

## המחלקה להנדסת חשמל ואלקטרוניקה

16.02.18 : תאריך הבחינה

8: 30-11: 30 : שעות הבחינה

# מבוא לאותות אקראיים

'מועד ב

דייר דימה בחובסקי, אביתר רימון

תשעייח סמסטר אי

חומר עזר - עד 2 דפי נוסחאות אישיים (משני צדדים), מחשבון הוראות מיוחדות:

- יש לציין באופן מלא וברור את שלבי הפתרון. תשובה ללא הסבר לא תתקבלנה.
  - אם לא מצויין אחרת, הסעיפים הם בעלי ניקוד זהה.

השאלון כולל 11 דפים (כולל דף זה)

בהצלחה!



# 19.2 (33 נק') – מתוך ,17.34 Kay, מתוך (35 נק') א

- $P_{\mathbf{x}}(f) = 1 + \cos(2\pi f)$  מהצורה (PSD) בעל צפיפות הפסק בעל צפיפות בדיד, ג[n], בעל גפיפות גמוון תהליך אקראי בדיד, האם הדגימות של התהליך הן חסרי קורלציה?
- $\sigma_w^2$  נתון תהליך אקראי בדיד,  $\mathbf{x}[n]$ , מהצורה  $\mathbf{w}[n] = \mathbf{w}[n] \mu$ , כאשר (ב) מחצורה, אונוריי, מהי פוקציה אוטו-קורלציה,  $R_\mathbf{w}[n,n+k]$  האם מדובר בתהליך סטציאונריי וו- $\mu$  יה קבוע ממשי. מהי פוקציה אוטו-קורלציה,
  - (ג) נתונים תהליכים

(1) 
$$\mathbf{y}(t) = a_1 \mathbf{x}_1(t) + a_2 \mathbf{x}_2(t)$$

(2) 
$$\mathbf{z}(t) = b_1 \mathbf{x}_1(t) + b_2 \mathbf{x}_2(t),$$

 $\mathbf{WSS}$  במשותף: הוכח/נמק:  $\mathbf{WSS}$  במשותף: האם  $\mathbf{y}(t),\mathbf{z}(t)$  האם  $\mathbf{WSS}$  במשותף: הוכח/נמק

## 18.25 Kay, מתוך – מרוץ 22) מרוץ 2

 $. heta \sim U\left[0,2\pi
ight]$  כאשר ג $\mathbf{x}[n] = \cos\left(2\pi f_0 n + heta
ight)$  נתון תהליך אקראי שפונקציית אוטו-קרלציה של התהליך נתונה ע"י

$$R_{\mathbf{x}}[k] = \cos\left(2\pi f_0 k\right)$$

.  $\hat{\mathbf{x}}[n+1] = a\mathbf{x}[n] + b\mathbf{x}[n-1]$  נדרש לעשות חיזוי לינארי עבור התהליך מהצורה מינימלית מינימלית שאגיאת חיזוי היא a,b במובן שגיאה ריבועית מינימלית (MMSE), מצא ערכים אופטימליים של

## 5.56 Shaum, מתוך – (מקוץ) Poisson 3

קצב הגעת הלקוחות לפקיד מסויים הינו  $\lambda=1/10$  לדקה, החל מפתיחת משרדו. הפקיד מתחיל לקבל לקוחות רק כאשר כבר יש 3 לקוחות בחדר המתנה.

- (א) מהו זמן המתנה ממוצע להתחלת קבלת הלקוחות!
- (ב) מהו הסיכוי, שאחרי 30 דקות מפתיחת המשרד לא התקבל אף לקוח!



# ('טאלה 33) Markov שאלה 4

1.3/5 במקום מסויים, סיכוי לגשם אחרי יום שמש הוא 1/20, וסיכוי לגשם אחרי יום גשום הוא

- (א) רשום את מטריצת המעברים, P
- (ב) אם היום הוא יום שמש, מהו הסיכוי לגשם עוד יומיים!
  - (ג) מהו סיכוי ממוצע ליום גשם/שמש!

## Random Processes – Formulas

## 1 Random Variables

### 1.1 Distributions

|             | Notation                    | PDF/PMF   | $\operatorname{CDF}$  | $\mid E[X] \mid$      | Var[X]                    |
|-------------|-----------------------------|---|---|-----------------------|---------------------------|
| Bernoulli   | Ber(p)                      | $\begin{cases} 1 - p & k = 0 \\ p & k = 1 \end{cases}$                                | $\begin{cases} 0 & x < 0 \\ 1 - p & 0 \le x < 1 \\ 1 & 1 \le x \end{cases}$                       | p                     | p(1-p)                    |
| Uniform     | U[a,b]                      | $\frac{1}{b-a}, a \leqslant x \leqslant b$  | $\begin{cases} 0 & x < a \\ \frac{x-a}{b-a} & a \leqslant x \leqslant b \\ 1 & b < x \end{cases}$ | $\frac{a+b}{2}$       | $\frac{(b-a)^2}{12}$      |
| Normal      | $N(\mu, \sigma^2)$          | $\frac{1}{\sigma\sqrt{2\pi}}\exp\left[-\frac{\left(x-\mu\right)^2}{2\sigma^2}\right]$ | $\Phi(x)$   | $\mu$                 | $\sigma^2$                |
| Exponential | $Exp(\lambda)$              | $\lambda \exp\left(-\lambda x\right), x \geqslant 0$                                  | $1 - \exp\left(-\lambda x\right)$   | $1/\lambda$           | $1/\lambda^2$             |
| Poisson     | $\mathcal{P}(\lambda)$      | $p(X = k) = \exp(-\lambda) \frac{\lambda^k}{k!}$                                      | $\exp\left(-\lambda\right) \sum_{i=0}^{k} \frac{\lambda^{i}}{i!}$                                 | $\lambda$             | λ                         |
| Erlang      | $   Erlang(k, \lambda t)  $ | $\lambda \frac{(\lambda t)^{k-1}}{(k-1)!} \exp(-\lambda t)$                           | $1 - \exp(-\lambda t) \sum_{n=0}^{k-1} \frac{(\lambda t)^n}{n!}$                                  | $\frac{k}{\lambda t}$ | $\frac{k}{(\lambda t)^2}$ |

## 1.2 Properties

Definitions:

$$F_X(x) = p(X \leqslant x) \tag{1a}$$

$$f_X(x) = \frac{\partial F_X(x)}{\partial x}$$
 (1b)

$$F_X(x) = \int_{-\infty}^x f_X(p) \, dp \tag{1c}$$

$$p(a < X \leqslant b) = F_X(b) - F_X(a) \tag{1d}$$

$$p_X[x_k] = p(X = x_k) \tag{2a}$$

$$F_X(x) = \sum_{k:x_k \leqslant x} p_X[x_k]$$
 (2b)

Expectation:

$$E[X] = \begin{cases} \int_{-\infty}^{\infty} x f_X(x) dx \\ \sum_i x_i p_x[x_i] \end{cases}$$
 (3a)

$$E[g(X)] = \begin{cases} \int_{-\infty}^{\infty} g(x) f_X(x) dx \\ \sum_{i} g(x_i) p_x[x_i] \end{cases}$$
 (3b)

$$E[aX + b] = aE[x] + b \tag{3c}$$

Variance:

$$Var[X] = E[(X - E[X])^2]$$

$$=E[X^2] - E^2[X]$$
 (4a)

$$Var[aX + b] = a^2 Var[X]$$
 (4b)

## 2 Two Random Variables

## 2.1 Joint Distributions

Definitions:

$$F_{XY}(x,y) = p(X \leqslant x, Y \leqslant y)$$
 (5a)

$$f_{XY}(x,y) = \frac{\partial^2 F_{XY}(x,y)}{\partial x \partial y} \geqslant 0$$
 (5b)

$$F_{XY}(x,y) = \int_{-\infty}^{x} \int_{-\infty}^{y} f_{XY}(s,p) \, dp \, ds \qquad (5c)$$

$$p[x_j, y_k] = p(X = x_j, Y = y_k)$$
 (6a)

$$F_{XY}(x,y) = p(X \leqslant x_j, Y \leqslant y_k) \tag{6b}$$

Conditional distribution (Bayes)  $(f_X(x), f_Y(y), p_X[x_k], p_Y[y_k] > 0)$ :

$$f_{Y|X}(y|x)f_X(x) = f_{X|Y}(x|y)f_Y(x) = f_{XY}(x,y) \quad (7a)$$

$$p_{Y|X}[y_j|x_k]p_X[x_k] = p_{X|Y}[x_k|y_j]p_Y[y_j] = p_{XY}[x_k,y_j] \quad (7b)$$

$$F_{Y|X}(y|x) = p(Y \leqslant y|X = x) = \int_{-\infty}^{y} f_{Y|X}(s|x)ds$$
(7c)

$$F_{Y|X}[y|x_k] = \frac{p[Y \leqslant y_j, X = x_k]}{p_X[x_k]}$$
(7d)

Expectation:

$$E[XY] = \iint xy f_{XY}(x, y) dx dy \tag{8a}$$

$$E[g(X)] = \begin{cases} \iint g(x,y) f_{XY}(x,y) dx dy \\ \sum_{i} \sum_{k} g(x_{i}, y_{k}) p_{x}[x_{i}, y_{k}] \end{cases}$$
(8b)

$$E[aX + bY] = aE[X] + bE[Y]$$
(8c)

Conditional expectation & Variance:

$$E[Y|X] = \begin{cases} \int y f_{Y|X}(y|x) dy \\ \sum_{j} y_{j} p[y_{j}|x_{k}] \end{cases}$$
 (9a)

$$E[X] = E[E[X|Y]] = \iint y f_{Y|X}(y|x) f_X(x) dx dy$$

(9b)

$$Var[Y|X] = E[Y^2|X] - E^2[Y|X]$$
(9c)

$$Var[Y] = Var[E[Y|X]] + E[Var[Y|X]]$$
(9d)

Independent random variables:

$$f_{XY}(x,y) = f_X(x)f_Y(y) \tag{10a}$$

$$p_{XY}[x_k, y_j] = p_X[x_k]p_Y[y_j]$$
 (10b)

$$F_{XY}(x,y) = F_X(x)F_Y(y)$$
(10c)

$$E[XY] = E[X]E[Y] \tag{10d}$$

$$E[g_1(X)g_2(Y)] = E[g_1(X)]E[g_2(Y)]$$
 (10e)

$$Var[aX + bY] = a^2 Var[X] + b^2 Var[Y]$$
 (10f)

Marginal distribution:

$$f_X(x) = \int_{-\infty}^{\infty} f_{XY}(x, y) dy \tag{11a}$$

$$p_X[x_k] = \sum_j p_{XY}[x_k, y_j]$$
 (11b)

$$F_X(x) = F_{XY}(x, \infty) \tag{11c}$$

$$F_Y(y) = F_{XY}(\infty, y) \tag{11d}$$

# 2.2 Correlation, Covariance & Correlation Coefficient

ullet For two jointly-distributed random variables X and Y, covariance is given by

$$Cov[X, Y] = E[(X - E[X])(Y - E[Y])]$$
  
=  $E[XY] - E[X]E[Y].$  (12)

Main covariance properties are:

$$Cov[X, X] = Var[X]$$
(13a)

$$Cov[X, Y] = Cov[Y, X]$$
(13b)

$$Cov[X, a] = 0 (13c)$$

$$Cov[aX, bY] = ab Cov[X, Y]$$
(13d)

$$Cov[X, Y] = Cov[X + a, Y + b]$$
(13e)

$$Var[X + Y] = Var[X] + Var[Y] + 2 Cov[X, Y]$$
(13f)

• Correlation coefficient (also termed as Pearson product-moment correlation coefficient) is given by

$$\rho_{XY} = \frac{\text{Cov}[X, Y]}{\sqrt{\text{Var}[X] \text{Var}[Y]}}$$
(14)

such that  $|\rho_{XY}| \leq 1$ .

## 2.3 Relations

- When X and Y are orthogonal, E[XY] = 0.
- When X and Y are uncorrelated,  $Cov[X, Y] = \rho_{XY} = 0$ .
- When X and Y are *independent*, they are also uncorrelated (see also Eqs. 10).
- When X and Y are jointly Gaussian and uncorrelated  $\Rightarrow X$  and Y are independent.
- Joint⇒ marginal, marginal ⇒ joint

## 3 Random Processes – General Properties

• PDF & CDF

$$F_{\mathbf{x}}(x;t) = p(\mathbf{x}(t) \leqslant x)$$
 (15a)

$$f_{\mathbf{x}}(x;t) = \frac{\partial}{\partial x} F_{\mathbf{x}}(x;t)$$
 (15b)

• Average:

$$E[\mathbf{x}(t)] = \int_{-\infty}^{\infty} x f_{\mathbf{x}}(x;t) dx$$
 (16a)

$$E[\mathbf{x}[n]] = \int_{-\infty}^{\infty} x f_{\mathbf{x}}(x; n) dx$$
 (16b)

• Variance:

$$Var[\mathbf{x}(t)] = E[\mathbf{x}^{2}(t)] - E^{2}[\mathbf{x}(t)]$$
(17a)

$$Var[\mathbf{x}[n]] = E[\mathbf{x}^{2}[n]] - E^{2}[\mathbf{x}[n]]$$
 (17b)

• Auto-correlation

$$R_{\mathbf{x}}(t_1, t_2) = E[\mathbf{x}(t_1)\mathbf{x}(t_2)] \tag{18a}$$

$$R_{\mathbf{x}}(t, t+\tau) = E[\mathbf{x}(t)\mathbf{x}(t+\tau)] \tag{18b}$$

$$R_{\mathbf{x}}(t_1, t_2) = R_{\mathbf{x}}(t_2, t_1)$$
 (18c)

$$R_{\mathbf{x}}(t,t) = E[\mathbf{x}^2(t)] \tag{18d}$$

$$R_{\mathbf{x}}[n_1, n_2] = E[\mathbf{x}[n_1]\mathbf{x}[n_2]] \tag{18e}$$

• Auto-covariance

$$C_{\mathbf{x}}(t_1, t_2) = R_{\mathbf{x}}(t_1, t_2) - E[\mathbf{x}(t_1)]E[\mathbf{x}(t_2)]$$
  
=  $E[\{\mathbf{x}(t_1) - E[\mathbf{x}(t_1)]\}\{\mathbf{x}(t_2) - E[\mathbf{x}(t_2)]\}]$  (19)

$$C_{\mathbf{x}}(t,t) = Var[\mathbf{x}(t)] \tag{20}$$

• Correlation Coefficient

$$\rho_{\mathbf{x}}(t_1, t_2) = \frac{C_{\mathbf{x}}(t_1, t_2)}{\sqrt{C_{\mathbf{x}}(t_1, t_1)C_{\mathbf{x}}(t_2, t_2)}}$$
(21a)

$$|\rho_{\mathbf{x}}(t_1, t_2)| \leqslant 1 \tag{21b}$$

- When  $\mathbf{x}(t_1)$  and  $\mathbf{x}(t_2)$  are orthogonal,  $R_{\mathbf{x}}(t_1, t_2) = 0$ .
- When  $\mathbf{x}(t_1)$  and  $\mathbf{x}(t_2)$  are uncorrelated,  $C_{\mathbf{x}}(t_1, t_2) = \rho_{\mathbf{x}}(t_1, t_2) = 0$ .
- When  $\mathbf{x}(t_1)$  and  $\mathbf{x}(t_2)$  are independent,  $R_{\mathbf{x}}(t_1, t_2) = E[\mathbf{x}(t_1)]E[\mathbf{x}(t_2)].$

## 4 Wide-Sense Stationary (WSS) Process

Definition:

$$E[\mathbf{x}(t)] = E[\mathbf{x}(0)] = \mu_{\mathbf{x}} = \text{const}$$
 (22a)

$$R_{\mathbf{x}}(t_1, t_2) = R_{\mathbf{x}}(\tau = |t_2 - t_1|), \quad \forall t_1, t_2$$
 (22b)

$$E[\mathbf{x}[n]] = E[\mathbf{x}[0]] = \mu_{\mathbf{x}} = \text{const}$$
 (22c)

$$R_{\mathbf{x}}[n_1, n_2] = R_{\mathbf{x}}(k = |n_2 - n_1|), \quad \forall n_1, n_2$$
 (22d)

• Auto-correlation

$$R_{\mathbf{x}}(\tau) = E[\mathbf{x}(t)\mathbf{x}(t+\tau)] \tag{23a}$$

$$R_{\mathbf{x}}[k] = E[\mathbf{x}[n]\mathbf{x}(n+k)] \tag{23b}$$

Properties:

$$R_{\mathbf{x}}(-\tau) = R_{\mathbf{x}}(\tau) \tag{24a}$$

$$R_{\mathbf{x}}(0) = E[|\mathbf{x}(0)|^2] = E[|\mathbf{x}(t)|^2]$$
 (24b)

$$Var[\mathbf{x}(t)] = C_{\mathbf{x}}(0) = \sigma_{\mathbf{x}}^2 \tag{24c}$$

$$|R_{\mathbf{x}}(0)| \geqslant R_{\mathbf{x}}(\tau) \tag{24d}$$

Deterministic definition  $(x[n] \text{ is } \underline{\text{not}} \text{ random})$ 

$$R_x(\tau) = x(\tau) * x(-\tau)$$
 (25a)

$$R_x[k] = x[k] * x[-k]$$
 (25b)

• Auto-covariance

$$C_{\mathbf{x}}(\tau) = R_{\mathbf{x}}(\tau) - \mu_{\mathbf{x}}^2 \tag{26a}$$

$$C_{\mathbf{x}}[k] = R_{\mathbf{x}}[k] - \mu_{\mathbf{x}}^2 \tag{26b}$$

• Correlation Coefficient

$$\rho_{\mathbf{x}}(\tau) = \frac{C_{\mathbf{x}}(\tau)}{C_{-}(0)} \tag{27a}$$

$$\rho_{\mathbf{x}}[k] = \frac{C_{\mathbf{x}}[k]}{C_{\mathbf{x}}[0]} \tag{27b}$$

• Power spectral density (PSD)

$$S_{\mathbf{x}}(f) = \mathcal{F}\left\{R_{\mathbf{x}}(\tau)\right\} =$$

$$= \int_{-\infty}^{\infty} R_{\mathbf{x}}(\tau) \exp\left(j2\pi f \tau\right) d\tau \qquad (28a)$$

$$=2\int_{0}^{\infty}R_{\mathbf{x}}(\tau)\cos\left(2\pi f\tau\right)d\tau\tag{28b}$$

$$P_{\mathbf{x}}(f) = \mathcal{F}\left\{R_{\mathbf{x}}[k]\right\} = \qquad -1/2 \leqslant f \leqslant 1/2$$

$$= \sum_{k=-\infty}^{\infty} R_{\mathbf{x}}[k] \exp(-j2\pi f k)$$
 (28c)

$$=2\sum_{k=0}^{\infty}R_{\mathbf{x}}[k]\cos\left(-2\pi fk\right) \tag{28d}$$

Properties:

$$S_{\mathbf{x}}(f) = S_{\mathbf{x}}(-f) \tag{29a}$$

$$S_{\mathbf{x}}(f) \geqslant 0, \ \forall f$$
 (29b)

$$S_{\mathbf{x}}(f) \in \mathbb{R}$$
 (real numbers) (29c)

$$P_{\mathbf{x}}(f) = P_{\mathbf{x}}(-f) \tag{29d}$$
  
$$P_{\mathbf{x}}(f) \ge 0, \ \forall f \tag{29e}$$

$$P_{\mathbf{x}}(f) \in \mathbb{R}$$
 (real numbers) (29f)

$$P_{\mathbf{x}}(f) = P_{\mathbf{x}}(f+1) \tag{29g}$$

Average power

$$P_{\mathbf{x}} = E[\mathbf{x}^{2}(t)] = R_{\mathbf{x}}(0) = \int_{-\infty}^{\infty} S_{\mathbf{x}}(f)df \qquad (30a)$$

$$= E[\mathbf{x}^{2}[n]] = R_{\mathbf{x}}[0] = \int_{-1/2}^{1/2} P_{\mathbf{x}}(f) df \quad (30b)$$

Deterministic definition:

$$S_x(f) = X(f)X^*(f) = |X(f)|^2$$
 (31)

# 4.1 White Noise & White Gaussian Noise (WGN) Process

White noise process is SSS (WSS) process that is characterized by

$$R_{\mathbf{n}}(\tau) = \sigma^2 \delta(\tau) \tag{32a}$$

$$R_{\mathbf{n}}[k] = \sigma^2 \delta[k] \tag{32b}$$

$$S_{\mathbf{n}}(f) = \sigma^2 \quad \forall f \tag{32c}$$

For WGN process,  $\mathbf{n}(t) \sim N(0, \sigma^2)$ ,

$$R_{\mathbf{n}}(\tau) = \frac{N_0}{2}\delta(\tau) \tag{33a}$$

$$S_{\mathbf{n}}(f) = \frac{N_0}{2} \quad \forall f \tag{33b}$$

## 5 Cross-Signal

• Cross-correlation

$$R_{\mathbf{x}\mathbf{y}}(t_1, t_2) = E[\mathbf{x}(t_1)\mathbf{y}(t_2)]$$
 (34)

• Cross-covariance

$$C_{\mathbf{x}\mathbf{y}}(t_1, t_2) = R_{\mathbf{x}\mathbf{y}}(t_1, t_2) - E[\mathbf{x}(t_1)]E[\mathbf{y}(t_2)]$$
 (35)

• Correlation Coefficient

$$\rho_{xy}(t_1, t_2) = \frac{C_{xy}(t_1, t_2)}{\sqrt{C_{xy}(t_1, t_1)C_{xy}(t_2, t_2)}}$$
(36)

### 5.1 WSS Cross-signal

•  $\mathbf{x}(t), \mathbf{y}(t)$  are jointly WSS, if  $\mathbf{x}(t)$  and  $\mathbf{y}(t)$  each of them is WSS and

$$R_{\mathbf{x}\mathbf{y}}(\tau) = E[\mathbf{x}(t)\mathbf{y}(t+\tau)] \tag{37}$$

• When  $\mathbf{x}(t)$  and  $\mathbf{y}(t+\tau)$  are uncorrelated jointly WSS,  $C_{\mathbf{x}\mathbf{y}}(\tau) = 0$ .

Properties

$$R_{\mathbf{x}\mathbf{y}}(\tau) = R_{\mathbf{y}\mathbf{x}}(-\tau) \tag{38a}$$

$$|R_{\mathbf{x}\mathbf{y}}(\tau)| \leqslant \sqrt{R_{\mathbf{x}}(0)R_{\mathbf{y}}(0)} \tag{38b}$$

$$|R_{\mathbf{x}\mathbf{y}}(\tau)| \le \frac{1}{2} [R_{\mathbf{x}}(0) + R_{\mathbf{y}}(0)]$$
 (38c)

Deterministic definition

$$R_{xy}(\tau) = x(\tau) * y(-\tau) \tag{39}$$

• Cross-covariance

$$C_{\mathbf{x}\mathbf{y}}(\tau) = R_{\mathbf{x}\mathbf{y}}(\tau) - \mu_{\mathbf{x}}\mu_{\mathbf{y}} \tag{40}$$

• Cross-PSD

$$S_{xy}(f) = \mathcal{F}\left\{R_{xy}(\tau)\right\} \tag{41}$$

Properties

$$S_{\mathbf{x}\mathbf{v}}(f) = S_{\mathbf{v}\mathbf{x}}(-f) = S_{\mathbf{x}\mathbf{v}}^*(-f) \tag{42}$$

Deterministic definition

$$S_{xy}(f) = X(f)Y^*(f) \tag{43}$$

• Coherence

$$\gamma_{\mathbf{x}\mathbf{y}}(f) = \frac{S_{\mathbf{x}\mathbf{y}}(f)}{\sqrt{S_{\mathbf{x}}(f)S_{\mathbf{y}}(f)}}$$
(44)

## 6 LTI and WSS Random Process

Output of LTI system with impulse response h(t) and random process x(t),

$$y(t) = x(t) * h(t) \tag{45}$$

Average

$$m_{\mathbf{y}} = m_{\mathbf{x}} \int_{-\infty}^{\infty} h(s)ds = m_{\mathbf{x}}H(f=0)$$
 (46)

Cross-correlation & cross-covariance:

$$R_{\mathbf{x}\mathbf{v}}(\tau) = R_{\mathbf{x}}(\tau) * h(\tau) \tag{47a}$$

$$C_{\mathbf{x}\mathbf{v}}\left(\tau\right) = C_{\mathbf{x}}\left(\tau\right) * h\left(\tau\right) \tag{47b}$$

$$R_{\mathbf{vx}}(\tau) = R_{\mathbf{x}}(\tau) * h(-\tau) \tag{47c}$$

$$C_{\mathbf{vx}}(\tau) = C_{\mathbf{x}}(\tau) * h(-\tau) \tag{47d}$$

$$R_{\mathbf{v}}(\tau) = R_{\mathbf{x}}(\tau) * h(\tau) * h(-\tau) \tag{47e}$$

$$C_{\mathbf{v}}(\tau) = C_{\mathbf{x}}(\tau) * h(\tau) * h(-\tau) \tag{47f}$$

Power-Spectral Density (PSD) & Cross-PSD: Given frequency response  $H(f) = \mathcal{F}\{h(\tau)\}, H^*(f) = \mathcal{F}\{h(-\tau)\}$ 

$$S_{\mathbf{x}\mathbf{y}}(f) = S_{\mathbf{x}}(f)H(f) \tag{48a}$$

$$S_{\mathbf{v}\mathbf{x}}(f) = S_{\mathbf{x}}(f) H^{*}(f) \tag{48b}$$

$$S_{\mathbf{y}}(f) = S_{\mathbf{x}}(f) H(f) H^{*}(f) = S_{\mathbf{x}}(f) |H(f)|^{2}$$
 (48c)

Power of the process:

$$P_x = R_{\mathbf{x}}(0) = \int_{-\infty}^{\infty} S_{\mathbf{x}}(f) df$$
 (49a)

$$P_{y} = R_{\mathbf{y}}(0) = \int_{-\infty}^{\infty} S_{\mathbf{x}}(f) |H(f)|^{2} df \qquad (49b)$$

### 6.1 SNR

Given input signal

$$\mathbf{x}(t) = \mathbf{s}(t) + \mathbf{n}(t),\tag{50}$$

where  $\mathbf{s}(t), \mathbf{n}(t)$  are independent and  $E[\mathbf{n}(t)] = 0$ , the PSD of output  $\mathbf{y}(t)$  is given by

$$S_{\mathbf{y}}(f) = S_{\mathbf{x}}(f) |H(f)|^{2}$$
  
=  $S_{\mathbf{s}}(f) |H(f)|^{2} + S_{\mathbf{n}}(f) |H(f)|^{2}$ , (51)

where  $S_{\mathbf{s}}(f)|H(f)|^2$  is signal output PSD and  $S_{\mathbf{n}}(f)|H(f)|^2$  is noise PSD.

The input and output SNRs is given by

$$SNR_{x} = \frac{E[\mathbf{s}^{2}(t)]}{E[\mathbf{n}^{2}(t)]} = \frac{R_{\mathbf{s}}(0)}{R_{\mathbf{n}}(0)} = \frac{\int_{-\infty}^{\infty} S_{\mathbf{s}}(f)df}{\int_{-\infty}^{\infty} S_{\mathbf{n}}(f)df}$$
(52a)

$$SNR_y = \frac{\int_{-\infty}^{\infty} S_{\mathbf{s}}(f |H(f)|^2 df}{\int_{-\infty}^{\infty} S_{\mathbf{n}}(f) |H(f)|^2 df}.$$
 (52b)

## 7 Multi-dimensional processes

### 7.1 Covariance matrix

Given random vector  $\mathbf{X} = (X_1, X_2, \dots, X_N)^T$ ,

$$C_{\mathbf{X}} = \operatorname{Cov}[\mathbf{X}, \mathbf{X}] = E[(\mathbf{X} - E[\mathbf{X}])(\mathbf{X} - E[\mathbf{X}])^{T}]$$

$$= E[\mathbf{X}\mathbf{X}^{T}] - E[\mathbf{X}]E[\mathbf{X}]^{T}$$

$$= \begin{bmatrix} \operatorname{Var}[X_{1}] & \operatorname{Cov}[X_{1}, X_{2}] & \cdots & \operatorname{Cov}[X_{1}, X_{N}] \\ \operatorname{Cov}[X_{2}, X_{1}] & \operatorname{Var}[X_{2}] & \cdots & \operatorname{Cov}[X_{2}, X_{N}] \\ \vdots & \vdots & \ddots & \vdots \\ \operatorname{Cov}[X_{N}, X_{1}] & \operatorname{Cov}[X_{N}, X_{2}] & \cdots & \operatorname{Var}[X_{N}] \end{bmatrix}$$
(53)

Properties:

• Symmetry

$$C_{\mathbf{X}} = C_{\mathbf{X}}^T \quad Cov[X_i, X_j] = Cov[X_j, X_i]$$
 (54)

• Variance of linear combination: Given vector  $\mathbf{a} = (a_1, a_2, \dots, a_N)^T$ ,

$$Var[\mathbf{a}^T \mathbf{X}] = \mathbf{a}^T C_{\mathbf{X}} \mathbf{a} \tag{55}$$

• Linear transformation: Given linear transformation  $\mathbf{Y} = \mathbf{A}\mathbf{X} + \mathbf{b}$ ,

$$E[\mathbf{Y}] = \mathbf{A}E[\mathbf{X}] + \mathbf{b} \tag{56a}$$

$$C_{\mathbf{Y}} = \mathbf{A}C_{\mathbf{X}}\mathbf{A}^T \tag{56b}$$

• Uncorrelated variables

$$C_{\mathbf{X}} = \operatorname{diag}\left[\operatorname{Var}[X_1], \operatorname{Var}[X_2], \dots, \operatorname{Var}[X_N]\right]$$
 (57)

• Cross-covariance: For two random vectors  $\mathbf{X} \in \mathbb{R}^m$  and  $\mathbf{Y} \in \mathbb{R}^n$ , the resulting  $m \times n$  cross-covariance matrix is given by

$$Cov[\mathbf{X}, \mathbf{Y}] = C_{\mathbf{XY}}$$

$$= E[(\mathbf{X} - E[\mathbf{X}])(\mathbf{Y} - E[\mathbf{Y}])^{T}]$$

$$= E[\mathbf{XY}^{T}] - E[\mathbf{X}]E[\mathbf{Y}]^{T}$$

$$C_{\mathbf{YX}} = C_{\mathbf{XY}}^{T}$$
(59)

# 7.2 Relation Between Covariance Matrix & Auto-covariance

Given WSS process  $\mathbf{x}(t)$ , the corresponding correlation matrix of  $\mathbf{X} = [\mathbf{x}(t_1), \dots, \mathbf{x}(t_N)]^T$  is given by

$$R_{\mathbf{X}} = E\left[\mathbf{X}\mathbf{X}^T\right] \tag{60}$$

$$R_{\mathbf{X}}(i,j) = E\left[X_i X_i\right] = R_{\mathbf{x}} \left(|t_i - t_j|\right) \tag{61}$$

### 7.3 MMSE Linear Prediction

Mean square error (MSE) of predictor  $\hat{Y}$  is given by

$$mse = E[(Y - \hat{Y})^2] \tag{62}$$

 $\bullet$  Given two random variables, X, Y, and predictor

$$\hat{Y} = aX + b, (63)$$

minimum MSE (MMSE) predictor given X = x is

$$\hat{Y} = E[Y] + \frac{\operatorname{Cov}[X, Y]}{\operatorname{Var}[X]} (x - E[X])$$
(64)

• Given N samples of process  $\mathbf{x}[n]$ , and predictor

$$\hat{\mathbf{x}}[n+1] = \sum_{i=1}^{N} a_i \mathbf{x}[n-i+1], \tag{65}$$

the values of  $a_i$  are given by solution of

$$\begin{bmatrix} R_{\mathbf{x}}[0] & R_{\mathbf{x}}[1] & \cdots & R_{\mathbf{x}}[N-1] \\ R_{\mathbf{x}}[1] & R_{\mathbf{x}}[0] & \cdots & R_{\mathbf{x}}[N-2] \\ \vdots & \vdots & \ddots & \vdots \\ R_{\mathbf{x}}[N-1] & R_{\mathbf{x}}[N-2] & \cdots & R_{\mathbf{x}}[0] \end{bmatrix} \begin{bmatrix} a_1 \\ a_2 \\ \vdots \\ a_N \end{bmatrix} = \begin{bmatrix} R_{\mathbf{x}}[1] \\ R_{\mathbf{x}}[2] \\ \vdots \\ R_{\mathbf{x}}[N] \end{bmatrix}$$

$$(66)$$

and the resulting MMSE is

$$mmse = R_{\mathbf{x}}[0] - \sum_{i=1}^{N} a_i R_{\mathbf{x}}[i]$$

$$(67)$$

## 8 Gaussian Variables & Processes

### 8.1 Bi-variate & Multivariate Normal Distribution

Joint Gaussian distribution of  $X_1$  and  $X_2$ 

$$f_{X_1X_2}(x_1, x_2) = \frac{1}{2\pi\sigma_1\sigma_2\sqrt{1-\rho^2}} \exp\left(-\frac{1}{2(1-\rho^2)} \left[ \frac{(x_1-\mu_1)^2}{\sigma_1^2} + \frac{(x_2-\mu_2)^2}{\sigma_2^2} - \frac{2\rho(x_1-\mu_1)(x_2-\mu_2)}{\sigma_1\sigma_2} \right] \right)$$
(68)

Multivariate Gaussian distribution of  $\mathbf{X} = (X_1, X_2, \dots, X_N)^T$  is given by

$$f_{\mathbf{X}}(\mathbf{x}) = \frac{1}{(2\pi)^{N/2} \det\left[C_{\mathbf{X}}\right]} \exp\left\{-\frac{1}{2} \left(\mathbf{x} - \boldsymbol{\mu}\right)^T C_{\mathbf{X}}^{-1} \left(\mathbf{x} - \boldsymbol{\mu}\right)\right\},\tag{69}$$

Properties:

- Linear combination of Gaussian variables is Gaussian variable,
- Linear transformation follows Eqs. (56a).
- If jointly distributed Gaussian random variables are uncorrelated, they are also independent

#### 8.2 Gaussian Process

A Gaussian process  $\mathbf{x}(t)$  a random process that for  $\forall k > 0$  and for all times  $t_1, \ldots, t_k$ , the set of random variable  $\mathbf{x}(t_1), \ldots, \mathbf{x}(t_k)$  is jointly Gaussian (i.e. described by Eq. (69)).

Properties:

- WSS Gaussian process is SSS.
- Gaussian process  $\mathbf{x}(t)$  that passes through LTI system,  $\mathbf{y}(t) = h(t) * \mathbf{x}(t)$ , is also Gaussian process but with corresponding change in expectation and auto-covariance function.

## 9 Poisson Process

• The Poisson process, N(t), is described by

$$p(N(t) = k) = e^{-\lambda t} \frac{(\lambda t)^k}{k!}, \quad k = 0, 1, \dots$$
 (70a)  
 $p(N(0) = 0) = 0$  (70b)

$$E[N(t)] = \lambda t \tag{70c}$$

$$Var[N(t)] = \lambda t \tag{70d}$$

$$p(N(t) \leqslant k) = \sum_{i=0}^{k} p(N(t) = k)$$
 (70e)

• Independent & stationary increments: For any  $t_4 > t_3 \ge t_2 > t_1$  and random variables  $I_1, I_2$  defined by

$$I_1 = N(t_2) - N(t_1)$$
 (71a)

$$I_2 = N(t_4) - N(t_3)$$
 (71b)

(a)  $I_1$  and  $I_2$  are independent

- (b)  $t_2 t_1 = t_4 t_3 \Rightarrow I_1, I_2$  has the same distribution (stationary property)
- Time increment property

$$p(N(t_2) - N(t_1) = k) = p(N(t_2 - t_1) = k)$$
 (72)

• Joint PMF  $(t_2 > t_1)$ 

$$p(N(t_1) = i, N(t_2) = j) =$$

$$= p(N(t_1) = i) \cdot p(N(t_2 - t_1) = j - i)$$
 (73)

• Conditional probability

$$p(N(t_1) = i | N(t_2) = j) =$$

$$= \frac{p(N(t_1) = i, N(t_2) = j)}{p(N(t_2) = j)}$$
 (74)

- Special properties:
  - \* Given sum of two independent distributions  $X \sim \mathcal{P}(\lambda_1)$  and  $Y \sim \mathcal{P}(\lambda_2)$ , the resulting distribution is given by  $X + Y \sim \mathcal{P}(\lambda_1 + \lambda_2)$ .
  - Sub-group of Poisson process is Poisson process.
  - Sum of two Poisson processes  $\lambda_1$  and  $\lambda_2$  is Poisson process  $\lambda_1 + \lambda_2$  (but not a subtraction).

• Erlang: If  $X_i \sim Exp(\lambda)$  is time difference between events, then

$$T_k = \sum_{i=1}^k X_i \sim Erlang(k, \lambda)$$
 (75a)

$$E[T_k] = \frac{k}{\lambda} \tag{75b}$$

$$Var[T_k] = \frac{k}{\lambda^2} \tag{75c}$$

## 9.1 Campbell Theorem

Given

$$z(t) = \sum_{k=1}^{\infty} \delta(t - T_k)$$
 (76)

and casual system impulse response, h(t), the resulting process is given by

$$y(t) = z(t) * h(t) = \sum_{k=1}^{\infty} h(t - T_k)$$
 (77)

and the resulting statistics is given by

$$E[y(t)] = \lambda \int_{0}^{t} h(s)ds$$
 (78a)

$$\operatorname{Var}[y(t)] = \lambda \int_{0}^{t} h^{2}(s)ds \tag{78b}$$

## 10 Markov Chain

• Transition matrix

$$\mathbf{P} = \begin{bmatrix} p_{00} & p_{01} \\ p_{10} & p_{11} \end{bmatrix}, \tag{79}$$

where  $p_{ij} = p(\mathbf{x}[n] = j | \mathbf{x}[n-1] = i)$ 

• Chapman-Kolmogorov equation

$$\mathbf{p}^{T}[n_1 + n] = \mathbf{p}^{T}[n_1]\mathbf{P}^n, \tag{80}$$

where  $\mathbf{p}[n]$  is state probability vector

$$\mathbf{p}[n] = \begin{bmatrix} p_0[n] \\ p_1[n] \end{bmatrix} \tag{81}$$

and  $p_i[n] = p(\mathbf{x}[n] = i), i = 0, 1.$ 

• For general transition matrix of the form

$$\mathbf{P} = \begin{bmatrix} 1 - \alpha & \alpha \\ \beta & 1 - \beta \end{bmatrix} \tag{82}$$

$$\mathbf{P}^{n} = \begin{bmatrix} \frac{\beta}{\alpha + \beta} & \frac{\alpha}{\alpha + \beta} \\ \frac{\beta}{\alpha + \beta} & \frac{\alpha}{\alpha + \beta} \end{bmatrix} + \\ + (1 - \alpha - \beta)^{n} \begin{bmatrix} \frac{\alpha}{\alpha + \beta} & -\frac{\alpha}{\alpha + \beta} \\ -\frac{\beta}{\alpha + \beta} & \frac{\beta}{\alpha + \beta} \end{bmatrix}$$
(83)

• Steady-state probability vector

$$\boldsymbol{\pi}^T = \begin{bmatrix} \pi_0 & \pi_1 \end{bmatrix}, \tag{84}$$

where  $\pi_i = \lim_{n \to \infty} p(\mathbf{x}[n] = i), i = 0, 1$ 

## 10.1 Ergodic Markov chain

For  $\mathbf{P}^n > 0$ .

$$\boldsymbol{\pi}^T = \boldsymbol{\pi}^T \mathbf{P} \tag{85}$$

Average number of time-steps to return to state i from the last occurrence of state i is  $1/\pi_i$ .

## 11 Different Supplementary Formulas

### 11.1 Derivatives

$$\frac{d}{dx}x^n = nx^{n-1}$$

$$\frac{d}{dx}\exp[f(x)] = \exp[f(x)]\frac{d}{dx}f(x)$$

## 11.2 Integrals

### 11.2.1 Indefinite

$$\int x^n dx = \frac{1}{n+1} x^{n+1}, \ n \neq -1$$

$$\int \exp(ax) dx = \frac{1}{a} \exp(ax)$$

$$\int x \exp(ax) dx = \exp(ax) \left[ \frac{x}{a} - \frac{1}{a^2} \right]$$

$$\int x^2 \exp(ax) dx = \exp(ax) \left[ \frac{x^2}{a} - \frac{2x}{a^2} + \frac{2}{a^3} \right]$$

$$\int \frac{1}{a^2 + x^2} dx = \frac{1}{a} \tan^{-1} \frac{x}{a}$$

#### 11.2.2 Definite

$$\int_0^\infty \exp(-a^2 x^2) dx = \frac{\sqrt{\pi}}{2a}$$
$$\int_0^\infty x^2 \exp(-a^2 x^2) dx = \frac{\sqrt{\pi}}{4a^3}$$
$$\int_{-\infty}^\infty \delta(x) dx = 1$$
$$\int_{-\infty}^\infty f(x) \delta(x - a) dx = f(a)$$

### 11.3 Fourier Transform

### 11.3.1 Properties

$$\frac{d^n}{dt^n}f(t) \stackrel{\mathscr{F}}{\Longleftrightarrow} (j2\pi f)^n F(f)$$

$$f(-t) \stackrel{\mathscr{F}}{\Longleftrightarrow} F^*(f)$$

$$f(t-t_0) \stackrel{\mathscr{F}}{\Longleftrightarrow} F(f)e^{-j2\pi ft_0}$$

$$f(t)e^{j2\pi f_0 t} \stackrel{\mathscr{F}}{\Longleftrightarrow} F(f-f_0)$$

#### 11.3.2 Transform

$$u(t) \stackrel{\mathscr{F}}{\Longleftrightarrow} \frac{1}{2} \left( \frac{1}{j\pi f} + \delta(f) \right)$$

$$\exp(-at)u(t) \stackrel{\mathscr{F}}{\Longleftrightarrow} \frac{1}{a + j2\pi f}$$

$$t \exp(-at)u(t) \stackrel{\mathscr{F}}{\Longleftrightarrow} \frac{1}{(a + j2\pi f)^2}$$

$$\exp(-a|t|) \stackrel{\mathscr{F}}{\Longleftrightarrow} \frac{2a}{a^2 + 4\pi^2 f^2}$$

$$\exp(-at^2) \stackrel{\mathscr{F}}{\Longleftrightarrow} \sqrt{\frac{\pi}{a}} \exp\left(-\frac{(\pi f)^2}{a}\right)$$

$$\cos(2\pi f_a t) \stackrel{\mathscr{F}}{\Longleftrightarrow} \frac{1}{2} \left[\delta(f - f_a) + \delta(f + f_a)\right]$$

$$\sin(2\pi f_a t) \stackrel{\mathscr{F}}{\Longleftrightarrow} \frac{1}{2i} \left[\delta(f - f_a) - \delta(f + f_a)\right]$$

## 11.4 Trigonometry

$$\sin^{2}(\alpha) = \frac{1}{2} (1 - \cos(2\alpha))$$

$$\cos^{2}(\alpha) = \frac{1}{2} (1 + \cos(2\alpha))$$

$$\cos(\alpha)\cos(\beta) = \frac{1}{2} [\cos(\alpha + \beta) + \cos(\alpha - \beta)]$$

$$\sin(\alpha)\sin(\beta) = \frac{1}{2} [\cos(\alpha - \beta) - \cos(\alpha + \beta)]$$

$$\sin(\alpha)\cos(\beta) = \frac{1}{2} [\sin(\alpha - \beta) + \sin((\alpha + \beta))]$$

#### 11.5 Matrices

$$A = \begin{bmatrix} a & b \\ c & d \end{bmatrix}, \quad \det[A] = ad - bc$$

$$A^{-1} = \frac{1}{ad - bc} \begin{bmatrix} d & -b \\ -c & a \end{bmatrix}$$