{y} = \text{proj}_{\text{col}(A)}(y)$ .

