

Periodic Sampling

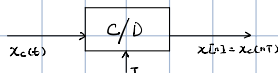
→ Def: A method of obtaining a discrete-time representation of a continuous-time signal $x_c(t)$, where a sequence of samples $x[n]$ is obtained according to the relation

$$x[n] = x_c(nT) \quad -\infty < n < \infty$$

where T is the sampling period, $f_s = \frac{1}{T}$ is the sampling frequency, $\omega_s = \frac{2\pi}{T}$ in radians per second.

→ System that implement the operation

→ continuous-to-discrete-time (C/D) converter or sampler:



→ Analog-to-digital (A/D) in practical setting.

→ Sampling operation is not invertible if not restrict the input signals to the sampler.

→ Sampling process:

→ the periodic impulse train: $s(t) = \sum_{n=-\infty}^{\infty} \delta(t-nT)$

$$x_s(t) = x_c(t)s(t)$$

$$= x_c(t) \sum_{n=-\infty}^{\infty} \delta(t-nT) = \sum_{n=-\infty}^{\infty} x_c(nT) \delta(t-nT)$$

$$\delta(x) = \begin{cases} 1 & x=0 \\ 0 & x \neq 0 \end{cases} \quad \begin{matrix} \text{对于任意 } n, \\ \text{若 } t \neq nT, \delta(t) = 0 \\ \text{若 } t = nT, \delta(t) = \delta(t-nT) \end{matrix}$$

$$x_s(t) = \sum_{n=-\infty}^{\infty} (\delta(t-nT) x_c(nT)) \xrightarrow{t=nT} x_c(nT)$$

Frequency-Domain Representation of Sampling

→ Fourier transform for a continuous time signal $x(t)$.

$$X(\omega) = \int_{-\infty}^{\infty} x(t) e^{-j\omega t} dt$$

$$x(t) = \frac{1}{2\pi} \int_{-\infty}^{\infty} X(\omega) e^{j\omega t} d\omega$$

$$s(t) = \sum_{n=-\infty}^{\infty} \delta(t-nT)$$

$$S(j\omega) = \sum_{k=-\infty}^{\infty} \delta(\omega - k\omega_s)$$



$$x_s(t) = x_c(t)s(t) \rightarrow X_s(j\omega) = \frac{1}{2\pi} X_c(j\omega) * S(j\omega) = \frac{1}{T} \sum_{k=-\infty}^{\infty} X_c(j(\omega - k\omega_s))$$

$$= \sum_{n=-\infty}^{\infty} x_c(nT) \delta(t-nT) \rightarrow X_s(j\omega) = \sum_{n=-\infty}^{\infty} x_c(nT) e^{-jn\omega T}$$

→ Nyquist Sampling Theorem:

→ Nyquist frequency: ω_N ; Nyquist rate: $2\omega_N$.

$x_c(t)$ is a bandlimited signal with $X_c(j\omega) = 0$ for $|\omega| > \omega_N$. Then $x_c(t)$ is uniquely determined by its samples

$$x[n] = x_c(nT), \text{ if } \omega_s = \frac{2\pi}{T} \geq 2\omega_N$$

$$X_s(j\omega) = X(e^{j\omega T})|_{\omega=\omega T} = X(e^{j\omega T})$$

$$X_s(j\omega) = \sum_{n=-\infty}^{\infty} x_c(nT) e^{jn\omega T} = \sum_{n=-\infty}^{\infty} x_c(nT) e^{jn\omega T} \quad (\omega = \omega T)$$

$$X(e^{j\omega T}) = \frac{1}{T} \sum_{k=-\infty}^{\infty} X_c(j(\omega - k\omega_s))$$

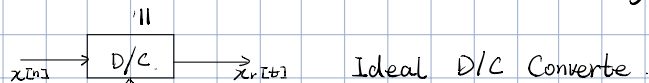
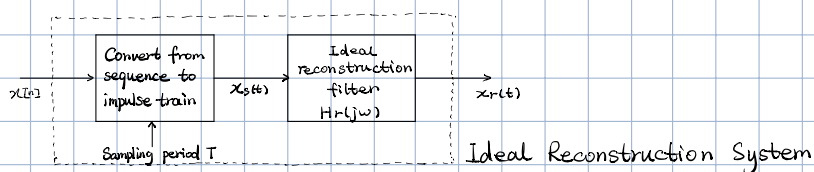
$$S(\omega) = \delta(-\omega) = \frac{1}{2\pi} \int_{-\infty}^{\infty} e^{j\omega t} dt$$

Reconstruction of A Bandlimited Signal From Its Samples

→ If the modulated impulse train $x_s(t)$ is filtered by an appropriate lowpass filter, then the filter output will be exactly $x_c(t)$.

$$x_r(t) = \sum_{n=-\infty}^{\infty} x[n] h_r(t-nT) = x_c(t)$$

→ Process:



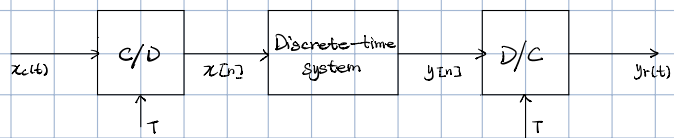
→ Ideal lowpass filter $H_r(j\omega) = \begin{cases} T & |\omega| \leq \frac{\pi}{T} \\ 0 & |\omega| > \frac{\pi}{T} \end{cases}$

→ corresponding impulse response: $h_r(t) = \frac{\sin(\pi t/T)}{\pi t/T}$

$$\text{Output: } x_r(t) = \sum_{n=-\infty}^{\infty} x[n] \frac{\sin(\pi(t-nT)/T)}{\pi(t-nT)/T}$$

$$y[n] = x[n - \alpha T] \rightarrow y[n] = x_c(t - \alpha T)|_{t=nT}$$

Discrete-Time Processing of Continuous-Time Signals.



Continuous-Time Processing of Discrete-Time Signals.

