

## Concurrency Control

Chapter 17



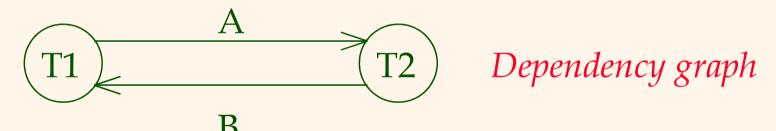
## Conflict Serializable Schedules

- Two schedules are conflict equivalent if:
  - Involve the same actions of the same transactions
  - Every pair of conflicting actions is ordered the same way
- Schedule S is conflict serializable if S is conflict equivalent to some serial schedule



## Example

\* A schedule that is not conflict serializable:



\* The cycle in the graph reveals the problem. The output of T1 depends on T2, and viceversa.



## Dependency Graph

- \* <u>Dependency graph</u>: One node per Xact; edge from *Ti* to *Tj* if *Tj* reads/writes an object last written by *Ti*.
- \* Theorem: Schedule is conflict serializable if and only if its dependency graph is acyclic



### Review: Strict 2PL

- \* Strict Two-phase Locking (Strict 2PL) Protocol:
  - Each Xact must obtain a S (*shared*) lock on object before reading, and an X (*exclusive*) lock on object before writing.
  - All locks held by a transaction are released when the transaction completes
  - If an Xact holds an X lock on an object, no other Xact can get a lock (S or X) on that object.
- Strict 2PL allows only schedules whose precedence graph is acyclic



## Two-Phase Locking (2PL)

- Two-Phase Locking Protocol
  - Each Xact must obtain a S (*shared*) lock on object before reading, and an X (*exclusive*) lock on object before writing.
  - A transaction can not request additional locks once it releases any locks.
  - If an Xact holds an X lock on an object, no other Xact can get a lock (S or X) on that object.



## View Serializability

- Schedules S1 and S2 are view equivalent if:
  - If Ti reads initial value of A in S1, then Ti also reads initial value of A in S2
  - If Ti reads value of A written by Tj in S1, then Ti also reads value of A written by Tj in S2
  - If Ti writes final value of A in S1, then Ti also writes final value of A in S2

```
T1: R(A) W(A)
T2: W(A)
T3: W(A)
T3: W(A)
T3: W(A)
T3: W(A)
T3: W(A)
```



## Lock Management

- Lock and unlock requests are handled by the lock manager
- Lock table entry:
  - Number of transactions currently holding a lock
  - Type of lock held (shared or exclusive)
  - Pointer to queue of lock requests
- Locking and unlocking have to be atomic operations
- Lock upgrade: transaction that holds a shared lock can be upgraded to hold an exclusive lock



#### Deadlocks

- ❖ Deadlock: Cycle of transactions waiting for locks to be released by each other.
- Two ways of dealing with deadlocks:
  - Deadlock prevention
  - Deadlock detection



#### Deadlock Prevention

- \* Assign priorities based on timestamps. Assume Ti wants a lock that Tj holds. Two policies are possible:
  - Wait-Die: It Ti has higher priority, Ti waits for Tj; otherwise Ti aborts
  - Wound-wait: If Ti has higher priority, Tj aborts; otherwise Ti waits
- If a transaction re-starts, make sure it has its original timestamp



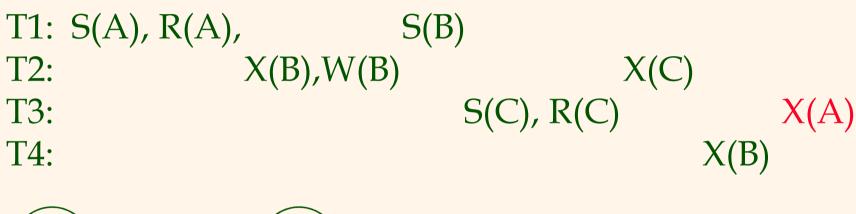
#### Deadlock Detection

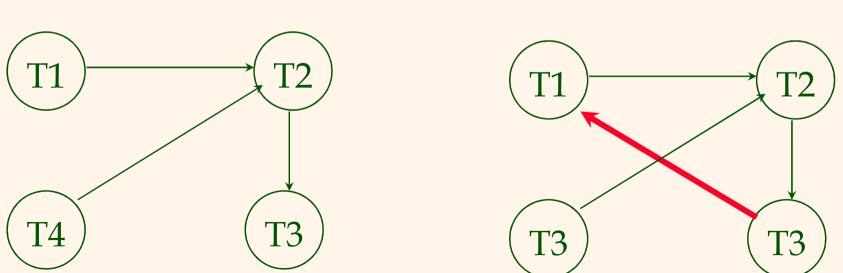
- Create a waits-for graph:
  - Nodes are transactions
  - There is an edge from Ti to Tj if Ti is waiting for Tj to release a lock
- Periodically check for cycles in the waits-for graph



## Deadlock Detection (Continued)

#### Example:

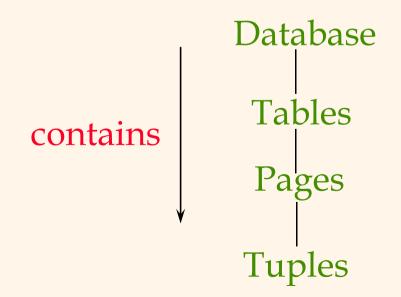






## Multiple-Granularity Locks

- Hard to decide what granularity to lock (tuples vs. pages vs. tables).
- Shouldn't have to decide!
- Data "containers" are nested:



### Solution: New Lock Modes, Protocol

- Allow Xacts to lock at each level, but with a special protocol using new "intention" locks:
- Before locking an item, Xact must set "intention locks" on all its ancestors.
- For unlock, go from specific to general (i.e., bottom-up).
- \* SIX mode: Like S & IX at the same time.

		IS	IX	S	X
	<b>√</b>	<b>√</b>	$\checkmark$		V
IS	V	$\sqrt{}$	$\checkmark$		
IX	<b>√</b>	<b>√</b>	$\checkmark$		
S	<b>V</b>	V		V	
X	1				

## Multiple Granularity Lock Protocol

- Each Xact starts from the root of the hierarchy.
- \* To get S or IS lock on a node, must hold IS or IX on parent node.
  - What if Xact holds SIX on parent? S on parent?
- \* To get X or IX or SIX on a node, must hold IX or SIX on parent node.
- Must release locks in bottom-up order.

Protocol is correct in that it is equivalent to directly setting locks at the leaf levels of the hierarchy.



## Examples

- T1 scans R, and updates a few tuples:
  - T1 gets an SIX lock on R, then repeatedly gets an S lock on tuples of R, and occasionally upgrades to X on the tuples.
- ❖ T2 uses an index to read only part of R:
  - T2 gets an IS lock on R, and repeatedly gets an S lock on tuples of R.
- \* T3 reads all of R:
  - T3 gets an S lock on R.
  - OR, T3 could behave like T2; can use lock escalation to decide which.

		IS	IX	S	X
	V	V			V
IS	V	V			
IX	V	V		·	
S		V	Ì		
Χ	V	,			



## Dynamic Databases

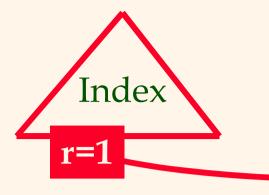
- If we relax the assumption that the DB is a fixed collection of objects, even Strict 2PL will not assure serializability:
  - T1 locks all pages containing sailor records with rating = 1, and finds oldest sailor (say, age = 71).
  - Next, T2 inserts a new sailor; *rating* = 1, *age* = 96.
  - T2 also deletes oldest sailor with rating = 2 (and, say, age = 80), and commits.
  - T1 now locks all pages containing sailor records with *rating* = 2, and finds <u>oldest</u> (say, *age* = 63).
- \* No consistent DB state where T1 is "correct"!



#### The Problem

- ❖ T1 implicitly assumes that it has locked the set of all sailor records with rating = 1.
  - Assumption only holds if no sailor records are added while T1 is executing!
  - Need some mechanism to enforce this assumption. (Index locking and predicate locking.)
- \* Example shows that conflict serializability guarantees serializability only if the set of objects is fixed!

## Index Locking



- ❖ If there is a dense index on the *rating* field using Alternative (2), T1 should lock the index page containing the data entries with *rating* = 1.
  - If there are no records with *rating* = 1, T1 must lock the index page where such a data entry *would* be, if it existed!
- ❖ If there is no suitable index, T1 must lock all pages, and lock the file/table to prevent new pages from being added, to ensure that no new records with *rating* = 1 are added.



## Predicate Locking

- ❖ Grant lock on all records that satisfy some logical predicate, e.g. age > 2\*salary.
- Index locking is a special case of predicate locking for which an index supports efficient implementation of the predicate lock.
  - What is the predicate in the sailor example?
- In general, predicate locking has a lot of locking overhead.



## Locking in B+ Trees

- How can we efficiently lock a particular leaf node?
  - Btw, don't confuse this with multiple granularity locking!
- \* One solution: Ignore the tree structure, just lock pages while traversing the tree, following 2PL.
- This has terrible performance!
  - Root node (and many higher level nodes) become bottlenecks because every tree access begins at the root.

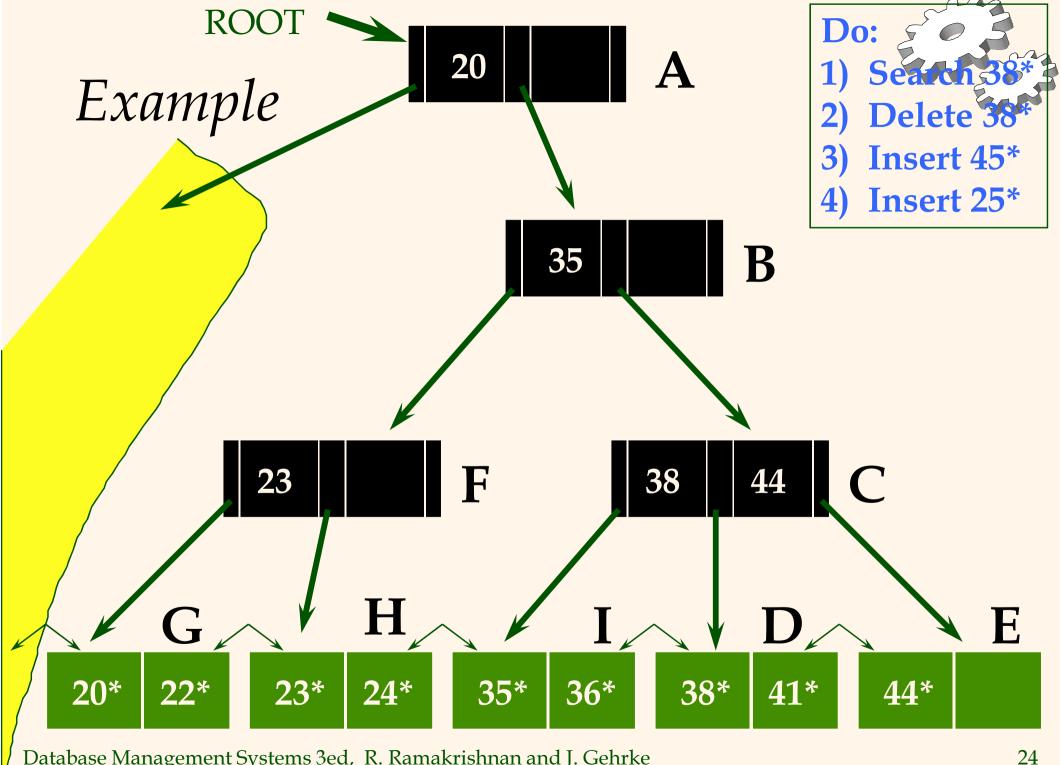


## Two Useful Observations

- Higher levels of the tree only direct searches for leaf pages.
- \* For inserts, a node on a path from root to modified leaf must be locked (in X mode, of course), only if a split can propagate up to it from the modified leaf. (Similar point holds w.r.t. deletes.)
- \* We can exploit these observations to design efficient locking protocols that guarantee serializability *even though they violate 2PL*.

## A Simple Tree Locking Algorithm

- Search: Start at root and go down; repeatedly, S lock child then unlock parent.
- Insert/Delete: Start at root and go down, obtaining X locks as needed. Once child is locked, check if it is <u>safe</u>:
  - If child is safe, release all locks on ancestors.
- Safe node: Node such that changes will not propagate up beyond this node.
  - Inserts: Node is not full.
  - Deletes: Node is not half-empty.





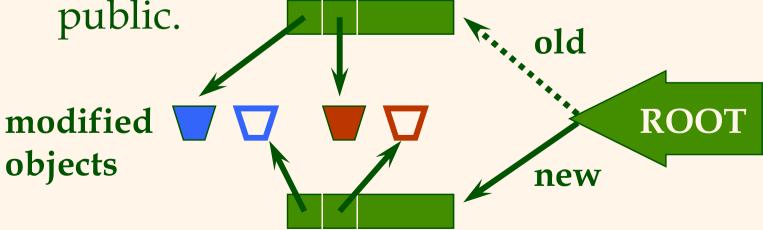
## Optimistic CC (Kung-Robinson)

- Locking is a conservative approach in which conflicts are prevented. Disadvantages:
  - Lock management overhead.
  - Deadlock detection/resolution.
  - Lock contention for heavily used objects.
- \* If conflicts are rare, we might be able to gain concurrency by not locking, and instead checking for conflicts before Xacts commit.



## Kung-Robinson Model

- Xacts have three phases:
  - READ: Xacts read from the database, but make changes to private copies of objects.
  - VALIDATE: Check for conflicts.
  - WRITE: Make local copies of changes public.





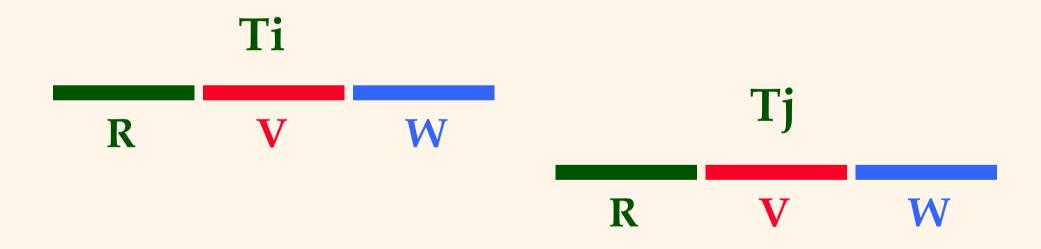
#### Validation

- \* Test conditions that are sufficient to ensure that no conflict occurred.
- Each Xact is assigned a numeric id.
  - Just use a timestamp.
- \* Xact ids assigned at end of READ phase, just before validation begins. (Why then?)
- \* ReadSet(Ti): Set of objects read by Xact Ti.
- WriteSet(Ti): Set of objects modified by Ti.



#### Test 1

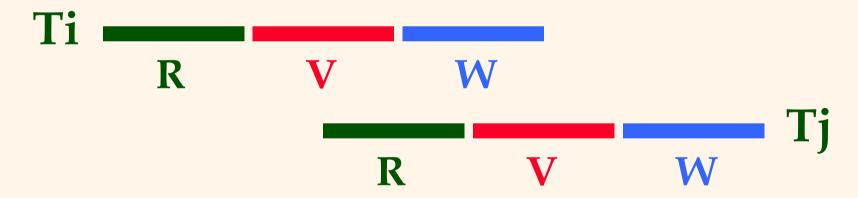
❖ For all i and j such that Ti < Tj, check that Ti completes before Tj begins.</p>





#### Test 2

- ❖ For all i and j such that Ti < Tj, check that:
  - Ti completes before Tj begins its Write phase +
  - WriteSet(Ti) ReadSet(Tj) is empty.

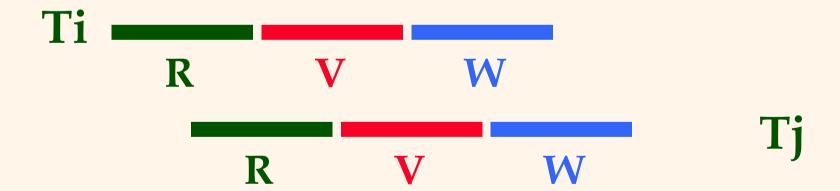


Does Tj read dirty data? Does Ti overwrite Tj's writes?



#### Test 3

- ❖ For all i and j such that Ti < Tj, check that:
  - Ti completes Read phase before Tj does +
  - WriteSet(Ti)
     ReadSet(Tj) is empty +
  - WriteSet(Ti) WriteSet(Tj) is empty.



Does Tj read dirty data? Does Ti overwrite Tj's writes?

## Applying Tests 1 & 2: Serial Validation



To validate Xact T:

```
valid = true;
// S = set of Xacts that committed after Begin(T)
< foreach Ts in S do {</pre>
 if ReadSet(Ts) does not intersect WriteSet(Ts)
      then valid = false;
 if valid then { install updates; // Write phase
              Commit T } >
          else Restart T
```

end of critical section



#### Comments on Serial Validation

- \* Applies Test 2, with T playing the role of Tj and each Xact in Ts (in turn) being Ti.
- \* Assignment of Xact id, validation, and the Write phase are inside a **critical section**!
  - I.e., Nothing else goes on concurrently.
  - If Write phase is long, major drawback.
- Optimization for Read-only Xacts:
  - Don't need critical section (because there is no Write phase).



### Serial Validation (Contd.)

- Multistage serial validation: Validate in stages, at each stage validating T against a subset of the Xacts that committed after Begin(T).
  - Only last stage has to be inside critical section.
- Starvation: Run starving Xact in a critical section (!!)
- ❖ Space for WriteSets: To validate Tj, must have WriteSets for all Ti where Ti < Tj and Ti was active when Tj began. There may be many such Xacts, and we may run out of space.
  - Tj's validation fails if it requires a missing WriteSet.
  - No problem if Xact ids assigned at start of Read phase.



## Overheads in Optimistic CC

- Must record read/write activity in ReadSet and WriteSet per Xact.
  - Must create and destroy these sets as needed.
- Must check for conflicts during validation, and must make validated writes ``global''.
  - Critical section can reduce concurrency.
  - Scheme for making writes global can reduce clustering of objects.
- Optimistic CC restarts Xacts that fail validation.
  - Work done so far is wasted; requires clean-up.



## ``Optimistic'' 2PL

- If desired, we can do the following:
  - Set S locks as usual.
  - Make changes to private copies of objects.
  - Obtain all X locks at end of Xact, make writes global, then release all locks.
- In contrast to Optimistic CC as in Kung-Robinson, this scheme results in Xacts being blocked, waiting for locks.
  - However, no validation phase, no restarts (modulo deadlocks).



## Timestamp CC

- \* Idea: Give each object a read-timestamp (RTS) and a write-timestamp (WTS), give each Xact a timestamp (TS) when it begins:
  - If action ai of Xact Ti conflicts with action aj of Xact Tj, and TS(Ti) < TS(Tj), then ai must occur before aj. Otherwise, restart violating Xact.

# When Xact T wants to read Object C

- ❖ If TS(T) < WTS(O), this violates timestamp order of T w.r.t. writer of O.
  - So, abort T and restart it with a new, larger TS. (If restarted with same TS, T will fail again! Contrast use of timestamps in 2PL for ddlk prevention.)
- $\star$  If TS(T) > WTS(O):
  - Allow T to read O.
  - Reset RTS(O) to max(RTS(O), TS(T))
- Change to RTS(O) on reads must be written to disk! This and restarts represent overheads.

## When Xact T wants to Write Object &

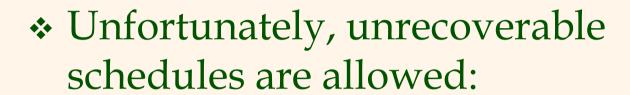
- ❖ If TS(T) < RTS(O), this violates timestamp order of T w.r.t. writer of O; abort and restart T.
- ❖ If TS(T) < WTS(O), violates timestamp order of T w.r.t. writer of O.
  - Thomas Write Rule: We can safely ignore such outdated writes; need not restart T! (T's write is effectively followed by another write, with no intervening reads.)

    Allows some serializable but non R(A)
- \* Else, allow T to write O.

<b>T1</b>	<b>T2</b>
R(A)	
	W(A)
	Commit
W(A)	
Commit	

conflict serializable schedules:

## Timestamp CC and Recoverability



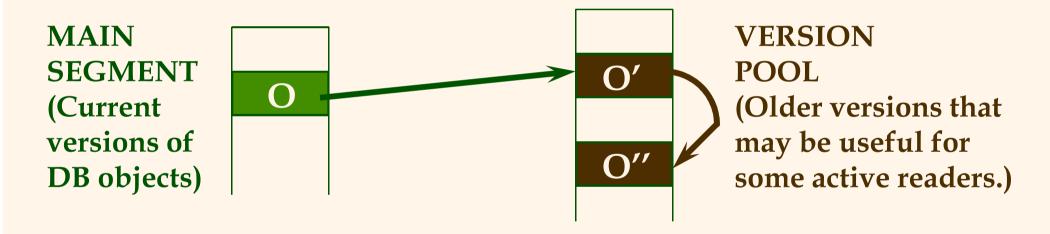
T1	<b>T2</b>
W(A)	
	R(A)
	R(A) W(B)
	Commit

- Timestamp CC can be modified to allow only recoverable schedules:
  - Buffer all writes until writer commits (but update WTS(O) when the write is allowed.)
  - Block readers T (where TS(T) > WTS(O)) until writer of O commits.
- Similar to writers holding X locks until commit, but still not quite 2PL.



## Multiversion Timestamp CC

❖ Idea: Let writers make a "new" copy while readers use an appropriate "old" copy:



- Readers are always allowed to proceed.
  - But may be blocked until writer commits.

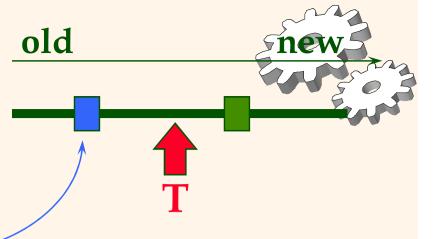


### Multiversion CC (Contd.)

- Each version of an object has its writer's TS as its WTS, and the TS of the Xact that most recently read this version as its RTS.
- Versions are chained backward; we can discard versions that are "too old to be of interest".
- \* Each Xact is classified as Reader or Writer.
  - Writer may write some object; Reader never will.
  - Xact declares whether it is a Reader when it begins.

#### WTS timeline

### Reader Xact



- For each object to be read:
  - Finds newest version with WTS < TS(T).</li>
     (Starts with current version in the main segment and chains backward through earlier versions.)
- \* Assuming that some version of every object exists from the beginning of time, Reader Xacts are never restarted.
  - However, might block until writer of the appropriate version commits.

#### Writer Xact

- To read an object, follows reader protocol.
- To write an object:
  - Finds newest version V s.t. WTS < TS(T).
  - If RTS(V) < TS(T), T makes a copy CV of V, with a pointer to V, with WTS(CV) = TS(T), RTS(CV) = TS(T). (Write is buffered until T commits; other Xacts can see TS values but can't read version CV.)
  - Else, reject write.



## Summary

- There are several lock-based concurrency control schemes (Strict 2PL, 2PL). Conflicts between transactions can be detected in the dependency graph
- \* The lock manager keeps track of the locks issued. Deadlocks can either be prevented or detected.
- Naïve locking strategies may have the phantom problem



## Summary (Contd.)

- \* Index locking is common, and affects performance significantly.
  - Needed when accessing records via index.
  - Needed for locking logical sets of records (index locking/predicate locking).
- \* Tree-structured indexes:
  - Straightforward use of 2PL very inefficient.
- In practice, better techniques now known; do record-level, rather than page-level locking.



## Summary (Contd.)

- Multiple granularity locking reduces the overhead involved in setting locks for nested collections of objects (e.g., a file of pages); should not be confused with tree index locking!
- Optimistic CC aims to minimize CC overheads in an ``optimistic'' environment where reads are common and writes are rare.
- \* Optimistic CC has its own overheads however; most real systems use locking.