

Basics of Covariance

①

Suppose X is a RV w/ prob mass p (will skip the formula of this for now.)

Def

$$EX := \int_{\Omega} x(\omega) dP(\omega)$$

Def Given RVs X & Y with finite first moment,

$$\text{Cov}(X, Y) := E[(X - EX)(Y - EY)]$$

Def (Correlation coeff)

$$\rho := \frac{\text{Cov}(X, Y)}{\sigma_X \sigma_Y}$$

The set of RVs w/ $EX^2 < \infty$ is the L_2 space over functions from

$\Omega \rightarrow \mathbb{R}$. ~~$\text{Cov}(X, Y)$ is a valid inner product on the space. The cosine of the angle θ between X and Y .~~ For U, V in the space

$$\langle U, V \rangle := EUV$$

is a valid inner product. The cosine of the angle θ between U, V ^{$\frac{\|U\|_2 \|V\|_2}{\|U\|_2 \|V\|_2} = 1$} is given by

$$\cos \theta = \frac{\langle U, V \rangle}{\|U\|_2 \|V\|_2}$$

If we let $U = X - EX$, $V = Y - EY$ ($EX, EY < \infty$ if $X, Y \in L_2$ by monotonicity of L_p on probability spaces), then $\text{Cov}(X, Y) = \langle U, V \rangle$ and the corr coeff is given by

$$\rho := \frac{\text{Cov}(X, Y)}{\sigma_X \sigma_Y}$$

Note that ρ is the angle between centered versions of X & Y .

(2)

Side note: A useful formula: $\text{Var } X = E[X^2] - (E[X])^2$

Example Suppose X, Y have joint distribution

$$\mu_x = EX = x_1(a+c) + x_2(1-(a+c))$$

$$\mu_y = y_1(c+d) + y_2(1-(c+d))$$

y_2	a	b
y_1	c	d
	x_1	x_2

$$\begin{aligned} \text{Var } X &= E[X^2] - (EX)^2 \\ &= x_1^2(a+c) + x_2^2(1-(a+c)) - \mu_x^2 \end{aligned}$$

$$\text{Var } Y = y_1^2(c+d) + y_2^2(1-(c+d)) - \mu_y^2$$

$$\text{Cov}(X, Y) = E[(X - \mu_x)(Y - \mu_y)]$$

$$= a(x_1 - \mu_x)(y_2 - \mu_y)$$

$$+ b(x_2 - \mu_x)(y_2 - \mu_y)$$

$$+ c(x_1 - \mu_x)(y_1 - \mu_y)$$

$$+ d(x_2 - \mu_x)(y_1 - \mu_y)$$

Run different values of the computer. Includes $c=b=0$, & $a=d=0$.
Compute ρ .

③

Def RVs X & Y are said to be independent if $\forall x, y$,

$$P(X \leq x \text{ and } Y \leq y) = P(X \leq x)P(Y \leq y)$$

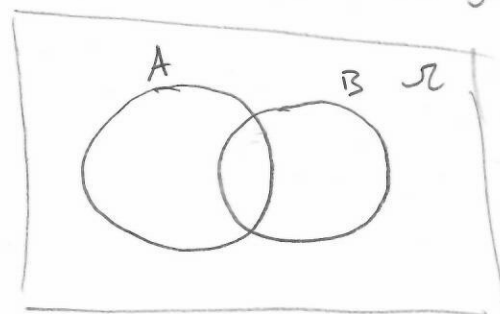
Intuition: We would like to capture the idea that knowing Y provides us no information about X . Bayes theorem tells us

$$P(\underbrace{X \leq x}_A, \underbrace{Y \leq y}_B) = P(A \cap B) = P(A|B)P(B)$$

events A B

If $P(A|B) = P(A)$ then we get $P(A \cap B) = P(A)P(B)$

Also, regarding Bayes theorem, note that the intuition for this just comes down to measuring the size of sets.



Right, If event B has occurred, then when we condition on B , we restrict things so B is our universe,

so $P(\cdot|B)$ is a probability measure &

$P(B|B) = 1$. If we have $P(A|B)$,

then we get back to normal scaling by multiplying by $P(B)$.



This can be explained better, but it's the gist. You can make this intuition clear & precise w/ a single example like this. The intuition generates, but it must really formalize using the standard def of indep.

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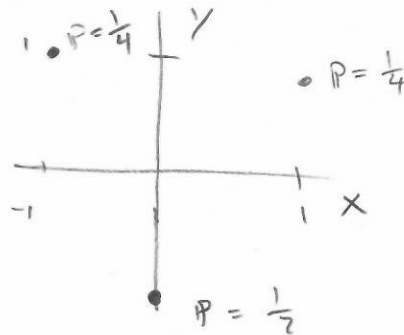
Ex Let $X \sim U(-1, 1)$, $Y = X^2$

Verify: $\text{Cor}(X, Y) = 0$

But clearly, $P(Y \leq y) \neq P(Y \leq y | X \leq x)$ Since $X \leq x \Rightarrow Y \leq x^2$

ToDo: Show visually on computer

Ex Let X, Y have joint distribution



Ex Let X & Y have ^{uniform} joint distribution with support where all corners are equidistant from 0.

