

# ENG1005: Lecture 25

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## Video link

[https://echo360.org.au/lesson/G\\_8402119b-734b-4e1e-a3b4-7e907e86ddba\\_b944cecf-8ba5-40d3-a870-022020-05-19T15:58:00.000\\_2020-05-19T16:53:00.000/classroom#sortDirection=desc](https://echo360.org.au/lesson/G_8402119b-734b-4e1e-a3b4-7e907e86ddba_b944cecf-8ba5-40d3-a870-022020-05-19T15:58:00.000_2020-05-19T16:53:00.000/classroom#sortDirection=desc)

## Example

Estimate the change in the period

$$T = 2\pi\sqrt{\frac{L}{g}}$$

of a simple pendulum due to a 2% increase in length  $L$  and a 0.6% decrease in the gravitational acceleration  $g$ .

## Solution

$$dL = \frac{2}{100}L \text{ and } dg = \frac{-6}{1000}g$$

Substituting this into

$$\begin{aligned}
 dT &= \frac{\partial T}{\partial L} dL + \frac{\partial T}{\partial g} dg \\
 &= 2\pi \frac{1}{2\sqrt{\frac{L}{g}}} \frac{1}{g} dL + 2\pi \frac{1}{2\sqrt{\frac{L}{g}}} \left( \frac{-L}{g^2} \right) dg \\
 &= \frac{\pi}{\sqrt{Lg}} dL - \frac{\pi\sqrt{L}}{g^{\frac{3}{2}}} dg
 \end{aligned}$$

yields

$$\begin{aligned}
 dT &= \frac{\pi}{\sqrt{Lg}} \frac{2}{100} L + \frac{\pi\sqrt{L}}{g^{\frac{3}{2}}} \frac{6}{1000} g \\
 &= \frac{2\pi}{100} \sqrt{\frac{L}{g}} + \frac{6\pi}{1000} \sqrt{\frac{L}{g}} \\
 &= \frac{26\pi}{1000} \sqrt{\frac{L}{g}} \\
 &= \frac{13}{1000} T
 \end{aligned}$$

So there is a 1.3% increase in the period of a pendulum.

## Tangent plane

Given a function  $f(x, y)$ , then the curves

$$\mathbf{r}(s) = (a + s, b, f(a + s, b)); \quad \mathbf{r}(0) = (a, b, f(a, b))$$

$$\tilde{\mathbf{r}}(t) = (a, b + t, f(a, b + t)); \quad \tilde{\mathbf{r}}(0) = (a, b, f(a, b))$$

lie on the graph

$$S = \{(x, y, f(x, y)) | (x, y) \in D\} \subset \mathbb{R}^3$$

and pass through the point  $p = (a, b, f(a, b))$  at  $s = 0$  and  $t = 0$ , respectively.

$$\begin{aligned}
 \frac{d\mathbf{r}}{ds}(0) &= \frac{d}{ds}((a + s, b, f(a + s, b))) \Big|_{s=0} \\
 &= \left( 1, 0, \frac{\partial f}{\partial x}(a + s, b) \frac{d}{ds}(a + s) \right) \Big|_{s=0} \\
 &= \left( 1, 0, \frac{\partial f}{\partial x}(a, b) \right)
 \end{aligned}$$

$$\begin{aligned}
 \frac{d\tilde{\mathbf{r}}}{dt} &= \frac{d}{dt}(a, b + t, f(a, b + t)) \Big|_{t=0} \\
 &= \left( 0, 1, \frac{\partial f}{\partial y}(a, b) \right)
 \end{aligned}$$

## Tangent plane parametrisation

$$\begin{aligned}\ell &= \mathbf{p} + h \frac{d\mathbf{r}}{ds}(0) + k \frac{d\tilde{\mathbf{r}}}{dt}(0) \\ &= (a, b, f(a, b)) + h \left(1, 0, \frac{\partial f}{\partial x}(a, b)\right) + k \left(0, 1, \frac{\partial f}{\partial y}(a, b)\right) \\ \Rightarrow \ell(h, k) &= \left(a + h, b + k, f(a, b) + \frac{\partial f}{\partial x}(a, b)h + \frac{\partial f}{\partial y}(a, b)k\right)\end{aligned}$$

Setting

$$h = x - a \text{ and } k = y - b$$

gives

$$\ell(x, y) = \left(x, y, f(a, b) + \frac{\partial f}{\partial x}(a, b)(x - a) + \frac{\partial f}{\partial y}(a, b)(y - b)\right)$$

So this has now given us a **parametrisation of the tangent plane** to the graph of  $S$  of  $f(x, y)$  at the point  $(a, b, f(a, b))$ .

But note that the tangent plane is the graph of the linearisation of  $f(x, y)$ ! This makes sense really since, when we're linearising, we take the first order terms around a given point, which seems analogous to taking the first order derivative of a line in  $\mathbb{R}^2$  (which gives the tangent line).

## Maximum and minimum values §9.7.2, 9.7.3

### Definition

A function  $f(x, y)$  has a

- (i) local maximum at  $(a, b)$  if there exists some  $R > 0$  such that  $f(x, y) \leq f(a, b)$  for all  $(x, y) \in B_R((a, b))$ .
- (ii) local minimum at  $(a, b)$  if there exists some  $R > 0$  such that  $f(x, y) \geq f(a, b)$  for all  $(x, y) \in B_R((a, b))$ .
- (iii) absolute maximum at  $(a, b)$  if  $f(x, y) \leq f(a, b)$  for all  $(x, y) \in D$  (where  $D$  is the domain of  $f$ ).
- (iv) absolute minimum at  $(a, b)$  if  $f(x, y) \geq f(a, b)$  for all  $(x, y) \in D$  (where  $D$  is the domain of  $f$ ).

### Definition

A point  $(a, b) \in \mathbb{R}^2$  is called a critical (stationary) point of  $f(x, y)$  if  $\nabla f(x, y) = \mathbf{0}$  or  $\nabla f(a, b)$  is undefined. (is that meant to be  $x, y$  or  $a, b$ , not sure?)

### Theorem

If the gradient  $\nabla f(x, y)$  exists at  $(a, b)$  and  $(a, b)$  is either a local maximum or a local minimum of  $f(x, y)$  then  $\nabla f(a, b) = \mathbf{0}$ .

### Definition

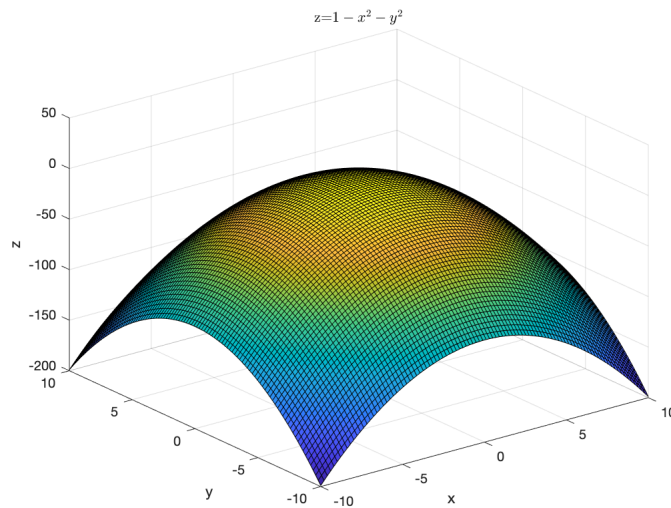
If  $(a, b)$  is a point such that  $\nabla f(a, b) = \mathbf{0}$  but  $(a, b)$  is neither a local minimum or a local maximum, then  $(a, b)$  is called a saddle point.

## Examples

(i)  $f(x, y) = 1 - x^2 - y^2$ .

$$\begin{aligned}\nabla f(x, y) &= (-2x, -2y) \\ \Rightarrow \nabla f(0, 0) &= (0, 0) \Rightarrow (0, 0) \text{ is a critical point}\end{aligned}$$

and if you look at the graph of  $f(x, y) = 1 - x^2 - y^2$ , we can see that  $f(x, y)$  has an absolute maximum at  $(0, 0)$ .



(ii)  $f(x, y) = x^2 + y^2$

$$\begin{aligned}\nabla f(x, y) &= (2x, 2y) \\ \nabla f(0, 0) &= (0, 0) \Rightarrow (0, 0) \text{ is a critical point}\end{aligned}$$

and we can similarly look at this graph to see that  $f(x, y) = x^2 + y^2$  has an absolute minimum at  $(0, 0)$ .

