

Wave Eqns for \mathbf{E} & \mathbf{B} : Motion of the EM Field.

ME2

Poynting's Energy Theorem (Ref. Jackson Sec. 6.8).

1) Now that we've added t -variation, all the quantities on the last page (\mathbf{E} , \mathbf{B} , ϕ , \mathbf{A} , etc.) can "travel"; the scale velocity is $c = 3 \times 10^{10}$ cm/sec. To see this...

ASIDE

1. Assume empty space ($\rho=0$, $\mathbf{J}=0$) \Rightarrow MAXWELL'S EQUATIONS (in vacuo) $\left\{ \begin{array}{l} \textcircled{1} \nabla \cdot \mathbf{E} = 0, \quad \textcircled{2} \nabla \cdot \mathbf{B} = 0, \\ \textcircled{3} \nabla \times \mathbf{E} = -\frac{1}{c} \frac{\partial \mathbf{B}}{\partial t}, \quad \textcircled{4} \nabla \times \mathbf{B} = +\frac{1}{c} \frac{\partial \mathbf{E}}{\partial t}. \end{array} \right.$

$$\begin{aligned} 2. \nabla \times \{ \text{Eq. } \textcircled{3} \} &\Rightarrow \nabla \times (\nabla \times \mathbf{E}) = -\frac{1}{c} \frac{\partial}{\partial t} (\nabla \times \mathbf{B}) \\ &\quad \nabla(\nabla \cdot \mathbf{E}) - \nabla^2 \mathbf{E} \quad \text{use Eq. } \textcircled{4} \\ &\quad \rightarrow 0, \text{ by Eq. } \textcircled{1} \end{aligned} \quad (9)$$

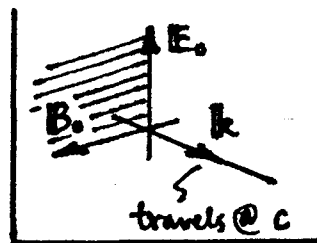
$$\text{i.e.} \quad 0 - \nabla^2 \mathbf{E} = -\frac{1}{c^2} \frac{\partial^2 \mathbf{E}}{\partial t^2}, \quad \text{or} \quad \boxed{(\nabla^2 - \frac{1}{c^2} \frac{\partial^2}{\partial t^2}) \mathbf{E}(\mathbf{r}, t) = 0}. \quad (10)$$

3. Eq. (10) is a wave equation for \mathbf{E} . Since the "in vacuo" Maxwell Eqns, in Eq. (9), are invariant under $(\mathbf{E}, \mathbf{B}) \rightarrow (\mathbf{B}, -\mathbf{E})$, we can derive the same eqn for \mathbf{B} , viz. $(\nabla^2 - \frac{1}{c^2} \frac{\partial^2}{\partial t^2}) \mathbf{B}(\mathbf{r}, t) = 0$. Prototype solutions to such eqns are: $(\mathbf{E}, \mathbf{B}) = (\mathbf{E}_0, \mathbf{B}_0) e^{i(\mathbf{k} \cdot \mathbf{r} - \omega t)}$, with $k = \omega/c$, and $\mathbf{E}_0 \perp \mathbf{B}_0$ const vectors. The solutions are "plane waves" at frequency ω , advancing in direction \mathbf{k} at const phase velocity $c = \omega/k$.

4. Max. Eq. $\textcircled{3}$ relates the amplitudes \mathbf{E}_0 & \mathbf{B}_0 by:

$$\mathbf{k} \times \mathbf{E}_0 = (\omega/c) \mathbf{B}_0. \text{ So we have a transverse wave of}$$

\mathbf{E} & \mathbf{B} fields traveling as shown. LET THERE BE LIGHT!



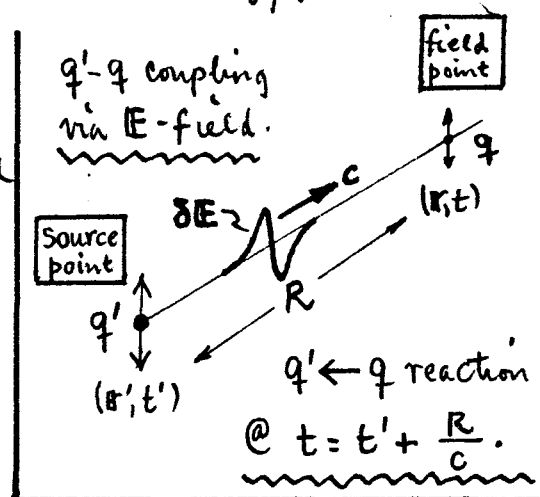
5. The light wave just invented is transporting a field energy density: $u = \frac{1}{8\pi} \langle \mathbf{E}_0^2 + \mathbf{B}_0^2 \rangle_{\text{avg}} = \frac{1}{8\pi} \mathbf{E}_0^2$, and therefore an effective mass density $\frac{u}{c^2}$, and therefore an effective momentum density $\sim u/c$.

... SO... Traveling fields \mathbf{E} & \mathbf{B} transport momentum as well as energy.

END ASIDE

- 2) Poynting's Theorems will establish energy & momentum conservation laws for EM systems which involve time-varying \mathbf{E} & \mathbf{B} fields, and they will do so by directly investing the fields themselves with energy & momentum.

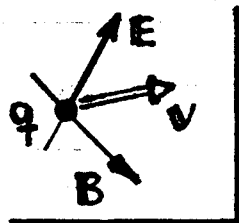
But first, there is a simpler way to look at why the fields carry momentum. For q' - q coupled by an \mathbf{E} -field, when q' is "jiggled", q will begin "jiggling" after a time delay $(t-t') = R/c$. The delay is due to the fact that the \mathbf{E} -field disturbance $\delta\mathbf{E}$, which relays to q the fact that q' has moved, travels over the separation distance R at finite speed c . During the interval $(t-t')$ the $q' \rightarrow q$ energy & momentum transfer resides in neither charge -- the energy & momentum transfer is transported (at c) by the fields themselves. This will be true so long as $c = \text{any finite \#}$. Also, any statement regarding energy/momentum conservation must necessarily involve the fields as well as the particles. This is what Poynting realized.



This is an astonishing idea. Conceptually, it is a very large step from characterizing energy/momentum & conservation laws for localized, discrete, Newtonian-type particles, to carrying out the same program for non-localized, diffuse Maxwellian-type fields. In fact, this step was the first time that classical physics began to give up on the previously sharp distinction between particles & fields -- these entities could now share similar properties (in fact they had to). This "blurring" of particle (point-like) and field (wave-like) characteristics set the stage for the invention and acceptance of QM, some 40 years later, where the main message is... it is a Big Mistake to call anything purely a particle or purely a wave.

3) Now for the nuts & bolts of Poynting's Theorem on conservation of energy.

1. For a single q in fields \mathbf{E} & \mathbf{B} ...



Fields do work on q at a rate $\left. \begin{array}{l} \text{Fields do work} \\ \text{on } q \text{ at a rate} \end{array} \right\} \frac{dW}{dt} = \mathbf{v} \cdot \mathbf{F}, \quad \text{w/ } \mathbf{F} = q(\mathbf{E} + \frac{\mathbf{v}}{c} \times \mathbf{B});$

so $\frac{dW}{dt} = q(\mathbf{v} \cdot \mathbf{E} + \frac{1}{c} \mathbf{v} \cdot (\mathbf{v} \times \mathbf{B})) = (q\mathbf{v}) \cdot \mathbf{E} \quad \text{--- } \equiv 0 \text{ (B does no work at all.)}$

(11)

Many q 's $\Rightarrow q\mathbf{v} \rightarrow \int (nq\mathbf{v}) d^3x$, so $\boxed{\frac{dW}{dt} = \int_V \mathbf{J} \cdot \mathbf{E} d^3x}$.

(12)

q 's/vol. \uparrow , and $nq\mathbf{v} \rightarrow \mathbf{J}$.

This energy change relates directly to the mechanical motion of the q 's comprising the current density \mathbf{J} -- it is really just $\frac{d}{dt}$ (kinetic energy) of that motion. We are not accounting explicitly for any radiation energy lost by \mathbf{J} during any accelerations it may undergo. *

2. We want to balance the energy gained by \mathbf{J} in Eq. (12) with the energy lost (supplied) by the fields. Accordingly, express $\mathbf{J} \cdot \mathbf{E}$ wholly in terms of fields:

$$(\nabla \times \mathbf{H} = \frac{1}{c} \frac{\partial \mathbf{D}}{\partial t} + \frac{4\pi}{c} \mathbf{J}) \cdot \mathbf{E} \Rightarrow \mathbf{J} \cdot \mathbf{E} = \frac{1}{4\pi} [c \mathbf{E} \cdot (\nabla \times \mathbf{H}) - \mathbf{E} \cdot \frac{\partial \mathbf{D}}{\partial t}]$$

$$= \mathbf{H} \cdot (\nabla \times \mathbf{E}) - \nabla \cdot (\mathbf{E} \times \mathbf{H}), \text{ by a vector identity}$$

$$= (-) \frac{1}{c} (\partial \mathbf{B} / \partial t), \text{ by Faraday's Law.}$$

... (next page) ...

* For nonrelativistic motion, a single q loses energy to EM radiation at a rate given by the Larmor formula [Jkⁿ Eq. (14.22)]: $(dW/dt)_{\text{rad}} = \frac{2}{3} (q^2/c^3) |\dot{\mathbf{v}}|^2$. This energy loss is not accounted for in dW/dt of Eq. (12), or in the Lorentz force law, unless \mathbf{E} includes the so-called "radiation fields" in Jkⁿ Eqs. (14.13) & (14.14) [the radⁿ fields are those parts of \mathbf{E} & \mathbf{B} generated by q itself which depend on $\dot{\mathbf{v}}$ and fall off with distance as $1/R$]. If the \mathbf{E} & \mathbf{B} appearing in Eqs. (11)-(15) here are thought of as external fields which exclude q 's self-fields, then Poynting's Theorem in Eq. (14) is correct only up to the neglect of q 's radiation. It is not clear that q 's self-fields have ever been satisfactorily included.

Poynting (cont'd), Conservation of Total Energy.

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So//

$$\mathbf{J} \cdot \mathbf{E} = -\nabla \cdot \mathbf{S} - \frac{1}{4\pi} \left(\mathbf{E} \cdot \frac{\partial \mathbf{D}}{\partial t} + \mathbf{H} \cdot \frac{\partial \mathbf{B}}{\partial t} \right), \quad \left. \vphantom{\frac{1}{4\pi}} \right\} (13)$$

where: $\underline{\mathbf{S}} = \frac{c}{4\pi} (\mathbf{E} \times \mathbf{H}) \leftarrow$ called "Poynting Vector".

If the medium is linear (e.g. $\mathbf{D} = \epsilon \mathbf{E}$ & $\mathbf{B} = \mu \mathbf{H}$, with ϵ and μ indpt of fields), then: $\mathbf{E} \cdot \frac{\partial \mathbf{D}}{\partial t} = \frac{1}{2} \frac{\partial}{\partial t} (\mathbf{E} \cdot \mathbf{D})$, and: $\mathbf{H} \cdot \frac{\partial \mathbf{B}}{\partial t} = \frac{1}{2} \frac{\partial}{\partial t} (\mathbf{B} \cdot \mathbf{H})$, so (13) becomes...

$$\boxed{\frac{\partial u}{\partial t} + \nabla \cdot \mathbf{S} = -\mathbf{J} \cdot \mathbf{E}}, \quad \text{w// } \underline{u} = \frac{1}{8\pi} (\mathbf{E} \cdot \mathbf{D} + \mathbf{B} \cdot \mathbf{H}) \quad \text{total field energy density.} \quad (14)$$

This is one form of Poynting's Theorem on energy conservation for fields + particles [Jk¹² Eq. (6.108)]... it balances energy flow out of the field sector on the LHS of the eqn against energy flow into the particle sector on the RHS.

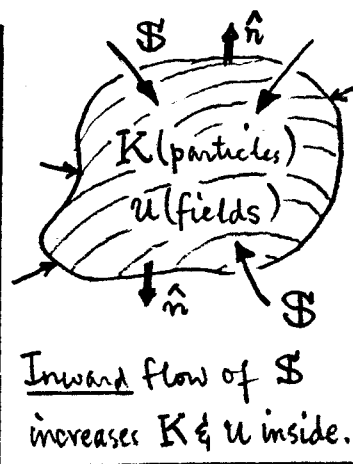
3. Integrate Eq. (14) over a volume V enclosed by surface S .

Assume no particles leave V , but that the particle kinetic energy K inside and field energy density u in V may change because of the motions. Then (14) \Rightarrow

$$\left[\int_V \mathbf{J} \cdot \mathbf{E} d^3x + \frac{\partial}{\partial t} \int_V u d^3x = - \oint_S \mathbf{S} \cdot \hat{n} da \right]$$

$\uparrow \frac{dK}{dt}, \text{ particles} \quad \uparrow \frac{dU}{dt}, \text{ fields}$

$$\text{i.e., } \boxed{\frac{d}{dt} [K(\text{particle}_{K.E.}) + U(\text{field energy})] = (-) P} \quad \int P = \oint_S \mathbf{S} \cdot \hat{n} da \text{ is the flux of } \mathbf{S} \text{ thru surface.} \quad (15)$$



Whether or not $(K+U)$ increases in V depends on whether or not $\mathbf{S} = \frac{c}{4\pi} (\mathbf{E} \times \mathbf{H})$ is flowing in across the surface. This is another form of Poynting's Energy Theorem -- it suggests that all changes in the total system energy $(K+U)$ are accompanied by an inward (or outward) flow of \mathbf{S} .

NOTE: If surface $S \rightarrow \infty$, and \mathbf{E} & \mathbf{H} vanish there, then (15) $\Rightarrow \frac{d}{dt} (K+U) = 0$, or: $K+U = \text{const.}$ Then any ΔK results in a $\Delta U = (-) \Delta K$, etc.

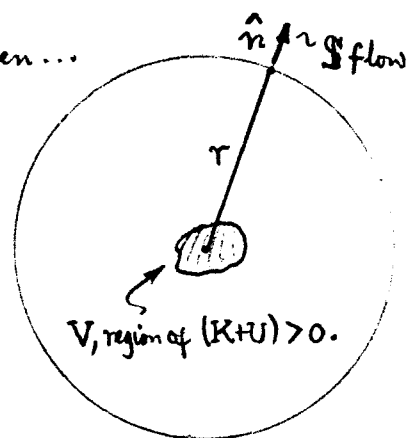
Poynting (cont'd) Remarks on the Energy Theorem.

ME 6

REMARKS on Poynting Energy Theorem.

4. If, in Eq. (15), we let the surface recede to ∞ , then...

$$\begin{aligned} \rightarrow \frac{d}{dt}(K+U) &= -\frac{c}{4\pi} \oint_{\infty} (\mathbf{E} \times \mathbf{H}) \cdot \hat{\mathbf{n}} da \\ &= -\frac{c}{4\pi} \lim_{r \rightarrow \infty} \oint (\mathbf{E} \times \mathbf{H})_r r^2 d\Omega. \quad (16) \end{aligned}$$

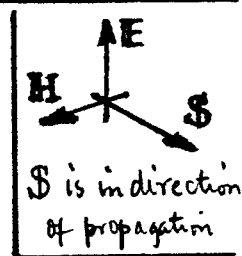


"Normal" fields \mathbf{E} fall off as $\frac{1}{r^2}$ (monopole) or faster, and \mathbf{H} falls off as $\frac{1}{r^3}$ (dipole) or faster. For such fields $(\mathbf{E} \times \mathbf{H})_r r^2$ falls off as $\frac{1}{r^3}$ or faster, and the \oint flow vanishes at ∞ .

BUT, THERE IS AN EXCEPTION. If the charges in V are accelerated, they generate "radiation fields" \mathbf{E} & \mathbf{H} transverse to $\hat{\mathbf{r}}$, which (each) fall off as $\frac{1}{r}$. Then $(\mathbf{E} \times \mathbf{H})_r r^2 = \text{const}$ as $r \rightarrow \infty$, and the RHS of (16) is finite.


For radiation fields, \oint flow at ∞ is finite, and energy is lost to the system.*

5. The Poynting vector $\mathbf{S} = \frac{c}{4\pi} (\mathbf{E} \times \mathbf{H})$ enters the theory [in the energy eqn: $\mathbf{J} \cdot \mathbf{E} + (\partial u / \partial t) = -\nabla \cdot \mathbf{S}$] as a field energy transport per unit time & area. We have also suggested that traveling fields transport momentum. \mathbf{S} accommodates this notion also, by means of the following picture...



A) Assume \mathbf{S} is a radiant energy transport (not transmitted by massive particles).

B) Let energy transported by \mathbf{S} be in form of massless "photons" hitting area A :

$\left. \begin{array}{l} n \text{ photons/unit vol.,} \\ \text{traveling at speed } c, \\ \text{each photon energy} = \mathcal{E} \end{array} \right\}$		$\left. \begin{array}{l} \# \text{ photons incident/sec} = nAc, \\ \text{energy transport} \\ \text{per unit time \& area} \end{array} \right\} \underline{\underline{S = \frac{(nAc)\mathcal{E}}{A} = cn\mathcal{E}.}} \quad (17)$
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C) But $\mathcal{E} = pc$ for photons, so: $S = c^2 np = c^2 \times (\text{momentum density of incident radiation})$.

This exercise thus connects \mathbf{S} with momentum transport as well as energy flux.

* We will study the peculiarities of radiation fields later, in Jackson's Chap. 9, 14 & 15.

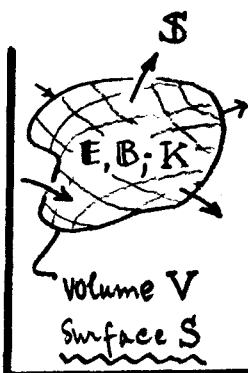
Poynting's Momentum Theorem (Ref. Jackson Sec. 6.8).

1) Having derived a statement re energy transfer between particles & EM fields... ★

$$\left[\frac{d}{dt} (\mathcal{E}_{\text{mech}} + \mathcal{E}_{\text{field}}) = - \oint_S \mathcal{S} \cdot \hat{n} da, \quad \mathcal{S} = \frac{c}{4\pi} (\mathbf{E} \times \mathbf{H}); \right.$$

$$\left[\begin{array}{l} \text{Where: } \dot{\mathcal{E}}_{\text{mech}} = \dot{K}(\text{particle K.E.}) = \int_V (\mathbf{J} \cdot \mathbf{E}) dV, \end{array} \right. \quad (18)$$

$$\left[\begin{array}{l} \text{and: } \dot{\mathcal{E}}_{\text{field}} = \dot{U}(\text{field energy}) = \int_V \frac{1}{8\pi} \left[\frac{\partial}{\partial t} (\mathbf{E} \cdot \mathbf{D} + \mathbf{B} \cdot \mathbf{H}) \right] dV; \end{array} \right.$$



We expect to find a similar statement re momentum transfer, e.g.

$$\rightarrow \frac{d}{dt} (\mathbf{P}_{\text{mech}} + \mathbf{P}_{\text{field}}) = (\text{vector}) \text{ flux of something.} \quad (19)$$

This is in fact true... it's part II of Poynting's Theorem. We have reason to believe that \mathcal{S} has something to do with the field momentum; in fact it turns out that $\mathbf{P}_{\text{field}} = \int_V (\mathcal{S}/c^2) dV$. The hard part of (19) is the RHS.

2) The LHS of (19) is a force, so start from Lorentz' Law...

$$\frac{d\mathbf{p}}{dt} = q(\mathbf{E} + \frac{\mathbf{v}}{c} \times \mathbf{B}) \rightarrow \frac{d\mathbf{P}_{\text{mech}}}{dt} = \int (\rho \mathbf{E} + \frac{1}{c} \mathbf{J} \times \mathbf{B}) dV. \quad (20)$$

\uparrow single q \uparrow many q 's ① $\frac{1}{4\pi} \nabla \cdot \mathbf{E}$, ② $\frac{1}{4\pi} (c \nabla \times \mathbf{B} - \frac{\partial \mathbf{E}}{\partial t})$.

This serves to define the particle forces $\dot{\mathbf{P}}_{\text{mech}}$. As before, we re-express the elements of $\dot{\mathbf{P}}_{\text{mech}}$ in terms of fields alone: put in $\rho = \frac{1}{4\pi} \nabla \cdot \mathbf{E}$, and eliminate

★ There is a fuzziness introduced here, in going from a time & space local energy statement: $\mathbf{J} \cdot \mathbf{E} + (\partial u / \partial t) = -\nabla \cdot \mathcal{S}$, to the global (integral) claim of Eq. (18), particularly in moving the energy flux term in \mathcal{S} out of the volume V and on to a distant surface S . The reason is that points in V separated by distance Δr have a built-in time delay $\Delta r/c$ for EM signals passing between them. So if the \mathbf{E} & \mathbf{H} fields in V are the source of \mathcal{S} passing through the surface, \mathcal{S} does not even appear there until a suitable time has elapsed. The LHS & RHS of: $\frac{d}{dt} (\mathcal{E}_{\text{mech}} + \mathcal{E}_{\text{field}}) = - \oint_S \mathcal{S} \cdot \hat{n} da$, are then running on different time scales.

$\mathbf{J} = \frac{1}{4\pi} (c \nabla \times \mathbf{B} - \partial \mathbf{E} / \partial t) \dots$ we are assuming a "non-medium", with $\epsilon = 1$ & $\mu = 1$.

With these substitutions and a few vector identities, we find that Eq. (21) yields:

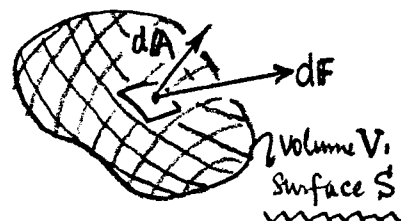
$$\left\{ \begin{aligned} \left[\frac{d}{dt} [\mathbf{P}_{\text{mech}} + \int_V (\mathbf{S}/c^2) dV] = \int_V \mathbf{F} dV \right], \quad \text{w/ } \mathbf{S} = \frac{c}{4\pi} (\mathbf{E} \times \mathbf{H}); \\ \text{and/ } \mathbf{F} = \frac{1}{4\pi} [\mathbf{E}(\nabla \cdot \mathbf{E}) - \mathbf{E} \times (\nabla \times \mathbf{E}) + \mathbf{B}(\nabla \cdot \mathbf{B}) - \mathbf{B} \times (\nabla \times \mathbf{B})]. \end{aligned} \right\} \quad (21)$$

The LHS of (21) is readily interpreted... $\dot{\mathbf{P}}_{\text{mech}} = \int_V (\rho \mathbf{E} + \frac{1}{c} \mathbf{J} \times \mathbf{B}) dV$ is clearly OK for the force exerted by the fields on the particles (represented by ρ & \mathbf{J}), while $\dot{\mathbf{P}}_{\text{field}} = \frac{d}{dt} \int_V (\mathbf{S}/c^2) dV$ will do for field momentum changes. What remains is to write \mathbf{F} in a more palatable form... in fact \mathbf{F} is the divergence of a "stress tensor".

ASIDE General definition of a stress tensor $\underline{\mathbf{T}}$.

For a force $d\mathbf{F}$ acting thru surface area element dA on volume V , write

$$\left\{ \begin{aligned} d\mathbf{F} = \underline{\mathbf{T}} d\mathbf{A}, \text{ or } dF_i = \sum_k T_{ik} dA_k, \\ \text{where } \underline{\mathbf{T}} = (T_{ik}) \text{ is the "stress tensor"}. \end{aligned} \right\} \quad (24)$$



Write: $dF_i = T_{ik} dA_k \leftarrow$ use "summation convention": sum over repeated indices.

This covers possible fact that $d\mathbf{F}$ does not act along dA ... in addition to compression at dA , the force $d\mathbf{F}$ may also cause a shear. Now we can say...

$$F_i = \oint_S T_{ik} dA_k \leftarrow i^{\text{th}} \text{ comp. of } \underline{\text{total } \mathbf{F}} \text{ on } V,$$

$$\text{w/ } F_i = \int_V (\partial T_{ik} / \partial x_k) dV \leftarrow \text{by use Gauss' Divergence Theorem,}$$

$$\text{so/ } \underline{F_i = \int_V \mathbf{F}_i dV}, \quad \text{w/ } i^{\text{th}} \text{ comp.}^t \text{ of } \underline{\text{force}} \text{ in } V \text{ is: } \boxed{F_i = \int_V \frac{\partial T_{ik}}{\partial x_k} dV} \quad (25)$$

More compactly, the volume force is: $\mathbf{F} = \text{div } \underline{\mathbf{T}}$, where $\text{div } \underline{\mathbf{T}}$ is a vector, whose $i^{\text{th}} \text{ comp.}^t$ is: $(\text{div } \underline{\mathbf{T}})_i = \partial T_{ik} / \partial x_k$ (sum on k). Now, with some impunity, we can convert volume force integrals to surface stress integral via:

$$\boxed{\int_V \mathbf{F}_i dV = \oint_S T_{ik} dA_k} \quad (26)$$

NOTE: these definitions do not depend on the specific nature of the forces involved.

END
of
ASIDE

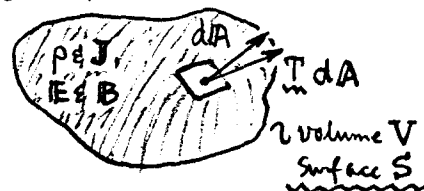
3) Some arithmetic [Jkⁿ Eqs. (6.119) & (6.120)] serves to show that for the \mathcal{F} in Eq. (21):

$$\rightarrow \mathcal{F}_i = \frac{1}{4\pi} [\mathbf{E}(\nabla \cdot \mathbf{E}) - \mathbf{E} \times (\nabla \times \mathbf{E}) + \mathbf{B}(\nabla \cdot \mathbf{B}) - \mathbf{B} \times (\nabla \times \mathbf{B})]_i = \partial T_{ik} / \partial x_k$$

where: $T_{ik} = \frac{1}{4\pi} (\mathbf{E}_i \mathbf{E}_k + \mathbf{B}_i \mathbf{B}_k) - u \delta_{ik}$ $\int \delta_{ik} = \text{Kronecker delta,}$
 $u = (\mathbf{E}^2 + \mathbf{B}^2)/8\pi.$ (27)

(T_{ik}) is called the "Maxwell stress tensor". Momentum conservation is now written:

$$\frac{d}{dt} (\mathcal{P}_{\text{mech}} + \mathcal{P}_{\text{field}}) = \oint_S \mathbf{T} \cdot \hat{n} dA \quad (28)$$



w/ $\dot{\mathcal{P}}_{\text{mech}} = \int_V (\rho \mathbf{E} + \frac{1}{c} \mathbf{J} \times \mathbf{B}) dV \leftarrow \text{mechanical (Lorentz) force on sources } \rho \text{ \& } \mathbf{J};$
 $\mathcal{P}_{\text{field}} = \int_V (\mathcal{S}/c^2) dV, \quad \mathcal{S} = \frac{c}{4\pi} (\mathbf{E} \times \mathbf{B}) \int \mathcal{S} = \text{Poynting vector,}$
 $\mathcal{S}/c^2 = \text{field momentum density;}$
 $T_{ik} = \frac{1}{4\pi} (\mathbf{E}_i \mathbf{E}_k + \mathbf{B}_i \mathbf{B}_k) - u \delta_{ik} \leftarrow \text{comp}^{\pm} \text{ of Maxwell stress tensor (in a non-).}$

4) In this picture, the total momentum of fields & particles in V does not change unless some \mathbf{T}_n flows in across the bounding surface S . This flow is measured by:

$$\rightarrow T_{ik} dA_k = \Delta(\text{momentum}) / \text{unit time, in } i^{\text{th}} \text{ direction across } dA. \quad (29)$$

the components T_{ik} have dimensions of: momentum/unit time & area.

Notice that if the surface S recedes to ∞ , where all nonradiative fields vanish faster than $1/R$, then $\oint_{\infty} \mathbf{T} \cdot \hat{n} dA \rightarrow 0$, and $(\mathcal{P}_{\text{mech}} + \mathcal{P}_{\text{field}}) = \text{const}$ is conserved.

We know, however, that this rule is "violated" for radiation fields.

[[Anyway, Poynting's Theorems make it clear that particles & fields must trade both momentum & energy during interactions. The fields really do have mechanical properties.]]

REMARKS

1. The global \leftarrow local caveat in footnote, p. ME 7, applies to Eq. (28) perforce.
2. Eq. (28) is done for a non-medium, where $\mathbf{D} = \mathbf{E}$, $\mathbf{B} = \mathbf{H}$. With matter present, the defⁿ of T_{ik} changes to: $T_{ik} = \frac{1}{4\pi} (\mathbf{E}_i \mathbf{D}_k + \mathbf{H}_i \mathbf{B}_k) - u \delta_{ik}$, $u = \frac{1}{8\pi} (\mathbf{E} \cdot \mathbf{D} + \mathbf{H} \cdot \mathbf{B})$. As discussed in Jkⁿ Sec. (6.9), there is some attendant interpretational flap on how to define the energy/momentum flow \mathcal{S} . We shall skip that discussion.