

Maxwell Equations: Vector & Scalar Potentials \mathbf{A} & ϕ .

In the static (time-independent) case, and for linear media ($\mathbf{D} = \epsilon \mathbf{E}$, $\mathbf{B} = \mu \mathbf{H}$):

$$\begin{cases} \nabla \cdot \mathbf{E} = \frac{4\pi}{\epsilon} \rho, & \nabla \times \mathbf{E} = 0 \Rightarrow \mathbf{E} = -\nabla \phi, & \text{w/ } \phi = \frac{1}{\epsilon} \int \frac{1}{R} \rho d^3x'; \\ \nabla \cdot \mathbf{B} = 0, & \nabla \times \mathbf{B} = \frac{4\pi\mu}{c} \mathbf{J} \Rightarrow \mathbf{B} = \nabla \times \mathbf{A}, & \text{w/ } \mathbf{A} = \frac{\mu}{c} \int \frac{1}{R} \mathbf{J} d^3x'. \end{cases} \quad (1)$$

This would be all of \mathbf{E} & \mathbf{M} , if it were not for the t -dependent terms we have left out. To accommodate those terms, we must modify the roles of ϕ & \mathbf{A} somewhat. The procedure goes as follows.

1) For t -dept. case, we have the "non-source" Maxwell Equations...

① $\nabla \cdot \mathbf{B} = 0$ \Rightarrow can use: $\boxed{\mathbf{B} = \nabla \times \mathbf{A}}$, with $\mathbf{A} = \mathbf{A}(\mathbf{r}, t)$ now a fun of t ; (2)

② $\nabla \times \mathbf{E} + \frac{1}{c} \frac{\partial \mathbf{B}}{\partial t} = 0$, or: $\nabla \times \left(\mathbf{E} + \frac{1}{c} \frac{\partial \mathbf{A}}{\partial t} \right) = 0$,

... so set: $\boxed{\mathbf{E} + \frac{1}{c} (\partial \mathbf{A} / \partial t) = -\nabla \phi}$, with $\phi = \phi(\mathbf{r}, t)$ now a fun of t . (3)

How \mathbf{A} & ϕ depend on t is dictated by the "Source" Maxwell Equations...

$$\begin{array}{l} \text{③ } \nabla \times \mathbf{H} = \frac{4\pi}{c} \mathbf{J} + \frac{1}{c} \frac{\partial \mathbf{D}}{\partial t} \\ \text{④ } \nabla \cdot \mathbf{D} = 4\pi \rho \end{array} \quad \left\| \begin{array}{l} \text{assume:} \\ \mathbf{D} = \epsilon \mathbf{E} \\ \mathbf{B} = \mu \mathbf{H} \end{array} \right\| \quad \begin{array}{l} \nabla \times \mathbf{B} = \frac{4\pi\mu}{c} \mathbf{J} + \frac{\mu\epsilon}{c} (\partial \mathbf{E} / \partial t), \\ \nabla \cdot \mathbf{E} = \frac{4\pi}{\epsilon} \rho. \end{array} \quad (4)$$

Put in: $\mathbf{B} = \nabla \times \mathbf{A}$, $\mathbf{E} = -\nabla \phi - \frac{1}{c} (\partial \mathbf{A} / \partial t)$, to Eqs. (4), use the identity $\nabla \times (\nabla \times \mathbf{A}) = \nabla (\nabla \cdot \mathbf{A}) - \nabla^2 \mathbf{A}$, and rearrange terms to get...

$$\boxed{\begin{aligned} \nabla^2 \phi + \frac{1}{c} \frac{\partial}{\partial t} (\nabla \cdot \mathbf{A}) &= -\frac{4\pi}{\epsilon} \rho, \\ \nabla^2 \mathbf{A} - (\mu\epsilon/\epsilon^2) \frac{\partial^2 \mathbf{A}}{\partial t^2} - \nabla \left[(\nabla \cdot \mathbf{A}) + \frac{\mu\epsilon}{c} \left(\frac{\partial \phi}{\partial t} \right) \right] &= -\frac{4\pi\mu}{c} \mathbf{J}. \end{aligned}} \quad (5)$$

Notice how the choice of potentials \mathbf{A} & ϕ in Eqs. (2) & (3) automatically satisfies Max. Eqs. ① & ②, while (4) Max. Eqs. ③ & ④ are left to specify (4) potentials (ϕ , \mathbf{A}).

2) The (ϕ, \mathbf{A}) eqns above [Eqs(5)] are 4 eqns in 4 unknowns (i.e. $(\phi; A_x, A_y, A_z)$).
 They can be made simpler, even decoupled, by imposing an additional condition linking ϕ & \mathbf{A} . In particular, we can choose...

$$\underbrace{\nabla \cdot \mathbf{A} + \frac{\mu\epsilon}{c} \frac{\partial \phi}{\partial t} = 0}_{\text{Called a "gauge condition".}} \Rightarrow \boxed{\begin{aligned} \nabla^2 \phi - \frac{\mu\epsilon}{c^2} \left(\frac{\partial^2 \phi}{\partial t^2} \right) &= -(4\pi/\epsilon)\rho, \\ \nabla^2 \mathbf{A} - \frac{\mu\epsilon}{c^2} \left(\frac{\partial^2 \mathbf{A}}{\partial t^2} \right) &= -(4\pi\mu/c)\mathbf{J}. \end{aligned}} \quad (6)$$

Marvelous, if true... now, by "just" solving these inhomogeneous wave eqns for ϕ & \mathbf{A} , we can solve the most general form of Maxwell's Eqs (in a linear medium) by calculating $\mathbf{B} = \nabla \times \mathbf{A}$, $\mathbf{E} = -\nabla\phi - \frac{1}{c}(\partial\mathbf{A}/\partial t)$.

Imposing the above "gauge condition" is possible because neither of the potentials ϕ & \mathbf{A} are uniquely defined by the fields \mathbf{E} & \mathbf{B} , i.e. more than one (ϕ, \mathbf{A}) corresponds to a given (\mathbf{E}, \mathbf{B}) . As follows...

$$\left\{ \begin{aligned} \text{if : } \phi \rightarrow \phi' &= \phi - \frac{1}{c}(\partial g / \partial t), \text{ and : } \mathbf{A} \rightarrow \mathbf{A}' = \mathbf{A} + \nabla g \quad \left\{ \begin{array}{l} \text{GAUGE} \\ \text{TRANSFORM} \end{array} \right. \\ \text{then : } \underline{\text{same}} \mathbf{B} = \nabla \times \mathbf{A} \text{ \& } \mathbf{E} = -\nabla\phi - \frac{1}{c} \frac{\partial \mathbf{A}}{\partial t} \end{aligned} \right. \text{ result from } (\phi', \mathbf{A}') \text{ \& } (\phi, \mathbf{A}). \quad (7)$$

The gauge fun $g(\mathbf{r}, t)$ is arbitrary, and it allows the following freedom...

$$\left\{ \begin{aligned} \text{If } (\phi, \mathbf{A}) \text{ don't satisfy : } \nabla \cdot \mathbf{A} + \frac{\mu\epsilon}{c} \left(\frac{\partial \phi}{\partial t} \right) &= 0, \text{ then let } (\phi, \mathbf{A}) \rightarrow (\phi', \mathbf{A}'), \\ \nabla \cdot \mathbf{A}' + \frac{\mu\epsilon}{c} \left(\frac{\partial \phi'}{\partial t} \right) &= \underbrace{\left[\nabla \cdot \mathbf{A} + \frac{\mu\epsilon}{c} \left(\frac{\partial \phi}{\partial t} \right) \right]}_{\textcircled{1}} + \underbrace{\left[\nabla^2 g - \frac{\mu\epsilon}{c^2} \left(\frac{\partial^2 g}{\partial t^2} \right) \right]}_{\textcircled{2}} = 0. \end{aligned} \right. \quad (8)$$

"Gauge condition" is satisfied by choosing g such that $\textcircled{2} = -\textcircled{1}$.

The new potentials (ϕ', \mathbf{A}') satisfy the "gauge condition" in Eq.(6), they are solutions to the inhomogeneous wave eqns in Eq.(6), and the fields (\mathbf{E}, \mathbf{B}) are unaffected by choice of g in this way. It all works on the tacit assumption that only the fields have directly measurable effects; the potentials themselves are just spectators.

3) The gauge condition $\nabla \cdot A + \frac{\mu\epsilon}{c} \left(\frac{\partial \phi}{\partial t} \right) = 0$ is useful for deriving the wave eqns in (6), but it is not a unique choice. Two particularized choices are in common use.

LORENTZ GAUGE \leftarrow used in SRT, where both ϕ & A relevant for particles.

(ϕ, A) are readily derived from Eqs. (6) which satisfy $\boxed{\nabla \cdot A + \frac{\mu\epsilon}{c} \left(\frac{\partial \phi}{\partial t} \right) = 0}$.

Now consider gauge transform $(\phi, A) \rightarrow (\phi', A')$, via $\phi' = \phi - \frac{1}{c} \dot{g}$, $A' = A + \nabla g$.

Then $\nabla \cdot A + \frac{\mu\epsilon}{c} \left(\frac{\partial \phi}{\partial t} \right) = 0 \rightarrow \nabla \cdot A' + \frac{\mu\epsilon}{c} \left(\frac{\partial \phi'}{\partial t} \right) = 0$, only if $\boxed{\left(\nabla^2 - \frac{\mu\epsilon}{c^2} \frac{\partial^2}{\partial t^2} \right) g = 0}$. (9)

All potentials (ϕ, A) , (ϕ', A') related by a gauge transform, with g restricted in this way, and with $\nabla \cdot A + \frac{\mu\epsilon}{c} \left(\frac{\partial \phi}{\partial t} \right) = 0$ for each pair, are said to belong to the "Lorentz Gauge". This is the most commonly used gauge condition.

COULOMB (radiation) GAUGE \leftarrow used in QED, where only A (photon) is important.

Impose $\boxed{\nabla \cdot A = 0}$ [instead of $\nabla \cdot A + \frac{\mu\epsilon}{c} \left(\frac{\partial \phi}{\partial t} \right) = 0$]. This condition is invariant under a gauge transform if we impose $\underline{\nabla^2 g = 0}$. In any case, from Eq. (5) above:

$$\left[\begin{aligned} \nabla^2 \phi &= -\frac{4\pi}{\epsilon} \rho \Rightarrow \phi(\mathbf{r}, t) = \frac{1}{\epsilon} \int \frac{d^3x'}{R} \rho(\mathbf{r}', t), \quad R = |\mathbf{r} - \mathbf{r}'| \quad \begin{matrix} \text{instantaneous} \\ \text{Coulomb potl.} \end{matrix} \\ \nabla^2 A - \frac{\mu\epsilon}{c^2} \frac{\partial^2 A}{\partial t^2} &= -\frac{4\pi\mu}{c} \mathbf{J} + \frac{\mu\epsilon}{c} \nabla \left(\frac{\partial \phi}{\partial t} \right). \end{aligned} \right. \quad (10)$$

If no charges are present, i.e. $\rho = 0$ & $\mathbf{J} = 0$, then $\left\{ \begin{aligned} \phi &= 0 \quad \text{instead of homog. wave eqn for } \phi, \text{ as in Lorentz gauge;} \\ \left(\nabla^2 - \frac{\mu\epsilon}{c^2} \frac{\partial^2}{\partial t^2} \right) A &= 0. \end{aligned} \right.$

The general wave eqn for A , Eq. (10), can be simplified in this gauge... see Jk² Eqs. (6.47) - (6.52) and prob #43. First decompose \mathbf{J} into transverse & longitudinal parts:

$$\rightarrow \mathbf{J} = \mathbf{J}_T + \mathbf{J}_L, \quad \mathbf{J}_T = \frac{1}{4\pi} \nabla \times \left[\nabla \times \int \frac{d^3x'}{R} \mathbf{J} \right] \quad \& \quad \mathbf{J}_L = -\frac{1}{4\pi} \nabla \int \frac{d^3x'}{R} \nabla' \cdot \mathbf{J}. \quad (11)$$

Have $\nabla \cdot \mathbf{J}_T = 0$ & $\nabla \times \mathbf{J}_L = 0$. Now: $\phi = \frac{1}{\epsilon} \int \frac{d^3x'}{R} \rho$, and: $\frac{\partial \rho}{\partial t} + \nabla \cdot \mathbf{J} = 0$, together imply that: $\nabla \left(\frac{\partial \phi}{\partial t} \right) = (4\pi/\epsilon) \mathbf{J}_L$. Use of this result in Eq. (10) yields a reduced eqn:

$$\boxed{\left(\nabla^2 - \frac{\mu\epsilon}{c^2} \frac{\partial^2}{\partial t^2} \right) A = -(4\pi\mu/c) \mathbf{J}_T}. \quad (12)$$

Maxwell Equations: Wave-like Solutions [Ref. Jackson Secs. (6.5) & (6.6)]

We have by now reduced Maxwell's Eqs. in a linear medium to the solution of two inhomogeneous wave equations...

$$\nabla \cdot \mathbf{E} = \left(\frac{4\pi}{\epsilon}\right) \rho,$$

$$\nabla \times \mathbf{E} = -\frac{1}{c} \frac{\partial \mathbf{B}}{\partial t},$$

$$\nabla \cdot \mathbf{B} = 0,$$

$$\nabla \times \mathbf{B} = \frac{4\pi\mu}{c} \mathbf{J} + \frac{\mu\epsilon}{c} \frac{\partial \mathbf{E}}{\partial t};$$

use potentials...

$$\mathbf{B} = \nabla \times \mathbf{A},$$

$$\mathbf{E} = -\nabla\phi - \frac{1}{c} \frac{\partial \mathbf{A}}{\partial t};$$

... and Lorentz Gauge

$$\nabla \cdot \mathbf{A} + \frac{\mu\epsilon}{c} \frac{\partial \phi}{\partial t} = 0$$

$$\boxed{\begin{aligned} \nabla^2 \phi - \frac{1}{v^2} \frac{\partial^2 \phi}{\partial t^2} &= -\frac{4\pi}{\epsilon} \rho, \\ \nabla^2 \mathbf{A} - \frac{1}{v^2} \frac{\partial^2 \mathbf{A}}{\partial t^2} &= -\frac{4\pi\mu}{c} \mathbf{J}; \end{aligned}}$$

$$\text{where: } v = c/\sqrt{\mu\epsilon}. \quad (1)$$

1) To proceed, evidently we should look at solutions to the generic wave eqn...

$$\boxed{\nabla^2 \psi - \frac{1}{v^2} \left(\frac{\partial^2 \psi}{\partial t^2} \right) = -4\pi f(\mathbf{r}, t)} \quad \begin{cases} \psi = \psi(\mathbf{r}, t) \text{ is the wave amplitude,} \\ f(\mathbf{r}, t) \text{ is a known source function.} \end{cases} \quad (2)$$

REMARK Plane wave solutions.

The homogeneous eqn is: $(\nabla^2 - \frac{1}{v^2} \frac{\partial^2}{\partial t^2}) \psi = 0$. Try plane wave: $\psi = A e^{i(\mathbf{k} \cdot \mathbf{r} - \omega t)}$.

So $(-k^2 + \frac{\omega^2}{v^2}) \psi = 0 \dots$ works $\nabla \nabla \omega = \pm kv = \pm kc/\sqrt{\mu\epsilon}$ \int relation: $\omega = \omega(k)$ is a "dispersion relation"

If μ & ϵ are indpt. of ω , then $\left\{ \begin{array}{l} \text{wave phase velocity: } \omega/k = \pm v \\ \text{wave group velocity: } \partial\omega/\partial k = \pm v \end{array} \right\}$ both const (wave shows zero dispersion)

If μ & ϵ depend on freq. ω , $v(\text{phase})$ & $v(\text{group}) \propto \omega$, and propagating wave distorts.

We first assume simplest case: $\omega = \text{const} \times k$, with no wave distortion/dispersion.

2) With no dispersion [$v(\text{phase})$ & $v(\text{group}) = \text{const}$], Fourier analysis of Eq. (2) is useful:

$$\begin{aligned} \xrightarrow{\text{transform}} \tilde{\psi}(\mathbf{r}, \omega) &= \int_{-\infty}^{\infty} \psi(\mathbf{r}, t) e^{i\omega t} dt \quad \xleftrightarrow{\text{inverse}} \psi(\mathbf{r}, t) = \frac{1}{2\pi} \int_{-\infty}^{\infty} \tilde{\psi}(\mathbf{r}, \omega) e^{-i\omega t} d\omega, \\ \tilde{f}(\mathbf{r}, \omega) &= \int_{-\infty}^{\infty} f(\mathbf{r}, t) e^{i\omega t} dt \quad \leftrightarrow \quad f(\mathbf{r}, t) = \frac{1}{2\pi} \int_{-\infty}^{\infty} \tilde{f}(\mathbf{r}, \omega) e^{-i\omega t} d\omega. \end{aligned} \quad (3)$$

This formulation anticipates problems that are unbounded in time. Plug these in (2):

$$\left(\nabla^2 - \frac{1}{v^2} \frac{\partial^2}{\partial t^2}\right) \psi = -4\pi f \Rightarrow \boxed{(\nabla^2 + k^2) \tilde{\psi}(\mathbf{r}, \omega) = -4\pi \tilde{f}(\mathbf{r}, \omega)}, \quad (4)$$

where $k = \frac{\omega}{v}$ is linear in ω . The transformed wave eqn in $\tilde{\psi}$ & \tilde{f} is called an "inhomogeneous Helmholtz equation"; evidently it includes the Poisson eqn $[\nabla^2 \tilde{\psi} = -4\pi \tilde{f}, \text{ for } k=0]$ as a special case. What's important about the Fourier transform is that it has reduced the t -variation to a "spectator" variable ω .

3) PDE's of the Helmholtz (and allied) type can be solved by using Green's functions.

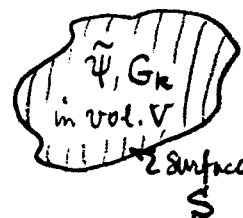
$$\left\{ \begin{array}{l} \text{Want } \tilde{\psi} \text{ in : } (\nabla^2 + k^2) \tilde{\psi}(\mathbf{r}, \omega) = -4\pi \tilde{f}(\mathbf{r}, \omega), \quad (1) \\ \text{Define } G_k \text{ by : } (\nabla^2 + k^2) G_k(\mathbf{r}, \mathbf{r}') = -4\pi \delta(\mathbf{r} - \mathbf{r}'). \quad (2) \end{array} \right. \quad \begin{array}{l} \text{assume we can} \\ \text{solve for } G_k(\mathbf{r}, \mathbf{r}') \end{array} \quad (5)$$

Connect these equations by Green's identity...

$$\tilde{\psi} \nabla^2 G_k - G_k \nabla^2 \tilde{\psi} = \nabla \cdot (\tilde{\psi} \nabla G_k - G_k \nabla \tilde{\psi}) \quad \begin{array}{l} \text{integrate } \int_V d^3x, \\ \text{use Divergence Thm} \end{array}$$

$$\int_V (\tilde{\psi} \nabla^2 G_k - G_k \nabla^2 \tilde{\psi}) d^3x = \oint_S (\tilde{\psi} \nabla G_k - G_k \nabla \tilde{\psi}) \cdot d\mathbf{S}$$

$$\text{integrand} = 4\pi [G_k \tilde{f} - \tilde{\psi} \delta(\mathbf{r} - \mathbf{r}')] \quad \begin{array}{l} \text{obtained by forming gth} \\ \tilde{\psi} \cdot E_g(2) - G_k \cdot E_g(1) \end{array}$$



So//

$$4\pi \left[\int_V G_k \tilde{f} d^3x - \tilde{\psi}(\mathbf{r}', \omega) \right] = - \oint_S (G_k \nabla \tilde{\psi} - \tilde{\psi} \nabla G_k) \cdot d\mathbf{S}. \quad (6)$$

Interchange labels \mathbf{r} & \mathbf{r}' [note that $G_k(\mathbf{r}', \mathbf{r}) = G_k(\mathbf{r}, \mathbf{r}')$], rearrange terms to get

$$\boxed{\tilde{\psi}(\mathbf{r}, \omega) = \int_V G_k(\mathbf{r}, \mathbf{r}') \tilde{f}(\mathbf{r}', \omega) d^3x' + \frac{1}{4\pi} \oint_S (G_k \nabla' \tilde{\psi} - \tilde{\psi} \nabla' G_k) \cdot d\mathbf{S}'} \quad (7)$$

Except for the "spectator" variable ω (& $k = \omega/v$), this solution is the same as for Poisson's eqn [see JK & Eg. (1.42)]. It gives a particular soln to $(\nabla^2 + k^2) \tilde{\psi} = -4\pi \tilde{f}$, provided G_k satisfies $(\nabla^2 + k^2) G_k = -4\pi \delta(\mathbf{r} - \mathbf{r}')$. The \int_V term accounts for $\tilde{\psi}$ generated in V by the source \tilde{f} ; the \oint_S term provides freedom for B.C. on surface.

REMARKS on soln: $\tilde{\Psi} = \int_V G_k \tilde{f} d^3x' + \frac{1}{4\pi} \oint_S (G_k \nabla' \tilde{\Psi} - \tilde{\Psi} \nabla' G_k) \cdot d\mathbf{S}'$.

1. Any soln $\tilde{\Psi}_0$ to homogeneous eqn $(\nabla^2 + k^2) \tilde{\Psi}_0 = 0$ can be added to this $\tilde{\Psi}$.
2. The surface term can be adjusted to meet B.C. on surface S enclosing volume V ...

Dirichlet conditions } $\tilde{\Psi}$ given on $S \Rightarrow$ construct $G_k(\text{on } S) \equiv 0$; then:
 surface term $\rightarrow (-) \frac{1}{4\pi} \oint_S (\tilde{\Psi} \nabla' G_k) \cdot d\mathbf{S}; \quad (8)$

Neumann conditions } $\nabla \tilde{\Psi}$ given on $S \Rightarrow$ construct $\nabla G_k(\text{on } S) \equiv 0$; then:
 surface term $\rightarrow (+) \frac{1}{4\pi} \oint_S (G_k \nabla' \tilde{\Psi}) \cdot d\mathbf{S}. \quad (9)$

Evidently the actual functional form of $G_k(\mathbf{r}, \mathbf{r}')$ depends on the B.C. required.

3. Sometimes the region of interest is an ∞ domain, i.e. the surface S is at ∞ -- where by definition $\tilde{\Psi}$ & $\nabla \tilde{\Psi}$ both vanish. Then our solution-to-date looks like:


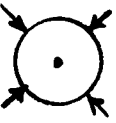
$\tilde{\Psi}(\mathbf{r}, \omega) = \int_{\infty} G_{k\infty}(\mathbf{r}, \mathbf{r}') \tilde{f}(\mathbf{r}', \omega) d^3x', \quad \parallel \text{ for } \infty \text{ domain, with}$
 with: $(\nabla^2 + k^2) G_{k\infty} = -4\pi \delta(\mathbf{r} - \mathbf{r}'). \parallel G_{k\infty} \rightarrow 0 \text{ as } |\mathbf{r} - \mathbf{r}'| \rightarrow \infty. \quad (10)$

4. Jackson shows how to solve the $G_{k\infty}$ problem in his Eqs. (6.58)-(6.62). Results:

$G_{k\infty}(\mathbf{r}, \mathbf{r}') = \frac{1}{R} e^{\pm i k R}, \quad \forall R = |\mathbf{r} - \mathbf{r}'|, \text{ on } \infty \text{ domain.} \quad (11)$

This can be verified by a plug-in, if you use $\nabla^2(1/R) = -4\pi \delta(\mathbf{r} - \mathbf{r}')$.

The results here have a geometrical interpretation...

(+) sign \leftrightarrow outgoing spherical wave from point source at origin:  $\frac{e^{+ikR}}{R}$
 (-) sign \leftrightarrow incoming " " to " " " " " "  $\frac{e^{-ikR}}{R}$

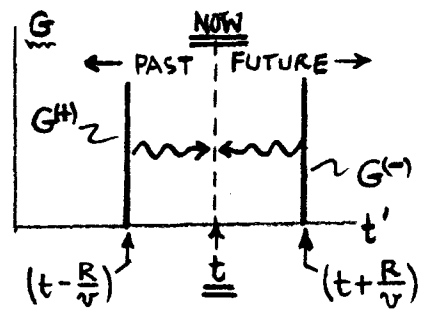
The wave amplitude $\Psi(\mathbf{r}, t)$ [on an ∞ domain] can now be obtained by using $G_{k\infty}$ of Eq. (11) in $\tilde{\Psi}(\mathbf{r}, \omega)$ of Eq. (10), and then inverting the Fourier transforms $\tilde{\Psi}$ and \tilde{f} . Jackson shows how this is done in his Eqs. (6.63)-(6.66).

4) With the procedure just noted, the resulting solution to the inhomogeneous wave eqn: $(\nabla^2 - \frac{1}{c^2} \frac{\partial^2}{\partial t^2}) \psi = -4\pi f(\mathbf{r}, t)$, on an ∞ domain may be quoted as:

(12)

$$\psi(\mathbf{r}, t) = \int_{\infty} d^3x' \int_{-\infty}^{\infty} dt' G^{(\pm)}(\mathbf{r}, t; \mathbf{r}', t') f(\mathbf{r}', t'),$$

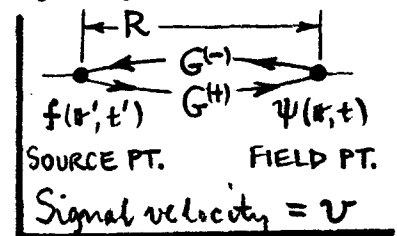
$$G^{(\pm)} = \frac{1}{R} \delta(t' - [t \mp \frac{R}{v}]) \quad \begin{matrix} R = |\mathbf{r} - \mathbf{r}'|, \\ v = c/\sqrt{\mu\epsilon}. \end{matrix}$$



Signal (from f at time t') propagates to observation pt (ψ at time t) from the past by $G^{(+)}$, or from future by $G^{(-)}$.

[this is the un-numbered eqn on Jk² p. 225]. The δ -fcn in $G^{(\pm)}$ is really present, and it has a Novel Feature: the signal from f at time t' can arrive to form the disturbance ψ at time t , at: $t = t' \pm (R/v)$, i.e. $f \Rightarrow \psi$ from either the past or the future. There is no mathematical distinction between past & future (since wave eqn is quadratic in x & t).

Time-ordering aside, we at least have a rational result for the finite propagation velocity v in the theory. The source & field points are (causally) connected only if: $R = v|t - t'|$.



Details of the two solutions for ψ go as follows...

① $G^{(+)}$ solution: f signal at t' reaches ψ pt. at: $t = t' + \frac{R}{v} > t'$ } signal at t is from past.

$\uparrow t' = t - \frac{R}{v} = t_{\text{ret}}$, is the "retarded time"; $G^{(+)}$ is called "retarded" Green's fcn;

and/ $\psi(\mathbf{r}, t) = \psi_{\text{inc}}(\mathbf{r}, t) + \int_{\infty} \frac{d^3x'}{R} f(\mathbf{r}', t_{\text{ret}})$ } ψ_{inc} = solution to homogeneous wave eqn as $t \rightarrow (-)\infty$ [starts in past]. (13)

② $G^{(-)}$ solution: f signal at t' reaches ψ pt. at: $t = t' - \frac{R}{v} < t'$ } signal at t is from future.

$\uparrow t' = t + \frac{R}{v} = t_{\text{adv}}$, is the "advanced time"; $G^{(-)}$ is called "advanced" Green's fcn;

and/ $\psi(\mathbf{r}, t) = \psi_{\text{out}}(\mathbf{r}, t) + \int_{\infty} \frac{d^3x'}{R} f(\mathbf{r}', t_{\text{adv}})$ } ψ_{out} = solution to homogeneous wave eqn as $t \rightarrow (+)\infty$ [starts in future]. (14)

The choice of $G^{(\pm)}$ for the ψ solution is dictated by whether we want the source integral to contribute \sim zero at very early [$G^{(+)}$] or very late [$G^{(-)}$] times t .

5) **SUMMARY** A Complete Solution to Maxwell's Equations.For a linear medium ($\mathbf{D} = \epsilon \mathbf{E}$, $\mathbf{B} = \mu \mathbf{H}$) ...

L gauge: $\nabla \cdot \mathbf{A} + \frac{\mu\epsilon}{c} \left(\frac{\partial \phi}{\partial t} \right) = 0$

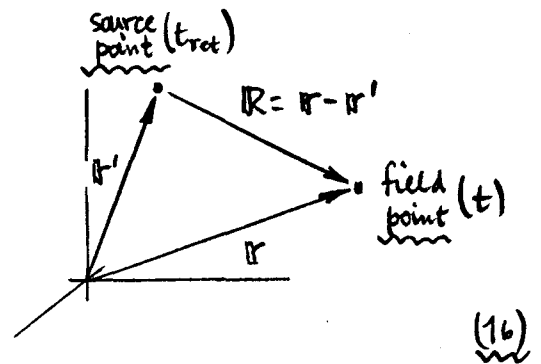
$$\left\{ \begin{array}{l} \nabla \cdot \begin{pmatrix} \mathbf{E} \\ \mathbf{B} \end{pmatrix} = \frac{4\pi}{\epsilon} \begin{pmatrix} \rho \\ 0 \end{pmatrix}, \\ \nabla \times \begin{pmatrix} \mathbf{E} \\ \mathbf{B} \end{pmatrix} = \frac{4\pi\mu}{c} \begin{pmatrix} 0 \\ \mathbf{J} \end{pmatrix} + \frac{1}{c} \begin{pmatrix} -\partial \mathbf{B} / \partial t \\ \mu \epsilon \partial \mathbf{E} / \partial t \end{pmatrix} \end{array} \right\} \left(\nabla^2 - \frac{1}{v^2} \frac{\partial^2}{\partial t^2} \right) \begin{pmatrix} \phi \\ \mathbf{A} \end{pmatrix} = -4\pi \begin{pmatrix} \rho/\epsilon \\ \mu \mathbf{J}/c \end{pmatrix},$$

where: $v = c/\sqrt{\mu\epsilon}$;

w/ $\mathbf{B} = \nabla \times \mathbf{A}$, $\mathbf{E} = -\nabla \phi - \frac{1}{c} (\partial \mathbf{A} / \partial t)$. (15)

Solutions on an ∞ domain...

$$\left\{ \begin{array}{l} \phi(\mathbf{r}, t) = \phi_0(\mathbf{r}, t) + \frac{1}{\epsilon} \int_{\text{sources}} \frac{d^3x'}{R} \rho(\mathbf{r}', t_{\text{ret}}), \\ \mathbf{A}(\mathbf{r}, t) = \mathbf{A}_0(\mathbf{r}, t) + \frac{\mu}{c} \int \frac{d^3x'}{R} \mathbf{J}(\mathbf{r}', t_{\text{ret}}); \\ \text{w/ } t_{\text{ret}} = t - \frac{1}{v} R(t_{\text{ret}}), \quad R = |\mathbf{r} - \mathbf{r}'|. \end{array} \right.$$

Here ϕ_0 & \mathbf{A}_0 are solutions to the homogeneous eqns: $(\nabla^2 - \frac{1}{v^2} \frac{\partial^2}{\partial t^2}) \begin{pmatrix} \phi_0 \\ \mathbf{A}_0 \end{pmatrix} = 0$.We have chosen the retarded solutions for ϕ & \mathbf{A} , per convention.**REMARKS**

1. The only apparent effect of adding the time-derivative terms (in \mathbf{B} & \mathbf{E}) to the static Maxwell Eqns [see Eqs. (1) above] is that in the integrals for ϕ & \mathbf{A} -- i.e. the integrals $\int \frac{d^3x'}{R} (\rho \text{ & } \mathbf{J})$ -- the time $t \rightarrow t_{\text{ret}} = t - (R/v)$. At first glance, this is an unexpectedly simple way to include the \mathbf{B} & \mathbf{E} terms... it just complicates the integrals a bit. BUT, the fact that the source pt - field pt distance R now becomes an explicit function of the time difference $(t - t_{\text{ret}})$ will cause grief, later.
2. The solutions of Eq. (16) hold only on an ∞ domain (i.e. the only B.C. are that the fields \mathbf{E} & \mathbf{B} and potentials ϕ & \mathbf{A} vanish at ∞). Problems which require B.C. on a finite domain are much more complicated, but are solvable w/ suitable surface terms.