

Dirac Equation: Lorentz Covariance

For an acceptable relativistic theory of the electron, which is what the Dirac Eqn purports to offer, it is essential that we demonstrate the Lorentz covariance of the theory (i.e. that the Dirac Eqn exhibits the same form in all inertial frames which are connected by Lorentz transformations). We do that now, for free particles.

1) The (free particle) Dirac Eqn in some reference inertial frame K is written:

$$\underline{(\gamma_\mu \frac{\partial}{\partial x_\mu} + k) \psi(x) = 0}, \quad \text{w/ } k = mc/\hbar \quad \int \{\gamma_\mu, \gamma_\nu\} = 2\delta_{\mu\nu}, \text{ for Dirac matrices, (1)}$$

$x \leftrightarrow x_\mu = (t, i\mathbf{r}), \text{ 4-position.}$

Now, make a Lorentz transformation from K to a new inertial frame K' :

$$K \rightarrow K' \text{ via Lorentz transf } \Lambda = (\Lambda_{\mu\nu}) : x_\mu \rightarrow x'_\mu = \Lambda_{\mu\nu} x_\nu,$$

$$\text{so } \partial/\partial x_\mu = (\partial x'_\nu / \partial x_\mu) \partial/\partial x'_\nu = \Lambda_{\nu\mu} \partial/\partial x'_\nu$$

$$\text{and } \underline{(\Lambda_{\nu\mu} \gamma_\mu \frac{\partial}{\partial x'_\nu} + k) \psi(x') = 0.} \quad \leftarrow \text{This is Eq.(1), directly transformed from } K \text{ to } K' \text{ cds.} \quad (2)$$

NOTE: the Dirac matrices γ_μ do not depend on \mathbf{r} & t , and hence do not change under Λ . The γ_μ , once chosen, should be the same for observers K & K' .

Now... Lorentz covariance demands that the K' version of the Dirac Eqn looks the same as the K version. That is, K' should write -- in his/her cds x' ...

$$\underline{(\gamma_\nu \frac{\partial}{\partial x'_\nu} + k) \psi'(x') = 0.} \quad \leftarrow \text{This is covariant form of Dirac Eq. in } K'. \quad (3)$$

The wavefn ψ in K has become ψ' in K' .

The covariance of the Dirac Eqn is manifest if we can reconcile Eqs. (2) & (3), i.e. the version of the K' eqn as written by K , and K' 's own version of the eqn. This reconciliation is readily possible if we can find a matrix S such that:

$$\boxed{\psi'(x') = S \psi(x), \text{ and } S^{-1} \gamma_\nu S = \Lambda_{\nu\mu} \gamma_\mu} \quad \int \text{needed for Lorentz covariance of Dirac Eq.} \quad (4)$$

This follows by direct substitution into Eq.(3). S is independent of \mathbf{r} & t .

REMARKS on the required covariance matrix S in Eq. (4).

1. The 4×4 matrices S & γ_ν operate on components of the 4-spinor ψ , while the 4×4 Lorentz transform matrix Λ operates on components of 4-vectors ($x = (t, \mathbf{x})$).
 S & γ_ν , and Λ , are defined in different spaces, so Λ commutes with S & γ_ν .
2. That the desired S exists is ensured by Pauli's Theorem [p. DE 10, Eq. (33)]. Note:

... if $\gamma'_\alpha = \Lambda_{\alpha\mu} \gamma_\mu$, then since $\{\gamma_\mu, \gamma_\nu\} = 2\delta_{\mu\nu}$...

$$\rightarrow \{\gamma'_\alpha, \gamma'_\beta\} = \Lambda_{\alpha\mu} \Lambda_{\beta\nu} \{\gamma_\mu, \gamma_\nu\} = 2 \Lambda_{\alpha\mu} \Lambda_{\beta\mu} = 2 \delta_{\alpha\beta} \quad \begin{array}{l} \text{using fact that} \\ \Lambda \text{ is orthogonal,} \\ \text{i.e. } \Lambda^T \Lambda = 1. \end{array} \quad (5)$$

So the γ'_α obey the same anticommutation rule as the γ_μ . Per Pauli, there does exist a nonsingular S (unique up to a phase) such that: $\gamma'_\nu = \Lambda_{\nu\mu} \gamma_\mu = S^{-1} \gamma_\nu S$.

3. Note that S is not unitary in general. From Eq. (4) as definition...

$$\gamma_\nu S = \Lambda_{\nu\mu} S \gamma_\mu \quad \leftarrow \text{have commuted } S \text{ & } \Lambda. \text{ Mult. on left by } S^\dagger \quad (6)$$

$$\Rightarrow S^\dagger \gamma_\nu S = \Lambda_{\nu\mu} (S^\dagger S) \gamma_\mu \quad \begin{array}{l} \text{take Herm. conjugate of both sides of Eq. (6).} \\ \text{Mult on right by } S \text{ (and use } \gamma_\nu^\dagger = \gamma_\nu) \dots \end{array}$$

and $S^\dagger \gamma_\nu S = \Lambda_{\nu\mu}^* \gamma_\mu (S^\dagger S)$. If S were unitary, $S^\dagger S = 1$, the last two eqns would demand that $\Lambda_{\nu\mu}^* = \Lambda_{\nu\mu}$, i.e. that the Lorentz transform Λ be pure real. But this is true for us only for pure spatial rotations [p. DE 3, Eq. (4)].
 A velocity boost \Rightarrow our Λ has imaginary components Λ_{k4} & Λ_{4k} . Hence the proposition that S is unitary in general fails.

- 2) It turns out that S is "almost unitary". What this means can be discovered by looking at the adjoint Dirac Eqn. The Dirac eqn and its adjoint are related by:

$$\underline{\underline{\frac{\partial}{\partial x_\mu} (\gamma_\mu \psi) + k \psi = 0}} \leftrightarrow \underline{\underline{\frac{\partial}{\partial x_\mu} (\bar{\psi} \gamma_\mu) - k \bar{\psi} = 0}}, \quad \begin{array}{l} \text{w/ } \bar{\psi} = \psi^\dagger \gamma_4 \quad \text{Eq. (27)} \\ \text{(adjoint spinor)} \quad \text{p. DE 9} \end{array} \quad (7)$$

(Get the adjoint eqn by taking the Hermitian conjugate of original eqn., then multiply on the right by γ_4). The Lorentz-transformed adjoint eqn (like (2) above) is:

Covariance of the adjoint Dirac Eqn. 4-vectorhood for the current J_μ . DE(32)

$$x_\mu \rightarrow x'_\mu = \Lambda_{\mu\nu} x_\nu \Rightarrow \frac{\partial}{\partial x'_\nu} \bar{\Psi}(x') \underbrace{\Lambda_{\nu\mu} \gamma_\mu}_{= S^{-1} \gamma_\nu S, \text{ by Eq. (4)}} - k \bar{\Psi}(x') = 0$$

...mult. on right by S^{-1} , so...

$$\frac{\partial}{\partial x'_\nu} \bar{\Psi}'(x') \gamma_\nu - k \bar{\Psi}'(x') = 0, \text{ iff } \boxed{\bar{\Psi}'(x') = \bar{\Psi}(x') S^{-1}}. \quad (8)$$

Eq.(8) is the required covariant form of the adjoint eqn. Now, upon $x \rightarrow x' = \Lambda x$, have:

$$\left\{ \begin{array}{l} \text{Dirac Eqn is covariant if [Eq.(4)] : } \psi(x) \rightarrow \psi'(x') = S \psi(x) \\ \text{Adjoint Eq. " " " [Eq.(8)] : } \bar{\psi}(x) \rightarrow \bar{\psi}'(x') = \bar{\psi}(x) S^{-1} \end{array} \right. \quad \int \quad \underline{\underline{\bar{\psi} = \psi^\dagger \gamma_4}}. \quad (9)$$

These two requirements are self-consistent if...

$$\begin{aligned} \bar{\psi}'(x') &= [\psi'(x')]^\dagger \gamma_4 = [S \psi(x)]^\dagger \gamma_4 = [\psi(x)]^\dagger S^\dagger \gamma_4 \\ \hookrightarrow &= [\psi(x)]^\dagger \gamma_4 S^{-1} \quad \xleftarrow{\text{equate}} \Rightarrow \boxed{S^\dagger \gamma_4 S = \gamma_4} \quad \text{w/ } \gamma_4 = \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix}. \quad (10) \end{aligned}$$

We see that S is "almost unitary", to the extent that γ_4 is "almost unity". We will actually derive what S is below (see next page), but first... note in passing...

ASIDE Dirac probability current $J_\mu(x)$ as a 4-vector.

Recall [p.DE9, Eq.(29)] : $J_\mu(x) = ic \bar{\psi}(x) \gamma_\mu \psi(x)$, w/ $\partial J_\mu(x) / \partial x_\mu = 0$, in frame K .

A Lorentz transform $K \rightarrow K'$ (i.e. $x_\mu \rightarrow x'_\mu = \Lambda_{\mu\nu} x_\nu$) transforms $J_\mu(x)$ to ...

$$\begin{aligned} \rightarrow J'_\mu(x') &= ic \bar{\psi}'(x') \gamma_\mu \psi'(x') = ic \bar{\psi}(x) \underbrace{S^{-1} \gamma_\mu S}_{= \Lambda_{\mu\nu} \gamma_\nu \text{ by using Eq. (4)}} \psi(x) \quad \int \text{by using Eq. (9)} \\ &= \Lambda_{\mu\nu} J_\nu(x) \quad \int \text{by using Eq. (4)} \end{aligned}$$

$$\text{i.e.} \quad \underline{\underline{J'_\mu(x') = ic \Lambda_{\mu\nu} \bar{\psi}(x) \gamma_\nu \psi(x) = \Lambda_{\mu\nu} J_\nu(x)}}. \quad (11)$$

So $J_\mu \rightarrow J'_\mu = \Lambda_{\mu\nu} J_\nu$ indeed transforms as an authentic 4-vector (x' in Eq.(11)

just fixes a given spacetime point; it happens to be labelled in K' cds).

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Now  $J_\mu$  as a 4-vector  $\Rightarrow$  the probability density, i.e. (note  $\bar{\psi} = \psi^\dagger \gamma_4$ )...

$$\rightarrow \rho = J_4 / ic = \bar{\psi} \gamma_4 \psi = \psi^\dagger \psi, \quad (12)$$

## Lorentz invariance of $\int \psi^\dagger \psi d^3x$ . Derivation of $S$ for an $\omega$ small $\Lambda$ .

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must transform as the 4<sup>th</sup> (time-like) component of a 4-vector. So, for a Lorentz boost at velocity  $\beta$  along the  $x_1$ -axis, say, we'll have  $\underline{p} \rightarrow \underline{p}' = \gamma \underline{p}$ , w/  $\gamma = 1/\sqrt{1-\beta^2}$  the usual dilation factor. Then, we see that since the 3-volume element contracts by the same factor, i.e.  $d^3x \rightarrow d^3x' = (dx_1/\gamma) dx_2 dx_3 = \frac{1}{\gamma} d^3x$ , the total probability measured by  $p$  is a Lorentz invariant:

$$\rightarrow \int p d^3x \rightarrow \int p' d^3x' = \int (\gamma p) \cdot \frac{1}{\gamma} d^3x = \int p d^3x \quad \checkmark \text{total probability is a Lorentz invariant.} \quad (13)$$

That's reassuring... we don't lose track of particles in Dirac theory.

3) We shall now derive the covariance matrix  $S$  for an  $\omega$ small Lorentz transform:<sup>9</sup>

$$\left\{ \begin{array}{l} \underline{\Lambda}_{\mu\nu} = \delta_{\mu\nu} + \epsilon_{\mu\nu} \quad \checkmark \text{ } \omega\text{small Lorentz transform} \leftrightarrow \mathcal{O}(\epsilon^2) \text{ negligible;} \\ \quad (\epsilon_{\mu\nu}) \text{ is an } \underline{\text{antisymmetric}} \text{ matrix: } \epsilon_{\mu\nu} = -\epsilon_{\nu\mu}; \\ \text{w/ } \underline{\Lambda}_{\mu\alpha} \underline{\Lambda}_{\mu\beta} = \delta_{\alpha\beta} = \underline{\Lambda}_{\alpha\mu} \underline{\Lambda}_{\beta\mu} \leftarrow \underline{\Lambda} \text{ is an } \underline{\text{orthogonal}} \text{ matrix.} \end{array} \right. \quad (14)$$

$S$  is defined by the two covariance requirements:

$$\left\{ \begin{array}{l} \underline{S}^{-1} \gamma_\mu \underline{S} = \underline{\Lambda}_{\mu\nu} \gamma_\nu, \text{ for covariance of Dirac Eqn [Eq.(4)],} \\ \underline{S}^\dagger \gamma_4 \underline{S} = \gamma_4, \text{ for covariance of adjoint Dirac Eq. [Eq.(10)].} \end{array} \right. \quad (15)$$

Clearly, when  $\epsilon_{\mu\nu} = 0$  and  $\underline{\Lambda}_{\mu\nu} = \delta_{\mu\nu}$ , we must have  $\underline{S} \equiv 1$ . So we try...

$$\rightarrow \underline{\underline{S}} = \underline{\underline{1}} + \epsilon_{\mu\nu} \underline{T}_{\mu\nu} \quad \checkmark \underline{\underline{S}}, \underline{\underline{1}} \text{ \& } \underline{T}_{\mu\nu} \text{ are } 4 \times 4 \text{ matrices. } \epsilon_{\mu\nu} \text{ is just a number [element of } (\epsilon_{\mu\nu}) \text{]. Sum over } \mu, \nu = 1 \text{ to } 4. \quad (16)$$

Since  $\epsilon_{\mu\mu} = -\epsilon_{\mu\mu}$  (and  $\epsilon_{\mu\mu} \equiv 0$ ), there are only 6 independent terms in this sum.

We could write it as:  $\underline{\underline{S}} = \underline{\underline{1}} + \sum_{\nu, \mu < \nu} \epsilon_{\mu\nu} \underline{T}'_{\mu\nu}$ , w/  $\underline{T}'_{\mu\nu} = \underline{T}_{\mu\nu} - \underline{T}_{\nu\mu}$ , a set of 6 indept  $4 \times 4$  antisymmetric matrices. In any case, it is clear that...

$$\rightarrow \underline{\underline{S}}^{-1} = \underline{\underline{1}} - \epsilon_{\alpha\beta} \underline{T}_{\alpha\beta}, \quad \text{w/ } \underline{\underline{S}}^{-1} \underline{\underline{S}} = \underline{\underline{S}} \underline{\underline{S}}^{-1} = \underline{\underline{1}}, \text{ neglecting } \mathcal{O}(\epsilon^2). \quad (17)$$

This form of  $\underline{\underline{S}}^{-1}$  is the inverse of  $\underline{\underline{S}}$  in Eq.(16), at least for  $\omega$ small Lorentz  $\Lambda$ 's.

<sup>9</sup> See problem 11.7, p. 564 of J.D. Jackson "Classical Electrodynamics" (Wiley, 1975).

## Form of Covariance Matrix $\underline{S}$ for osmal Lorentz Transform.

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With the  $\underline{S}$  &  $\underline{S}^{-1}$  forms in Eqs. (16) & (17), the first of the defining eqs. (15) is...

$$\underline{S}^{-1} \underline{\gamma}_\mu \underline{S} = \Lambda_{\mu\nu} \underline{\gamma}_\nu \Rightarrow (1 - \epsilon_{\alpha\beta} \underline{T}_{\alpha\beta}) \underline{\gamma}_\mu (1 + \epsilon_{\rho\sigma} \underline{T}_{\rho\sigma}) = (\delta_{\mu\nu} + \epsilon_{\mu\nu}) \underline{\gamma}_\nu$$

$$\text{or} // \boxed{\epsilon_{\alpha\beta} [\underline{\gamma}_\mu, \underline{T}_{\alpha\beta}] = \epsilon_{\mu\nu} \underline{\gamma}_\nu}, \text{ to 1st order in } \epsilon. \quad (18)$$

This relation defines the 6 antisymmetric covariance matrices  $\underline{T}_{\alpha\beta}$  ( $\beta \neq \alpha$ ) that are needed [per Eq. (16)] for the osmal Lorentz transform in Eq. (14). Evidently the  $\underline{T}_{\alpha\beta}$  are related to the  $\underline{\gamma}_\mu$ ; in fact they must be of order  $\underline{\gamma}_\mu^2$ , so that we get terms linear in  $\underline{\gamma}_\mu$  on both sides of Eq. (18). A reasonable guess is...

$$\boxed{\underline{T}_{\alpha\beta} = \begin{cases} 0, & \text{when } \alpha = \beta; \\ \kappa \underline{\gamma}_\alpha \underline{\gamma}_\beta, & \alpha \neq \beta. \end{cases}} \quad \left. \begin{array}{l} \text{with } \{\underline{\gamma}_\alpha, \underline{\gamma}_\beta\} = 0, \text{ for } \alpha \neq \beta, \text{ this Ansatz} \\ \Rightarrow 6 \text{ indept } \underline{T}_{\alpha\beta}, \text{ obeying: } \underline{T}_{\beta\alpha} = -\underline{T}_{\alpha\beta} \end{array} \right\} \quad (19)$$

With this Ansatz, the commutator in (18) is...

$$\begin{aligned} \rightarrow \frac{1}{\kappa} [\underline{\gamma}_\mu, \underline{T}_{\alpha\beta}] &= (\underline{\gamma}_\mu \underline{\gamma}_\alpha) \underline{\gamma}_\beta - \underline{\gamma}_\alpha (\underline{\gamma}_\beta \underline{\gamma}_\mu) \\ &= (2\delta_{\mu\alpha} \underline{1} - \underline{\gamma}_\alpha \underline{\gamma}_\mu) \underline{\gamma}_\beta - \underline{\gamma}_\alpha (2\delta_{\beta\mu} \underline{1} - \underline{\gamma}_\mu \underline{\gamma}_\beta) \\ &= 2(\delta_{\mu\alpha} \underline{\gamma}_\beta - \delta_{\beta\mu} \underline{\gamma}_\alpha) \end{aligned} \quad (20)$$

Use this result in Eq. (18) to obtain...

$$\begin{aligned} \text{i.e.} // \quad \epsilon_{\mu\nu} \underline{\gamma}_\nu &= 2\kappa \epsilon_{\alpha\beta} (\delta_{\mu\alpha} \underline{\gamma}_\beta - \delta_{\beta\mu} \underline{\gamma}_\alpha) = 2\kappa (\epsilon_{\mu\beta} \underline{\gamma}_\beta - \epsilon_{\alpha\mu} \underline{\gamma}_\alpha) \\ \epsilon_{\mu\nu} \underline{\gamma}_\nu &= 4\kappa \epsilon_{\mu\alpha} \underline{\gamma}_\alpha \quad \leftarrow \text{this eqn is an identity if } \underline{\kappa} = \underline{1/4}. \end{aligned} \quad (21)$$

Now, with  $\kappa = \frac{1}{4}$ , and the Ansatz of Eq. (19), we have the desired T-matrices:

$$\rightarrow \underline{T}_{\mu\nu} = \frac{1}{4} \underline{\gamma}_\mu \underline{\gamma}_\nu, \text{ for } \nu \neq \mu; \quad \underline{T}_{\mu\mu} = 0.$$

$$\text{So} // \boxed{\underline{S} = \underline{1} + \frac{1}{4} \epsilon_{\mu\nu} \underline{\gamma}_\mu \underline{\gamma}_\nu} \quad \left. \begin{array}{l} \text{is the desired covariance matrix (to } \mathcal{O}(\epsilon) \text{) for} \\ \text{the osmal Lorentz transform } \Lambda_{\mu\nu} = \delta_{\mu\nu} + \epsilon_{\mu\nu}. \end{array} \right\} \quad (22)$$

The "unitarity" condition  $\underline{S}^\dagger \underline{\gamma}_4 \underline{S} = \underline{\gamma}_4$  in Eq. (15) then restricts the  $\epsilon_{\mu\nu}$ . It is ~ easy to show that:  $\epsilon_{kl}^* = \epsilon_{kl}$  (real),  $\epsilon_{k4}^* = -\epsilon_{k4}$  (imag.), satisfied for proper  $\Lambda^S$ .

**REMARKS** on the covariance matrix  $\underline{S}$  of Eq. (22).

1.  $\underline{S}$  in Eq. (22) is not unique, because the  $\underline{\gamma}_\mu$  are not unique [p. DE 9, Eqs. (30)-(32)].

As well,  $\underline{S}$  may contain an arbitrary phase factor, as we see by the following.

Let:  $\underline{S} \rightarrow \underline{S}' = (1 + \epsilon_{\mu\nu} \lambda_{\mu\nu}) \underline{S}$ , to  $\mathcal{O}(\epsilon)$   $\sqrt{\text{LT, Eq. (14)}}$ . The  $\epsilon_{\mu\nu}$  are numbers specifying the small LT, Eq. (14). The  $\lambda_{\mu\nu}$  are numbers  $\sim 1$ . (23)

Then  $\underline{S}'$  obeys the first of Eqs. (15), i.e.  $\underline{S}'^{-1} \underline{\gamma}_\mu \underline{S}' = \Lambda_{\mu\nu} \underline{\gamma}_\nu$  (neglect  $\mathcal{O}(\epsilon^2)$ ).

The second of the defining eqns in Eq. (15) then relates  $\underline{S}'$  &  $\underline{S}$ , as...

$$\underline{S}'^\dagger \underline{\gamma}_4 \underline{S}' = \underline{\gamma}_4 \Rightarrow [1 + (\epsilon_{\mu\nu} \lambda_{\mu\nu})^*] \underline{S}'^\dagger \underline{\gamma}_4 \underline{S} [1 + (\epsilon_{\mu\nu} \lambda_{\mu\nu})] = \underline{\gamma}_4$$

$= \underline{\gamma}_4$ , by 2nd of Eqs. (15)

So

$$[1 + (\epsilon_{\mu\nu} \lambda_{\mu\nu}) + (\epsilon_{\mu\nu} \lambda_{\mu\nu})^*] = 1, \text{ to } \mathcal{O}(\epsilon) \Rightarrow (\epsilon_{\mu\nu} \lambda_{\mu\nu}) \text{ is pure imag}^y = i\delta.$$

$$\text{Then: } \underline{S}' = (1 + i\delta) \underline{S} = (e^{i\delta}) \underline{S}, \text{ to 1st order in } \delta = -i \epsilon_{\mu\nu} \lambda_{\mu\nu}. \quad (24)$$

This analysis shows that if  $\underline{S}$  obeys the defining eqns in Eq. (15), so does  $\underline{S} e^{i\delta}$ , with  $\delta =$  arbitrary phase (to  $\mathcal{O}(\epsilon)$ ). This phase can be adjusted to give the same effective  $\underline{S}$  when and if the  $\underline{\gamma}_\mu$ 's are shifted. In what follows, we will not do this... we'll use  $\delta=0$  and the standard representation of the  $\underline{\gamma}_\mu$ 's.

2. It is convenient to rewrite  $\underline{S}$  of Eq. (22) in terms of a new matrix  $\underline{\sigma}_{\mu\nu}$ , i.e.:

$$\underline{\sigma}_{\mu\nu} = -\frac{1}{2}i (\underline{\gamma}_\mu \underline{\gamma}_\nu - \underline{\gamma}_\nu \underline{\gamma}_\mu) = \begin{cases} -i \underline{\gamma}_\mu \underline{\gamma}_\nu, & \text{for } \nu \neq \mu, \\ 0, & \text{for } \nu = \mu. \end{cases} \quad \begin{matrix} \text{antisymmetric} \\ \underline{\sigma}_{\nu\mu} = (-1) \underline{\sigma}_{\mu\nu} \end{matrix} \quad (25)$$

All the nonzero  $\underline{\sigma}_{\mu\nu}$ 's exhibit the property:

$$\rightarrow \underline{\sigma}_{\mu\nu}^2 = -(\underline{\gamma}_\mu \underline{\gamma}_\nu)(\underline{\gamma}_\mu \underline{\gamma}_\nu) = +(\underline{\gamma}_\mu \underline{\gamma}_\mu)(\underline{\gamma}_\nu \underline{\gamma}_\nu) = \underline{1} \times \underline{1} = \underline{1}. \quad (26)$$

In terms of the  $\underline{\sigma}_{\mu\nu}$ , we can write our Dirac covariance matrix of Eq. (22) as...

$$\underline{S} = \underline{1} + \frac{1}{4}i \epsilon_{\mu\nu} \underline{\sigma}_{\mu\nu}, \text{ for small LT: } \Lambda_{\mu\nu} = \delta_{\mu\nu} + \epsilon_{\mu\nu}. \quad (27)$$

The matrices  $\underline{\sigma}_{\mu\nu}$  relate to how the Dirac particle's spin transform under LT's  $\underline{\Lambda}$ .

# Explicit form of $\underline{S}$ for a pure spatial rotation.

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4) We shall now construct the covariance matrices  $\underline{S}$  explicitly for 2 specific LT's.

Two things change during the LT: the cds  $x \rightarrow x' = \Lambda x$ , and the wavefn  $\psi \rightarrow \psi' = \underline{S}\psi$ :

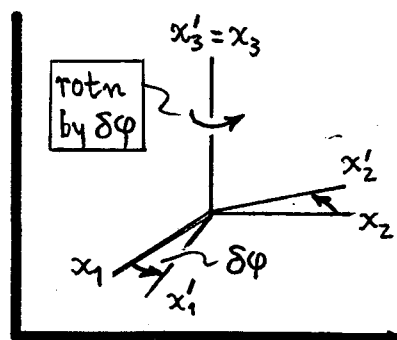
$$\text{under: } x_\mu \rightarrow x'_\mu = \Lambda_{\mu\nu} x_\nu, \quad \forall \Lambda_{\mu\nu} = \delta_{\mu\nu} + \epsilon_{\mu\nu} \text{ [to 1st order in } \epsilon], \text{ have:} \\ \psi(x) \rightarrow \psi'(x') = \underline{S}\psi(x), \quad \forall \underline{S} = \underline{1} + \frac{i}{4} \epsilon_{\mu\nu} \underline{\sigma}_{\mu\nu}, \text{ the } \underline{\sigma}_{\mu\nu} \text{ per Eq. (25).} \quad (28)$$

We will look at explicit  $\underline{S}$ 's for: (A) a pure space rotation about the  $x_3$ -axis, (B) a pure Lorentz boost along the  $x_3$ -axis (both to  $\mathcal{O}(\epsilon)$ ). These exercises will show more clearly how the LT properties of the Dirac 4-spinors  $\psi$  differ from 4-vectors.

(A) Pure space rotation by  $\delta\varphi$  about  $x_3$ -axis.

The usual LT is in this case...

$$\rightarrow \underline{\Lambda} = \begin{bmatrix} 1 & +\delta\varphi & 0 & 0 \\ -\delta\varphi & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix} \quad \left\{ \begin{array}{l} \text{So, the } \epsilon\text{'s are:} \\ \underline{\epsilon}_{12} = \delta\varphi = -\underline{\epsilon}_{21}, \\ \text{all other } \epsilon_{\mu\nu} = 0. \end{array} \right. \quad (29)$$



The prescribed covariance matrix is...

$$\underline{S}_3(\delta\varphi) = \underline{1} + \frac{1}{4} i [ (+\delta\varphi) \underline{\sigma}_{12} + (-\delta\varphi) \underline{\sigma}_{21} ] = \underline{1} + \frac{1}{2} i \delta\varphi \underline{\sigma}_{12}$$

$$\text{or } \underline{S}_3(\delta\varphi) = \underline{1} \exp\left(\frac{1}{2} i \delta\varphi \underline{\sigma}_{12}\right), \text{ to 1st order in } \delta\varphi;$$

$$\text{and } \underline{S}_3(\varphi) = \underline{1} \exp\left(\frac{1}{2} i \varphi \underline{\sigma}_{12}\right), \text{ for a finite rotation } \varphi \text{ about } x_3\text{-axis.} \quad (30)$$

$\underline{S}_3(\varphi)$  can be put in trig form as follows...

$$\underline{S}_3(\varphi) = \underline{1} e^{\frac{1}{2} i \varphi \underline{\sigma}_{12}} = \underline{1} \left\{ \underline{1} + i \left(\frac{\varphi}{2}\right) \underline{\sigma}_{12} - \frac{1}{2!} \left(\frac{\varphi}{2}\right)^2 \underline{\sigma}_{12}^2 - \frac{i}{3!} \left(\frac{\varphi}{2}\right)^3 \underline{\sigma}_{12}^3 + \dots \right\}$$

$$\text{or } \underline{S}_3(\varphi) = \underline{1} \cos(\varphi/2) + i \underline{\sigma}_{12} \sin(\varphi/2). \quad (31)$$

¶ Prove Eq. (30) by claiming rotations about the  $x_3$ -axis (alone) are associative, so...

$$\underline{S}(\varphi + \delta\varphi) = \underline{S}(\varphi) \underline{S}(\delta\varphi) \Rightarrow \underline{S}(\varphi) + \delta\varphi (d\underline{S}/d\varphi) = \underline{S}(\varphi) [\underline{1} + \frac{1}{2} i \delta\varphi \underline{\sigma}_{12}],$$

$$\text{or } d\underline{S}/d\varphi = \frac{1}{2} i \underline{S} \underline{\sigma}_{12} \leftarrow \text{a differential eqn for } \underline{S} = \underline{S}(\varphi).$$

Solution is Eq. (30):  $\underline{S}(\varphi) = \underline{S}(0) \exp\left(\frac{1}{2} i \varphi \underline{\sigma}_{12}\right)$ , with choice  $\underline{S}(0) = \underline{1}$  obvious.

# Form & character of covariance matrix $\underline{S}$ for spatial rotations.

DE(37)

**REMARKS** on:  $\underline{S}_2(\varphi) = \underline{1} \cos(\varphi/2) + i \underline{\sigma}_{12} \sin(\varphi/2)$ , of Eq. (31).

1. An immediate surprise: upon a  $360^\circ$  spatial rotation,  $\underline{S}_2(360^\circ) = (-) \underline{1}$  is not the identity. We need a rotation of  $2 \times 360^\circ$  to get back to where we started.

2. We calculate  $\underline{\sigma}_{12}$  explicitly as follows...

$$\rightarrow \underline{\sigma}_{12} = -i \underline{\gamma}_1 \underline{\gamma}_2 = -i \begin{pmatrix} 0 & -i\sigma_1 \\ +i\sigma_1 & 0 \end{pmatrix} \begin{pmatrix} 0 & -i\sigma_2 \\ +i\sigma_2 & 0 \end{pmatrix} = -i \begin{pmatrix} \sigma_1 \sigma_2 & 0 \\ 0 & \sigma_1 \sigma_2 \end{pmatrix} \quad \begin{matrix} \text{the } \sigma_k = \\ \text{Pauli} \\ \text{matrices} \end{matrix} \quad (32)$$

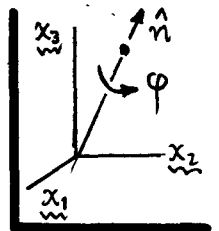
... but:  $\sigma_1 \sigma_2 = i \sigma_3$ , so:  $\underline{\sigma}_{12} = \begin{pmatrix} \sigma_3 & 0 \\ 0 & \sigma_3 \end{pmatrix}$ . Generally:  $\sigma_{ij} = \epsilon_{ijk} \begin{pmatrix} \sigma_k & 0 \\ 0 & \sigma_k \end{pmatrix}$ .

Then, for a rotation by  $\varphi$  about the  $x_3$ -axis, the covariance matrix is...

$$\underline{S}_2(\varphi) = \underline{1} \cos(\varphi/2) + i \underline{\sigma}_3 \sin(\varphi/2) = \exp[i\varphi(\underline{\sigma}_3/2)], \quad \text{w/ } \underline{\sigma}_3 = \begin{pmatrix} \sigma_3 & 0 \\ 0 & \sigma_3 \end{pmatrix}. \quad (33)$$

3. An obvious generalization of Eq. (33) for rotation by  $\varphi$  about an arbitrary axis specified by unit vector  $\hat{n}$  is...

$$\left[ \begin{array}{l} \underline{S}_n(\varphi) = \exp[i\varphi(\hat{n} \cdot \underline{\Sigma}/2)] = \underline{1} \cos(\varphi/2) + i(\hat{n} \cdot \underline{\Sigma}) \sin(\varphi/2), \\ \text{w/ } \underline{\Sigma} = \begin{pmatrix} \sigma & 0 \\ 0 & \sigma \end{pmatrix}, \hat{n} = \text{unit vector along rotation axis, and: } (\hat{n} \cdot \underline{\Sigma})^2 = \underline{1}. \end{array} \right. \quad (34)$$



This means that the Dirac wavefn  $\psi$  will transform under space rotations as...

$$\left[ \psi = \begin{pmatrix} \phi \\ \chi \end{pmatrix} \xrightarrow[\text{about axis } \hat{n}]{\text{rotn by } \varphi} \psi' = \underline{S}_n(\varphi) \psi = \begin{pmatrix} [\exp(i\varphi \hat{n} \cdot \underline{\sigma}/2)] \phi \\ [\exp(i\varphi \hat{n} \cdot \underline{\sigma}/2)] \chi \end{pmatrix}. \right. \quad (35)$$

4. An important feature of Eq. (35): under a space rotation by  $\varphi$  about axis  $\hat{n}$ , any scalar wavefn  $\psi$  transforms via an angular momentum operator  $\underline{J}$  as<sup>#</sup>:

$$\left[ \psi \xrightarrow[\text{about } \hat{n}]{\varphi} \psi' = [\exp(i\varphi \hat{n} \cdot \underline{J}/\hbar)] \psi \quad \begin{matrix} \text{J = } \varphi \text{ momentum operator,} \\ \text{obeying: } \underline{J} \times \underline{J} = i\hbar \underline{J}. \end{matrix} \right. \quad (36)$$

All 4 of the scalar entries in Dirac's  $\psi$  in Eq. (35) undergo such a (unitary) transform under rotation by  $\varphi$ , if we identify  $\underline{J} = (\hbar/2)\underline{\sigma}$ . So we confirm:

Particles described by the Dirac wave equation possess an intrinsic angular momentum:  $\underline{J} = (\hbar/2)\underline{\sigma}$ . This is the particle's spin, w/ eigenvalues  $\pm \hbar/2$ . (37)

<sup>#</sup> Davydov, Sec. II. 18(c); Schiff "QM" (3rd ed), Sec. 27; etc.



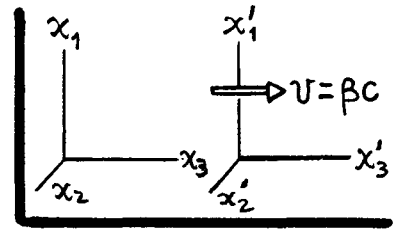
## Explicit form of covariance matrix $S$ for pure Lorentz boost.

DE (38)

### (B) Pure Lorentz boost along $x_3$ -axis.

The cosmal LT for this case is ( $\beta = \text{cosmal}$ ,  $\gamma = 1/\sqrt{1-\beta^2} \rightarrow 1$ )...

$$\rightarrow \Lambda = \left[ \begin{array}{cc|cc} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & +\delta\theta \\ 0 & 0 & -\delta\theta & 1 \end{array} \right] \quad \begin{array}{l} \text{the cosmals are now:} \\ \underline{E_{34} = \delta\theta = i\beta = -E_{43}}, \\ \text{all other } E_{\mu\nu} = 0 \end{array} \quad (38)$$



Compare with Eq. (29). We now have a "rotation" in the 34 rather than 12 plane.

By analogy with the treatment in Eqs. (30) & (31), the covariance matrix is:

$$\underline{S_3(\beta)} = \underline{1} \exp\left(\frac{1}{2} i \theta \underline{\sigma_{34}}\right) = \underline{1} \cos(\theta/2) + i \underline{\sigma_{34}} \sin(\theta/2)$$

$$\text{or } \boxed{\underline{S_3(\beta)} = \underline{1} \exp\left(-\frac{1}{2} \varphi \underline{\sigma_{34}}\right) = \underline{1} \cosh(\varphi/2) - \underline{\sigma_{34}} \sinh(\varphi/2)}, \quad \begin{array}{l} \text{w/ } \varphi = i\theta, \text{ and:} \\ \underline{\tanh \varphi = \beta}. \end{array} \quad (39)$$

For  $\sigma_{34}$ , we calculate:  $\left[ \sigma_{34} = -i \gamma_3 \gamma_4 = - \begin{pmatrix} 0 & -i\sigma_3 \\ i\sigma_3 & 0 \end{pmatrix} \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix} = \begin{pmatrix} 0 & \sigma_3 \\ \sigma_3 & 0 \end{pmatrix} \right]$ , and so:

$$\underline{S_3(\beta)} = \left( \begin{array}{cc} 1 \cosh(\varphi/2) & -\sigma_3 \sinh(\varphi/2) \\ -\sigma_3 \sinh(\varphi/2) & 1 \cosh(\varphi/2) \end{array} \right), \quad \tanh \varphi = \beta; \quad (40)$$

$$\begin{array}{l} \text{w/ } \cosh \varphi = \gamma = E/mc^2 \Rightarrow \underline{\cosh(\varphi/2)} = \sqrt{\frac{1}{2}(\cosh \varphi + 1)} = \sqrt{(E+mc^2)/2mc^2}, \\ \text{and } \underline{\sinh(\varphi/2)} = \sqrt{\cosh^2(\varphi/2) - 1} = \sqrt{(E-mc^2)/2mc^2}. \end{array}$$

### REMARKS on $\underline{S_3(\beta)}$ .

1. Now the Dirac wavefunction transforms under a Lorentz boost along the  $x_3$  axis as:

$$\left[ \begin{pmatrix} \phi \\ \chi \end{pmatrix} \xrightarrow[\text{along } x_3\text{-axis}]{\text{boost } \beta} \begin{pmatrix} \phi' \\ \chi' \end{pmatrix} = \begin{pmatrix} 1 \cosh(\varphi/2) & -\sigma_3 \sinh(\varphi/2) \\ -\sigma_3 \sinh(\varphi/2) & 1 \cosh(\varphi/2) \end{pmatrix} \begin{pmatrix} \phi \\ \chi \end{pmatrix}. \quad (41)$$

2. In contrast to the pure space rotation [Eq. (35)] ( $\text{rot}^n$  in 12 plane), the spacetime rotation [Eq. (41)] ( $\text{rot}^n$  in 34 plane) mixes components of the otherwise independent bispinors  $\phi$  &  $\chi$ . There is a distant analogy with 4-vectors here... a pure space rotation does not mix space & time components, while a spacetime rotation does. (This suggests that Dirac's  $\psi$  must have at least 4 components). But  $\psi$  by itself is not a 4-vector; it doesn't transform that way [Remark 1, p. DE37]. On the other hand,  $\bar{\psi} \gamma_\mu \psi$  is a 4-vector, as we showed in Eq. (11).