TAO KONG

BASIC INFORMATION

- Homepage: https://taokong.github.io
- Google Scholar: https://scholar.google.com/citations?user=kSUXLPkAAAAJ&hl=en
- Github: https://github.com/taokong
- Email: taokongcn@gmail.com Phone: (+86)-18710113786 (China), 15713151377 (USA)
- Main research: Computer Vision, Deep learning, Instance Level Recognition, Object Detection

EDUCATION

University of Pennsylvania, Philadelphia, USA

2018.10 - now

Visiting scholar in GRASP Lab, advised by Prof. Jianbo Shi, expected 2019.03

Tsinghua University, Beijing, China

2014.09 - now

Ph.D in Computer Science & Technology, expected 2019.07

Shandong University, Jinan, China

2010.09 - 2014.06

B.Eng. in Computer Science & Technology

SELECTED PUBLICATIONS

- **Tao Kong**, Fuchun Sun, Huaping Liu, Wenbing Huang. Deep Feature Pyramid Reconfiguration for Object Detection, **ECCV** 2018.
 - A novel architecture reconfiguring the feature hierarchy in a flexible yet effective way: global attention and local reconfiguration.
 - The models achieve consistent and significant boosts compared with other state-of-the-arts.
- **Tao Kong**, Fuchun Sun, Anbang Yao, Huaping Liu, Yurong Chen, Ming Lu. RON: Reverse Connection with Objectness Prior Networks for Object Detection, **CVPR** 2017.
 - We propose reverse connection to traditional convolutional networks to enable the network to detect objects on multi-levels **in real-time**!
 - Utilizing objectness prior to reduce the searching space of objects.
 - The 1st place of 2016 IROS Robotic Grasping and Manipulation Competition based on RON and HyperNet!
 - Code: https://github.com/taokong/RON, 320+ stars, 130+ forks, 40+ citations.
- **Tao Kong**, Anbang Yao, Yurong Chen, Fuchun Sun. HyperNet: Towards Accurate Region Proposal Generation and Joint Object Detection, **CVPR** 2016 (*Spotlight Presentation*).
 - The Hyper Features well incorporate deep but highly semantic, intermediate but really complementary, and shallow but naturally high-resolution features of the image.
 - Adding Hyper Features to Faster R-CNN achieves **42.0 AP on COCO object detection task**, which outperforms the winner of MS COCO 2016!
 - 200+ citations according to Google Scholar and the idea has been successfully used in PVANet (one of the top lightweight deep neural networks), winner of the MS COCO 2017 pose estimation task (https://arxiv.org/abs/1711.07319), and pedestrian detection (https://arxiv.org/abs/1705.02757).

- Di Guo, **Tao Kong**, Fuchun Sun, Huaping Liu, Object discovery and grasp detection with a shared convolutional neural network, **ICRA** 2016 (*Oral Presentation*).
 - 100 fps on a real robotic platform to discover and grasp a target object from the stack!
- **Tao Kong**, Gongping Yang, Lu Yang. A hierarchical classification method for finger knuckle print recognition. EURASIP Journal on Advances in Signal Processing 2014 (1), 44, 2014 (*SCI*)
- Tao Kong, Gongping Yang, Lu Yang. A new finger-knuckle-print ROI extraction method based on probabilistic region growing algorithm. International Journal of Machine Learning and Cybernetics 5 (4), 569-578, 2014 (SCI)

EXPERIENCE

Research Intern 2018.04 - 2018.08

- Microsoft Research Asia (MSRA), Beijing, China
- Advisor: Dr. Jifeng Dai
- Design computer vision algorithms to deal with large scale missing/noisy label instance-level recognition problems.

Technology Partner 2016.07 - 2018.02

- A Machine Vision Startup
- Defect inspection systems using modern computer vision/machine learning algorithms.

Research Intern 2015.07 - 2016.07

- Intel Labs China (ILC), Beijing, China
- Advisor: Dr. Anbang Yao
- Develop Convolutional Neural Networks to learn better representations for fast and accurate object detection.

Research Assistant 2014.09 - now

- Tsinghua University
- Advisor: Prof. Fuchun Sun & Huaping Liu
- Design computer vision algorithms using Deep Learning for object detection & robot grasping.

PROFESSIONAL ACTIVITIES

Peer reviewer of TIP, CVPR 2018, IJCAI 2018, IROS 2017, AAAI 2019

AWARDS AND HONOR

- **Top 2** on PASCAL VOC 2012 leaderboard, 2016.11
- The 1st place of 2016 IROS Robotic Grasping and Manipulation Competition, 2016.10
- Division Recognition Award (DRA): Excellence in Speed & Execution, ILC, 2016
- The 1st Price of CUMCM(China Undergraduate Mathematical Contest in Modeling), 2014
- The CCF Outstanding Undergraduate: The IBM Outstanding Undergraduate, 2014

TECHNICAL STRENGTHS

Computer Languages Python, C++, Java, Matlab Programming Library Caffe, Pytorch, OpenCV, PCL