

המחלקה להנדסת חשמל ואלקטרוניקה

תאריך הבחינה : 23.02.20  
שעות הבחינה : 13:30-16:30

## מבוא לאותות אקראיים

מועד ב'

ד"ר דימה בחובסקי

תשע"ט סמסטר א'

חומר עזר - דף נוסחאות אישי (משני צדדים), מחשבון  
הוראות מיוחדות :

- סעיפים הם בעלי ניקוד זהה, אלא אם צוין אחרת.
- יש לציין באופן מלא וברור את שלבי הפתרון. תשובה ללא הסבר לא תתקבלנה.
- במקום בו נדרש חישוב מספרי, יש קודם לרשום את הנוסחא, ורק אח"כ להציב!
- יש לציין יחידות למספרים, ובמידה וקיימות!
- כל השרטוטים יהיו גדולים, ברורים, עם סימון צירים!
- אין חובה להגיע לערך מספרי של הפונקציה  $Q(x)$ , במידה ומופיעה בתשובה.

השאלון כולל 10 דפים (כולל דף זה)

בהצלחה !

## 1 קשר בין משתנים (15 נק')

נתונים קשרים הבאים בין המשתנים  $X, Y$  :

- (1)  $\text{Var}[X + 2Y] = 40$
- (2)  $\text{Var}[X - 2Y] = 20$
- (3)  $\text{Var}[X] = \text{Var}[Y]$

חשב מספרית את כל האיברים של מטריצת covariance בין המשתנים  $X, Y$ .

## 2 תהליכים בזמן רציף (90 נק')

נתונים תהליכים  $\mathbf{x}(t), \mathbf{y}(t)$

$\mathbf{x}(t)$  בעל מאפיינים הבאים :

• גאוס

• סטציאונרי

$$E[\mathbf{x}(t)] = 0$$

$$R_{\mathbf{x}}(\tau) = \exp\left(-\frac{|\tau|}{4}\right)$$

$$\mathbf{y}(t) = \mathbf{x}(t) + \cos(2\pi 30t)$$

1. חשב הספק הממוצע של  $\mathbf{x}(t)$ .

2. חשב הספק ממוצע של  $\mathbf{x}(t)$  עבור תחום תדרים של  $|F| < 4\text{Hz}$ .

3. חשב הסתברות  $\Pr(\mathbf{x}(1) > 3)$ .

4. חשב הסתברות  $\Pr(\mathbf{x}(0) + \mathbf{x}(1) > 3)$ .

5. חשב  $\text{Var}[\mathbf{y}(t)]$  והספק ממוצע של  $\mathbf{y}(t)$ .

6. חשב  $R_{\mathbf{y}}(\tau), E[\mathbf{y}(t)]$ . האם מדובר בתהליך WSS?

# Random Processes – Formulas

## 1 Distributions

### 1.1 Continuous

	Notation	PDF	CDF	$E[X]$	$\text{Var}[X]$
Uniform	$U[a, b]$	$\begin{cases} \frac{1}{b-a} & a \leq x \leq b \\ 0 & \text{otherwise} \end{cases}$	$\begin{cases} 0 & x < a \\ \frac{x-a}{b-a} & a \leq x \leq b \\ 1 & b < x \end{cases}$	$\frac{a+b}{2}$	$\frac{(b-a)^2}{12}$
Normal	$N(\mu, \sigma^2)$	$\frac{1}{\sigma\sqrt{2\pi}} \exp\left[-\frac{(x-\mu)^2}{2\sigma^2}\right]$	$\Phi(x)$	$\mu$	$\sigma^2$
Exponential	$Exp(\lambda)$	$\lambda \exp(-\lambda x), x \geq 0$	$1 - \exp(-\lambda x)$	$1/\lambda$	$1/\lambda^2$

#### 1.1.1 Q-function

Given  $Y \sim N(\mu, \sigma^2)$

$$p(Y > y) = Q\left(\frac{y-\mu}{\sigma}\right) \quad (1a)$$

$$Q(x) = 1 - \Phi(x) \quad (1b)$$

$$Q(-x) = 1 - Q(x) \quad (1c)$$

$$Q(x) = \frac{1}{\sqrt{2\pi}} \int_x^\infty \exp\left(-\frac{s^2}{2}\right) ds. \quad (2)$$

### 1.2 Discrete

	Notation	PMF	CDF	$E[X]$	$\text{Var}[X]$
Bernoulli	$\text{Ber}(p)$	$\begin{cases} 1-p & k=0 \\ p & k=1 \end{cases}$	$\begin{cases} 0 & x < 0 \\ 1-p & 0 \leq x < 1 \\ 1 & 1 \leq x \end{cases}$	$p$	$p(1-p)$

## 2 Random Variables

Definitions:

$$F_X(x) = p(X \leq x) \quad (3a)$$

$$f_X(x) = \frac{\partial F_X(x)}{\partial x} \geq 0 \quad (3b)$$

$$F_X(x) = \int_{-\infty}^x f_X(p) dp \quad (3c)$$

$$p(a < X \leq b) = F_X(b) - F_X(a) \quad (3d)$$

$$f_X(x) \geq 0 \quad (3e)$$

$$\int_{-\infty}^{\infty} f_X(x) dx = 1 \quad (3f)$$

$$p_X[x_k] = \Pr[X = x_k] \quad (4a)$$

$$0 \leq p_X[x_i] \leq 1 \quad \forall i \quad (4b)$$

$$\sum_i p_X[x_i] = 1 \quad (4c)$$

$$F_X(x) = \Pr(X \leq x), \quad x \in \mathbb{R} \quad (4d)$$

$$F_X(x) = \sum_{k: x_k \leq x} p_X[x_k] \quad (4e)$$

Expectation:

$$E[X] = \begin{cases} \int_{-\infty}^{\infty} x f_X(x) dx \\ \sum_i x_i p_X[x_i] \end{cases} \quad (5a)$$

$$E[g(X)] = \begin{cases} \int_{-\infty}^{\infty} g(x) f_X(x) dx \\ \sum_i g(x_i) p_X[x_i] \end{cases} \quad (5b)$$

$$E[aX + b] = aE[X] + b \quad (5c)$$

Variance:

$$\begin{aligned} \text{Var}[X] &= E[(X - E[X])^2] \\ &= E[X^2] - E^2[X] \end{aligned} \quad (6a)$$

$$\text{Var}[aX + b] = a^2 \text{Var}[X] \quad (6b)$$

$$\text{Var}[b] = 0 \quad (6c)$$

## 3 Two Random Variables

### 3.1 Joint Distributions

Definitions:

$$F_{XY}(x, y) = p(X \leq x, Y \leq y) \quad (7a)$$

$$f_{XY}(x, y) = \frac{\partial^2 F_{XY}(x, y)}{\partial x \partial y} \geq 0 \quad (7b)$$

$$F_{XY}(x, y) = \int_{-\infty}^x \int_{-\infty}^y f_{XY}(s, p) dp ds \quad (7c)$$

$$p[x_j, y_k] = p(X = x_j, Y = y_k) \quad (8a)$$

$$F_{XY}(x, y) = p(X \leq x_j, Y \leq y_k) \quad (8b)$$

Expectation:

$$E[g(X, Y)] = \begin{cases} \iint g(x, y) f_{XY}(x, y) dx dy \\ \sum_i \sum_k g(x_i, y_k) p_X[x_i, y_k] \end{cases} \quad (9a)$$

$$E[aX + bY] = aE[X] + bE[Y] \quad (9b)$$

For **independent** random variables:

$$f_{XY}(x, y) = f_X(x) f_Y(y) \quad (10a)$$

$$p_{XY}[x_k, y_j] = p_X[x_k] p_Y[y_j] \quad (10b)$$

$$F_{XY}(x, y) = F_X(x) F_Y(y) \quad (10c)$$

$$E[XY] = E[X]E[Y] \quad (10d)$$

$$E[g_1(X)g_2(Y)] = E[g_1(X)]E[g_2(Y)] \quad (10e)$$

$$\text{Var}[aX + bY] = a^2 \text{Var}[X] + b^2 \text{Var}[Y] \quad (10f)$$

Marginal distribution:

$$f_X(x) = \int_{-\infty}^{\infty} f_{XY}(x, y) dy \quad (11a)$$

$$p_X[x_k] = \sum_j p_{XY}[x_k, y_j] \quad (11b)$$

$$F_X(x) = F_{XY}(x, \infty) \quad (11c)$$

$$F_Y(y) = F_{XY}(\infty, y) \quad (11d)$$

### 3.2 Conditional Relations

Conditional distribution (Bayes),  
for  $f_X(x), f_Y(y), p_X[x_k], p_Y[y_k] > 0$ :

$$f_{Y|X}(y|x) f_X(x) = f_{X|Y}(x|y) f_Y(y) = f_{XY}(x, y) \quad (12a)$$

$$p_{Y|X}[y_j|x_k] p_X[x_k] = p_{X|Y}[x_k|y_j] p_Y[y_j] = p_{XY}[x_k, y_j] \quad (12b)$$

$$F_{Y|X}(y|x) = p(Y \leq y | X = x) \quad (12c)$$

$$= \int_{-\infty}^y f_{Y|X}(s|x) ds \quad (12d)$$

$$F_{Y|X}[y|x_k] = \frac{p[Y \leq y_j, X = x_k]}{p_X[x_k]} \quad (12e)$$

Conditional expectation & Variance:

$$E[Y|X] = \begin{cases} \int y f_{Y|X}(y|x) dy \\ \sum_j y_j p[y_j|x_k] \end{cases} \quad (13a)$$

$$E[X] = E[E[X|Y]] = \iint y f_{Y|X}(y|x) f_X(x) dx dy \quad (13b)$$

$$\text{Var}[Y|X] = E[Y^2|X] - E^2[Y|X] \quad (13c)$$

$$\text{Var}[Y] = \text{Var}[E[Y|X]] + E[\text{Var}[Y|X]] \quad (13d)$$

### 3.3 Correlation, Covariance & Correlation Coefficient

- For two jointly-distributed random variables  $X$  and  $Y$ , covariance is given by

$$\begin{aligned} \text{Cov}[X, Y] &= E[(X - E[X])(Y - E[Y])] \\ &= E[XY] - E[X]E[Y]. \end{aligned} \quad (14)$$

Main covariance properties are:

$$\text{Cov}[X, X] = \text{Var}[X] \quad (15a)$$

$$\text{Cov}[X, Y] = \text{Cov}[Y, X] \quad (15b)$$

$$\text{Cov}[X, a] = 0 \quad (15c)$$

$$\text{Cov}[aX, bY] = ab \text{Cov}[X, Y] \quad (15d)$$

$$\text{Cov}[X, Y] = \text{Cov}[X + a, Y + b] \quad (15e)$$

$$\text{Var}[X + Y] = \text{Var}[X] + \text{Var}[Y] + 2\text{Cov}[X, Y] \quad (15f)$$

$$|E[XY]| \leq \sqrt{E[X^2]E[Y^2]} \text{ Cauchy-Schwarz} \quad (15g)$$

- Correlation coefficient (also termed as Pearson product-moment correlation coefficient) is given by

$$\rho_{XY} = \frac{\text{Cov}[X, Y]}{\sqrt{\text{Var}[X]\text{Var}[Y]}} \quad (16)$$

such that  $|\rho_{XY}| \leq 1$ .

### 3.4 MMSE Linear Prediction

Mean square error (MSE) of predictor  $\hat{Y}$  is given by

$$mse = E[(Y - \hat{Y})^2] \quad (17)$$

Linear prediction of  $\hat{Y} = ax + b$  for  $X = x$  is

$$\hat{Y} = E[Y] + \frac{\text{Cov}[X, Y]}{\text{Var}[X]} (x - E[X]) \quad (18)$$

and

$$mse_{min} = E[(Y - (aX + b))^2] = \text{Var}(Y)(1 - \rho_{XY}^2) \quad (19)$$

When  $X, Y$  are jointly Gaussian, this prediction is optimal among **all** possible predictors

### 3.5 Relations

- When  $X$  and  $Y$  are *orthogonal*,  $E[XY] = 0$ .
- When  $X$  and  $Y$  are *uncorrelated*,  $\text{Cov}[X, Y] = \rho_{XY} = 0$ .
- When  $X$  and  $Y$  are *independent*, they are also uncorrelated (see also Eqs. 10).
- When  $X$  and  $Y$  are *jointly* Gaussian and uncorrelated  $\Rightarrow X$  and  $Y$  are independent.

## 4 Multi-dimensional Random Variables

### 4.1 Covariance matrix

Given random vector  $\mathbf{X} = (X_1, X_2, \dots, X_N)^T$ ,

$$\begin{aligned} \mathbf{C}_X &= \text{Cov}[\mathbf{X}, \mathbf{X}] = E[(\mathbf{X} - E[\mathbf{X}])(\mathbf{X} - E[\mathbf{X}])^T] \\ &= E[\mathbf{X}\mathbf{X}^T] - E[\mathbf{X}]E[\mathbf{X}]^T \\ &= \begin{bmatrix} \text{Var}[X_1] & \text{Cov}[X_1, X_2] & \cdots & \text{Cov}[X_1, X_N] \\ \text{Cov}[X_2, X_1] & \text{Var}[X_2] & \cdots & \text{Cov}[X_2, X_N] \\ \vdots & \vdots & \ddots & \vdots \\ \text{Cov}[X_N, X_1] & \text{Cov}[X_N, X_2] & \cdots & \text{Var}[X_N] \end{bmatrix} \end{aligned} \quad (20)$$

Properties:

- Symmetry

$$\mathbf{C}_X = \mathbf{C}_X^T \quad \text{Cov}[X_i, X_j] = \text{Cov}[X_j, X_i] \quad (21)$$

- Variance of linear combination: Given vector  $\mathbf{a} = (a_1, a_2, \dots, a_N)^T$ ,

$$\text{Var}[\mathbf{a}^T \mathbf{X}] = \mathbf{a}^T \mathbf{C}_X \mathbf{a} \quad (22)$$

- Linear transformation: Given linear transformation  $\mathbf{Y} = \mathbf{A}\mathbf{X} + \mathbf{b}$ ,

$$E[\mathbf{Y}] = \mathbf{A}E[\mathbf{X}] + \mathbf{b} \quad (23a)$$

$$\mathbf{C}_Y = \mathbf{A}\mathbf{C}_X\mathbf{A}^T \quad (23b)$$

- Uncorrelated variables

$$\mathbf{C}_X = \text{diag}[\text{Var}[X_1], \text{Var}[X_2], \dots, \text{Var}[X_N]] \quad (24)$$

- Cross-covariance: For two random vectors  $\mathbf{X} \in \mathbb{R}^m$  and  $\mathbf{Y} \in \mathbb{R}^n$ , the resulting  $m \times n$  cross-covariance matrix is given by

$$\begin{aligned} \text{Cov}[\mathbf{X}, \mathbf{Y}] &= \mathbf{C}_{\mathbf{XY}} \\ &= E[(\mathbf{X} - E[\mathbf{X}])(\mathbf{Y} - E[\mathbf{Y}])^T] \\ &= E[\mathbf{XY}^T] - E[\mathbf{X}]E[\mathbf{Y}]^T \end{aligned} \quad (25)$$

$$\mathbf{C}_{\mathbf{YX}} = \mathbf{C}_{\mathbf{XY}}^T \quad (26)$$

### 4.2 Bi-variate & Multivariate Normal Distribution

Joint Gaussian distribution of  $X_1$  and  $X_2$  with expectation  $\boldsymbol{\mu} = \begin{bmatrix} \mu_1 \\ \mu_2 \end{bmatrix}$  and covariance matrix  $\mathbf{C}_X = \begin{bmatrix} \sigma_1^2 & \rho\sigma_1\sigma_2 \\ \rho\sigma_1\sigma_2 & \sigma_2^2 \end{bmatrix}$  is

$$f_{X_1 X_2}(x_1, x_2) = \frac{1}{2\pi\sigma_1\sigma_2\sqrt{1-\rho^2}} \exp\left(-\frac{1}{2(1-\rho^2)} \left[ \frac{(x_1 - \mu_1)^2}{\sigma_1^2} + \frac{(x_2 - \mu_2)^2}{\sigma_2^2} - \frac{2\rho(x_1 - \mu_1)(x_2 - \mu_2)}{\sigma_1\sigma_2} \right] \right) \quad (27)$$

Multivariate Gaussian distribution of  $\mathbf{X} = (X_1, X_2, \dots, X_N)^T$  is given by

$$f_{\mathbf{X}}(\mathbf{x}) = \frac{1}{(2\pi)^{N/2} \det[\mathbf{C}_{\mathbf{X}}]} \exp \left\{ -\frac{1}{2} (\mathbf{x} - \boldsymbol{\mu})^T \mathbf{C}_{\mathbf{X}}^{-1} (\mathbf{x} - \boldsymbol{\mu}) \right\}, \quad (28)$$

Properties:

- Random vector  $\mathbf{X}$  is **jointly** Gaussian distributed, iff (if and only if) for all possible real vectors  $\mathbf{a} = (a_1, \dots, a_n)^T$  linear combination  $Y = \mathbf{a}^T \mathbf{X}$  is Gaussian,  

$$Y \sim N(\mathbf{a}^T \boldsymbol{\mu}, \mathbf{a}^T \mathbf{C}_{\mathbf{X}} \mathbf{a}). \quad (29)$$
- If  $X_1, X_2, \dots, X_N$ ,  $X_k \sim N(0, 1)$ ,  $1 \leq k \leq n$  are identically and independently distributed (IID) normal Gaussian random variables, it is termed as *normalized Gaussian random vector*. Its joint PDF is given by

$$f_{\mathbf{X}}(\mathbf{x}) = f_{X_1}(x_1) f_{X_2}(x_2) \cdots f_{X_N}(x_N) = \frac{1}{(2\pi)^{N/2}} \exp \left( -\frac{x_1^2 + x_2^2 + \dots + x_N^2}{2} \right) = \frac{1}{(2\pi)^{N/2}} \exp \left( -\frac{\mathbf{x}^T \mathbf{x}}{2} \right) \quad (30)$$

The covariance matrix of such vector is given by identity matrix of size  $N \times N$ ,  $\mathbf{C}_{\mathbf{X}} = \mathbf{I}_n$  and its expectation is  $\boldsymbol{\mu} = \mathbf{0}_{N \times 1}$ .

- Linear combination of **independent** Gaussian variables,  $X_i \sim N(\mu_i, \sigma_i^2)$  is Gaussian

$$\sum_{i=1}^n a_i X_i \sim N \left( \sum_{i=1}^n a_i \mu_i, \sum_{i=1}^n (a_i \sigma_i)^2 \right). \quad (31)$$

- Linear transformation – follows Eqs. (23a).
- If jointly distributed Gaussian random variables are *uncorrelated*, they are also *independent*

## 5 Random Processes – General Properties

- PDF & CDF

$$F_{\mathbf{X}}(x; t) = p(\mathbf{x}(t) \leq x) \quad (32a)$$

$$f_{\mathbf{X}}(x; t) = \frac{\partial}{\partial x} F_{\mathbf{X}}(x; t) \quad (32b)$$

$$p_{\mathbf{X}}[x_k; n] = p(\mathbf{x}[n] = x_k) \quad (32c)$$

- Average:

$$E[\mathbf{x}(t)] = \int_{-\infty}^{\infty} x f_{\mathbf{X}}(x; t) dx \quad (33a)$$

$$E[\mathbf{x}[n]] = \sum_i x_i p_{\mathbf{X}}[x_k; n] \quad (33b)$$

- Variance:

$$\text{Var}[\mathbf{x}(t)] = E[\mathbf{x}^2(t)] - E^2[\mathbf{x}(t)] = \sigma_{\mathbf{x}}(t) \quad (34a)$$

$$\text{Var}[\mathbf{x}[n]] = E[\mathbf{x}^2[n]] - E^2[\mathbf{x}[n]] = \sigma_{\mathbf{x}}[n] \quad (34b)$$

- Auto-correlation

$$R_{\mathbf{X}}(t_1, t_2) = E[\mathbf{x}(t_1) \mathbf{x}(t_2)] \quad (35a)$$

$$R_{\mathbf{X}}(t, t + \tau) = E[\mathbf{x}(t) \mathbf{x}(t + \tau)] \quad (35b)$$

$$R_{\mathbf{X}}(t_1, t_2) = R_{\mathbf{X}}(t_2, t_1) \quad (35c)$$

$$R_{\mathbf{X}}(t, t) = E[\mathbf{x}^2(t)] \quad (35d)$$

$$R_{\mathbf{X}}[n_1, n_2] = E[\mathbf{x}[n_1] \mathbf{x}[n_2]] \quad (35e)$$

$$R_{\mathbf{X}}[n, n] = E[\mathbf{x}^2[n]] \quad (35f)$$

- Auto-covariance

$$C_{\mathbf{X}}(t_1, t_2) = E \left[ \{ \mathbf{x}(t_1) - E[\mathbf{x}(t_1)] \} \{ \mathbf{x}(t_2) - E[\mathbf{x}(t_2)] \} \right] \quad (36)$$

$$= R_{\mathbf{X}}(t_1, t_2) - E[\mathbf{x}(t_1)] E[\mathbf{x}(t_2)] \quad (37)$$

$$C_{\mathbf{X}}[n_1, n_2] = E \left[ \{ \mathbf{x}[n_1] - E[\mathbf{x}[n_1]] \} \{ \mathbf{x}[n_2] - E[\mathbf{x}[n_2]] \} \right] \quad (38)$$

$$= R_{\mathbf{X}}[n_1, n_2] - E[\mathbf{x}[n_1]] E[\mathbf{x}[n_2]] \quad (39)$$

$$C_{\mathbf{X}}(t, t) = \text{Var}[\mathbf{x}(t)] \quad (40a)$$

$$C_{\mathbf{X}}[n, n] = \text{Var}[\mathbf{x}[n]] \quad (40b)$$

- Correlation Coefficient

$$\rho_{\mathbf{X}}(t_1, t_2) = \frac{C_{\mathbf{X}}(t_1, t_2)}{\sqrt{C_{\mathbf{X}}(t_1, t_1) C_{\mathbf{X}}(t_2, t_2)}} \quad (41a)$$

$$|\rho_{\mathbf{X}}(t_1, t_2)| \leq 1 \quad (41b)$$

- When  $\mathbf{x}(t_1)$  and  $\mathbf{x}(t_2)$  are *orthogonal*,  $R_{\mathbf{X}}(t_1, t_2) = 0$ .
- When  $\mathbf{x}(t_1)$  and  $\mathbf{x}(t_2)$  are *uncorrelated*,  $C_{\mathbf{X}}(t_1, t_2) = \rho_{\mathbf{X}}(t_1, t_2) = 0$ .
- When  $\mathbf{x}(t_1)$  and  $\mathbf{x}(t_2)$  are *independent*,  $R_{\mathbf{X}}(t_1, t_2) = E[\mathbf{x}(t_1)] E[\mathbf{x}(t_2)]$ .

## 6 Wide-Sense Stationary (WSS) Process

Definition:

$$E[\mathbf{x}(t)] = E[\mathbf{x}(0)] = \mu_{\mathbf{x}} = \text{const} \quad (42a)$$

$$R_{\mathbf{x}}(t_1, t_2) = R_{\mathbf{x}}(\tau = |t_2 - t_1|), \quad \forall t_1, t_2 \quad (42b)$$

$$E[\mathbf{x}[n]] = E[\mathbf{x}[0]] = \mu_{\mathbf{x}} = \text{const} \quad (42c)$$

$$R_{\mathbf{x}}[n_1, n_2] = R_{\mathbf{x}}(k = |n_2 - n_1|), \quad \forall n_1, n_2 \quad (42d)$$

- Auto-correlation

$$R_{\mathbf{x}}(\tau) = E[\mathbf{x}(t)\mathbf{x}(t+\tau)] \quad (43a)$$

$$R_{\mathbf{x}}[k] = E[\mathbf{x}[n]\mathbf{x}[n+k]] \quad (43b)$$

Properties:

$$R_{\mathbf{x}}(-\tau) = R_{\mathbf{x}}(\tau) \quad (44a)$$

$$R_{\mathbf{x}}(0) = E[|\mathbf{x}(0)|^2] = E[|\mathbf{x}(t)|^2] \quad (44b)$$

$$\text{Var}[\mathbf{x}(t)] = C_{\mathbf{x}}(0) = \sigma_{\mathbf{x}}^2 \quad (44c)$$

$$R_{\mathbf{x}}(0) \geq |R_{\mathbf{x}}(\tau)| \quad (44d)$$

- Auto-covariance

$$C_{\mathbf{x}}(\tau) = R_{\mathbf{x}}(\tau) - \mu_{\mathbf{x}}^2 \quad (45a)$$

$$C_{\mathbf{x}}[k] = R_{\mathbf{x}}[k] - \mu_{\mathbf{x}}^2 \quad (45b)$$

- Correlation Coefficient

$$\rho_{\mathbf{x}}(\tau) = \frac{C_{\mathbf{x}}(\tau)}{C_{\mathbf{x}}(0)} \quad (46a)$$

$$\rho_{\mathbf{x}}[k] = \frac{C_{\mathbf{x}}[k]}{C_{\mathbf{x}}[0]} \quad (46b)$$

### 6.1 Power Spectral Density (PSD)

$$\begin{aligned} S_{\mathbf{x}}(F) &= \mathcal{F}\{R_{\mathbf{x}}(\tau)\} = -\infty \leq f \leq \infty \\ &= \int_{-\infty}^{\infty} R_{\mathbf{x}}(\tau) \exp(-j2\pi F\tau) d\tau \end{aligned} \quad (47a)$$

$$\begin{aligned} R_{\mathbf{x}}(\tau) &= \mathcal{F}^{-1}\{S_{\mathbf{x}}(F)\} = \\ &= \int_{-\infty}^{\infty} S_{\mathbf{x}}(f) \exp(j2\pi F\tau) dF \end{aligned} \quad (47b)$$

$$S_{\mathbf{x}}(f) = \text{DTFT}\{R_{\mathbf{x}}[k]\} = \sum_{k=-\infty}^{\infty} R_{\mathbf{x}}[k] e^{-j2\pi f k} \quad (47c)$$

Properties:

$$S_{\mathbf{x}}(F) = S_{\mathbf{x}}(-F) \quad (48a)$$

$$S_{\mathbf{x}}(F) \geq 0, \quad \forall F \quad (48b)$$

$$S_{\mathbf{x}}(F) \in \mathbb{R} \quad (48c)$$

$$S_{\mathbf{x}}(f) = S_{\mathbf{x}}(-f) \quad (48d)$$

$$S_{\mathbf{x}}(f) \geq 0, \quad \forall f \quad (48e)$$

$$S_{\mathbf{x}}(f) \in \mathbb{R} \quad (48f)$$

$$S_{\mathbf{x}}(f) = S_{\mathbf{x}}(f+1) \quad (48g)$$

Average power

$$P_{\mathbf{x}} = E[\mathbf{x}^2(t)] = R_{\mathbf{x}}(0) = \int_{-\infty}^{\infty} S_{\mathbf{x}}(F) dF \quad (49a)$$

$$P_{\mathbf{x}} = E[\mathbf{x}^2[n]] = R_{\mathbf{x}}[0] = \int_{-\frac{1}{2}}^{\frac{1}{2}} S_{\mathbf{x}}(f) df \quad (49b)$$

### 6.2 White Noise & White Gaussian Noise (WGN) Process

White noise process is SSS (WSS) process that is characterized by

$$R_{\mathbf{n}}(\tau) = \sigma^2 \delta(\tau) \quad (50a)$$

$$S_{\mathbf{n}}(F) = \sigma^2 \quad \forall F \quad (50b)$$

For WGN process,  $\mathbf{n}(t) \sim N(0, \sigma^2)$ ,

$$R_{\mathbf{n}}(\tau) = \frac{N_0}{2} \delta(\tau) \quad (51a)$$

$$S_{\mathbf{n}}(F) = \frac{N_0}{2} \quad \forall F \quad (51b)$$

### 6.3 Relation Between Covariance Matrix & Auto-covariance

Given WSS process  $\mathbf{x}(t)$ , the corresponding correlation matrix of  $\mathbf{X} = [\mathbf{x}(t_1), \dots, \mathbf{x}(t_N)]^T$  is given by

$$R_{\mathbf{X}} = E[\mathbf{X}\mathbf{X}^T] \quad (52)$$

$$R_{\mathbf{X}}(i, j) = E[X_i X_j] = R_{\mathbf{x}}(|t_i - t_j|) \quad (53)$$

## 7 Cross-Signal

- Cross-correlation

$$R_{\mathbf{xy}}(t_1, t_2) = E[\mathbf{x}(t_1)\mathbf{y}(t_2)] \quad (54)$$

- Cross-covariance

$$C_{\mathbf{xy}}(t_1, t_2) = R_{\mathbf{xy}}(t_1, t_2) - E[\mathbf{x}(t_1)]E[\mathbf{y}(t_2)] \quad (55)$$

- Correlation Coefficient

$$\rho_{\mathbf{xy}}(t_1, t_2) = \frac{C_{\mathbf{xy}}(t_1, t_2)}{\sqrt{C_{\mathbf{x}}(t_1, t_1)C_{\mathbf{y}}(t_2, t_2)}} \quad (56)$$

### 7.1 WSS Cross-signal

- $\mathbf{x}(t), \mathbf{y}(t)$  are jointly WSS, if  $\mathbf{x}(t)$  and  $\mathbf{y}(t)$  each of them is WSS and

$$R_{\mathbf{xy}}(\tau) = E[\mathbf{x}(t)\mathbf{y}(t+\tau)] \quad (57)$$

- When  $\mathbf{x}(t)$  and  $\mathbf{y}(t+\tau)$  are *uncorrelated jointly WSS*,  $C_{\mathbf{xy}}(\tau) = 0$ .

Properties

$$R_{\mathbf{xy}}(\tau) = R_{\mathbf{yx}}(-\tau) \quad (58a)$$

$$|R_{\mathbf{xy}}(\tau)| \leq \sqrt{R_{\mathbf{x}}(0)R_{\mathbf{y}}(0)} \quad (58b)$$

$$|R_{\mathbf{xy}}(\tau)| \leq \frac{1}{2} [R_{\mathbf{x}}(0) + R_{\mathbf{y}}(0)] \quad (58c)$$

- Cross-covariance

$$C_{\mathbf{xy}}(\tau) = R_{\mathbf{xy}}(\tau) - \mu_{\mathbf{x}}\mu_{\mathbf{y}} \quad (59)$$

- Cross-PSD

$$S_{\mathbf{xy}}(f) = \mathcal{F} \{ R_{\mathbf{xy}}(\tau) \} \quad (60)$$

Properties

$$S_{\mathbf{xy}}(f) = S_{\mathbf{yx}}(-f) = S_{\mathbf{xy}}^*(-f) \quad (61)$$

Correlation coefficient

$$\rho_{\mathbf{xy}}(\tau) = \frac{C_{\mathbf{xy}}(\tau)}{C_{\mathbf{xy}}(0)} \quad (62)$$

- Coherence

$$\gamma_{\mathbf{xy}}(f) = \frac{S_{\mathbf{xy}}(f)}{\sqrt{S_{\mathbf{x}}(f)S_{\mathbf{y}}(f)}} \quad (63)$$

## 8 LTI and WSS Random Process

Output of LTI system with impulse response  $h(t)$  and random process  $x(t)$ ,

$$y(t) = x(t) * h(t) \quad (64)$$

Average

$$m_{\mathbf{y}} = m_{\mathbf{x}} \int_{-\infty}^{\infty} h(s) ds = m_{\mathbf{x}} H(f=0) \quad (65)$$

Cross-correlation & cross-covariance:

$$R_{\mathbf{xy}}(\tau) = R_{\mathbf{x}}(\tau) * h(\tau) \quad (66a)$$

$$C_{\mathbf{xy}}(\tau) = C_{\mathbf{x}}(\tau) * h(\tau) \quad (66b)$$

$$R_{\mathbf{yx}}(\tau) = R_{\mathbf{x}}(\tau) * h(-\tau) \quad (66c)$$

$$C_{\mathbf{yx}}(\tau) = C_{\mathbf{x}}(\tau) * h(-\tau) \quad (66d)$$

$$R_{\mathbf{y}}(\tau) = R_{\mathbf{x}}(\tau) * h(\tau) * h(-\tau) \quad (66e)$$

$$C_{\mathbf{y}}(\tau) = C_{\mathbf{x}}(\tau) * h(\tau) * h(-\tau) \quad (66f)$$

Power-Spectral Density (PSD) & Cross-PSD: Given frequency response  $H(F) = \mathcal{F} \{ h(\tau) \}$ ,  $H^*(F) = \mathcal{F} \{ h(-\tau) \}$

$$S_{\mathbf{xy}}(F) = S_{\mathbf{x}}(F) H(F) \quad (67a)$$

$$S_{\mathbf{yx}}(F) = S_{\mathbf{x}}(F) H^*(F) \quad (67b)$$

$$S_{\mathbf{y}}(F) = S_{\mathbf{x}}(F) H(F) H^*(F) = S_{\mathbf{x}}(f) |H(F)|^2 \quad (67c)$$

Power of the process:

$$P_x = R_x(0) = \int_{-\infty}^{\infty} S_x(F) dF \quad (68a)$$

$$P_y = R_y(0) = \int_{-\infty}^{\infty} S_x(F) |H(F)|^2 dF \quad (68b)$$

$$P_x = R_x[0] = \int_{-1/2}^{1/2} S_x(f) df \quad (68c)$$

$$P_y = R_y[0] = \int_{-1/2}^{1/2} S_x(f) |H(f)|^2 df \quad (68d)$$

Same process passes two different systems

$$R_{\mathbf{yz}}(\tau) = R_{\mathbf{x}}(\tau) * h_1(-\tau) * h_2(\tau) \quad (69)$$

$$S_{\mathbf{yz}}(F) = S_{\mathbf{x}}(F) H_1^*(F) H_2(F) \quad (70)$$

### 8.1 Z-Transform

Auto-correlation

$$H(z) = \mathcal{Z} \{ h[n] \} = \frac{B(z)}{A(z)}$$

$$\mathcal{Z} \{ h[n] * h[-n] \} = \frac{B(z)B(z^{-1})}{A(z)A(z^{-1})}$$

$$S_{\mathbf{x}}(z) = \mathcal{Z} \{ R_{\mathbf{x}}[n] \}$$

PSD

$$S_{\mathbf{xy}}(z) = S_{\mathbf{x}}(z) H(z) \quad (71a)$$

$$S_{\mathbf{yx}}(z) = S_{\mathbf{x}}(z) H(z^{-1}) \quad (71b)$$

$$S_{\mathbf{y}}(z) = S_{\mathbf{x}}(z) H(z) H(z^{-1}) \quad (71c)$$

Two different systems

$$R_{\mathbf{yz}}[k] = R_{\mathbf{x}}[k] * h_1[-k] * h_2[k] \quad (72a)$$

$$S_{\mathbf{yz}}(f) = S_{\mathbf{x}}(f) H_1^*(f) H_2(f) \quad (72b)$$

$$S_{\mathbf{yz}}(z) = S_{\mathbf{x}}(z) H_1(1/z) H_2(z) \quad (72c)$$

### 8.2 Gaussian Process

A Gaussian process  $\mathbf{x}(t)$  a random process that for  $\forall k > 0$  and for all times  $t_1, \dots, t_k$ , the set of random variable  $\mathbf{x}(t_1), \dots, \mathbf{x}(t_k)$  is jointly Gaussian (i.e. described by Eq. (28)).

Properties:

- WSS Gaussian process is SSS.
- Gaussian process  $\mathbf{x}(t)$  that passes through LTI system,  $\mathbf{y}(t) = h(t) * \mathbf{x}(t)$ , is also Gaussian process that may be described by the change of expectation and auto-correlation,

$$E[\mathbf{y}(t)] = E[\mathbf{x}(t)] \int_{-\infty}^{\infty} h(s) ds \quad (73a)$$

$$= E[\mathbf{x}(t)] H(0), \quad H(F) = \mathcal{F} \{ h(t) \}$$

$$C_{\mathbf{y}}(\tau) = C_{\mathbf{x}}(\tau) * h(\tau) * h(-\tau) \quad (73b)$$

- The resulting autocorrelation may be used for producing the correspondent covariance matrix  $C_{\mathbf{Y}}$  of a multivariate Gaussian  $\mathbf{Y} = [\mathbf{y}(t_1), \dots, \mathbf{y}(t_N)]^T$



### 8.3 Linear Prediction

Given  $N$  samples of process  $\mathbf{x}[n]$ , and predictor

$$\hat{\mathbf{x}}[n+1] = \sum_{i=1}^N a_i \mathbf{x}[n-i+1], \quad (74)$$

the values of  $a_i$  are given by a solution of

$$\begin{bmatrix} R_{\mathbf{x}}[0] & R_{\mathbf{x}}[1] & \cdots & R_{\mathbf{x}}[N-1] \\ R_{\mathbf{x}}[1] & R_{\mathbf{x}}[0] & \cdots & R_{\mathbf{x}}[N-2] \\ \vdots & \vdots & \ddots & \vdots \\ R_{\mathbf{x}}[N-1] & R_{\mathbf{x}}[N-2] & \cdots & R_{\mathbf{x}}[0] \end{bmatrix} \begin{bmatrix} a_1 \\ a_2 \\ \vdots \\ a_N \end{bmatrix} = \begin{bmatrix} R_{\mathbf{x}}[1] \\ R_{\mathbf{x}}[2] \\ \vdots \\ R_{\mathbf{x}}[N] \end{bmatrix} \quad (75)$$

and the resulting minimum MSE is

$$mse_{min} = R_{\mathbf{x}}[0] - \sum_{i=1}^N a_i R_{\mathbf{x}}[i] \quad (76)$$

## 9 Different Supplementary Formulas

### 9.1 Derivatives

$$\frac{d}{dx} x^n = nx^{n-1}$$

$$\frac{d}{dx} \exp[f(x)] = \exp[f(x)] \frac{d}{dx} f(x)$$

### 9.2 Integrals

#### 9.2.1 Indefinite

$$\int x^n dx = \frac{1}{n+1} x^{n+1}, \quad n \neq -1$$

$$\int \exp(ax) dx = \frac{1}{a} \exp(ax)$$

$$\int x \exp(ax) dx = \exp(ax) \left[ \frac{x}{a} - \frac{1}{a^2} \right]$$

$$\int x^2 \exp(ax) dx = \exp(ax) \left[ \frac{x^2}{a} - \frac{2x}{a^2} + \frac{2}{a^3} \right]$$

$$\int \frac{1}{a^2 + x^2} dx = \frac{1}{a} \tan^{-1} \frac{x}{a}$$

#### 9.2.2 Definite

$$\int_0^\infty \exp(-a^2 x^2) dx = \frac{\sqrt{\pi}}{2a}$$

$$\int_0^\infty x^2 \exp(-a^2 x^2) dx = \frac{\sqrt{\pi}}{4a^3}$$

$$\int_{-\infty}^\infty \delta(x) dx = 1$$

$$\int_{-\infty}^\infty f(x) \delta(x-a) dx = f(a)$$

### 9.3 Fourier Transform

#### 9.3.1 Properties

$$\frac{d^n}{dt^n} f(t) \xleftrightarrow{\mathcal{F}} (j2\pi f)^n F(f)$$

$$f(-t) \xleftrightarrow{\mathcal{F}} F^*(f)$$

$$f(t-t_0) \xleftrightarrow{\mathcal{F}} F(f) e^{-j2\pi f t_0}$$

$$f(t) e^{j2\pi f_0 t} \xleftrightarrow{\mathcal{F}} F(f-f_0)$$

#### 9.3.2 Transform pairs

$$u(t) \xleftrightarrow{\mathcal{F}} \frac{1}{2} \left( \frac{1}{j\pi f} + \delta(f) \right)$$

$$\exp(-at) u(t) \xleftrightarrow{\mathcal{F}} \frac{1}{a + j2\pi f}$$

$$t \exp(-at) u(t) \xleftrightarrow{\mathcal{F}} \frac{1}{(a + j2\pi f)^2}$$

$$\exp(-a|t|) \xleftrightarrow{\mathcal{F}} \frac{2a}{a^2 + 4\pi^2 f^2}$$

$$\exp(-at^2) \xleftrightarrow{\mathcal{F}} \sqrt{\frac{\pi}{a}} \exp\left(-\frac{(\pi f)^2}{a}\right)$$

$$\cos(2\pi f_a t) \xleftrightarrow{\mathcal{F}} \frac{1}{2} [\delta(f-f_a) + \delta(f+f_a)]$$

$$\sin(2\pi f_a t) \xleftrightarrow{\mathcal{F}} \frac{1}{2j} [\delta(f-f_a) - \delta(f+f_a)]$$

### 9.4 Convolution

$$x(t) * y(t) = \int_{-\infty}^\infty f(s) g(t-s) ds$$

$$x(t) * y(t) \xleftrightarrow{\mathcal{F}} X(f) Y(f)$$

$$\delta(t) * y(t) = y(t)$$

## 9.5 Trigonometry

$$\begin{aligned}\sin^2(\alpha) &= \frac{1}{2}(1 - \cos(2\alpha)) \\ \cos^2(\alpha) &= \frac{1}{2}(1 + \cos(2\alpha)) \\ \cos(\alpha)\cos(\beta) &= \frac{1}{2}[\cos(\alpha + \beta) + \cos(\alpha - \beta)] \\ \sin(\alpha)\sin(\beta) &= \frac{1}{2}[\cos(\alpha - \beta) - \cos(\alpha + \beta)] \\ \sin(\alpha)\cos(\beta) &= \frac{1}{2}[\sin(\alpha - \beta) + \sin(\alpha + \beta)]\end{aligned}$$

## 9.6 Matrices

$$\begin{aligned}\mathbf{A} &= \begin{bmatrix} a & b \\ c & d \end{bmatrix}, \\ \det[\mathbf{A}] &= ad - bc \\ \mathbf{A}^{-1} &= \frac{1}{ad - bc} \begin{bmatrix} d & -b \\ -c & a \end{bmatrix}\end{aligned}$$

## 10 Z-transforms

$$X(z) = \sum_{k=-\infty}^{\infty} x[k]z^{-k}$$

### 10.1 Usual Transforms

Signal	Z transform	ROC
$\delta[n]$	1	$\mathbb{C}$
$u[n]$	$\frac{1}{1 - z^{-1}}$	$ z  > 1$
$-u[-n - 1]$	$\frac{1}{1 - z^{-1}}$	$ z  < 1$
$\delta[n - m]$	$z^{-m}$	$\mathbb{C} - \{0\}$ if $m > 0$ , $\mathbb{C} - \{\infty\}$ if $m < 0$
$a^n u[n]$	$\frac{1}{1 - az^{-1}}$	$ z  > a$
$-a^n u[-n - 1]$	$\frac{1}{1 - az^{-1}}$	$ z  < a$

### 10.2 Properties

Property	Discrete Signal	Z transform	ROC
Linearity	$a_1 x_1[n] + a_2 x_2[n]$	$a_1 X_1(z) + a_2 X_2(z)$	includes $R_1 \cap R_2$
Time shift	$x[n - n_0]$	$z^{-n_0} X(z)$	$R$
Frequency scaling	$z_0^n x[n]$	$X\left(\frac{z}{z_0}\right)$	$ z_0 R$
Time reversal	$x[-n]$	$X(z^{-1})$	$R^{-1}$ if $m < 0$
Convolution	$(x_1 * x_2)[n]$	$X_1(z)X_2(z)$	$R_1 \cap R_2$ (or possibly more)
Time differentiation	$x[n] - x[n - 1]$	$(1 - z^{-1})X(z)$	$R \cap \{ z  > 0\}$
Accumulation	$\sum_{k=-\infty}^n x[k]$	$\frac{X(z)}{1 - z^{-1}}$	$R \cap \{ z  > 1\}$