

ENG1005: Lecture 20

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May 12, 2020

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Video link

[Click here for a recording of the lecture.](#)

Repeated eigenvalues §5.7.4

If A is an $n \times n$ matrix, then the characteristic polynomial of A is

$$c(\lambda) = |A - \lambda \mathbb{I}_n| = (\lambda - \lambda_1)^{m_1}(\lambda - \lambda_2)^{m_2} + \dots + (\lambda - \lambda_p)^{m_p}$$

where

- (i) the λ_i , $1 \leq i \leq p \leq n$, are the distinct roots ($\lambda_i \neq \lambda_j$ for $i \neq j$) of $c(\lambda)$ (in general, they are complex).
- (ii) and the m_i , $1 \leq i \leq p$, is the algebraic multiplicity of the root λ_i .

Remarks

- (a) If $p < n$, then A may not possess a complete set of eigenvectors.
- (b) If $m_i > 1$, then the number n_i of linearly independent eigenvectors with associated eigenvalue λ_i satisfies

$$1 \leq n_i \leq m_i$$

Parametric curves

A parametric curve in \mathbb{R}^3 (can do this in \mathbb{R}^n also) is a set of the form

$$\mathcal{C} = \{\mathbf{r}(t) | t \in (a, b)\} \quad (\text{note whether interval is open or closed doesn't matter})$$

where

$$\mathbf{r}(t) = (x(t), y(t))$$

We call $\mathbf{r}(t)$ the **parametrisation** of the curve \mathcal{C} (i.e. $\mathbf{r}(t)$ is NOT the curve).

The parametric curve \mathcal{C} is said to be continuous (differentiable) if the parametrisation $\mathbf{r}(t)$ is continuous (differentiable).

If $\mathbf{r}(t)$ is differentiable, then we define

$$\mathbf{r}'(t) = (x'(t), y'(t))$$

Examples

1. $\mathbf{r}(t) = (\cos(t), \sin(t))$, $0 \leq t \leq 2\pi$.

Let $x = \cos(t)$, $y = \sin(t)$, and then note that

$$x^2 + y^2 = 1$$

So this parametrisation clearly traces out a circle.

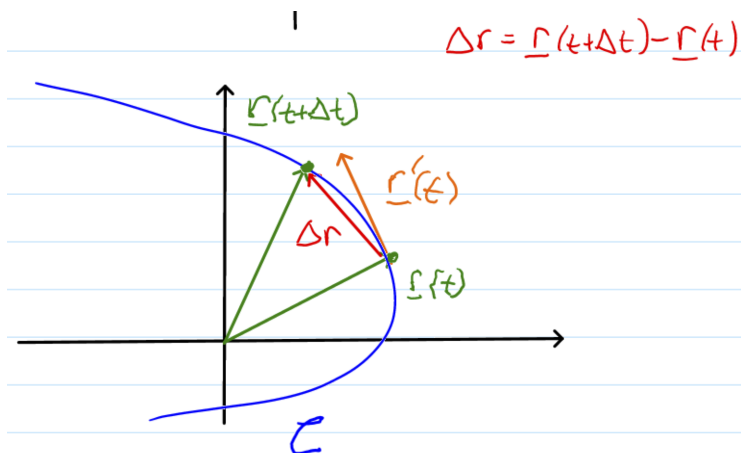
2. $\mathbf{r}(t) = (t, t^2)$, $t \in \mathbb{R}$

Let $x = t$ and $y = t^2$ and then note that

$$y = x^2$$

So this parametrisation traces a parabola.

Tangent vectors



The approximate tangent vector is given by

$$\frac{\Delta \mathbf{r}}{\Delta t} = \frac{\mathbf{r}(t + \Delta t) - \mathbf{r}(t)}{\Delta t}$$

So clearly, the tangent is given by

$$\lim_{\Delta t \rightarrow 0} \frac{\mathbf{r}(t + \Delta t) - \mathbf{r}(t)}{\Delta t} = \mathbf{r}'(t)$$

So $\mathbf{r}'(t)$ gives a tangent vector to the parametric curve \mathcal{C} at the point $\mathbf{r}(t)$.

Example

$$\mathbf{r}(t) = (\cos(t), \sin(t)), \quad 0 \leq t \leq 2\pi$$

Note: I already know that the tangent vector of a circle is at 90 degrees to the radius vector.

$$\mathbf{r}'(t) = (-\sin(t), \cos(t))$$

If this is indeed perpendicular to the radius vector then we would expect the dot product to be zero:

$$\begin{aligned}\Rightarrow \mathbf{r}(t) \cdot \mathbf{r}'(t) &= (\cos(t), \sin(t)) \cdot (-\sin(t), \cos(t)) \\ &= -\cos(t)\sin(t) + \sin(t)\cos(t) \\ &= 0\end{aligned}$$

Functions of several variables §9.6, 9.6.1

Definition

A function of n variables, denoted $f(\mathbf{x})$, ($\mathbf{x} = (x_1, x_2, \dots, x_n)$) is a rule that associates to each point $\mathbf{x} \in D \subset \mathbb{R}^n$, D is called the domain, a number $f(\mathbf{x}) \in \mathbb{R}$; symbolically, we write

$$f : D \subset \mathbb{R}^n \rightarrow \mathbb{R} : \mathbf{x} \mapsto f(\mathbf{x})$$

Note that $f(\mathbf{x})$ is *usually* defined by a formula.

Examples

(a) $f(x, y) = \ln(x^2 + y^2)$. We can assume $D = \mathbb{R}^2 \setminus \{(0, 0)\}$

(b) $f(x, y, z) = e^{xyz}$, $D = \mathbb{R}^3$

Parametric surfaces

Definition

A parametric surface in \mathbb{R}^3 is a set S that is defined by

$$S = \{\mathbf{r}(u, v) \mid (u, v) \in D \subset \mathbb{R}^2\}$$

where $\mathbf{r}(u, v) = (x(u, v), y(u, v), z(u, v))$.

We call $\mathbf{r}(u, v)$ the **parametrisation** (or parametric equation) of S .

An important special case of a parametric surface is the graph of a function $f(x, y)$ that is defined by

$$S = \{(x, y, f(x, y)) \mid (x, y) \in D\}$$

