# Linux Driver for Audio

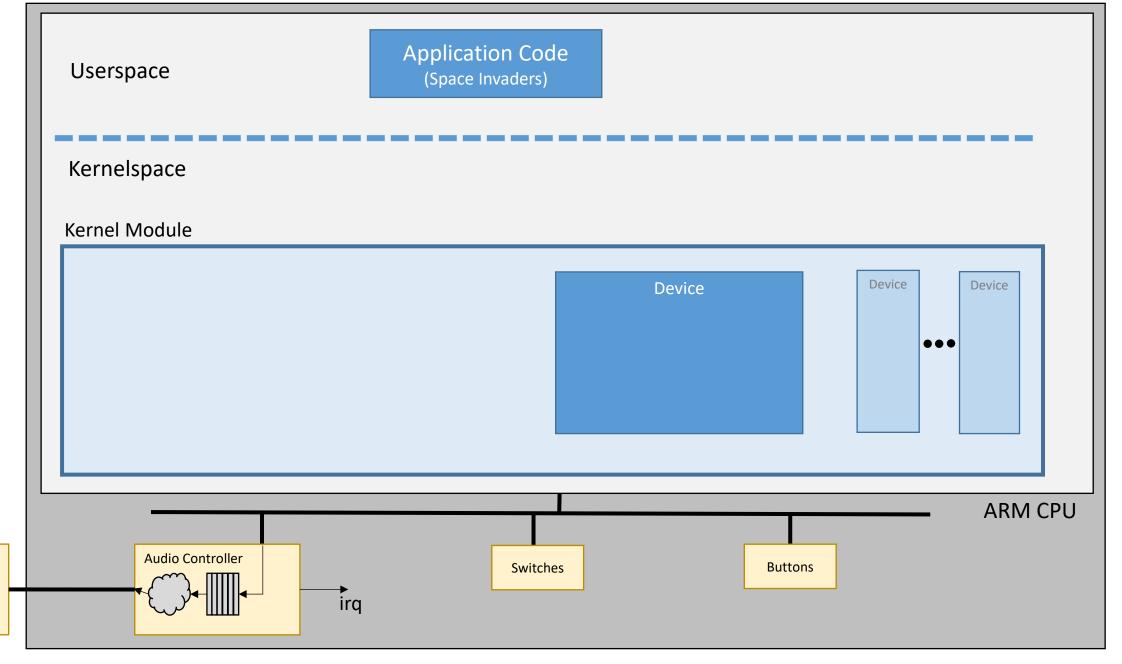
Lab 5 Milestone 1 & 2

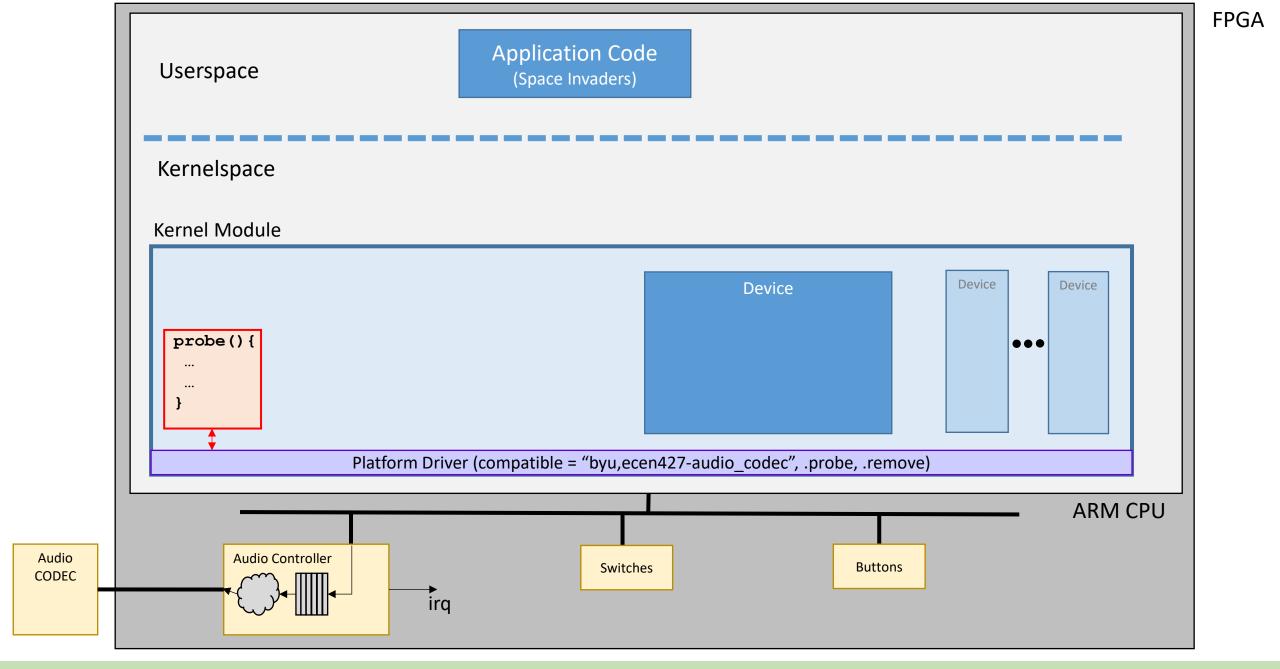
### What our driver needs to do:

- Be notified of hardware in the system (Milestone 1)
- Allow user code to talk to the driver (Milestone 1)
- Talk to the hardware (Milestone 2)
- Handle interrupts from the hardware (Milestone 2)

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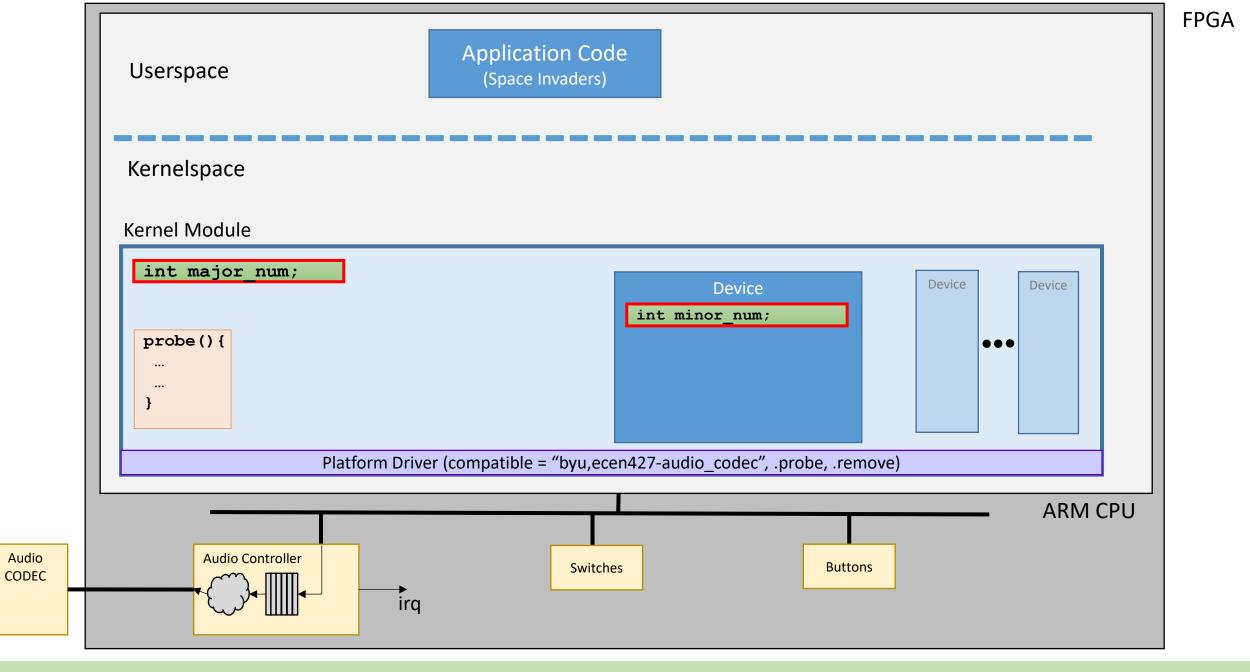
### User Code Needs to Talk to Driver

**End Goal:** Create a device file (/dev/xxx) that we can read() and write() to. (Recall how you used /dev/uio)

The device file (/dev/xxx) is an interface to a character device.

#### Steps:

- 1. Create a character device
- 2. Create a device file



alloc\_chrdev\_region(dev\_t \* output, minor\_start, count, MODULE\_NAME)

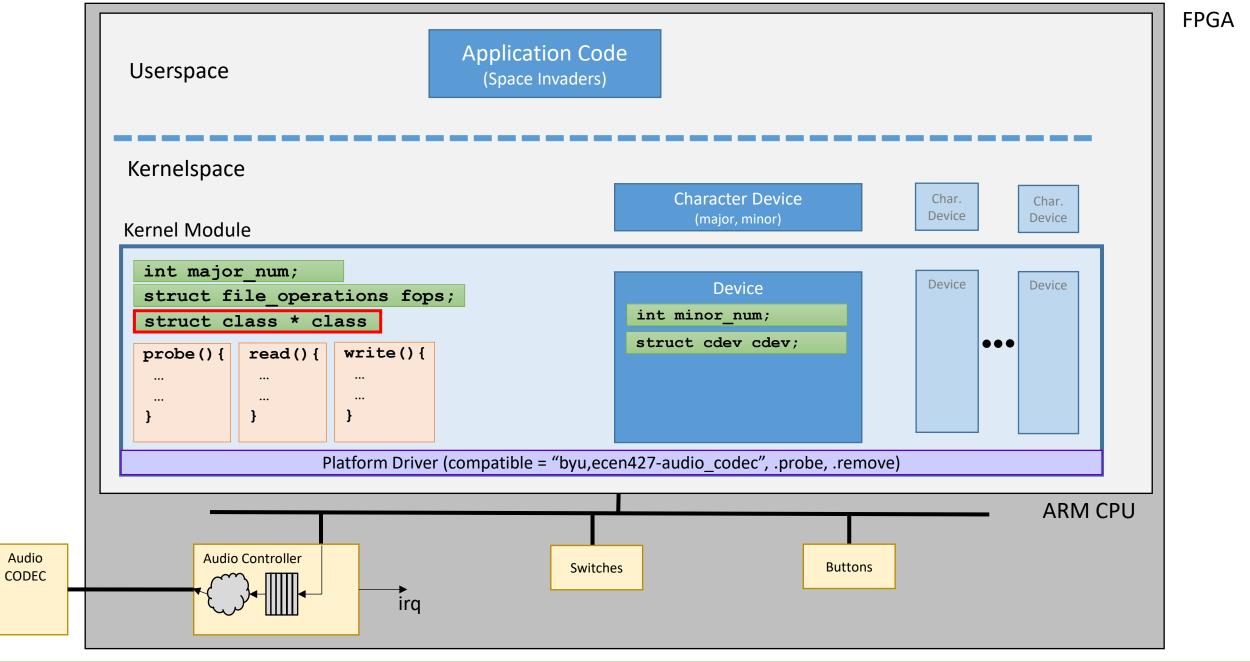
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The device file (/dev/xxx) is an interface to a character device.

#### Steps:

- 1. Create a character device
- 2. <u>Create a device file</u>



device create (struct class\*, parent = NULL, dev t, "your device name")

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### What our driver needs to do:

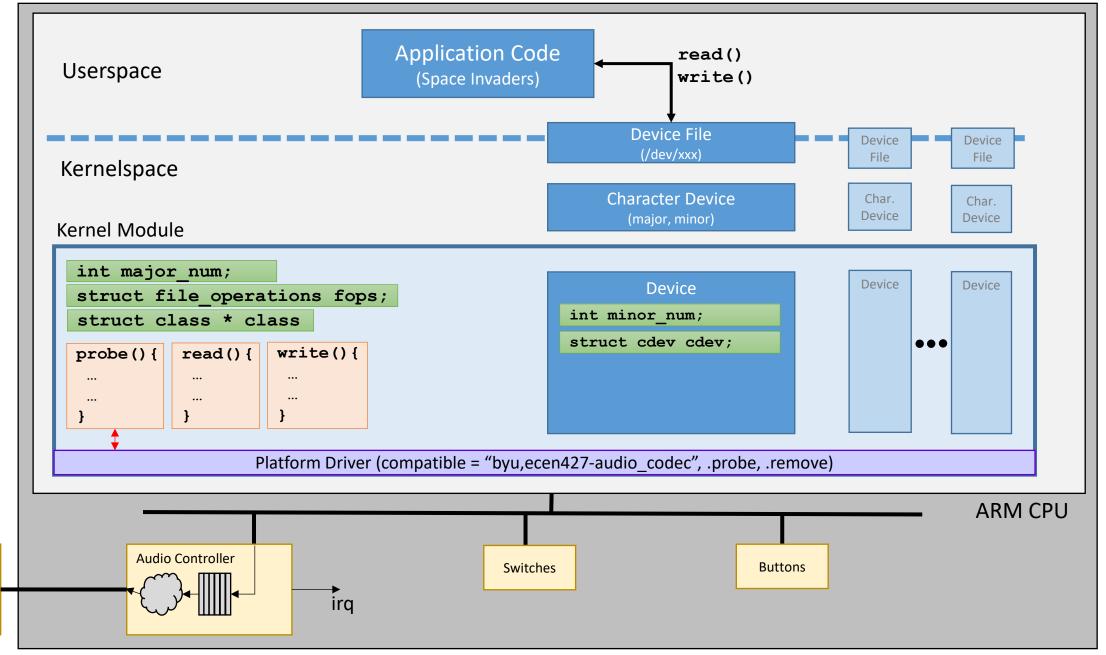
- Be notified of hardware in the system (Milestone 1)
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### Driver needs to talk to the hardware

1. Need to figure out physical address

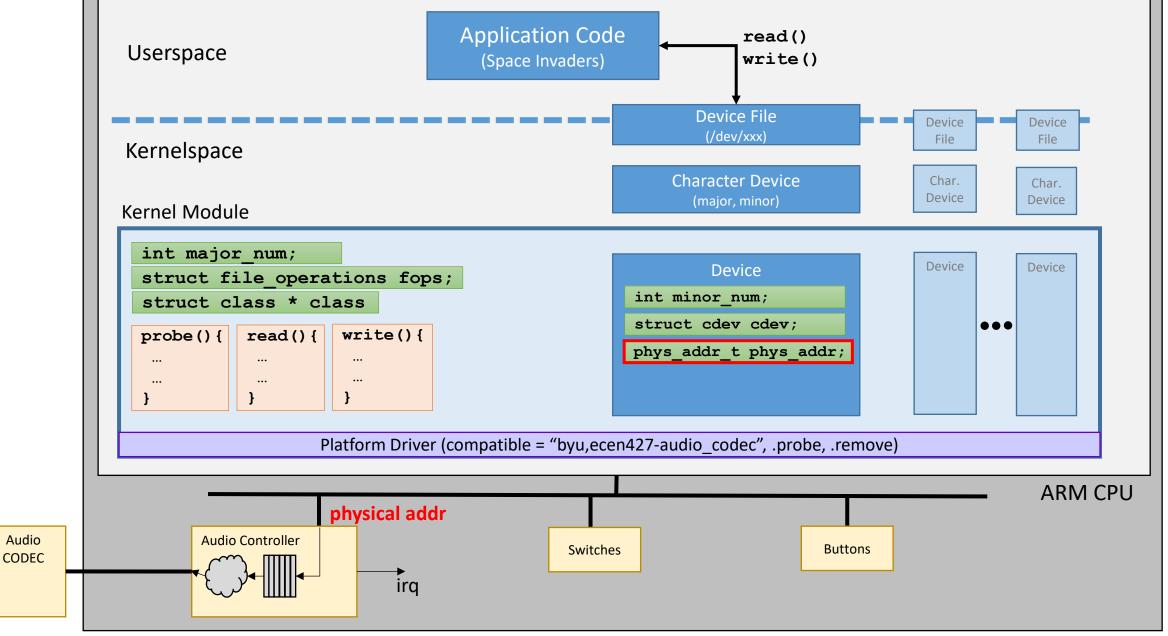
2. Need to reserve the physical address

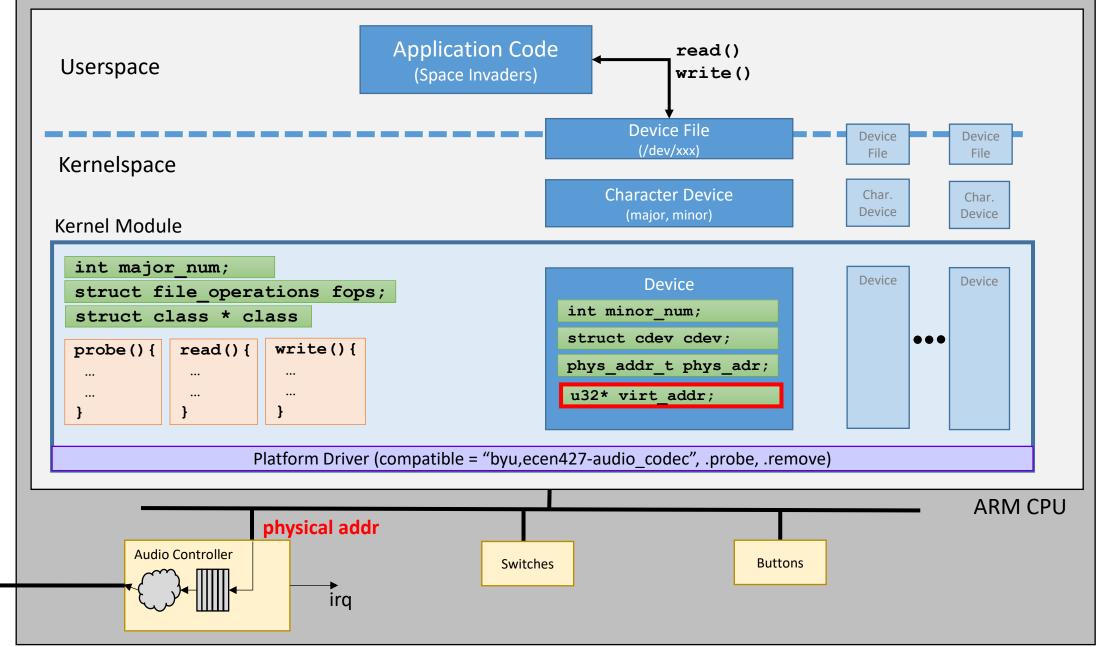
3. Need to get a pointer (virtual address) to the physical address



platform\_get\_resource(struct plaform\_device \* dev, IORESOURCE\_MEM, 0);

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### Driver needs to talk to the hardware

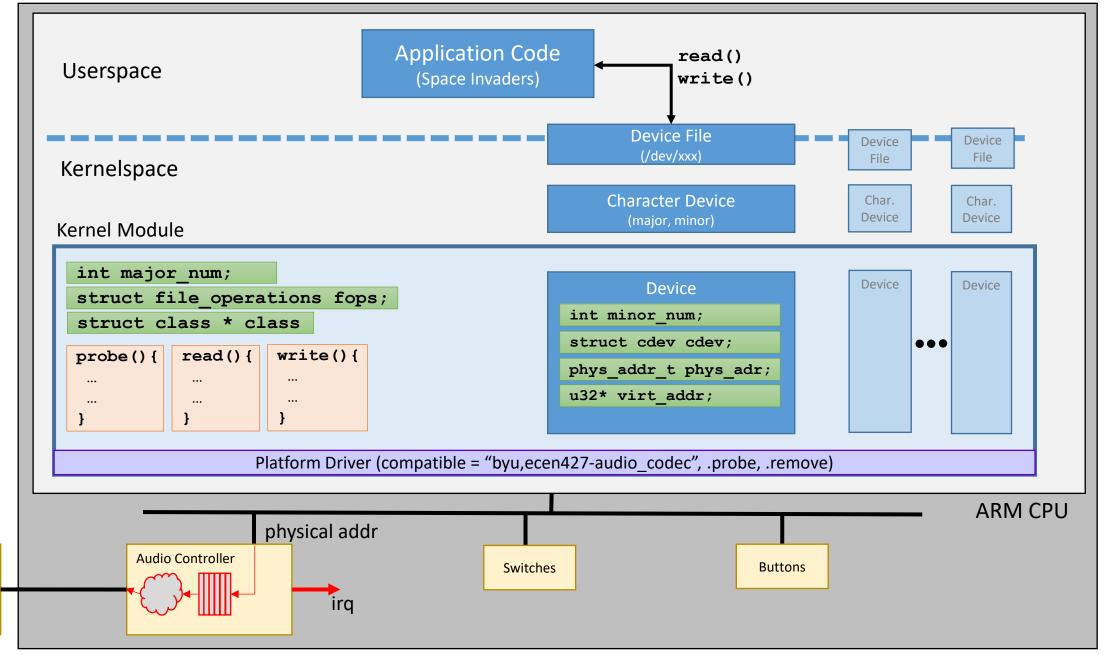
1. Need to figure out physical address

2. Need to reserve the physical address

3. Need to get a pointer (virtual address) to the physical address

- 4. Talk to the hardware with:
  - iowrite32 (value, virt\_addr + offset)
  - ioread32(virt\_addr + offset)

# Driver Needs to Handle Interrupts



## Driver Needs to Handle Interrupts

1. Get IRQ Number

2. Register Interrupt Handler with Linux

irq = platform\_get\_resource(struct platform\_device \* dev, IORESOURCE\_IRQ, 0);

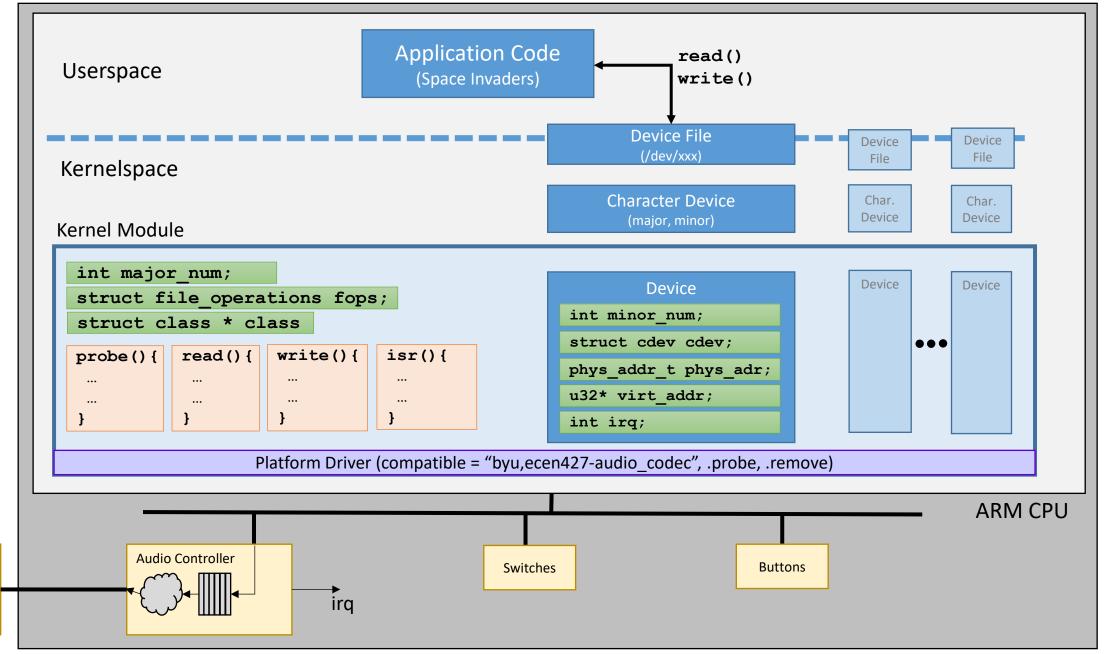
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request\_irq(irq, isr, IRQ\_NO\_FLAGS, MODULE\_NAME, void\*)

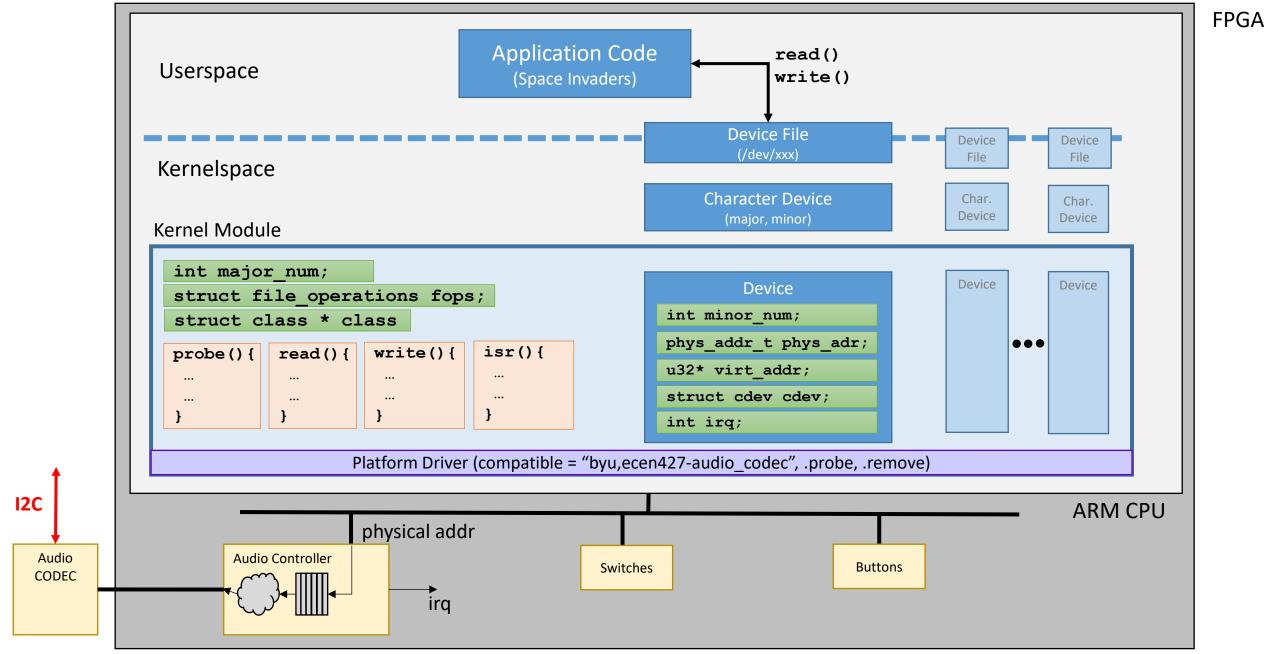
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One last thing...



Before you actually send data to the CODEC chip, you need to configure it via I2C. I have provided you with a userspace library to do this. Run it before loading your driver.