Lorentz Force Tay. Invariance of change q.

The Covariance of Electro Dynamics [ref. Jk Sec. 11.9].

With the 4-vector and Lorentz transf¹² formalism in hand, it is relatively easy to show the form-invariance -- or "covariance" -- of Maxwell's Egtns, and thus all of electrodynamics, under the Lorentz transf¹². This means that any two observers in inertial frames -- no matter how fast they may be moving relative to one another -- will write down exactly the same laws of E&M.

1) We work first on the Torentz force low [per Jk Sec. 11.9], viz.

AP = 9(E+ & xB), for charge q @ v in ref. frame K. (1)

This is a 3-vector force law; we want a 4-vector law.

FIRST: we assert that charge q is a relavistic (Ibrentz) invariant. Evidence:

[electron in
$$n \stackrel{\text{th}}{=} \text{ orbit}$$
] $\beta = \frac{v}{c} \simeq \frac{z\alpha}{n}$, $w = \frac{e^{z}}{\hbar c} = \frac{1}{137}$. (2)

This B is exact for a 1e atom, and is NOK for lown in high Zatoms. Colculate;

[for hydrogen:
$$\frac{Z=1}{n=1}$$
] $\beta_H = \frac{1}{137} = 0.0073$, and; $\gamma_H = 1/\sqrt{1-\beta_H^2} = 1+\frac{27}{127} + \frac{1}{127} + \frac$

If the charge e transformed as e-> ye, we would expect charge imbalances of order $\Delta e/e = \Delta y \sim 9.2\%$ to develop between the e-p couplings in H & Cs. They don't ... both atoms are electrically neutral within $|\Delta e/e| \sim 10^{-20}$ And so to that accuracy, q is a <u>Lorentz scalar</u>, just as is the particle mass m.

^{*} Curionsly, when the "ancients" (Iorentz, Fitzgerald, Poincaré) tried to explain the null results of the Michelson-Morley experiment, they discovered that Maxwell's Egths were Iorentz covariant (~10 yrs before Einstein's SRT).

SECOND: put the particle (q,m) proper time dt = dt/8v into Torentz law, 50:

... recall 4-velocity: $\tilde{V} = \gamma_v(c, v) = (u_0, u) \left\{ \frac{u_0 = \gamma_v c}{u = \gamma_v v} \right\}$

Soy dp = q (uo E + UxB) NOTE: $\tilde{p} = m(u_0, u)$ is the relativistic 4-momentum of m.

The IHS of Eq. (5) is by now the spacelike part of a 4-vector, namely the Minkowski force $\tilde{K} = m \frac{d\tilde{u}}{d\tau}$ [recall prob Φ]. This 4-vector force is ...

$$\rightarrow \widetilde{K} = \frac{d\widetilde{p}}{d\tau} = (K_0, \frac{dp}{d\tau}), \quad W/K_0 = dp_0/d\tau = \frac{1}{c} \frac{d}{d\tau} (\gamma_{vmc^2}) \text{ energy } \varepsilon$$

$$S_0//K_0 = \frac{y_v}{c} \frac{d\varepsilon}{dt} = \frac{y_v}{c} F_1 V = \frac{y_v}{c} q(E + \frac{v}{c} \times B) \cdot V,$$

i.e.// Ko= 9 E. 10, W/ U= Xv. V.

(6)

The relation Ko = dpo dt = q E. 11 is the relativistic version of the workenergy theorem for the EM field. The 4-vector form of the Toventz force how can now be written as ...

$$\frac{d\tilde{b}}{d\tau} = \frac{9}{c} \left(\text{N.E., } u_0 \text{E} + u_0 \text{E} \right) \int u_0 = \gamma_0 c, u = \gamma_0 v, \quad (7)$$
and: $\gamma_0 = 1/\sqrt{1-|v/c|^2}$.

The LHS of Eq. (7) is manifestly a 4-vector. With q as an invariant, it must be true that the () on the RHS is also a 4-vector. Then, the Torentz transfor properties of the () on the RHS can be used to establish how the E& B feelds must transform. We could do this, but wont.

2) Instead of unravelling the E& 1B transforms from the Torentz law, Eq. (7), we Shall find those transforms by looking at how true potentials \$ \$ A behave (recall: E = - VA - = (OA/Ot), B = VXA). This atternative is pursued in order to show how the potentials themselves form a 4-vector A=(\$,A),

4-vector character of $\widetilde{J} = (cp, J)$ and $\widetilde{A} = (\phi, A)$.

SUMMATION COV 13

and also how the sources $p \notin J = \text{charge} \notin \text{current density form another}$ 4-vector $\underline{\mathcal{T}} = (cp, J)$. In fact, that $\overline{\mathcal{T}}$ is a 4-vector is demanded by charge conservation -- a universal requirement -- as we can see from ...

CONTINUITY $\left\{ \begin{array}{l} \frac{\partial \rho}{\partial t} + \nabla \cdot J = 0 \end{array} \right\} \stackrel{\text{off}}{=} \frac{\partial}{\partial x^{o}} (c\rho) + \frac{\partial}{\partial x^{k}} J^{k} = 0,$

Since Da is a 4-vector, the only way that Da Ja = 0 in all Torentz frames (1.e. that the O, signifying Charge conservation, always appears RHS), is for Jd to be a 4-vector. Then da Jd is a 4-vector scalar product, the same in all Irrentz frames, and daJx=0 is a Toventz-invariant statement.

As for the 4-vector character of $\widetilde{A}=(\phi, A)$, recall the defining extrs...

[Lorentz gauge: $\frac{1}{c} \frac{\partial \phi}{\partial t} + \nabla \cdot A = 0 \Rightarrow \partial_{\alpha} A^{\alpha} = 0$, $A^{\alpha} = (\phi, A)$.

The Torentz gauge choice is available to all mertil observers if A^{α} is a 4-vector. A^{α} is a 4-vector because it obeys the wave extu...

 $\frac{1}{c} \left[\left(\frac{1}{c^2} \frac{\partial^2}{\partial t^2} - \nabla^2 \right) (\phi, A) = \frac{4\pi}{c} (c\rho, J), \quad \Box \widetilde{A} = (4\pi/c) \widetilde{J} \right] + VECTOR$ WAVE
EQTN Dα Dα = □, D'Alembertian [Jk 11.78)]

Now □ = Da Da is a Torentz scalar, so the wave extraceds: (Torentz) ~ = (Coventy) \$\tilde{J}\$, so \$\tilde{A}\$ has the same borentz transfor character as \$\tilde{J}\$ -- \$\tilde{A}\$ is a 4-vector if Jis.

3) We shall now write the fields IE& IB in terms of the 4-potential A = (\$\phi\$, A). In so doing, we find it convenient to use the contravariant del operator ∂ = (∂/∂x0, - V), [Jk= Eq. (11.76)]. With A° = φ, and with the coordi-

nate assignment $(x^0, x^1, x^2, x^3) = (ct, x, y, z)$, we exhauste...

$$\begin{bmatrix} E_{x} = -\frac{\partial}{\partial x} \phi - \frac{1}{c} \frac{\partial}{\partial t} A_{x} = -\frac{\partial}{\partial x^{1}} A^{\circ} - \frac{\partial}{\partial x^{\circ}} A^{1} = -(\partial^{\circ} A^{1} - \partial^{1} A^{\circ}), \\ B_{x} = \frac{\partial}{\partial y} A_{z} - \frac{\partial}{\partial z} A_{y} = \frac{\partial}{\partial x^{z}} A^{3} - \frac{\partial}{\partial x^{3}} A^{2} = -(\partial^{2} A^{3} - \partial^{3} A^{2}). \end{bmatrix}$$
(11)

Evidently, the E& B fields are components of a 4x4 second rank contravariant tensor FOB. FOB is called the EM feeld tensor, and is defined:

$$F^{\alpha\beta} = \partial^{\alpha}A^{\beta} - \partial^{\beta}A^{\alpha}, \quad F^{\alpha\alpha} = 0, \quad F^{01} = -E_{x}, \quad F^{23} = -B_{x}, \quad \text{etc.}$$
i.e.,

$$T^{\alpha\beta} = \begin{bmatrix} 0 & | -E_{x} & -E_{y} & -E_{z} \\ E_{x} & | & 0 & -B_{z} & B_{y} \\ E_{y} & | & B_{z} & 0 & -B_{x} \\ E_{z} & | & -B_{y} & B_{x} & 0 \end{bmatrix}$$

$$T^{\alpha\beta} = \begin{bmatrix} 0 & | -E_{x} & -E_{y} & -E_{z} \\ E_{x} & | & 0 & -B_{z} \\ E_{y} & | & B_{z} & 0 & -B_{x} \\ E_{z} & | & -B_{y} & B_{x} & 0 \end{bmatrix}$$

$$T^{\alpha\beta} = \begin{bmatrix} 0 & | -E_{x} & -E_{y} & -E_{z} \\ E_{x} & | & 0 & -B_{x} \\ E_{y} & | & B_{z} & 0 & -B_{x} \\ E_{z} & | & -B_{y} & B_{x} & 0 \end{bmatrix}$$

$$T^{\alpha\beta} = \begin{bmatrix} 0 & | -E_{x} & -E_{y} & -E_{z} \\ E_{x} & | & 0 & -B_{x} \\ E_{y} & | & 0 & -B_{x} \\ E_{z} & | & -B_{y} & B_{x} & 0 \end{bmatrix}$$

$$T^{\alpha\beta} = \begin{bmatrix} 0 & | -E_{x} & -E_{y} & -E_{z} \\ E_{x} & | & 0 & -B_{x} \\ E_{y} & | & 0 & -B_{x} \\ E_{z} & | & -B_{y} & B_{x} & 0 \end{bmatrix}$$

$$T^{\alpha\beta} = \begin{bmatrix} 0 & | -E_{x} & -E_{y} & -E_{z} \\ E_{x} & | & 0 & -B_{x} \\ E_{y} & | & 0 & -B_{x} \\ E_{z} & | & -B_{y} & B_{x} & 0 \end{bmatrix}$$

$$T^{\alpha\beta} = \begin{bmatrix} 0 & | -E_{x} & -E_{y} & -E_{y} \\ E_{x} & | & 0 & -B_{x} \\ E_{y} & | & 0 & -B_{x} \\ E_{z} & | & 0$$

Several other versions of FXB are used...

2 covariant
$$F$$
: $F_{\alpha\beta} = g_{\alpha\lambda} F^{\lambda\epsilon}g_{\epsilon\beta}$, 3 dual of F : $F^{\alpha\beta} = \frac{1}{2} \epsilon^{\alpha\beta\gamma\epsilon} F_{\gamma\epsilon}$,

i.e.,

 $F_{\alpha\beta} = \begin{bmatrix} 0 & E_x & E_y & E_z \\ -E_x & 0 & -B_z & B_y \\ -E_y & B_z & 0 & -B_x \end{bmatrix}$

The second of F : $F^{\alpha\beta} = \frac{1}{2} \epsilon^{\alpha\beta\gamma\epsilon} F_{\gamma\epsilon}$,

 $F_{\alpha\beta} = \begin{bmatrix} 0 & -B_x & -B_y & -B_z \\ B_x & 0 & E_z & -E_y \\ B_y & -E_z & 0 & E_x \\ B_z & E_y & -E_x & 0 \end{bmatrix}$

NOTE: Fap = Fap E>(-) E Jinversion

Tap = $\begin{bmatrix} \frac{0}{Bx} & -Bx & -By & -Bz \\ Bx & 0 & Ez & -Ey \\ By & -Ez & 0 & Ex \\ Bz & Ey & -Ex & 0 \end{bmatrix}$

NOTE: FOR = FOR EDB, BO(-) E Strange

So far, these various field tensors are just bookkalping procedures, to keep track of how to calculate field components from the 4-potential Ad (e.g. in Eq. (12) : $F^{\alpha\beta} = \partial^{\alpha}A^{\beta} - \partial^{\beta}A^{\alpha} = -E_{x}$ when $\alpha, \beta = 0,1$, etc.). But now we will show: (1) the Maxwell Egths can be written in a very elegant form in terms of FOB, (2) FOB is actually a Torentz 4-tensor (per Eq. (39a), p. SRT 21).

* Expre = Tevi-Civita pseudo-tensor of 4 indices. It is totally antisymmetric, with: EXPRE = ± 1, when dBYE = and permutation of 0123; Eapre = 0, when two indicus sine. 4) Recall the operation of tensor "divergence"... *

Summation Convention M Effect

$$\rightarrow (\text{div}_{\overline{F}})^{\beta} = \frac{\partial}{\partial x^{\alpha}} F^{\alpha\beta} = \partial_{\alpha} F^{\alpha\beta} = \partial_{0} F^{0\beta} + \partial_{1} F^{1\beta} + \partial_{2} F^{2\beta} + \partial_{3} F^{3\beta}. \tag{15}$$

This produces a 4-vector out of a (2nd rank) 4-tensor. Apply this operation to the field tensor Fap of Eq. (12) above...

Evidently the inhomogeneous (source-dept.) Maxwell Egtus can be written

This compact operation on Faß thus produces <u>Gauss' Law</u> and the <u>An</u><u>pere-Maxwell Law</u>. We note further the transformation properties
of Faß according to (17); we have a known 4-vector JB on the RHS,
and a known 4-vector da on the LHS... what's in between, Faß, can
only transform as a (2nd rank) Lorentz 4-tensor. Faß's transform is:

$$F^{\alpha\beta} \rightarrow F'^{\alpha\beta} = \left(\frac{\partial x'^{\alpha}}{\partial x^{\gamma}}\right) \left(\frac{\partial x^{\beta}}{\partial x^{\epsilon}}\right) F^{\gamma\epsilon} = \Lambda^{\alpha}_{\gamma} F^{\gamma\epsilon} \Lambda^{\beta}_{\epsilon} \int_{\text{transform}}^{\infty} is \text{ Loventz}$$
(18)

Iper def! in Eq. (39a), p. SRT 21 of Class notes). So the EM field tensor Faβ is, in fact, a contravariant Lorentz 4-tensor. This means that the Maxwell Eq. this in (Δ) above, viz. $\partial_{\alpha} F^{\alpha \beta} = (4\pi/c) J^{\beta}$, are "Lorentz Covariant"... any two inertial observers, exchanging information via Lorentz transforms, will write down exactly the same equations.

^{* \$ 519} Notes, p. ME 18, " Jk" Sec. 6.8, Eq. (6.119) [on Poynting's Thm].

The sourc-independent extres: Ox Fxp=0. Manifest covariance.

5) Maxwell's homogeneous (source-inapt) extres, V.B=0 & VXE=-10B, are actually ensured by the way we have chosen the potentials (\$, A). $E = -\nabla \phi - \frac{1}{c}(\partial A/\partial t)$ and $B = \nabla \times A$ immediately give $\nabla \cdot B = 0$ and VXE = - = (10B/0t). So the very form of Fap = da Ap - OBAa, with Ax = (p, 1A) implicitly => the source-free extres.

But also we can write the source-free extrs in terms of the dual Fax:

YNO.

SUM. B
$$\partial \alpha F^{\alpha\beta} = 0$$
 $\int_{a}^{b} \int_{a}^{b} \int_{b}^{c} \int_{c}^{c} \int_{c}^{c}$

Recall FOB -> FOB under E>B, B>1-)E; then clearly (19) implies the same operations as (17) on the fields on the ZHS, and the RHS=0 because there is no magnetic monopole 4-current. While Fab clearly exposes the nature of the source-free Maxwell Egths, they can also be recovered from FXB directly, but in a somewhat clumsy form. "

Because FOB = 1 EXPRE Fre, and Fre is a Loventz 4-tensor, then FOB is also a Torentz 4-tensor, and B above, viz. Ta Fx = 0, is a Lorentz covariant statement... all inestial observers agree on these Maxwell Eqs.

We now have a manifestly covariant statement of Maxwell's Egtns, by $\triangle \xi B$ above: $\partial_{\alpha} F^{\alpha\beta} = (4\pi/c)J^{\beta}$, $\partial_{\alpha} F^{\alpha\beta} = 0$. These elegant equations imply:

1. Maxwell's E&M can be cast in 4-vector, 4-tensor form, obeying the Torentz transform and thus SRT. So E&M is universal, and C = cost everywhere.

2. The Coventz transform FOB > F'OB of Eq. (18) will tell us how the fields transform. E&B do not transform as vectors, but as elements of a 4-tensor.

 $\{ (\alpha, \beta, \gamma) = 6 + 1 \text{ three of } (0,1,2,3),$ $\{ (\alpha, \beta, \gamma) = 6 + 1 \text{ three of } (0,1,2,3), \}$ 4 Jk Eq. (11.143): 20 FB8 + 38 F80 + 24 F08 =0

TIF there were a MM 4-current Jmm, (19) would read: TaFap = 4TT JAmm.

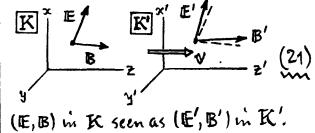
CoV17

6) In Eq. (18), we have that the EM field tensor FXB transforms as a 4-tensor:

$$\begin{bmatrix}
F^{\alpha\beta} (\text{in } K) \rightarrow F'^{\alpha\beta} (\text{in } K') = \Lambda_{\gamma}^{\alpha} F^{\gamma\epsilon} \Lambda_{\epsilon}^{\beta} = (\Lambda F \Lambda_{\tau})^{\alpha\beta}, \\
\nu_{\beta} \Lambda_{\lambda}^{\kappa} = (\partial x'^{\kappa} / \partial x^{\lambda}) \text{ is the Lorentz transfr for } K \rightarrow K',
\end{bmatrix}$$
(20)

By doing the actual matrix multer, one finds [Jkh Eg. (11.148)]...

$$E'_{z} = E_{z}$$
 $E'_{x} = \gamma(E_{x} - \beta B_{y})$
 $B'_{x} = \gamma(B_{x} + \beta E_{y})$
 $E'_{y} = \gamma(E_{y} + \beta B_{x})$
 $B'_{y} = \gamma(B_{y} - \beta E_{x})$



(E,B) in K seen as (E,B') in K'. β= V/c, γ= 1/√1-β², as usual.

for a velocity boost along the Z-axis. These laws of transf= for (IE, IB) ensure that Maxwell's Egths (e.g. V. E = 417 p) are manifestly evvariant, i.e. assume exactly the same form in K&K'. Note that the fields are completely mixed together by the relative motion of K&K'... in that sense, the fields do not show unique & independent existences. The should not speak of E&B separately, but rather just the "EM field" embodied in the tensor Fab

In case the K-K' relative velocity B=V/c is not || some common K-K'axis (but the K & K' axes are still || each other), the (E, B) -> (E', B') transform in Eq. (21) is generalized to [Jk Eq. (11.149)]...

$$E' = \gamma (E + \beta \times B) - \frac{\gamma^2}{\gamma + 1} (\beta \cdot E) \beta,$$

$$B' = \gamma (B - \beta \times E) - \frac{\gamma^2}{\gamma + 1} (\beta \cdot B) \beta.$$

NOTE: the first terms RHS look (22) like Loventz force laws as $\beta \rightarrow 0$, e.g. $E' \simeq (E + \frac{v}{c} \times B)$, as $\beta \rightarrow 0$.

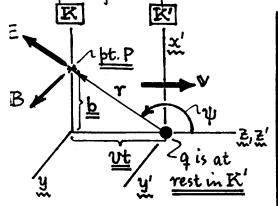
Note also: $(E=0, B) \rightarrow (E'=\gamma \beta \times B, B'=\gamma [B-\frac{\gamma \beta}{\gamma+1}(\beta \cdot B)])$. E'is called a "motional electric fièld", generated by movement thru B. Also $(E,0) \rightarrow (E',B'\neq 0)$.

Eqs. (11)-(22) completes the program for establishing the covariance of Maxwell Eqs.

(24)

Explicit E& B transformation.

7) As an example of field transforms, consider the fields for a single q, moving uni-formly. We follow the treatment in Jackson's Sec. 11.10, pp. 552-556.



9. fixed at origin of K', passes K origin at velocity V. When t'= t = 0. Impact parameter (closest approach) = b.

[fields at pt. P]
$$E'_z = -\frac{qvt'}{r'^3}$$
, $E'_x = \frac{qb}{r'^3}$, $E'_y = 0$;
and $B' = 0$, W'' $r' = \sqrt{b^2 + (vt')^2} = dist. q \leftrightarrow P$. (73)

Can transform K'→ K time via: t=y[t-vz]=yt, Since Z-cd=0 for pt. P. Rewrite the above Ei in terms of K-time t. Then transform (E', B') - (E, B) by the Lorentz transformation prescribed for the fields. The result is ...

[fields at pt.P]
$$E_z = (-) \gamma q v t / r^3$$
, $E_x = \gamma q b / r^3$, $E_y = 0$;
[\(\text{in K cds}\)\) $B_z = 0$, $B_x = 0$, $B_y = \beta E_x$, $^{2}/(r^2 + (8vt)^2)$.

The radial position I'(in K') = (b, 0, -vt') -> I'(in K) = (b, 0, -vvt).

REMARKS on fields of a moving charge. (this is the Biot-Savart law)

1. We now have a motional magnetic field: B= $\gamma \frac{q}{c} (\frac{vb}{r^3}) \hat{y} = \gamma \frac{q}{c} (\frac{v \times r}{r^3})$, in

frame K. B + 0 so long as β + 0, and becomes as large as | E | when $\beta \rightarrow 1$.

2. Write Elink) in terms of q's "present position": R= (b, 0, vt). Then...

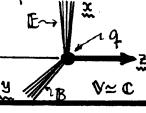
$$E = \left(\frac{yq}{\tau^{3}}\right)R\int_{-R}^{but/r^{2}} \int_{-R}^{z} \left[1+(\gamma^{2}-1)(\frac{vt}{R})^{2}\right]; \qquad \psi = \chi(v, r)$$

$$\frac{vt}{R} = (-)\cos\psi, \quad \chi^{2}-1=\chi^{2}\beta^{2} \Rightarrow r^{2}=\chi^{2}R^{2}(1-\beta^{2}\sin\psi); \qquad \text{as above.}$$

[E = (qR/R³). [(1-β²)/(1-β²sm²ψ)³/2] (25) ← equivalent to Jkt Eq. (11.154).

This E(in K) is radial, per Coulomb law, but the field lines "burch-up" in the Erolly lquatorial plane (4~90°); B behaves similarly. In Erolling

the limit v > c, K sees only an E-13 comb which is ~ transverse to v. Kinda like a photon? I MrB V= C



AFTERTHOUGHTS on the covariant formulation of E&M.

The 4-vector \Leftrightarrow 4-tensor formulation of $E \nleq M$ is an elegant, compact, and useful way to write down the principal equations of the theory, particularly w.n.t. to making certain that Loventz covariance is respected—this regularizement is an absolute "must" for all meaningful $E \nleq M$ equations. The fields $E \nleq B$ now disappear from the theory and are replaced by the field tensor $F^{\alpha\beta} = \partial^{\alpha}A^{\beta} - \partial^{\beta}A^{\alpha}$. Maxwells Egtus are: $\partial_{\alpha}F^{\alpha\beta} = \frac{4\pi}{c}J^{\beta}$, and: $\partial_{\alpha}F^{\alpha\beta} = 0$ [Eqs (17) \(\delta (19) \) above], the wave exth [Eq. (10) above] is: $(\partial_{\alpha}\partial^{\alpha})A^{\beta} = (4\pi/c)J^{\beta}$, etc. Other covariant statements are:

- Lorentz force law [Eq. (7) above] becomes Jk² Eq. (11.144);

 miα = 9 Fαβ up Juα = γ_ν(c, ν) is the 4-velocity,

 = differentiation d/dτ (propertime).
- 2. Poynting's Theorems [\$\phi 519 Notes: pp. ME2-ME9], involving energy & momentum balances between particle (sources) & fields, can be done covariantly -- see Jk Secs. 12.10 & 17.5. We will look at this later;
 there are some surprises [e.g. Poynting's original form of the field
 energy density (E²+B²)/8\pi has to be corrected].
- 3. The covariant formulation of $E\notin M$ can be extended, but with some difficulty, to material media. There $E\to D=\in E$, $B\to H=\frac{1}{\mu}B$, and the field tensor: $F^{\alpha\beta}(E,B)\to G^{\alpha\beta}(D,H)$. Maxwell's Egtus. in a medium have the same general form, viz. $\partial_{\alpha}G^{\alpha\beta}=(4\pi/c)J^{\beta}$, $\partial_{\alpha}F^{\alpha\beta}=0$, but care is needed in how one defines polarization P, magnetization M, etc.

In any case, in much of what follows, we will be using covariant notation -- particularly in analysing the motion of relativistic particles. \$520: Maxwell Egtns +> Covariance Summery.

1) Charge conservation: Da Ja = 0, Ja = (cp, I) = 4-votor source density.

Florentz gange: Da Ad = 0, W/ Ad = (\$\phi, A) = 4-vector potential.

Wave equation: (Ox da) AB = (4m/c) JB, Ox da = [{ Cltorantzinvariant)

3) Maxwell full tensor...

$$\frac{F \alpha \beta}{E} = 3^{\alpha} A \beta - 3^{\beta} A \alpha = \begin{bmatrix}
0 & -E_{1} & -E_{2} & -E_{3} \\
E_{1} & 0 & -B_{3} & B_{2} \\
E_{2} & B_{3} & 0 & -B_{1}
\end{bmatrix}, for \{B_{2} (B_{1}, B_{2}, B_{3})\}$$
... dual tensor...
$$E_{3} = B_{2} B_{1} = 0 \quad [a \text{ Torents } 4-tensor]$$

$$\underline{\underline{T}^{A\beta}} = \begin{bmatrix}
0 & -B_1 & -B_2 & -B_3 \\
B_1 & 0 & E_3 & -E_2 \\
B_2 & -E_3 & 0 & E_1 \\
B_3 & E_2 & -E_1 & 0
\end{bmatrix} = F^{\alpha} \begin{pmatrix} E \rightarrow +B \\ B \rightarrow -E \end{pmatrix} \int duality$$
[a Torientz 4-tensor]

4) Mixwell Equations ...

$$\frac{\partial_{\alpha} F^{\alpha\beta} = (4\pi/c) J^{\beta}_{elec.}}{\partial_{\alpha} F^{\alpha\beta} = (4\pi/c) J^{\beta}_{elec.}} \Rightarrow \begin{cases} \nabla \cdot E = 4\pi \rho, & (Gauss' Taw) \\ \nabla \times B = \frac{1}{c} (\partial E/\partial t) = \frac{4\pi}{c} J; (Ampere maxwell) \\ \partial_{\alpha} F^{\alpha\beta} = (4\pi/c) J^{\beta}_{maye} = 0 \Rightarrow \begin{cases} \nabla \cdot B = 0, & (Dirac taw) \\ \nabla \times E + \frac{1}{c} (\partial B/\partial t) = 0 \end{cases}$$

These laws are "manifestly covariant" (Some from in all mentral frames).

5) From Torentz transfor on field 4-tensor FXB, get field transfors ...

$$E'_{1} = E_{1}$$

$$E'_{1} = F_{1}$$

$$E'_{1} = \gamma (E_{1} - \beta B_{3})$$

$$B'_{1} = \gamma (B_{1} + \beta E_{3})$$

$$B'_{2} = \gamma (B_{2} + \beta E_{3})$$

$$E'_{3} = \gamma (E_{3} + \beta B_{2})$$

$$B'_{3} = \gamma (B_{3} - \gamma E_{2})$$

$$X_{3}$$

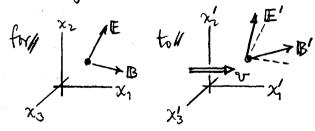
$$X_{4}$$

$$X_{5}$$

$$X_{5}$$

$$X_{5}$$

$$X_{5}$$



for velocity boost @ B = v/c (" Y= 1/1-B2) along the 1- axis. The components of E&B transform as components of a 2nd rank tensor (i.e. Fab).