

Bikram Subedi

Naturalized Citizen

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OBJECTIVE

Seeking an internship/co-op as a software engineer using programming, design and teamwork skills.

Available June 2020 – January 2021.

EDUCATION

Rochester Institute of Technology

Bachelor of Science, Software Engineering

Rochester, NY

Aug 2017 - May 2022

SKILLS

Programming Languages: Java, Python, C, JavaScript, Ruby

Modeling Languages: ERD, Promela (Jspin), Alloy

Developer Tools: IntelliJ, RubyMine, WebStorm, Atom, Keil, Vim, PyCharm, Github

Languages: English, Nepali, Hindi

Interests: Table tennis, Chess, Soccer, Reading, Programming

Communication Tools: Slack, TrelloBoard, Discord, Zoom

PROJECTS

Web Checkers, Personal Software Engineering (SWEN 261)

Spring 2019

- Collaborated with 5 teammates, follow the general software development flow to create an online web checker game; communicated via TrelloBoard and Slack.
- Designed the UI and controller in Java and HTML/CSS, focusing on GRASP and SOLID design principles.
- Refactored code during Sprint4 to reduce multiple responsibilities of classes and enhance low coupling/high cohesion principle.

NPhalanx, Ride Requesting System (iOS and web application)

2019 – present

- Collaborating with 8 developers to build ride requesting and managing system
- Designed and implemented UI to meet the project's requirements
- Used React Native for mobile platform and Ruby on Rails for the web.

Flashing Light (STM 32 KIT Board), Engineer Fund Computer Systems

Spring 2019

- Executed basic bitwise operations (C) and learned basic serial communication on an embedded system.

Library Book Management System

Summer 2019

- Collaborated with a team of 5 to create a Library Book Management System.
- Acted as a general programmer and implemented several library management features focusing on design pattern.
- Refactored code to reduce complexity and improved quality of code.

RIT Transportation System, Computer Science II

Fall 2018

- Used idea of a graph to generate a big picture of public bus stations.
- Applied concept of BFS, DFS and Dijkstra algorithm to find the shortest path and cheapest path between two exist stops.

ACTIVITIES

FIRST Robotics Team

Rochester, NY

Member

October 2014 – June 2016

- Worked with Mentors and Engineers to build a robot.