5T2: Sinusoidal model (2 of 3)

Xavier Serra

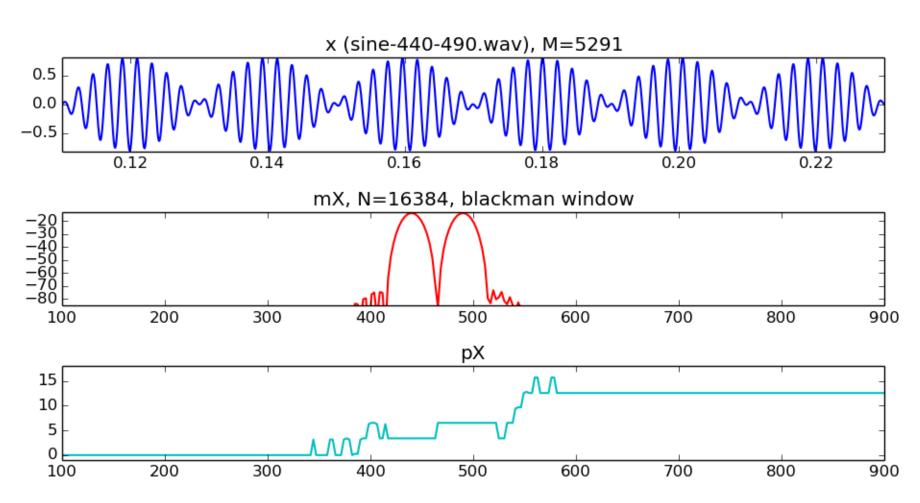
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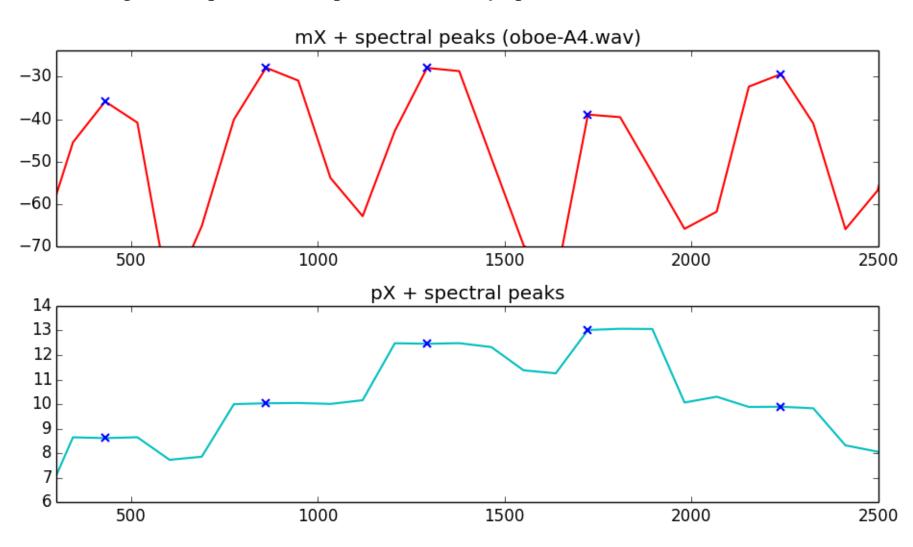
Sinusoidal model

$$y[n] = \sum_{r=1}^{R} A_r[n] \cos(2\pi f_r[n]n)$$

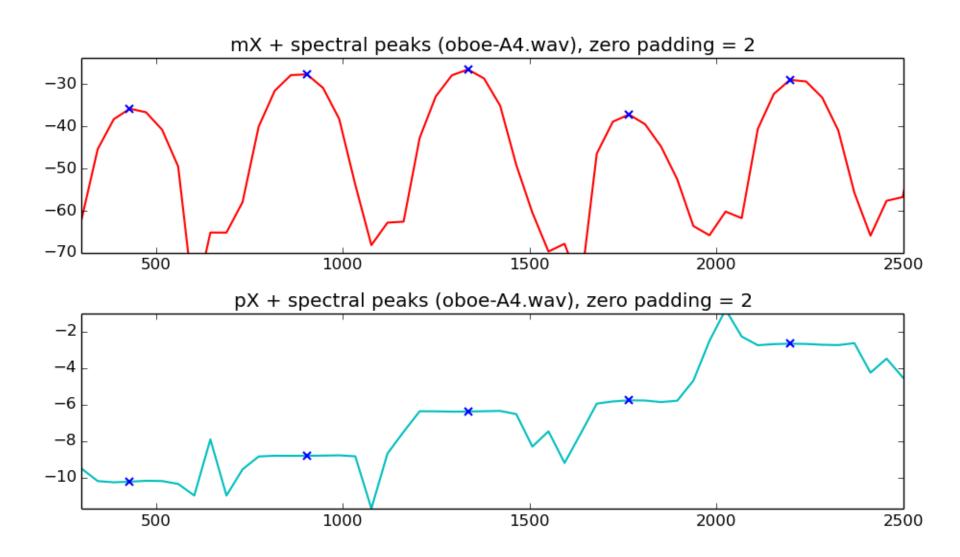


Peak detection

 $p_r = mX[k_0]$ when $mX[k_0-1] < mX[k_0] > mX[k_0+1]$ mX = magnitude spectrum; r = peak number; $k_0 = \text{peak location}$



Peak detection with zero-padding



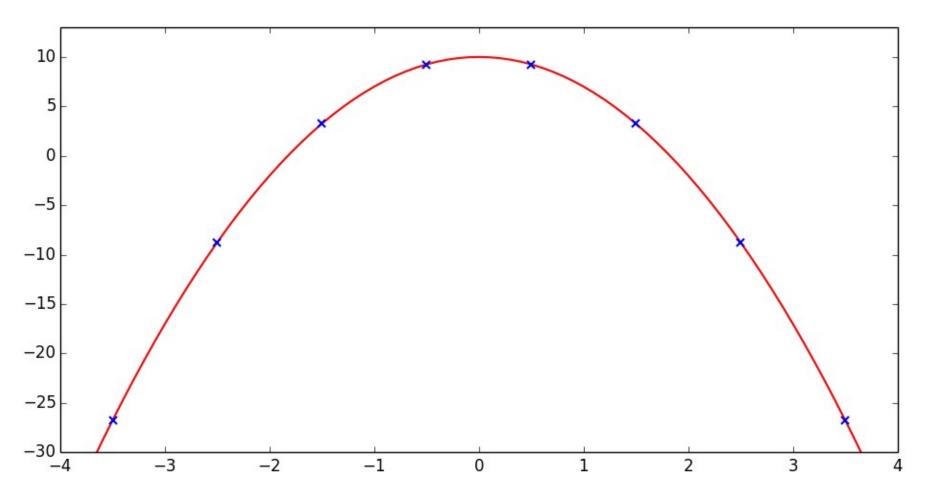
Parabola

$$x[n]=a(n-p)^2+b$$

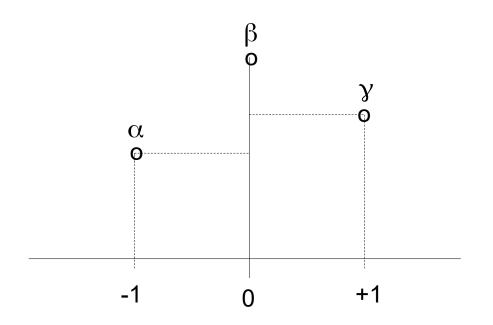
p: center of parabola

a: concavity measure

b: offset



Peak interpolation



$$x[-1] = \alpha = mX[k_{\beta}-1]$$

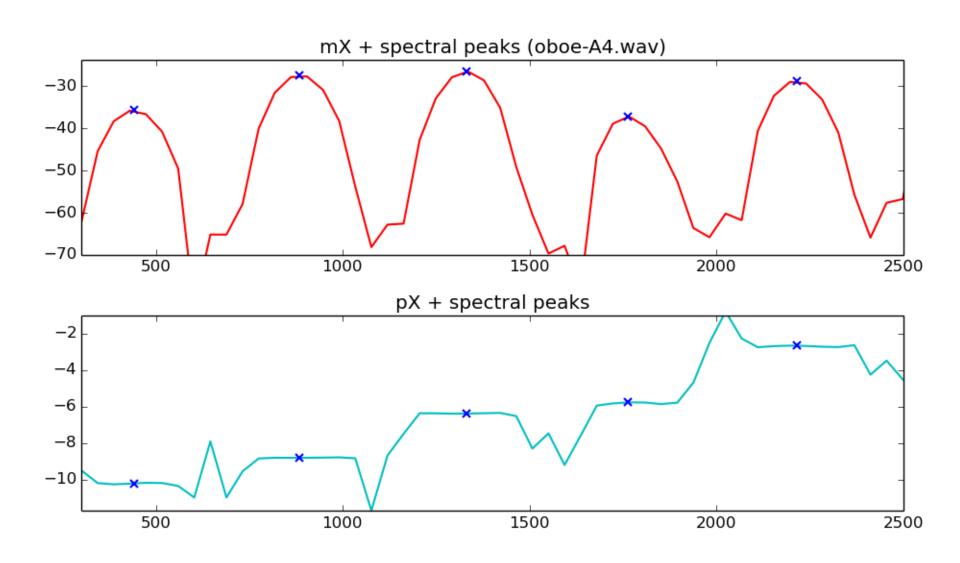
$$x[0] = \beta = mX[k_{\beta}]$$

$$x[1] = \gamma = mX[k_{\beta}+1]$$

center of the parabola:
$$\hat{k}_p = k_p + \frac{1}{2} \frac{\alpha - \gamma}{(\alpha - 2\beta + \gamma)}$$

amplitude: $\hat{a} = \beta - \frac{1}{4} (\hat{k}_p - k_p)(\alpha - \gamma)$

Peak detection with interpolation



Sinusoidal parameters from peaks

$$\hat{k}_{p} = k_{p} + \frac{0.5 * (|X[k_{p}-1]| - |X[k_{p}+1]|)}{|X[k_{p}-1]| - 2 * |X[k_{p}]| + |X[k_{p}+1]|}$$

$$f_p = \frac{f_s * \hat{k}_p}{N}$$

$$A_p = |X[k_p]| - 0.25 * (|X[k_p - 1]| - |X[k_p + 1]|) * (\hat{k}_p - k_p)$$

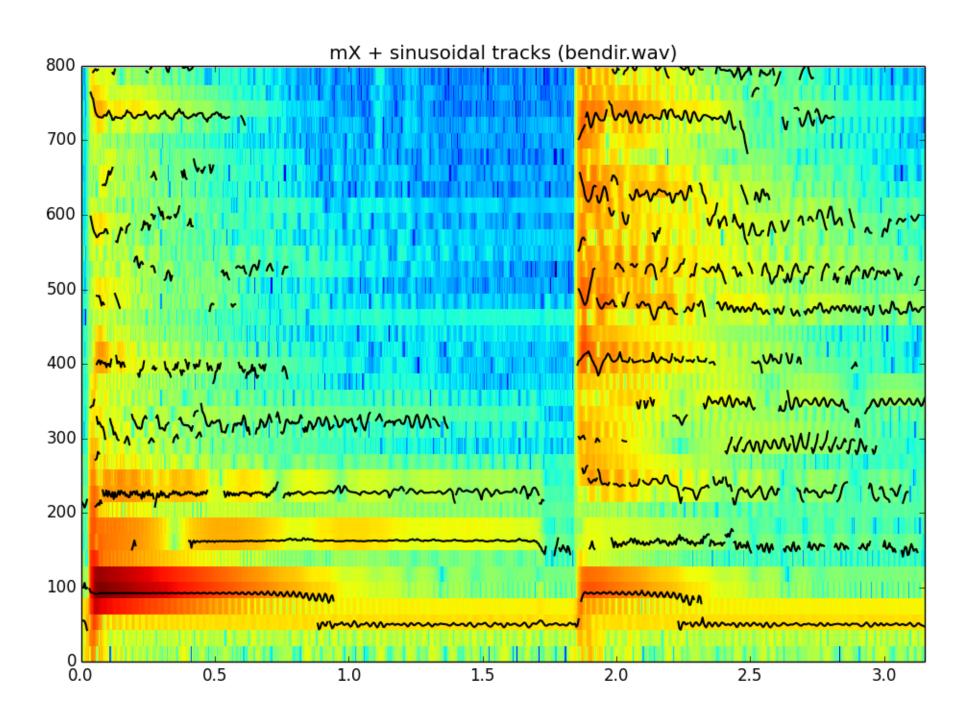
$$ph_p = \not\prec X[\hat{k}_p]$$

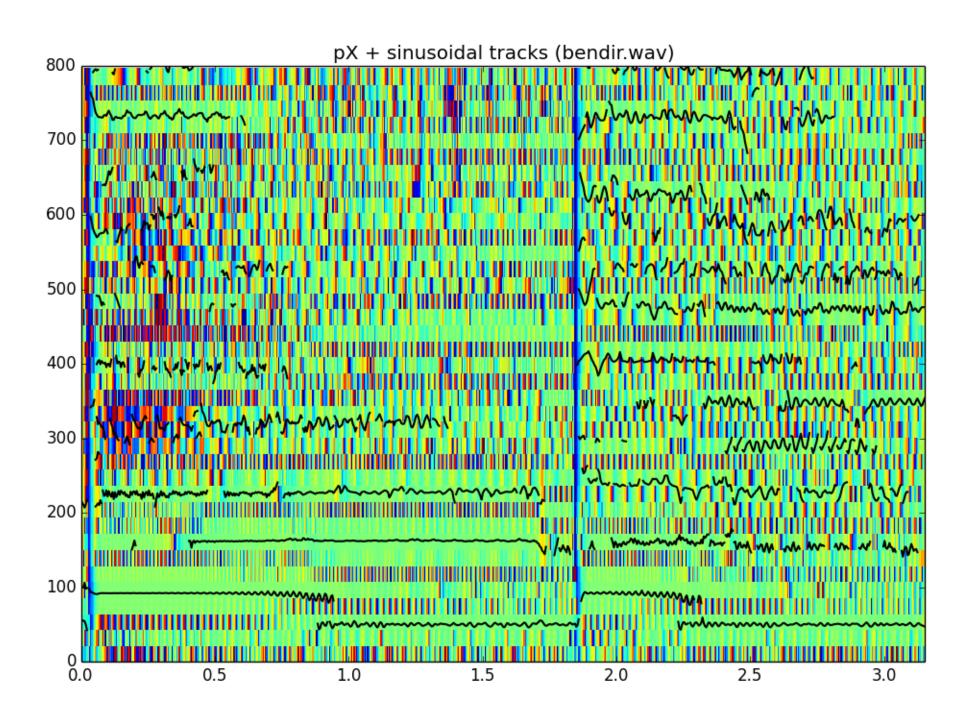
Sinewaves in spectrogram

- Sinusoid → stable peak track in spectrogram
- Stability identified by
 - frequency and amplitude in succesive frames
 - phase derivative in time/freq

Condition for a peak f_p of frame l to be part of a track t:

$$f_p[l] = f_t[l]$$
 if $(|f_p[l] - f_t[l-1]| < threshold)$
and if exists $f_t[l-2], f_t[l-3], ..., f_t[l-L]$





References and credits

- More information in: http://en.wikipedia.org/wiki/Sinusoidal_model
- Reference on sinusoidal modeling by Julius O. Smith: https://ccrma.stanford.edu/~jos/sasp/Spectrum_Analysis_ Sinusoids.html
- Sounds from: http://www.freesound.org/people/xserra/packs/13038/
- Slides released under CC Attribution-Noncommercial-Share Alike license and code under the Affero GPL license; available from https://github.com/MTG/sms-tools

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