ENG1005: Lecture 29

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Video link

Linear differential equations - continued

Reduction of non-homogeneous ODE to a homogeneous ODE

Suppose $y_p(x)$ is a (particular) solution of the linear non-homogeneous ODE

$$\sum_{k=0}^{n} a_k(x) \frac{d^k y}{dx^k} = q(x).$$

Setting

$$y_h(x) = y(x) - y_p(x),$$

we see that

$$\sum_{k=0}^{n} a_k(x) \frac{d^k y_h}{dx^k} = \sum_{k=0}^{n} a_k(x) \frac{d^k y}{dx^k} - \sum_{k=0}^{n} a_k(x) \frac{d^k y_p}{dx^k} = 0.$$

This shows that

$$y_h(x) = y(x) - y_p(x)$$

satisfies the linear, homogeneous ODE

$$\sum_{k=0}^{n} a_k(x) \frac{d^k y}{dx^k} = 0$$

So you could find a general solution for a non-homogeneous equation as follows

$$y = y_h + y_p$$

General solutions of linear ODEs §10.8.2

Definition

Functions $y_1(x), y_2(x), ..., y_p(x)$ are said to be **linearly dependent** if there exists numbers $c_1, c_2, ..., c_p$, not all zero, such that

$$\sum_{j=1}^{p} c_j y_j(x) = 0.$$

Otherwise, the functions $y_1(x), y_2(x), ..., y_p(x)$ are said to be **linearly independent**.

Example

Determine if any of the following sets of functions are linearly independent.

- (i) $\{1, t, t^2, (1+t)^2\}$
- (ii) $\{\sin(x), \cos(x)\}$

Solution

(i) Since

$$(1+t)^2 = t^2 + 2t + 1,$$

we see that

$$1 + 2t + t^2 - (1+t)^2 = 0.$$

This shows that $\{1, t, t^2, (1+t)^2\}$ is linearly dependent.

(ii) Suppose there exists $c_1, c_2 \in \mathbb{R}$ such that

$$c_1\sin(x) + c_2\cos(x) = 0.$$

Evaluating this at x = 0 and $x = \frac{\pi}{2}$ show that

$$c_2 = 0$$
 and $c_1 = 0$.

So clearly, $\{\sin(x), \cos(x)\}$ is linearly independent.

Theorem

If $y_1(x), y_2(x), ..., y_n(x)$ are linearly independent solutions of the following nth order linear homogeneous ODE,

$$\sum_{k=1}^{n} a_k(x) \frac{d^k y}{dx^k} = 0,$$

then the general solution is given by

$$y(x) = \sum_{k=1}^{n} c_k y_k(x), \ c_k \in \mathbb{R}$$

(note this is an n-parameter family of solutions).

Moreover, if $y_p(x)$ is any solution of the non-homogeneous linear ODE

$$\sum_{k=1}^{n} a_k(x) \frac{d^k y}{dx^k} = q(y),$$

then the general solution of the non-homogeneous linear ODE

$$y(x) = \sum_{k=1}^{n} c_k y_k(x) + y_p(x)s.$$

Linear homogeneous 2nd order constant coefficients ODEs §10.9.1, 10.10

A 2nd order linear homogeneous ODE with constant coefficients is of the form

$$a\frac{d^2y}{dt^2} + b\frac{dy}{dt} + cy = 0,$$

where,

$$a, b, c \in \mathbb{R}$$
 and $a \neq 0$.

To find solutions, we try

$$y(t) = e^{\lambda t}$$
 (λ is constant).

Then,

$$a\frac{d^2y}{dt^2} + b\frac{dy}{dt} + cy = (a\lambda^2 + b\lambda + c)e^{\lambda t}.$$

We want this to equal zero. This shows that $y(t) = e^{\lambda t}$ will solve the ODE if and only if

$$a\lambda^2 + b\lambda + c = 0.$$

This is called the **characteristic equation**.

Case 1: $b^2 - 4ac > 0$

Then

$$\lambda_{\pm} = \zeta \pm \omega$$
,

where

$$\zeta = -\frac{b}{2a}$$
 and $\omega = \frac{\sqrt{|b^2 - 4ac|}}{2a}$

are the distinct real roots of the characteristic equation that yield the linearly independent solution

$$y_{\pm}(t) = e^{\lambda_{\pm}t} = e^{(\zeta \pm \omega)t}.$$

Thus the general solution is then

$$y(t) = c_1 + e^{(\zeta + \omega)t} + c_2 - e^{(\zeta - \omega)t}, \ c_1, c_2 - \in \mathbb{R}$$

Case 2: $b^2 - 4ac < 0$

Then

$$\lambda_{\pm} = \zeta \pm \omega i$$
,

are distinct complex roots of the characteristic equation that yield complex solutions

$$y_{\pm}(t) = e^{\lambda_{\pm}t} = e^{\zeta t}e^{\pm\omega ti} = e^{\zeta t}(\cos(\omega t) \pm i\sin(\omega t)).$$

These complex solutions yield the real, linearly independent solution

$$y_1(t) = e^{\zeta t} \cos(\omega t)$$
 and $y_2(t) = e^{\zeta t} \sin(\omega t)$.

Thus the general solution is given by

$$y(t) = c_1 e^{\zeta t} \cos(\omega t) + c_2 e^{\zeta t} \sin(\omega t), \ c_1, c_2 \in \mathbb{R}$$

Case 3: $b^2 - 4ac = 0$

Then

$$\lambda = \zeta$$

is the only root of the characteristic equation which yields the solution

$$y_1(t) = e^{\zeta t}$$
.

But we need 2 linearly independent solutions to form a general solutions. So, to find a second, linearly independent solution, we set

$$y_2(t) = ty_1(t) = te^{\zeta t}$$
.

Now, quickly note that the first and second derivatives are given by

$$\frac{dy_2}{dt} = y_1 + t \frac{dy_1}{dt},$$

$$\frac{d^2y_2}{dt^2} = \frac{dy_1}{dt} + \left(t \frac{d^2y_1}{dt^2} + \frac{dy_1}{dt}\right) = 2 \frac{dy_1}{dt} + t \frac{d^2y_1}{dt^2}.$$

Now, observe that

$$a\frac{d^{2}y_{2}}{dt^{2}} + b\frac{dy_{2}}{dt} + cy_{2} = a\left(2\frac{dy_{1}}{dt} + t\frac{d^{2}y_{1}}{dt^{2}}\right) + b\left(y_{1} + t\frac{dy_{1}}{dt}\right) + cty_{1}$$

$$= t\left(a\frac{d^{2}y_{1}}{dt^{2}} + b\frac{dy_{1}}{dt} + cy_{1}\right) + \left(2a\frac{dy_{1}}{dt} + by_{1}\right)$$

$$= 0t + (2a\zeta + b)e^{\zeta t}$$

$$= \left(2a\left(\frac{-b}{2a}\right) + b\right)e^{\zeta t}$$

$$= 0$$