

## Welcome to SENG 480B / CSC 485B / CSC 586B Self-Adaptive and Self-Managing Systems

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University of Victoria

<http://courses.seng.uvic.ca/courses/2013/summer/seng/480b>  
<http://courses.seng.uvic.ca/courses/2013/summer/csc/485b>  
<http://courses.seng.uvic.ca/courses/2013/summer/csc/586b>



## Announcements

- Marking
  - A2 graded
  - Midterm graded
  - A3 being graded
  - Marks are posted on website
- Group presentations of A3
  - Excellent
  - One more today
- A4
  - posted
  - Due Thu, Aug 1
- Grad student presentations
  - July 23 – July 31
- Teaching Eval
- Review for final exam
  - Wed, Aug 7
- Last day of classes
  - Wed, Aug 7
- Final exam
  - Tue, Aug 13, 9:00-12:00 am in ECS 124
  - Closed books, closed notes
  - Materials: entire course
  - Format: like midterm

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## A2 Marking Guide

### Part I (50 marks)

- Describe managed resource and describe its properties in detail: model, sensors, effectors. (10 marks)
- Define policy for managing the resource (5 marks)
- Defines events which are exchanged across the manageability interface. (5 marks)
- Design AM: all four stages. (20 marks)
- Identify information to be store in knowledge base. (5 marks)
- Describe the type of feedback that is used in the system: positive, negative, bipolar. (5 marks)

### Part II (50 marks)

In Part II you are to implement an autonomic element consisting of the managed resource of your choice and an autonomic manager governed by a policy.

- Implement the managed resource you have chosen. (5 marks)
- Implement an autonomic manager to manage the resource. Code the four phases of the MAPE-K loop and the knowledge as separate components. Make sure that the documents exchanged among the components are well defined. (20 marks)
- Implement a manageability interface to close the feedback loop between the managed resource and the autonomic manager. (5 marks)
- Make the autonomic manager policy driven. (5 marks)
- Demonstrate that your implementation is compliant with respect to the your chosen policy. (5 marks)
- Document the design and implementation of your project. (10 marks)

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## Graduate Student Research Paper Presentations

- Garlan, D., Cheng, S.-W., Huang, A.-C., Schmerl, B., Steenkiste, P.: Rainbow: Architecture-Based Self-Adaptation with Reusable Infrastructure. *IEEE Computer* 37(10):46-54 (2004) — **Angela Rook, July 23**
- Kramer, J., Magee, J.: Self-Managed Systems: An Architectural Challenge. In: *ACM/IEEE International Conference on Software Engineering 2007 Future of Software Engineering (ICSE)*, pp. 259-268 (2007) — **Pratik Jain, July 23**
- Oreizy, P., Medvidovic, N., Taylor, R.N.: Runtime Software Adaptation: Framework, Approaches, and Styles. In: *ACM/IEEE International Conference on Software Engineering (ICSE 2008)*, pp. 899-910 (2008) — **Alessia Knauss, July 24**
- Brun, Y., Di Marzo Serugendo, G., Gacek, C., Giese, H., Kienle, H.M., Litoiu, M., Müller, H.M., Pezzè, M., Shaw, M.: *Engineering Self-Adaptive Systems through Feedback Loops*. SE for Self-Adaptive Systems, pp. 48-70 (2009) — **Samra Ramandeep, July 24**
- Kaushik, R.T., Cherkasova, L., Campbell, R.H., Nahrstedt, K.: Lightning: self-adaptive, energy-conserving, multi-zoned, commodity green cloud storage system, *ACM International Symposium on High Performance Distributed Computing (HPDC 2010)*, 332-335 (2010) — **Andi Bergen, July 26**

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## Graduate Student Research Paper Presentations

- Villegas, N.M., Müller, H.A., Tamura, G., Duchien, L., Casallas, R.: A framework for evaluating quality-driven self-adaptive software systems. In: *Proc. 6th Int. Symposium on Software Engineering for Adaptive and Self-Managing Systems (SEAMS 2011)*, pp. 80-89 (2011) — **Lorena Castaneda, July 30**
- Ebrahimi, S., Villegas, N.M., Müller, H.A., Thomo, A.: SmarterDeals: a context-aware deal recommendation system based on the SmarterContext engine. *CASCON 2012*: 116-130 (2012) — **Nina Taherimakhosousi, July 30**
- McKinley, P.K., Sadjati, M., Kasten, E.P., Cheng, B.H.C.: Composing Adaptive Software. *IEEE Computer* 37(7):56-64 (2004) — **Carlos Gomez, July 31**
- Tewari, V., Milenkovic, M.: Standards for Autonomic Computing, *Intel Technology Journal*, 10(4):275-284 (2006) — **Nitin Goyal, July 31**

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## Guidelines for Grad Presentations

- Format of presentation
  - Presentation 15-20 mins
  - Q&A 5 mins
  - Practice talk (!)
- Slides
  - High quality
  - Submit slides 2 days before presentation to instructor for approval
  - Submit final slides 1 day after presentation for posting on website
- Talk outline
  - Motivation
  - Problem
  - Approach
  - Relation to what we heard in the course so far
  - Contributions of the paper

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## MIDTERM DISCUSSION FINAL EXAM — PREREVIEW

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Self-Adaptive and Self-Managing Systems

### Midterm Test

This test contains four questions worth a total of 100 points. Each question is worth 25 marks. This is a 50 minutes, closed books, closed notes, no calculators, no phones, and no gadgets test. Answer all questions in examination booklets.

1. ULS Systems
  - a) What are the main characteristics of Ultra Large Scale (ULS) systems? [15]
  - b) Explain in detail why the web is qualifies as a ULS system [10].
2. Autonomic Systems
  - a) Define and describe the notion of an autonomic manager [15]
  - b) Describe the purpose of each component in the MAPE-K loop in detail [10].
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4. Self-Adaptive Systems
  - a) Define and describe the notion of a self-adaptive system [10].
  - b) What kind of information must be monitored and collected to make adaptation decisions at runtime? [15].

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## Characteristics of ULS Systems

- Ultra-large size in terms of
  - Lines of code
  - Amount of data stored, accessed, manipulated, and refined
  - Number of connections and interdependencies
  - Number of hardware elements
  - Number of computational elements
  - Number of system purposes and user perception of these purposes
  - Number of routine processes, interactions, and "emergent behaviours"
  - Number of (overlapping) policy domains and enforceable mechanisms
  - Number of people involved in some way
  - .....

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## What is an ULS System

- A ULS System has unprecedented scale in some of these dimensions
  - Lines of code
  - Amount of data stored, accessed, manipulated, and refined
  - Number of connections and interdependencies
  - Number of hardware elements
  - Number of computational elements
  - Number of system purposes and user perception of these purposes
  - Number of routine processes, interactions, and "emergent behaviours"
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**ULS systems will be interdependent webs of software-intensive systems, people, policies, cultures, and economics.**

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## Scale Changes Everything

- Characteristics of ULS systems arise because of their scale
  - Decentralization
  - Inherently conflicting, unknowable, and diverse requirements
  - Continuous evolution and deployment
  - Heterogeneous, inconsistent, and changing elements
  - Erosion of the people/system boundary
  - Normal failures
  - New paradigms for acquisition and policy

**These characteristics may appear in today's systems, but in ULS systems they dominate. These characteristics undermine the assumptions that underlie today's software engineering approaches.**

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## From Systems of Systems to Ecosystems

- A ULS system comprises a dynamic community of interdependent and competing organisms in a complex and changing environment
- The concept of an ecosystem connotes complexity, decentralized control, hard-to-predict reactions to disruptions, difficulty of monitoring and assessment

**In many ways, legacy systems are already participating in socio-technical ecosystems**

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## Decentralized Ecosystems

- For 40 years we have embraced the traditional centralized engineering perspective for building software
  - Central control, top-down, tradeoff analysis
- Beyond a certain complexity threshold, traditional centralized engineering perspective is no longer sufficient and cannot be the primary means by which ultra-complex systems are made real
  - Firms are engineered—but the structure of the **economy** is not
  - The protocols of the **Internet** were engineered—but not the **Web** as a whole
- Ecosystems** exhibit high degrees of complexity and organization—but not necessarily through engineering



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## ULS Systems Solve Wicked Problems

- Wicked problem**  
An ill-defined design and planning problem having incomplete, contradictory, and changing requirements.
- Solutions to wicked problems are often difficult to recognize because of complex interdependencies.
- This term was suggested by H. Rittel & M. Webber in "Dilemmas in a General Theory of Planning," *Policy Sciences* 4, Elsevier (1973)

- Wicked problems are problems that are not amenable to *analytic, reductionist analysis*.



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## Characteristics of Wicked Problems

- You don't understand the problem until you have developed a solution
  - There is no definitive formulation of the problem.
  - The problem is ill-structured
  - An evolving set of interlocking issues and constraints
- There is no stopping rule
  - There is also no definitive Solution
  - The problem solving process ends when you run out of resources
- Every wicked problem is essentially unique and novel
  - There are so many factors and conditions, all embedded in a dynamic social context, that no two wicked problems are alike
  - No immediate or ultimate test of a solution
  - Solutions to them will always be custom designed and fitted
- Solutions are not right or wrong
  - Simply better, worse, good enough, or not good enough.
  - Solutions are not true-or-false, but good-or-bad.
- Every solution to a wicked problem is a one-shot operation.
  - You can't learn about the problem without trying solutions.
  - Every implemented solution has consequences.
  - Every solution you try is expensive and has lasting unintended consequences (e.g., spawn new wicked problems).
- Wicked problems have no given alternative solutions
  - May be no feasible solutions
  - May be a set of potential solutions that is devised, and another set that is never even thought of.



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Spring 2013

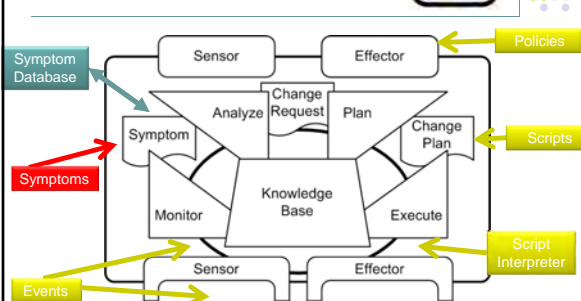
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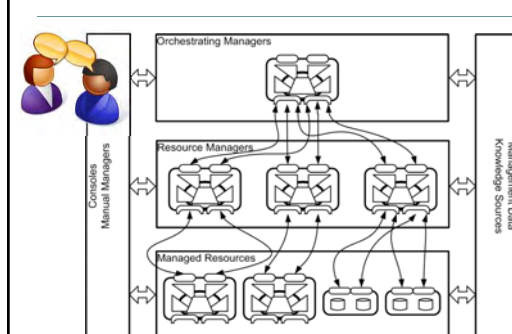
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## MAPE-K Loop Standards & Interfaces



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## ACRA AC Reference Architecture



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## MAPE-K Loop Monitor

### Analyzer

- Senses the managed process and its context
- Collects data from the managed resource
- Provides mechanisms to aggregate and filter incoming data stream
- Stores relevant and critical data in the knowledge base or repository for future reference.
- Compares event data against patterns in the knowledge base to diagnose symptoms and stores the symptoms
- Correlates incoming data with historical data and policies stored in repository
- Analyzes symptoms
- Predicts problems

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## MAPE-K Loop Planner

### Execute Engine

- Interprets the symptoms and devises a plan
- Decides on a plan of action
- Constructs actions
  - building scripts
- Implements policies
- Often performed manually
- Executes the change in the managed process through the effectors
- Perform the execution plan
- Often performed manually

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## MAPE-K Loop Knowledge Base



- The four components of a MAPE-K loop work together by exchanging knowledge through the **knowledge base** to achieve the control objective.
- An autonomic manager
  - maintains its own knowledge
    - Information about its current state as well as past states
  - But also has access to knowledge which is shared among collaborating autonomic managers
    - Configuration database, symptoms database, business rules, provisioning policies, or problem determination expertise

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## Symptoms

- A *symptom* is a form of knowledge that indicates a possible problem or situation in the managed environment.
  - For example, "high fever" might be defined as a temperature "greater than 39 degrees Celsius"
  - The symptom is defined by the expression "temperature greater than 39 degrees Celsius" and described as "high fever"
- Symptoms are
  - Recognized in the monitor component of the MAPE-K loop
  - Used as a basis for analysis of a problem or a goal
  - Based on predefined elements—for example, definitions and descriptions in a symptoms DB
- Symptom definition
  - Expresses conditions used by the monitor to recognize the existence of a symptom
  - Specifies the unique characteristics of a particular symptom that is recognized.
- Symptoms are not just for self-healing
  - Symptoms are connected to self-healing because their primary intent is to indicate a problem
  - Symptoms can also be used as triggers for other kinds of problems
  - Virtually all kinds of problems or predictions may start due to the occurrence of a symptom

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IBM: Symptoms Reference Specification Version 2.0 2006

## Symptom Artifacts

- **Symptom element**
  - Contains all information necessary to create a new symptom occurrence
- **Symptom occurrence**
  - Contains the run-time information associated with a specific instance of a symptom element
  - Each occurrence basically refers to the same symptom as it is defined in the symptom element, but the context to which it is applied may vary.
- **Correlation engine**
  - Contains the logic used to create symptom elements
  - As input the correlation engine receives external stimuli and checks if a symptom occurrence should be created as a response.

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IBM: Symptoms Reference Specification Version 2.0 2006

## Symptom Artifacts

- **Symptom metadata**
  - The generic part of the information that composes a symptom
  - It is present on all kinds of knowledge, and is used when knowledge must be treated generically, even though it is a symptom element
  - This is the "what" part of a symptom
- **Symptom schema**
  - The specific part of the information that composes a symptom
  - It is the template that is used when a symptom occurrence is created
  - The symptom schema contributes to the "what" part of a symptom
- **Symptom definition**
  - A generic piece of logic that can be used to recognize a symptom
  - As expected, this logic should be compatible with the respective correlation engine that will be used to process the symptom
  - This is the "how" part of a symptom

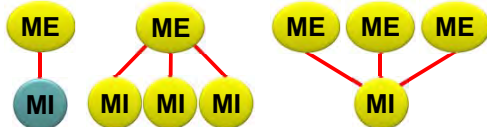
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IBM: Symptoms Reference Specification, Version 2.0, 2006

## Manageability Endpoints



- A **Manageability Endpoint (ME)** exposes the state and the management operations for a resource
- An autonomic manager communicates with a manageability endpoint through the **Manageability Interface (MI)**



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## Manageability Interface



- An MI for monitoring and controlling a managed resource consists of sensors and effectors
- **Sensors** obtain data from the resource
  - read state variables in the ME
- **Effectors** perform operations on the resource
  - call methods in the ME
- Critical success factors for AC initiative
  - **Separating AMs and MEs**
  - **Standardizing MIs**

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## Characteristics of Autonomic Systems



- Self awareness, reflexivity, identity
  - Possesses a system identity
  - Must know itself
  - Needs detailed knowledge of its components, current status interconnections with other systems and available resources to manage itself
- Able to configure and reconfigure itself under varying and unpredictable conditions
  - For example, adaptive algorithms running on each subsystem could learn the best configurations to deliver functionality in different ways to achieve mandated performance
- Continually seek to optimize its operations
  - Adaptive algorithms for monitoring and execution

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## Characteristics of Autonomic Systems



- Systems that **self-manage**
  - self-configure, self-tune, self-repair, self-protect, ...
- For a software system to be autonomic, it needs to support a range of behaviours; then
  - **Self-configuring** means choosing a suitable behaviour, based on user preferences, context, ...
  - **Self-tuning** means choosing behaviours that optimize certain qualities (performance, year-end profits, ...)
  - **Self-repairing** means shifting execution to another behaviour, given that the current one is failing
  - **Self-protecting** means choosing a behaviour that minimizes risks (attacks, viruses, ...)

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## What Do Self-Managing Systems Deliver?



### Increased Responsiveness

Adapt to dynamically changing environments

### Operational Efficiency

Tune resources and balance workloads to maximize use of IT resources



### Business Resiliency

Discover, diagnose, and act to prevent disruptions

### Secure Information and Resources

Anticipate, detect, identify, and protect against attacks

*Self - \**

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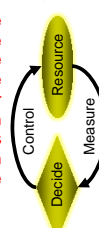
## Most Famous Feedback System Autonomic Nervous System (ANS)



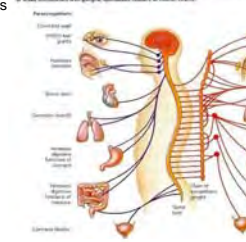
Autonomic nervous system (ANS)

- Parasympathetic
  - Day-to-day internal processes
- Sympathetic
  - Stressful situation processes

Temperature  
Heart rate  
Breathing rate  
Blood pressure  
Blood sugar  
Pupil dilation  
Tears  
Digestion  
Immune response



The Autonomic Nervous System



Monitor and Regulate

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## Interesting Architectural Note

- Architecturally the ANS seems to separate the normal day-to-day internal processes from the exceptional, stressful situation processes
  - Parasympathetic
    - Day-to-day internal processes
  - Sympathetic
    - Stressful situation processes
- Could we use this interesting architectural design decision for self-managing and self-adaptive systems?

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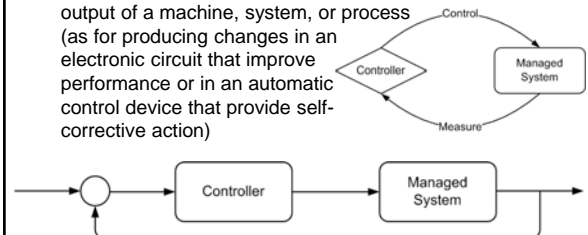
## Types of Feedback

- Negative feedback**
  - Stabilizes operation; regulates within a set and narrow range
  - Classic examples
    - Thermostat control
    - Homeostasis
- Positive feedback**
  - Increase, accelerate, or enhance output created by a stimulus that has already been activated
  - Classic example
    - Audio feedback—sound from loudspeakers enters a poorly placed microphone and gets amplified, and as a result the sound gets louder and louder
    - Blood platelet accumulation, which, in turn, causes blood clotting in response to a break or tear in the lining of blood vessels
    - Release of oxytocin to intensify the contractions that take place during childbirth
- Bipolar feedback**
  - Either increase or decrease output
  - Bipolar feedback is present in many natural and human systems
  - Feedback is usually bipolar in natural environments producing synergic and antagonistic responses to the output of system

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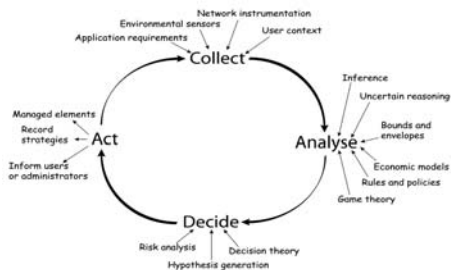
## Feedback Systems

- Merriam-Webster's Online Dictionary**  
the return to the input of a part of the output of a machine, system, or process (as for producing changes in an electronic circuit that improve performance or in an automatic control device that provide self-corrective action)



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## Autonomic Feedback Loop



Dobson, S. et al.: A Survey of Autonomic Communications. ACM Trans. on Autonomous and Adaptive Systems (TAAS) 1(2):223-259 (2006)

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## Physiological Regulation Homeostasis

- **Homeostasis** is the property of a system that regulates its internal environment and tends to maintain a stable, constant condition
- In animals the internal environment of our bodies must have certain conditions within tolerable limits to continue the healthy functioning.
- This is done by a process called negative feedback control, where various receptors and effectors bring about a reaction to ensure that such conditions remain favourable—the control of blood sugar concentrations, water concentrations, or temperature.
- Physiological homeostasis = Physical equilibrium
  - Glucose level in the bloodstream drops
  - Person requires glucose in cells to meet the demand for ATP—Adenosine triphosphate
  - The body detects this with a particular receptor designed for this function
  - These receptors release hormones, chemical messages that initiate the start of the feedback mechanism
  - The hormones travel to their target tissue and initiate a corrective response
  - In this case, the response is the secretion of more glucose into the bloodstream



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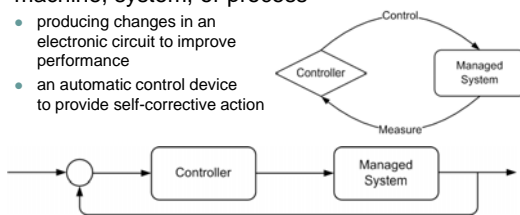
## Ice-Albedo Feedback

- Albedo
  - The amount of energy reflected by a surface; scale from zero to one
  - For dark colors albedo close to zero; light ones close to one
- Arctic sea ice is covered with snow all winter.
- Bright white, the snow-covered ice has a high albedo so it absorbs very little of the solar energy that gets to it.
- Because Earth's temperature is climbing, the snow on top of the ice melts earlier in the spring
- There is more time during the summer for the compounding cycle of melting ice, lowering albedo, trapping of more solar energy, and more ice to melt.
- Albedo feedback is positive because the initial temperature change is amplified.

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## Feedback Control System

- **Merriam-Webster's Online Dictionary** the return to the input of a part of the output of a machine, system, or process
  - producing changes in an electronic circuit to improve performance
  - an automatic control device to provide self-corrective action



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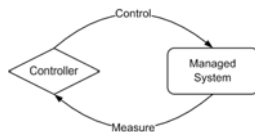
## Control Theory

- A theory that deals with influencing the behavior of dynamical systems
- An interdisciplinary subfield of science, which originated in engineering and mathematics

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## Control Systems are Ubiquitous

- Cruise control
- Fuel injection
- Flight control
- Climate Control
- Health Care
- Model Helicopters
- Rumba
- iRobots
- Radiotherapy



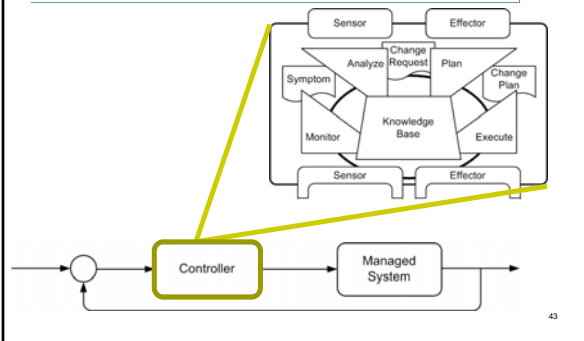
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## Control System Goals: Self-Management

- Regulation
  - Thermostat, target service levels
- Tracking
  - Robot movement
  - Adjust TCP window to network bandwidth
- Optimization
  - Best mix of chemicals
  - Minimize response times

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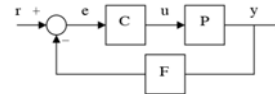
## Controller as an Autonomic Element



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## Closed Loop Controller or Feedback Controller

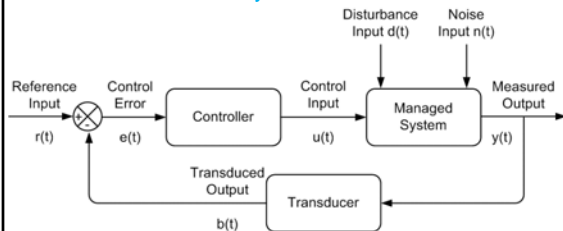
- The output  $y(t)$  of the feedback system is fed back through a sensor measurement  $F$  to the reference value  $r(t)$ .
- The controller  $C$  then takes the error  $e$  (difference) between the reference and the output to change the inputs  $u$  to the control process  $P$ .
- SISO
  - Single-input-single-output (SISO) control system
  - Variables are simple scalar values (i.e.,  $r(t)$ ,  $e(t)$ ,  $u(t)$ ,  $y(t)$ )
- MIMO
  - Multi-Input-Multi-Output systems, with more than one input/output, are common
  - Variables are vectors



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## Realization of a Dynamic Architecture

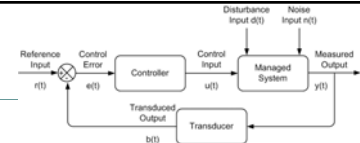
- Feedback control system with disturbance and



Hellerstein, Diao, Parekh, Tilbury: *Feedback Control of Computing Systems*. John Wiley & Sons (2004)

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## Realization of a Dynamic Architecture



- Reference input
  - Goal, objectives, specified desired output
- Control Error
  - Reference input minus transduced output
- Control Input
  - Parameters which affect behavior of the system—number of threads, CPU, memory
- Disturbance input
  - Affects control input—arrival rate

- Controller
  - Change control input to achieve reference input—design is based on a model of the managed system
- Managed system
  - Dynamical system, process, plant—often characterized by differential equations
- Measured output
  - Measurable feature of the system—response time
- Noise input
  - Affects measured output
- Transducer
  - Transforms measured output to compare with reference

## Controller Algorithm based on Managed System Model

- "All models are wrong, some models are useful."
  - generally attributed to the statistician George Box
- The design of the controller algorithm is based on a model of the managed system or process
- Approaches
  - Analytical modeling: physical and mathematical laws
  - Experimental modeling: data fitting from observed input and output
- The control algorithm changes  $u(t)$  based on the error  $e(t) = r(t) - b(t)$ 
  - Proportional—if  $e(t)$  is high, then  $u(t)$  should be high
  - Integrative—eliminates transients; sum of all previous errors
  - Derivative—anticipate the trends; rate of change of the error
  - PID—computation based on the error (proportional), the sum of all previous errors (integral) and the rate of change of the error (derivative)

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## PID Controller

- The PID algorithm is the most popular feedback controller algorithm used
- It is a robust easily understood algorithm that can provide excellent control performance despite the varied dynamic characteristics of processes
- PID algorithm consists of three basic modes:
  - Proportional mode
  - Integral mode
  - Derivative mode

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## P, PI, or PID Controller

- When utilizing the PID algorithm, it is necessary to decide which modes are to be used (P, I or D) and then specify the parameters (or settings) for each mode used.
- Generally, only three basic algorithms are used: P, PI or PID

$$u(t) = K_p e(t) + K_i \int_0^t e(t) dt + K_d \frac{de(t)}{dt}$$

proportional gain
integral gain
derivative gain

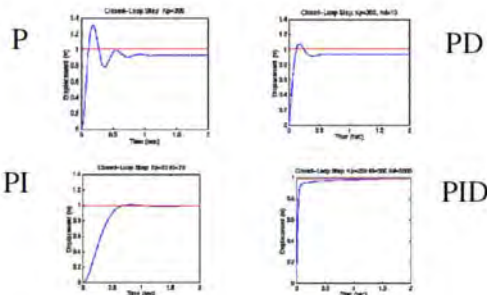
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## Controller Effects

- A proportional controller (P) reduces error responses to disturbances, but still allows a steady-state error.
- When the controller includes a term proportional to the integral of the error (I), then the steady state error to a constant input is eliminated, although typically at the cost of deterioration in the dynamic response.
- A derivative control typically makes the system better damped and more stable

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## PID Controller



## Closed-Loop Response

	Rise time	Max overshoot	Settling time	Steady-state error
P	Decrease	Increase	Small change	Decrease
I	Decrease	Increase	Increase	Eliminate
D	Small change	Decrease	Decrease	Small change

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## PID Controller

- Output feedback
  - From Proportional action
  - Compare output with set-point
- Eliminate steady-state offset or error
  - From Integral action
  - Apply constant control even when error is zero
  - Eliminates transients; sum of all previous errors
- Anticipation
  - From Derivative action
  - React to rapid rate of change before errors grows too big
  - Anticipate the trends; rate of change of the error

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Dr. H.A. Müller

SENG 480B / CSC 485C / CSC 586B  
Self-Adaptive and Self-Managing Systems

Spring 2013

### Midterm Test

This test contains four questions worth a total of 100 points. Each question is worth 25 marks. This is a 50 minutes, closed books, closed notes, no calculators, no phones, and no gadgets test. Answer all questions in examination booklets.

- ULS Systems
  - What are the main characteristics of Ultra Large Scale (ULS) systems? [15]
  - Explain in detail why the web is qualifies as a ULS system [10].
- Autonomic Systems
  - Define and describe the notion of an autonomic manager [15]
  - Describe the purpose of each component in the MAPE-K loop in detail [10].
- Feedback Systems
  - Explain the differences between positive and negative feedback [10]
  - Describe the notion of a PID controller in detail [15].
- Self-Adaptive Systems
  - Define and describe the notion of a self-adaptive system [10].
  - What kind of information must be monitored and collected to make adaptation decisions at runtime? [15].

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## Self-Adaptive Systems (SAS)

- A SAS can alter its behaviour at runtime (on the fly) in response to its perception of
  - its environment
  - its own state
 by adapting itself



- SAS abilities
  - Assess its own behaviour
  - Observe its context or environment
  - Adapt without shut down

➤ Oreizy, et al.: An Architecture-Based Approach to Self-Adaptive Software, *IEEE Intelligent Systems*, pp. 54-62 (1999)  
 ➤ MacManus: Why Software is More Important Than Sensors in the Internet of Things, *ReadWriteWeb* (2010)

## Situational Awareness (SA)

- SA is the perception of environmental and personal context with respect to time and space
- Comprehension of its meaning and its projection into the future
- Critical to decision-making in complex, dynamic situations



### Applications

- Mars Curiosity
- Aviation—UAV, drones
- Military command and control
- Emergency services

### Applications

- Driving a car
- Crossing a street
- Playing basketball
- Shopping

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Intuitively we know how critical and valuable context is.  
But context is complicated.

“Context is the new battleground between Android, iOS, Windows, Symbian and Apple, Google, IBM, Microsoft, Nokia, Samsung.”

## The Age of Context

Simple can be harder than complex. You have to work hard to get your thinking clean to make it simple.  
Steve Jobs, *BusinessWeek*, 1998

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## Context is Big Data



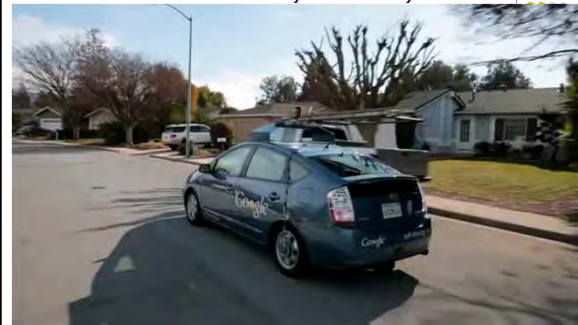
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## Capture Context with Sensors and Wearable Computers



Telepathy

## Google Driverless Car Licensed in Florida, Nevada, California


<http://www.youtube.com/watch?v=cdgQpa1pUU>

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## Monitoring in Dynamical Systems



- Perform critical regression tests dynamically to observe satisfaction of requirements
  - Testing run-time (and design-time) governance
  - Govern and enforce rules and regulations
- Perform V&V operations (transformations) regularly to ascertain V&V properties
  - Monitor compliance and conformance
  - Assess whether services are used properly
  - Recognizing normal and exceptional behaviour
- Monitor functional & non-functional requirements when the environment evolves
  - SLAs
  - Assess and maintain quality of service (QoS)
  - Manage tradeoffs

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**END MIDTERM DISCUSSION**



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