

המחלקה להנדסת חשמל ואלקטרוניקה

תאריך הבחינה: 1.2.17

שעות הבחינה: 30-16:30

מבוא לאותות אקראיים

מועד אי

דייר דימה בחובסקי

תשעייז סמסטר אי

חומר עזר - עד 4 דפי נוסחאות אישיים (משני צדדים), מחשבון הוראות מיוחדות:

- השאלון כולל 3 שאלות ללא בחירה, סך הכל של 110 נקודות.
- יש לציין באופן מלא וברור את שלבי הפתרון. תשובה ללא הסבר לא תתקבלנה.
 - אם לא מצויין אחרת, הסעיפים הם בעלי ניקוד זהה.

השאלון כולל 9 דפים (כולל דף זה)

בהצלחה!



1 מסנן מתואם (30 נק')

נתון אות דטרמיניסטי u(t)=u(t) [$\exp{(-\alpha t)}-\exp{(-\alpha \beta t)}$] נתון אות דטרמיניסטי $S_n(f)=N_0/2$ כאשר פקטראלית פקטראלית בעל צפיפות הספק בעל צפיפות הספק הספקטראלית נוסף בעל אוסי בעל צפיפות הספק

- h(t) , מהו מסנן המתואם עבור האות. 1
- t_0 מהו הספק האות במוצא המסנן בזמן .2
- 3. מהו הספק הרעש במוצא המסנן ? מהו SNR המתקבל?

2 תכונות ומאפיינים של תהליכים אקראיים (50 נק')

 $X(t)=At^2, Y(t)=A^2t^2$: נתונים תהליכים אקראיים

 $A \sim U[0,1]$, הינו משתנה אקראי המתפלג אחיד, A כאשר

: חשב

- E[X(t)] .1
- $R_x(t_1, t_2)$.2

האם התהליך X(t) הוא סטציואנריי

- E[Y(t)] .3
- $R_{xy}(t,t+ au),C_{xy}(t,t+ au)$.4

י פטציאונריים פאטאירים אונריים מטציאונריים אונריים א

$$p(Y(t) > 3|X(t) = 2)$$
 .5

30) תהליכים סטציאונריים – גוזר (30 נק')

$$.Y(t)=rac{d}{dt}X(t)$$
 נתון גוזר,

 $E[X(t)] = 0, R_x(au) = \sigma_x^2 e^{-lpha^2 au^2}$ הכניסה היא תהליך אקראי גאוסי בעל

:חשב



$$R_{xy}(t,t+\tau)$$
 .1

י פטציאונריים פטציאונריים אונריים או

- $.P_u$ הספק.

4 נוסחאות שימושיות

מסויים 4.2.2

4.1 נגזרת

(9)
$$\int_0^\infty \exp(-a^2x^2) dx = \frac{\sqrt{\pi}}{2a}$$
 (10)
$$\int_0^\infty x^2 \exp(-a^2x^2) dx = \frac{\sqrt{\pi}}{4a^3}$$

4.3 התמרות פוריה

4.3.1 תכונות

$$\frac{d}{dx}x^n = nx^{n-1}$$

(2)
$$\frac{d}{dx}\exp(x) = \exp(x)$$

(3)
$$\frac{d}{dx}\exp(f(x)) = f'(x)\exp(ax)$$

(11) $\frac{d^n}{dt^n}f(t) \stackrel{\mathscr{F}}{\Longleftrightarrow} (j2\pi f)^n F(f)$

(12)

....

(13)
$$u(t) \stackrel{\mathscr{F}}{\Longleftrightarrow} \frac{1}{2} \left(\frac{1}{j\pi f} + \delta(f) \right)$$

(14)
$$\exp(-at)u(t) \stackrel{\mathscr{F}}{\Longleftrightarrow} \frac{1}{a+j2\pi f}$$

(15)
$$t \exp(-at)u(t) \stackrel{\mathscr{F}}{\Longleftrightarrow} \frac{1}{(a+j2\pi f)^2}$$

(16)
$$\exp(-a|t|) \stackrel{\mathscr{F}}{\Longleftrightarrow} \frac{2a}{a^2 + 4\pi^2 f^2}$$

(17)
$$\exp(-at^2) \stackrel{\mathscr{F}}{\Longleftrightarrow} \sqrt{\frac{\pi}{a}} \exp\left(-\frac{(\pi f)^2}{a}\right)$$

$$\int \exp(-ax)dx = \frac{1}{a}\exp(-ax)$$

(6)
$$\int x \exp(-ax) dx = \exp(-ax) \left[\frac{x}{a} - \frac{1}{a^2} \right]$$

$$\int x^2 \exp(-ax) dx = \exp(-ax) \left[\frac{x^2}{a} - \frac{2x}{a^2} - \frac{2}{a^3} \right]$$

(8)
$$\int \frac{1}{a^2 + x^2} dx = \frac{1}{a} \tan^{-1} \frac{x}{a}$$

Random Processes – Formulas

1 Random Variables

1.1 Distributions

	Notation	PDF/PMF	CDF	E[X]	Var[X]
Uniform	U[a,b]	$\frac{1}{b-a}, a \leqslant x \leqslant b$	$\begin{cases} 0 & x < a \\ \frac{x-a}{b-a} & a \le x \le b \\ 1 & b < x \end{cases}$	$\frac{a+b}{2}$	$\frac{(b-a)^2}{12}$
Normal	$N(\mu,\sigma^2)$	$\frac{1}{\sqrt{2\pi}\sigma}e^{-\frac{(x-\mu)^2}{2\sigma^2}}$	$\Phi(x)$	μ	σ^2
Exponential	$Exp(\lambda)$	$\lambda e^{-\lambda x}, x \geqslant 0$	$1 - e^{-\lambda x}$	$1/\lambda$	$1/\lambda^2$
Poisson	$\mathcal{P}(\lambda)$	$p(X = k) = \lambda^k \frac{e^{-\lambda}}{k!}$	$e^{-\lambda} \sum_{i=0}^{k} \frac{\lambda^i}{i!}$	λ	λ
Erlang	$Erlang(k, \lambda t)$	$\lambda \frac{(\lambda t)^{k-1}}{(k-1)!} e^{-\lambda t}$	$1 - \sum_{n=0}^{k-1} \frac{(\lambda t)^n}{n!} e^{-\lambda t}$	$k/\lambda t$	$k/(\lambda t)^2$

Special properties:

- Given sum of two independent distributions $X \sim \mathcal{P}(\lambda_1)$ and $Y \sim \mathcal{P}(\lambda_2)$, the resulting distribution is given by $X + Y \sim \mathcal{P}(\lambda_1 + \lambda_2)$.
- If $X_i \sim Exp(\lambda)$ then $\sum_{i=1}^k X_i \sim Erlang(k, \lambda)$.

1.2 Properties

Definitions:

$$F_X(x) = p(X \leqslant x)$$
 (1a)

$$f_X(x) = \frac{\partial F_X(x)}{\partial x}$$
 (1b)

$$F_X(x) = \int_{-\infty}^x f_X(p) \, dp \tag{1c}$$

Expectation

$$E[X] = \begin{cases} \int_{-\infty}^{\infty} x f_X(x) dx \\ \sum_i x_i p(X = x_i) \end{cases}$$
 (2a)

$$E[X] = \begin{cases} \int_{-\infty}^{\infty} x f_X(x) dx \\ \sum_i x_i p(X = x_i) \end{cases}$$

$$E[g(X)] = \begin{cases} \int_{-\infty}^{\infty} g(x) f_X(x) dx \\ \sum_i g(x_i) p(X = x_i) \end{cases}$$
(2a)

$$E[aX] = aE[x] \tag{2c}$$

Variance

$$Var[X] = E[(X - E[X])^{2}]$$

$$= E[X^{2}] - E^{2}[X]$$
 (3a)

$$Var[aX + b] = a^2 Var[X]$$
 (3b)

2 Two Random Variables

2.1 Joint Distributions

Definitions:

$$F_{XY}(x,y) = p(X \leqslant x, Y \leqslant y) \tag{4a}$$

$$f_{XY}(x,y) = \frac{\partial^2 F_{XY}(x,y)}{\partial x \partial y}$$
 (4b)

$$F_{XY}(x,y) = \int_{-\infty}^{x} \int_{-\infty}^{y} f_{XY}(s,p) \, dp \, ds \qquad (4c)$$

Conditional distribution:

$$f_{Y|X}(y|x) = \frac{f_{XY}(x,y)}{f_X(x)}, \ f_X(x) > 0$$
 (5a)

$$p(Y = y_j | X = x_k) = \frac{p(Y = y_j, X = x_k)}{p(X = x_k)}, \ p(X = x_k) > 0$$
(5b)

Expectation:

$$E[XY] = \int xy f_{XY}(x, y) dx dy$$
 (6a)

$$E[g(X,Y)] = \int g(x,y)f_{XY}(x,y)dxdy \qquad (6b)$$

$$E[X+Y] = E[X] + E[Y] \tag{6c}$$

Conditional expectation & Variance:

$$E[Y|X] = \begin{cases} \int y f_{Y|X}(y|x) dx dy \\ \sum_{k} y_{k} p(Y = y_{k}|X = x_{j}) \end{cases}$$
 (7a)

$$E[X] = E[E[X|Y]] \tag{7b}$$

$$Var[Y|X] = E[Y^2|X] - E^2[Y|X]$$
 (7c)

$$Var[Y] = Var[E[Y|X]] + E[Var[Y|X]]$$
 (7d)

Independent random variables:

$$f_{XY}(x,y) = f_X(x)f_Y(y) \tag{8a}$$

$$F_{XY}(x,y) = F_X(x)F_Y(y) \tag{8b}$$

$$E[XY] = E[X]E[Y] \tag{8c}$$

$$Var[X + Y] = Var[X] + Var[Y]$$
 (8d)

Marginal distribution:

$$f_X(x) = \int_{-\infty}^{\infty} f_{XY}(x, y) dy$$
 (9a)

$$f_Y(y) = \int_{-\infty}^{\infty} f_{XY}(x, y) dx$$
 (9b)

$$F_X(x) = F_{XY}(x, \infty) \tag{9c}$$

$$F_Y(y) = F_{XY}(\infty, y) \tag{9d}$$

2.2 Correlation, Covariance & Correlation Coefficient

• For two jointly-distributed random variables *X* and *Y*, covariance is given by

$$Cov[X, Y] = E[(X - E[X])(Y - E[Y])]$$

= $E[XY] - E[X]E[Y].$ (10)

Main covariance properties are:

$$Cov[X, X] = Var[X]$$
 (11a)

$$Cov[X, Y] = Cov[Y, X]$$
 (11b)

$$Cov[X, a] = 0 (11c)$$

$$Cov[aX, bY] = ab Cov[X, y]$$
 (11d)

$$Cov[X + a, Y + b] = Cov[X, Y]$$
(11e)

$$Cov[X + Y, Z] = Cov[X, Z] + Cov[Y, Z]$$
(11f)

$$Var[X + Y] = Var[X] + Var[Y] + 2 Cov[X, Y]$$
(11g)

• Correlation coefficient (also termed as Pearson product-moment correlation coefficient) is given by

$$\rho_{XY} = \frac{\text{Cov}[X, Y]}{\sqrt{\text{Var}[X] \text{Var}[Y]}}$$
(12)

such that $|\rho_{XY}| \leq 1$.

• For two random vectors $\mathbf{X} \in \mathbb{R}^m$ and $\mathbf{Y} \in \mathbb{R}^n$, the resulting $m \times n$ covariance matrix is given by

$$Cov[\mathbf{X}, \mathbf{Y}] = C_{\mathbf{XY}}$$

$$= E[(\mathbf{X} - E[\mathbf{X}])(\mathbf{Y} - E[\mathbf{Y}])^{T}]$$

$$= E[\mathbf{XY}^{T}] - E[\mathbf{X}]E[\mathbf{Y}]^{T}$$
(13)

2.3 Relations

- When X and Y are orthogonal, E[XY] = 0.
- When X and Y are uncorrelated, $Cov[X, Y] = \rho_{XY} = 0$.
- When X and Y are *independent*, they are also uncorrelated (see also Eqs. 8).
- When X and Y are jointly Gaussian and uncorrelated $\Longrightarrow X$ and Y are independent.

2.4 Bi-variate & Multivariate Normal Distribution

Joint Gaussian distribution of X_1 and X_2

$$f_{X_1X_2}(x_1, x_2) = \frac{1}{2\pi\sigma_1\sigma_1\sqrt{1-\rho^2}} \exp\left(-\frac{1}{2(1-\rho^2)} \times \left[\frac{(x_1-\mu_1)^2}{\sigma_1^2} + \frac{(x_2-\mu_2)^2}{\sigma_2^2} - \frac{2\rho(x_1-\mu_1)(x_2-\mu_2)}{\sigma_1\sigma_2}\right]\right)$$
(14)

Multivariate Gaussian distribution of $\mathbf{X} = (X_1, X_2, \dots, X_n)$ is given by

$$f_{\mathbf{X}}(\mathbf{x}) = \frac{1}{2\pi \det \left[\mathbf{C}_{\mathbf{X}} \right]} \exp \left\{ -\frac{1}{2} \left(\mathbf{x} - \boldsymbol{\mu} \right)^T \mathbf{C}_{\mathbf{X}}^{-1} \left(\mathbf{x} - \boldsymbol{\mu} \right) \right\}, \tag{15}$$

3 Signal Characterization

3.1 Auto-signal

• Average:

$$E[x(t)] = \int_{-\infty}^{\infty} x f_x(x;t) dx$$
 (16)

• Variance:

$$Var[x(t)] = E[x^{2}(t)] + E^{2}[x(t)]$$
 (17)

• Auto-correlation

$$R_x(t_1, t_2) = E[x(t_1)x(t_2)]$$
 (18a)

$$R_x(t_1, t_2) = R_x(t_2, t_1)$$
 (18b)

$$R_x(t,t) = E[x^2(t)] \tag{18c}$$

• Auto-covariance

$$C_x(t_1, t_2) = E[x(t_1)x(t_2)] - E[x(t_1)]E[x(t_2)]$$
(19a)

$$C_x(t,t) = Var[x(t)] \tag{19b}$$

• Correlation Coefficient

$$\rho_x(t_1, t_2) = \frac{C_x(t_1, t_2)}{\sqrt{C_x(t_1, t_1)C_x(t_2, t_2)}}$$
 (20a)

$$|\rho_x(t_1, t_2)| \leqslant 1 \tag{20b}$$

- When $x(t_1)$ and $x(t_2)$ are orthogonal, $R_x(t_1, t_2) = 0$.
- When $x(t_1)$ and $x(t_2)$ are uncorrelated, $C_x(t_1, t_2) = \rho_x(t_1, t_2) = 0$.
 - When $x(t_1)$ and $x(t_2)$ are independent, $R_x(t_1, t_2) = E[x(t_1)]E[x(t_2)].$

3.2 Cross-Signal

• Cross-correlation

$$R_{xy}(t_1, t_2) = E[x(t_1)y(t_2)] \tag{21}$$

• Cross-covariance

$$C_{xy}(t_1, t_2) = R_{xy}(t_1, t_2) - E[x(t_1)]E[y(t_2)]$$
(22)

• Correlation Coefficient

$$\rho_{xy}(t_1, t_2) = \frac{C_{xy}(t_1, t_2)}{\sqrt{C_{xy}(t_1, t_1)C_{xy}(t_2, t_2)}}$$
 (23)

4 Wide-Sense Stationary (WSS) Process

Definition:

$$E[x(t)] = E[x(0)] = m_x = \text{const}$$
(24a)

$$R_x(t_1, t_2) = R_x(0, \tau) = R_x(\tau), \quad \tau = t_2 - t_1, \quad \forall t_1, t_2$$
 (24b)

4.1 Auto-signal

• Auto-correlation

$$R_x(\tau) = E[x(t)x^*(t+\tau)] = E[x(t-\tau)x^*(t)]$$
(25)

Properties:

$$R_x(-\tau) = R_x(\tau) \tag{26a}$$

$$R_x(0) = E[|x(0)|^2] = E[|x(t)|^2]$$
 (26b)

$$Var[x(t)] = C_x(0) = \sigma_x^2$$
 (26c)

$$|R_x(0)| \geqslant R_x(\tau) \tag{26d}$$

Deterministic definition

$$R_x(\tau) = x(\tau) * x^*(-\tau) \tag{27}$$

• Auto-covariance

$$C_x(\tau) = R_x(\tau) - m_x^2 \tag{28}$$

• Correlation Coefficient

$$\rho_x(\tau) = \frac{C_x(\tau)}{C_x(0)} \tag{29}$$

• Power spectral density (PSD)

$$S_x(f) = \mathcal{F}\left\{R_x(\tau)\right\} \tag{30}$$

Properties:

$$S_x(f) = S_x(-f) \tag{31a}$$

$$S_x(f) \geqslant 0, \ \forall f$$
 (31b)

$$S_x(f) \in \mathbb{R}$$
 (real numbers) (31c)

Average power

$$P_x = E[x^2(t)] = R_x(0) = \int_{-\infty}^{\infty} S_x(f)df$$
 (32)

Deterministic $X(f) = \mathcal{F}\{x(t)\}, X^*(f) = \mathcal{F}\{x^*(-\tau)\}\ definition$

$$S_x(f) = X(f)X^*(f) = |X(f)|^2$$
 (33)

4.2 Cross-signal

• Cross-correlation

$$R_{xy}(\tau) = E[x(t)y^*(t+\tau)] \tag{34}$$

Properties

$$R_{xy}(\tau) = R_{yx}^*(-\tau) \tag{35a}$$

$$|R_{xy}(\tau)| \leqslant \sqrt{R_x(0)R_y(0)} \tag{35b}$$

$$|R_{xy}(\tau)| \le \frac{1}{2} [R_x(0) + R_y(0)]$$
 (35c)

Deterministic definition

$$R_{xy}(\tau) = x(\tau) * y^*(-\tau) \tag{36}$$

• Cross-covariance

$$C_{xy}(\tau) = R_{xy}(\tau) - m_x m_y \tag{37}$$

• Cross-PSD

$$S_{xy}(f) = \mathcal{F}\left\{R_{xy}(\tau)\right\} \tag{38}$$

Properties

$$S_{xy}(f) = S_{yx}(-f) = S_{xy}^*(-f)$$
 (39)

Deterministic definition

$$S_{xy}(f) = X(f)Y^*(f)$$
 (40)

4.3 White Noise Process

White noise process, n(t), is WSS process that is characterized by

$$R_n(\tau) = \sigma^2 \delta(\tau) \tag{41a}$$

$$S_n(f) = \sigma^2 \tag{41b}$$

5 LTI and WSS Random Process

For LTI system with impulse response h(t)

$$y(t) = x(t) * h(t)$$
(42)

Average

$$m_y = m_x \int_{-\infty}^{\infty} h(s)ds = m_x H(f=0)$$
 (43)

5.1 Cross-correlation & cross-covariance

$$R_{xy}(\tau) = R_x(\tau) * h(\tau) \tag{44a}$$

$$C_{xy}(\tau) = C_x(\tau) * h(\tau)$$
(44b)

$$R_{yx}(\tau) = R_x(\tau) * h^*(-\tau)$$
 (44c)

$$C_{ux}(\tau) = C_x(\tau) * h^*(-\tau)$$
(44d)

$$R_y(\tau) = R_x(\tau) * h(\tau) * h^*(-\tau)$$
 (44e)

$$C_y(\tau) = C_x(\tau) * h(\tau) * h^*(-\tau)$$
(44f)

5.2 Power-Spectral Density (PSD) & Cross-PSD

Given frequency response $H(f) = \mathcal{F}\{h(\tau)\}, H^*(f) = \mathcal{F}\{h^*(-\tau)\}$

$$S_{xy}(f) = S_x(f) H(f)$$
(45a)

$$S_{yx}(f) = S_x(f) H^*(f)$$

$$(45b)$$

$$S_{yy}(f) = S_x(f) H(f) H^*(f) = S_x(f) |H(f)|^2$$
(45c)

Power of the process:

$$P_x = R_x(0) = \int_{-\infty}^{\infty} S_x(f) df$$
 (46a)

$$P_y = R_y(0) = \int_{-\infty}^{\infty} S_x(f) |H(f)|^2 df$$
 (46b)

6 Filtering of WSS Process

6.1 SNR

For an input

$$x(t) = s(t) + n(t), \tag{47}$$

where signal s(t) and noise n(t) are independent and E[n(t)] = 0, and output y(t)

$$S_y(f) = S_x(f) |H(f)|^2 = S_s(f) |H(f)|^2 + S_n(f) |H(f)|^2,$$
(48)

where $S_s(f) |H(f)|^2$ is signal output PSD and $S_n(f) |H(f)|^2$ is noise PSD.

The input and output SNRs is given by

$$SNR_x = \frac{E[s^2(t)]}{E[n^2(t)]} = \frac{R_{ss}(0)}{R_{nn}(0)} = \frac{\int S_{ss}(f)df}{\int S_{nn}(f)df}$$
(49a)

$$SNR_{y} = \frac{\int S_{ss}(f |H(f)|^{2} df}{\int S_{nn}(f) |H(f)|^{2} df}.$$
 (49b)

6.2 Match Filter

The goal of filter h(t) is to provide maximum SNR at time $t = t_0$ for deterministic signal x(t) and noise n(t). For white noise, n(t), with $S_N(f) = N_0/2$, the filter is given by

$$H_{\rm mf}(f) = X^*(f)e^{-j2\pi f t_0} \longleftrightarrow h_{\rm mf}(t) = x(t_0 - t) \tag{50}$$

and the resulting maximum SNR is given by

$$SNR_{\text{max}} = \frac{2}{N_0} \int_{-\infty}^{\infty} |X(f)|^2 df = \frac{2E_x}{N_0}$$
 (51)

7 Poisson Process

The Poisson process, N(t), is described by

$$p(N(t) = k) = e^{\lambda t} \frac{(\lambda t)^k}{k!}, \quad k = 0, 1, \dots$$
 (52)

Time increment property

$$N(t_2) - N(t_1) = N(t_2 - t_1)$$
(53)

7.1 Campbell Theorem

Given the relation

$$y(t) = \sum_{k=1}^{\infty} g(t - t_k)$$

$$\tag{54}$$

where t_k are Poisson event times and g(t) is casual system impulse response, resulting statistics is given by

$$E[y] = \lambda \int_{0}^{\infty} g(u)du \tag{55a}$$

$$Var[y] = \lambda^2 \int_{0}^{\infty} g^2(u) du$$
 (55b)