

# One-dimensional turbulence (ODT): computationally efficient modeling and simulation of turbulent flows

Victoria B. Stephens, David O. Lignell\*

*Chemical Engineering Department, Brigham Young University, Provo, UT 84602, USA*

---

## Abstract

Write this last. About 100 words.

*Keywords:* turbulence, reacting flows, one-dimensional turbulence

---

## Code Metadata

Nr.	Code metadata description	Please fill in this column
C1	Current code version	1.0
C2	Permanent link to code/repository used for this code version	<i>github.com/BYUignite/ODT</i>
C3	Code Ocean compute capsule	N/A
C4	Legal Code License	MIT
C5	Code versioning system used	Git
C6	Software code languages, tools, and services used	C++, Python 3.x, Yaml,
C7	Compilation requirements, operating environments & dependencies	CMake 3.12+, Cantera, Git, Doxygen (optional)
C8	If available Link to developer documentation/manual	N/A
C9	Support email for questions	davidlignellbyu.edu

Table 1: Code metadata (mandatory)

## 1. Motivation and significance

Turbulent flows characterize the vast majority of fluid flows in practical engineering applications, and simulations of turbulent flows provide re-

---

\*Corresponding author.

*Email address:* davidlignell@byu.edu (David O. Lignell)

4 searchers with valuable insights into complex systems, particularly reacting  
5 turbulent flows such as combustion processes. Turbulence is a complex phe-  
6 nomenon that affects the full range of a flow’s length and time scales. As a  
7 result, resolving the entire flow field by numerically solving the Navier-Stokes  
8 equations of fluid flow, as is done in direct numerical simulations (DNS), re-  
9 quires substantial computational resources. DNS is a powerful research tool,  
10 but its high computational cost makes it intractable for simulating most  
11 practical engineering flows. In order to achieve numerical solutions to prac-  
12 tical flow problems, researchers can use alternative frameworks that model  
13 turbulence rather than resolving it directly.

14 Large-eddy simulations (LES) address the problem of wide-ranging length  
15 and time scales by combining direct resolution of grid-scale quantities, as in  
16 DNS, with subgrid modeling of smaller turbulence structures. The more  
17 complex the flow, the more modeling is required; for example, a jet flame  
18 simulation might require subgrid modeling for the combustion chemistry, ra-  
19 diative heat transfer, or soot chemistry in addition to turbulence structures,  
20 all of which form a tightly coupled system in which each model interacts  
21 heavily with the others. While subgrid modeling makes LES more computa-  
22 tionally affordable than DNS, it can introduce empiricism into simulations,  
23 which can lead to inaccurate results. Additionally, unresolved quantities are  
24 often parameterized in state space with empirical relationships or assumed  
25 distributions that lack universal applicability. LES is a valuable simulation  
26 tool, but its approach to turbulence modeling can introduce unwanted em-  
27 piricism and make errors difficult to isolate and quantify.

28 The one-dimensional turbulence model (ODT) functionally reverses the  
29 LES approach, modeling large-scale turbulent advection and directly resolv-  
30 ing small-scale flow structures, simulating the full range of length and time  
31 scales in a single dimension. Because large-scale structures are much easier  
32 to study and model than small-scale structures, ODT mitigates or sidesteps  
33 many of the subgrid modeling issues that complicate LES. Previous stud-  
34 ies show that ODT can attain accuracy comparable to DNS at a fraction  
35 of the computational cost [1, 2], making it an attractive tool for simulating  
36 turbulent flows. Because the model is one-dimensional, it is limited to ho-  
37 mogeneous or boundary layer flows such as jets, wakes, and mixing layers;  
38 such flows, however, are extremely common in both nature and turbulence  
39 research. ODT’s computational efficiency and resolution of a full range of  
40 scales make it a valuable tool that complements experimental studies and  
41 other simulation tools like DNS and LES.

## 42 2. Software description

### 43 2.1. Model description

44 The ODT model is described in detail in the literature [3, 4, 5, 6, 7]; only a  
45 brief explanation will be given here. In ODT, turbulent advection is modeled  
46 with stochastic processes called eddy events, which punctuate the solution  
47 of unsteady, one-dimensional transport equations for mass, momentum, and  
48 enthalpy. The ODT code uses a Lagrangian finite-volume formulation for  
49 diffusive advancement that includes adaptive mesh refinement [7]. In this  
50 approach, mass remains constant inside each grid cell while cell volumes  
51 increase or decrease according to dilation. Because the ODT model is one-  
52 dimensional, it is limited to homogeneous or boundary-layer flows, such as  
53 jets, wakes, and mixing layers; these types of flows, however, are common in  
54 nature and central to turbulence research.

55 Eddy events occur as a Poisson process in accordance with their eddy  
56 rates, where a given eddy event of size  $l$  and location  $x_0$  has an eddy timescale  
57  $t$  and an associated eddy rate  $1/t$ . Three user-defined ODT parameters  
58 control the eddy event process: the eddy rate parameter  $C$  scales the rate of  
59 occurrence of the eddies; the viscous penalty parameter  $Z$  suppresses small  
60 eddies; and the large eddy suppression parameter  $\beta$  constrains eddies such  
61 that they do not reach over the elapsed simulation time.

62 Eddy events modify domain variables using triplet maps, as illustrated  
63 for a cylindrical domain in Figure 1. For a region of eddy size  $l$ , the do-  
64 main is copied to create three map images; the three images are then placed  
65 back to back with the middle image inverted to maintain continuity, and  
66 the composite is reapplied to the domain. This process applies to all trans-  
67 ported variables on the domain. Applied properly, the triplet map increases  
68 scalar gradients and decreases length scales consistent with the application  
69 of turbulent eddies in real flows, conserves all quantities and their statistical  
70 moments, and maintains continuity in property profiles. Subsequent eddies  
71 in the same region will result in a cascade of scales, and eddy rates depend  
72 on eddy size and the local kinetic energy such that they follow turbulent  
73 cascade scaling laws.

### 74 2.2. Software Architecture

75 The ODT code is a relatively self-contained C++ package. The system of  
76 nonlinear ODEs is solved using CVODE [8] and user input files are processed  
77 with YAML [9], both of which are installed locally during the ODT build  
78 process. For reacting flow cases, chemical kinetics and transport are handled  
79 by Cantera [10], which must be previously installed by the user.

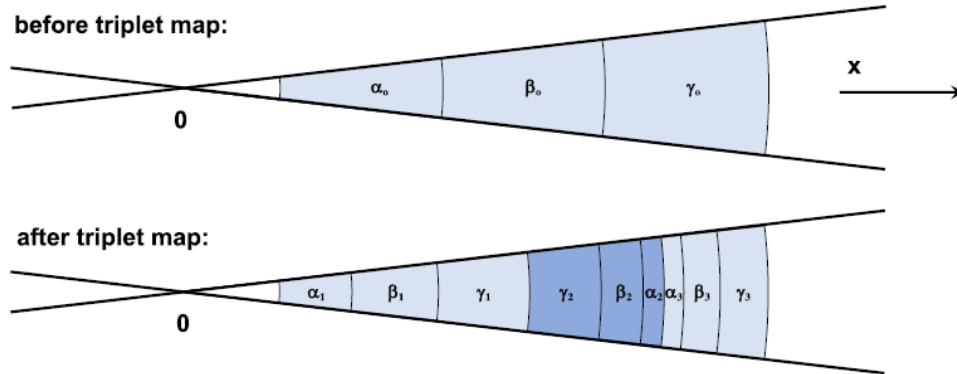


Figure 1: Schematic diagram of a cylindrical triplet map, adapted from [6]. Before the triplet map, the domain contains three grid cells of equal volume, while after the triplet map has been applied, the domain contains nine cells. The nine final cells are labeled according to the cells from which they originated and shaded to indicate that three map images were combined to create the final composite.

### 3. Example Cases

### 4. Impact

Questions to answer in this section (from SoftwareX template)

1. How can new research questions be pursued with this software?
  - possibility of parametric studies (much harder with DNS/LES/RANS)
  - study of late-flame soot and radiation interactions, soot emissions as smoke
  - comparative radiation model studies?
2. How does the software improve pursuit of existing research questions?
  - late-flame behavior becomes easier to study
  - validation of LES subgrid models
  - soot stuff, especially late in the flame (because soot moves slowly compared to gas species and therefore short simulation times like in DNS aren't enough to study it effectively)
3. How does the software change the daily practice of its users?
  - cases take hours or days rather than weeks using supercomputer resources
  - test cases can be run on local computers (unlike something like DNS) and as background tasks without disrupting other tasks

- 99           • ODT as a tool complements other approaches, can cover blind  
100           spots and be used in validation
- 101       4. How widespread is the software? Who uses it? (Within and outside of  
102       intended research area and/or group.)
- 103           • BYU group
- 104           • JCH at Sandia
- 105           • Chalmers group in Sweden (Marco Fistler, etc.)
- 106           • German university group (Heiko Schmidt, Juan Media, Marten  
107           Klein, etc.)
- 108           • TO DO: find other groups who have used or currently use ODT
- 109       5. How is the software used in commercial settings (if any)? Has it led to  
110       creation of spin-off companies?
- 111           • No commercial use (I think).

## 112   **5. Conclusion**

113       Write this part next to last

## 114   **6. Conflict of Interest**

115       We wish to confirm that there are no known conflicts of interest associated  
116       with this publication and there has been no significant financial support for  
117       this work that could have influenced its outcome.

## 118   **Acknowledgements**

119       This work is supported in part by the National Science Foundation under  
120       Grant No. CBET-1403403.

## 121   **References**

- 122   [1] D. O. Lignell, G. C. Fredline, A. D. Lewis, Comparison of one-  
123       dimensional turbulence and direct numerical simulations of soot for-  
124       mation and transport in a nonpremixed ethylene jet flame 35 (2) (2015)  
125       1199–1206. doi:10.1016/j.proci.2014.05.046.
- 126   [2] A. W. Abboud, C. Schulz, T. Saad, S. T. Smith, D. D. Harris, D. O.  
127       Lignell, A numerical comparison of precipitating turbulent flows between  
128       large-eddy simulation and one-dimensional turbulence 61 (10) (2015)  
129       3185–3197. doi:10.1002/aic.14870.

- [3] A. R. Kerstein, One-dimensional turbulence: model formulation and application to homogeneous turbulence, shear flows, and buoyant stratified flows 392 (1999) 277–334. doi:10.1017/S0022112099005376.
- [4] A. R. Kerstein, W. T. Ashurst, S. Wunsch, V. Nilsen, One-dimensional turbulence: vector formulation and application to free shear flows 447 (2001) 85–109. doi:10.1017/S0022112001005778.
- [5] W. T. Ashurst, A. R. Kerstein, One-dimensional turbulence: Variable-density formulation and application to mixing layers 17 (2). doi:10.1063/1.1847413.
- [6] D. O. Lignell, V. B. Lansinger, J. Medina, M. Klein, A. R. Kerstein, H. Schmidt, M. Fistler, M. Oevermann, One-dimensional turbulence modeling for cylindrical and spherical flows: model formulation and application 32 (4) (2018) 495–520. doi:10.1007/s00162-018-0465-1.
- [7] D. O. Lignell, A. R. Kerstein, G. Sun, E. I. Monson, Mesh adaption for efficient multiscale implementation of one-dimensional turbulence 27 (3-4) (2013) 273–295. doi:10.1007/s00162-012-0267-9.
- [8] A. C. Hindmarsh, R. Serban, D. R. Reynolds, CVODE, [https://computing.llnl.gov/sites/default/files/public/cv\\_guide.pdf](https://computing.llnl.gov/sites/default/files/public/cv_guide.pdf) (2020).  
URL <https://computing.llnl.gov/projects/sundials/cvode>
- [9] J. Beder, yaml-cpp v0.6.3 (2008).  
URL <https://github.com/jbeder/yaml-cpp/>
- [10] D. G. Goodwin, R. L. Speth, H. K. Moffat, B. W. Weber, Cantera (2018). doi:10.5281/zenodo.1174508.  
URL <https://cantera.org/>

## Current executable software version

Ancillary data table required for sub version of the executable software: (x.1, x.2 etc.) kindly replace examples in right column with the correct information about your executables, and leave the left column as it is.

Nr.	(Executable) software meta-data description	Please fill in this column
S1	Current software version	2.1
S2	Permanent link to executables of this version	For example: <i>https</i> : <i>//github.com/combogenomics/DuctApe/releases/tag/DuctApe-0.16.4</i>
S3	Legal Software License	MIT
S4	Computing platforms/Operating Systems	Linux, OS X, Microsoft Windows
S5	Installation requirements & dependencies	CMake 3.12+, Cantera, Git, Doxygen (optional)
S6	If available, link to user manual - if formally published include a reference to the publication in the reference list	For example: <i>http</i> : <i>//mozart.github.io/documentation/</i>
S7	Support email for questions	davidlignell@byu.edu

Table 2: Software metadata (optional)