## view frames Result

Recorded at time: 249.350006104

map Broadcaster: /slam gmapping Average rate: 16.327 Buffer length: 4.9 Most recent transform: 249.4 Oldest transform: 244.5 odom Broadcaster: /rf2o laser odometry Average rate: 5.208 Buffer length: 4.8 Most recent transform: 249.25 Oldest transform: 244.45 base link Broadcaster: /sim ros interface` Broadcaster: /sim ros interface Average rate: 20.202 Average rate: 20.202 Buffer length: 4.95 Buffer length: 4.95 Most recent transform: 249.3 Most recent transform: 249.3 Oldest transform: 244.35 Oldest transform: 244.35 laser link camera link