Bahram Yaghooti

Research and Work Experience

http://alum.sharif.edu/~bahramyaghooti/

Research Projects

Control Laboratory, Sharif University of Technology

Oct. 2016 - present

- Modeling and Control of Flexible Structures
 - Finite Element Analysis of Structures Using ANSYS Workbench
 - Modal Testing
 - Validation of Finite Element Model Using Test Results
 - Design, Simulation, and Implementation of Closed Loop Control System
 - Comparison and Verification of Control System Simulation Results and Experimental Testing
- Design and Manufacture of Motion Simulator and Hardware-In-the-Loop (HIL) Test System
 - Mechanical Design and Manufacture of Servomechanism
 - Dynamic Simulation of Servomechanism Using ADAMS and Simulink
 - Design and Implementation of Closed-loop Control System Using ARM-Cortex-M3 Microcontroller
- Design and Manufacture of Vibration Analyzer and Modal Testing
 - Programming ARM-Cortex-M3 Microcontroller for Data Gathering
 - Development of a LabVIEW program for Signal Processing and Data Analysis
 - Design of a Graphical User Interface (GUI) with LabVIEW
 - Comparison of Finite Element Simulation Results and Experimental Vibration and Modal Testing

Fankavan Aral Company

Jan. 2016 - Sep. 2016

- Design and Implementation of a Distributed Control and Monitoring System for Automatic Fault Detection of Railway Vehicles
 - Design and Development of Embedded Devices for Measuring Acceleration, Temperature,
 Voltage and Current
 - Implementation of a Network for Data Gathering
 - Data Analysis and Signal Processing (used for fault pattern detections)
 - Design of a Graphical User Interface (GUI) with LabVIEW

Control Laboratory, Sharif University of Technology

May 2014 - Sep. 2015

- Developing Adaptive Fractional Order PID Controller Design Methods for Fractional Order Systems
 - Self-Tuning Regulator Design for Linear Fractional Order Systems
 - * Parameters of the system are determined by identification methods
 - * The controller gains are updated online based on pole placement method using Sequential Quadratic Programming (SQP) algorithm
 - Design of an Automatic Tuning Method of Fractional Order PID Controller for a Class of Linear Fractional Order Systems Using Model Reference Adaptive Control Techniques

- Robust Adaptive Fractional Order PID controller Design for a Class of Fractional Order Nonlinear Systems based on Sliding Mode Control Techniques
- Design of Direct Self-Tuning Fractional Order PID Control for a Class of Fractional Order Nonlinear Systems based on the Lyapunov Approach

• Design and Implementation of Controller and Converter of Standard G-Code for Hexaglide CNC

- Development of an Algorithm for Converting Standard G-Code to Hexaglide G-Code Using Inverse Kinematics
- Implementation of the Proposed Controller on Hexaglide CNC

Joint Project between Iran Khodro Company and Sharif University Dec. 2013 - Feb. 2014

- Dynamic and Stress analysis of Hitachi Double Press Machine
 - Comparison of Dynamic and Stress Analysis of a Die Press in Single and Double Action Modes Using Finite Eement Methods

Durali System Design and Automation Center

Jun. 2013 - Sep. 2013

- Wind Turbine Gearbox Detailed Design
 - Design of Gears, Bearings and Shafts
 - Design and Stress Analysis of Gearbox Casing
 - Design of the Gearbox Lubrication System

Control Laboratory, Sharif University of Technology

Jan. 2013 - Jun. 2013

- Development of Simulation Software for Global Navigation Satellite System (GLONASS)
 - Developing a Program with C++ for Simulation of GLONASS Using High Precision Orbit Propagator (HPOP) Algorithm
 - Comparison of Numerical Simulation Results and STK Software Results Using the SDP4 Algorithm.
 - Design of a Graphical User Interface (GUI) with C#

Selected Course Projects

Adaptive PID Controller Design for Nonlinear Systems Using Lyapunov Approach

Nonlinear Control, under supervision of Prof. Vossoughi

Spring 2014

Design, Manufacture, and Control of a Double Pendulum

Mechatronics Lab., Team Project, under supervision of Prof. Vossoughi

Fall 2014

- Control implementation (a DC-Motor with a gear-box attached to a disk) Using the STM32F407VG Microcontroller
- Comparison between Simulation and Experimental Results Using PID Controller

Design of Hydraulic, Pneumatic and Automation Systems

Hydraulics and Pneumatics, Team Project, under supervision of Prof. Durali Sp

Spring 2013

- Design of a Power Pack
- Design of a Compressed Air System

Developing a G-code for Three Axis CNC Machine

Production Methods, under supervision of Prof. Movahhedy

Spring 2013

Analysis of Structures Using Finite Element Method

Applied Finite Element Methods, under supervision of Prof. Naghdabadi

Spring 2013

- Modal Analysis
- Transient Analysis
- Buckling Analysis
- Contact Analysis
- Optimization Analysis

Design of Mechanical Machines Elements

Design of Machine Elements II, Team Project, under supervision of Prof. Durali Spring 2012

- Design of Belts, Chains, Drums, and Pulleys of a Power Transmission System
- Design of **Gearbox** of Power Transmission System of a Ropeway
- Design of Rear Axle of a Truck
- Design of a **Clutch**

Stress Analysis

Solid Mechanics III, under supervision of Prof. Naghdabadi

Fall 2012

 Thick-Walled Functionally Graded Cylinder Subjected to Temperature Gradient with Properties varying Exponentially along the Radius

Design of Several Heat Exchangers Using Aspen B-jac

Design of Heat Exchangers, under supervision of Prof. Afshin

Spring 2013

- Design of an Oil-Water Heat Exchanger
- Design of an Air Cooler