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# Continuing Education: Searching Algorithms

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# Agenda

- Introduction
- Time Complexity -  $O(n)$
- List Search
  - Linear/Sequential Search
  - Binary Search
- Graph Search
  - Breadth First Search
  - Depth First Search
- Python Exercises
- Code Review

# Github Repository For Exercises

[https://github.com/byujan/searching\\_algorithms](https://github.com/byujan/searching_algorithms)

# Introduction

**Searching Algorithms** are a series of instructions that retrieves an end goal stored within some data structure.

End Goal:

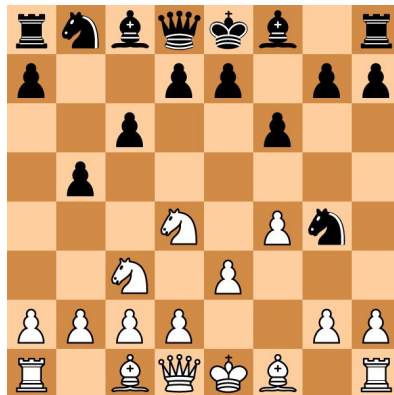
- Integer
- Object
- Solution

Data Structures:

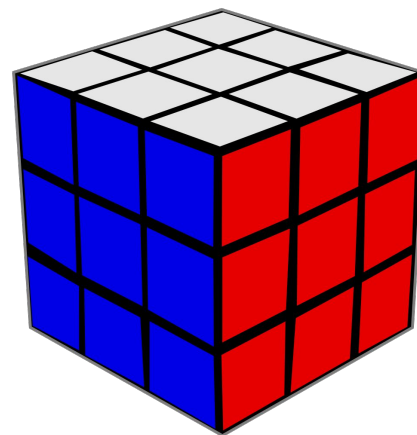
- Lists
- Matrices
- Graphs

# Applications of Searching Algorithms

- Navigation Apps
- Game Playing Agents
  - Go
  - Chess
  - Tic Tac Toe
- Solving Puzzles
  - 2048
  - River Crossing
  - Rubiks Cube
- General Problem Solving



			4
	4	4	8
	4	8	16
4	8	16	32



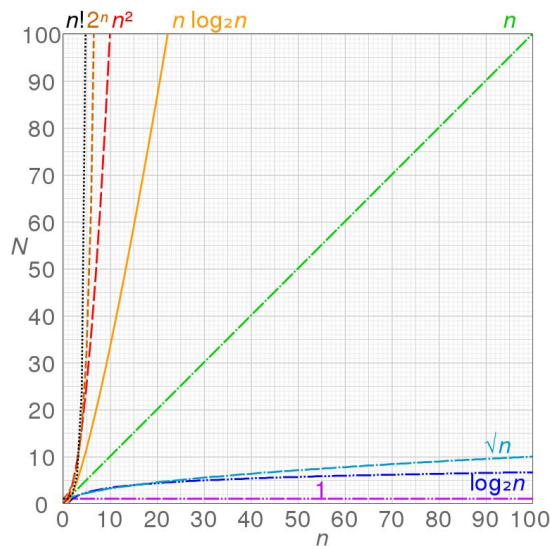
# Time Complexity

**Time Complexity** is an analysis of a computing problem in which we define the time as a function of the problem size and try to estimate the growth of the execution time with respect to the dynamic problem size


## Big O Notation

1. Efficiency
2. Time Factor
3. Space Complexity


Always refers to worst case scenario




# Big O Notation : $O(n)$

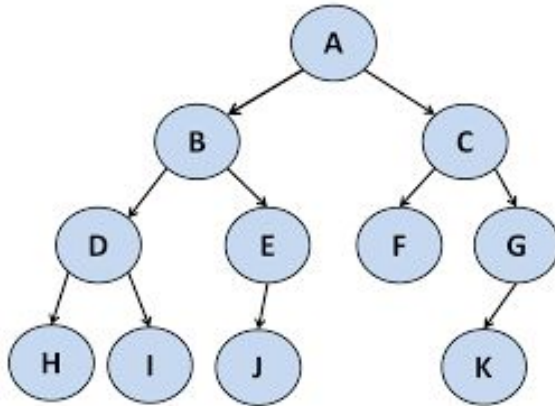
0  N

12	9	3	15	21	43	25	1
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0  N

 N

1	2	3	4
5	6	7	8
9	10	11	12
13	14	15	16



$$\begin{array}{r} 652 \\ +471 \\ \hline 3 \end{array}$$

# Linear / Sequential Search

A list search method in which every value is checked to see if it is the goal you are searching for

Goal : 17

Current: 6



List	6	15	5	3	9	3
Indices	0	1	2	3	4	5



# Linear / Sequential Search

Goal : 17

Current: 15



List	6	15	5	3	9	3
Indices	0	1	2	3	4	5

# Linear / Sequential Search

Goal : 17

Current: 5




List	6	15	5	3	9	3
Indices	0	1	2	3	4	5

# Linear / Sequential Search

Goal : 17

Current: 17



List	6	15	5	17	9	3
Indices	0	1	2	3	4	5

Returns the index at which Goal = Current : 3

# Binary Search

A list search method in which the sorted list to be searched is halved at each iteration in order to find the goal

	Low			Mid			Hi
	↓			↓			↓
List	2	5	8	12	40	67	73
Ind	0	1	2	3	4	5	6

Goal: 40

Current: 12

# Binary Search

A list search method in which the sorted list to be searched is halved at each iteration in order to find the goal

					Low ↓	Mid ↓	Hi ↓
List	2	5	8	12	40	67	73
Ind	0	1	2	3	4	5	6

Goal: 40

Current: 67

# Binary Search

A list search method in which the sorted list to be searched is halved at each iteration in order to find the goal

	Low Mid					Hi	
	↓ ↓					↓	
List	2	5	8	12	40	67	73
Ind	0	1	2	3	4	5	6

Goal: 40

Current: 40

Because Goal = Current, returns the index of Current: 4

# Breadth First Search

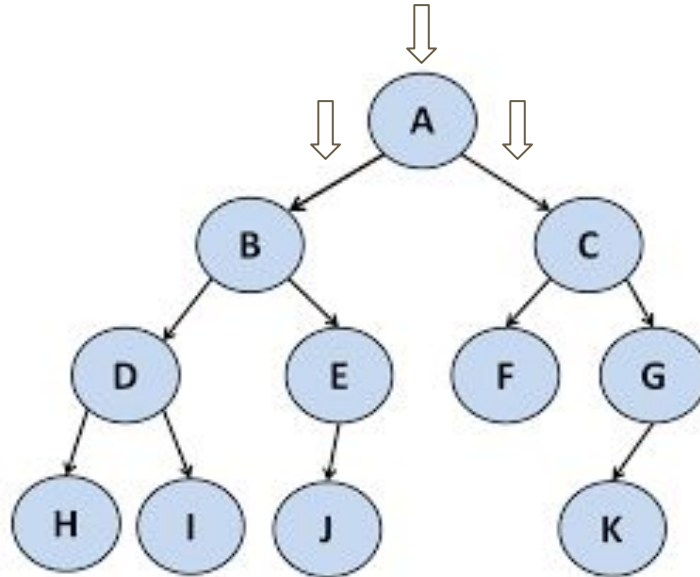
A tree/graph search algorithm that starts at an arbitrary point in the graph and explores all of the neighbor nodes

Goal: I

Current: A

Frontier: [B, C]

Visited: [A, B, C]



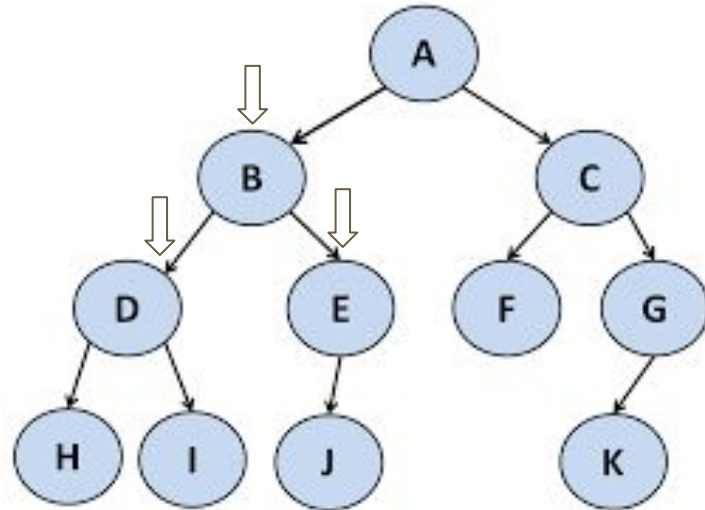
# Breadth First Search

Goal: I

Current: C

Frontier: [C, D, E]

Visited: [A, B, C, D, E]





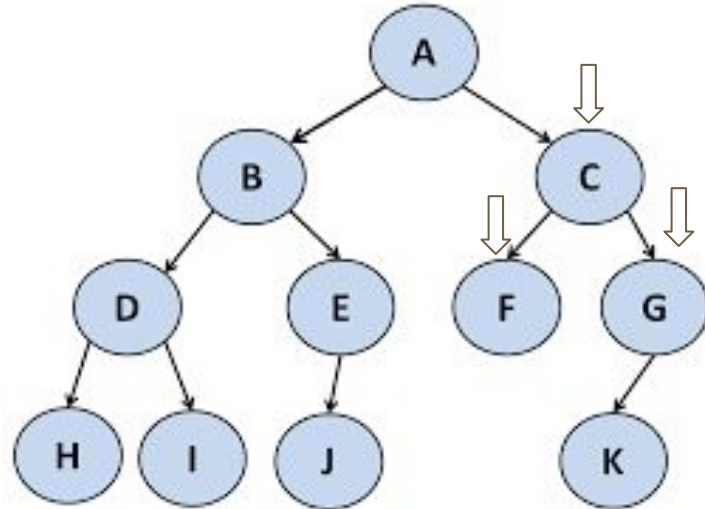
# Breadth First Search

Goal: I

Current: C

Frontier: [D, E, F, G]

Visited: [A, B, C, D, E, F, G]



# Breadth First Search

Goal: I

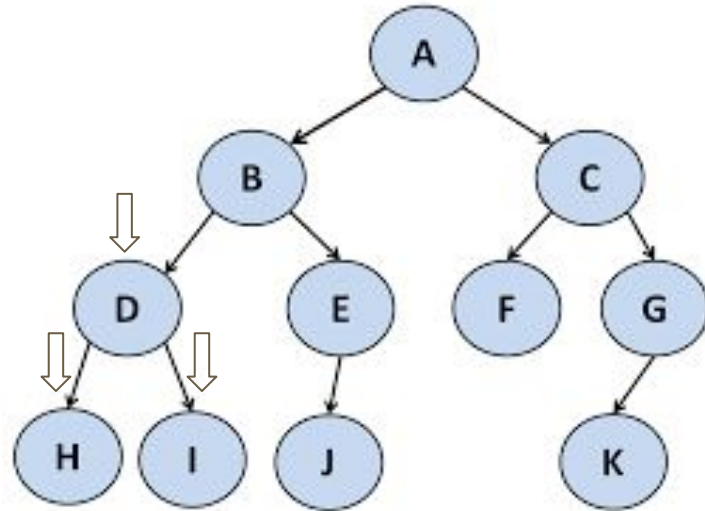
Current: D

Frontier: [E, F, G, H, I]

Visited: [A, B, C, D, E, F, G, H, I]

One of current's children is the Goal State. Follow back up the tree and return the path to I

[A, B, D, I]



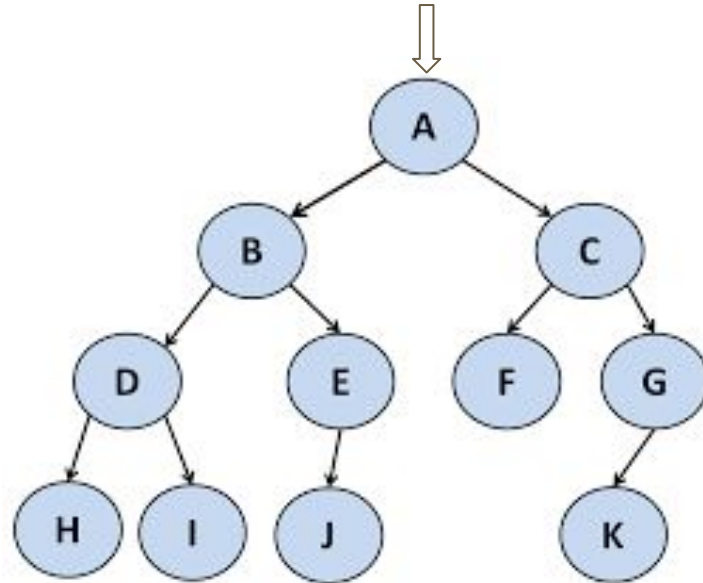
# Depth First Search

A tree/graph search algorithm that starts at an arbitrary point in the graph and explores all the way down one branch until the program hits an edge

Goal: J

Current: A

Visited: [A]

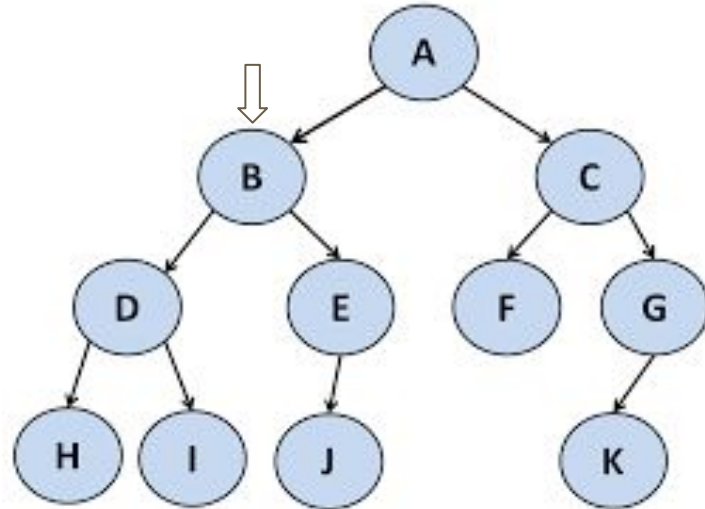


# Depth First Search

Goal: J

Current: B

Visited: [A, B]

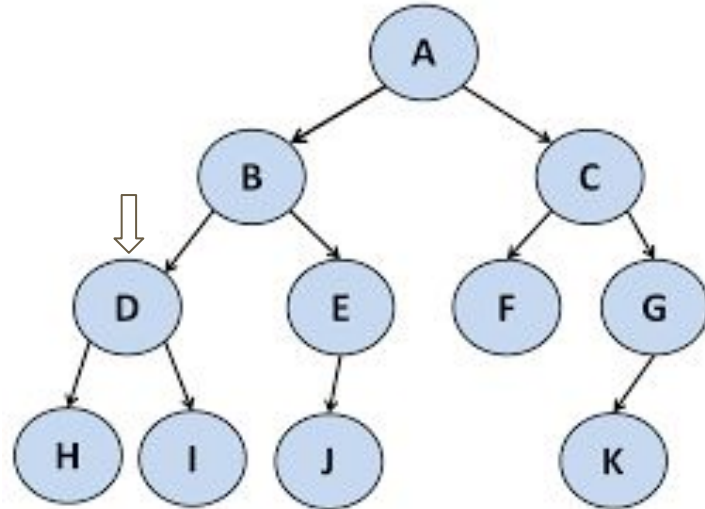


# Depth First Search

Goal: J

Current: D

Visited: [A, B, D]

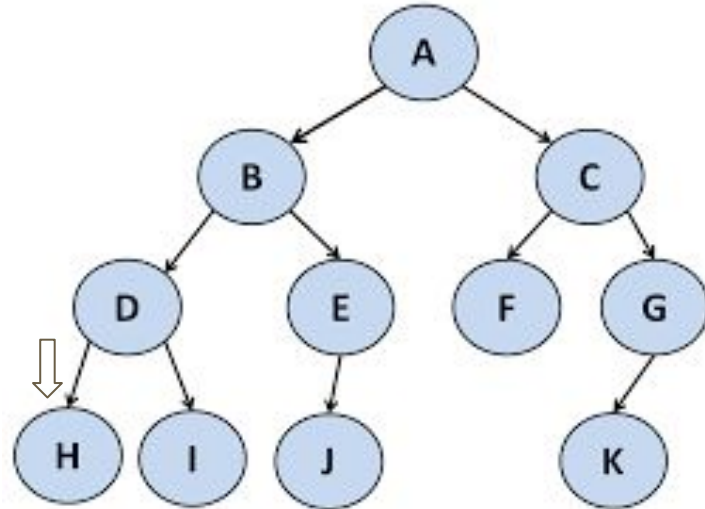


# Depth First Search

Goal: J

Current: H

Visited: [A, B, D, H]

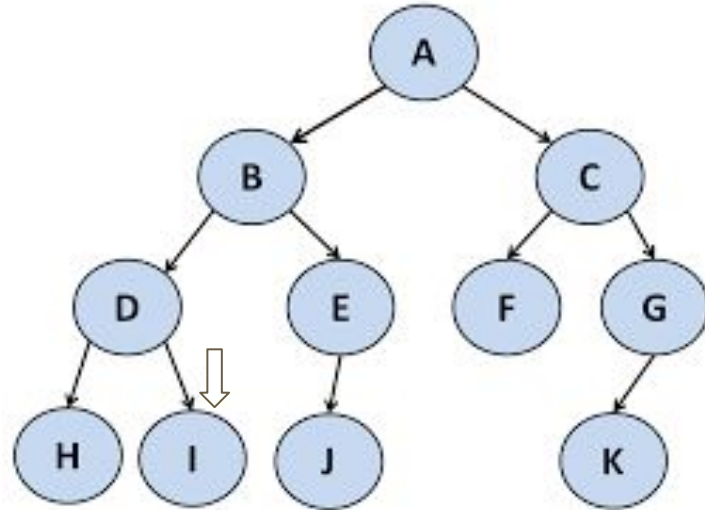


# Depth First Search

Goal: J

Current: I

Visited: [A, B, D, H, I]

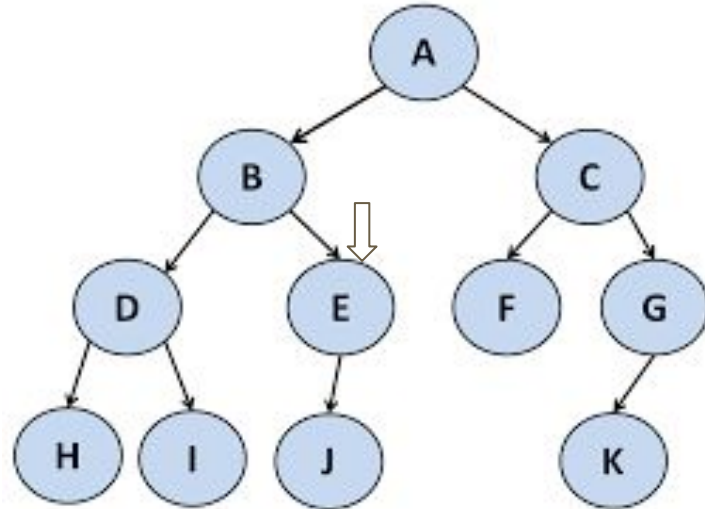


# Depth First Search

Goal: J

Current: E

Visited: [A, B, D, H, I, E]





# Depth First Search

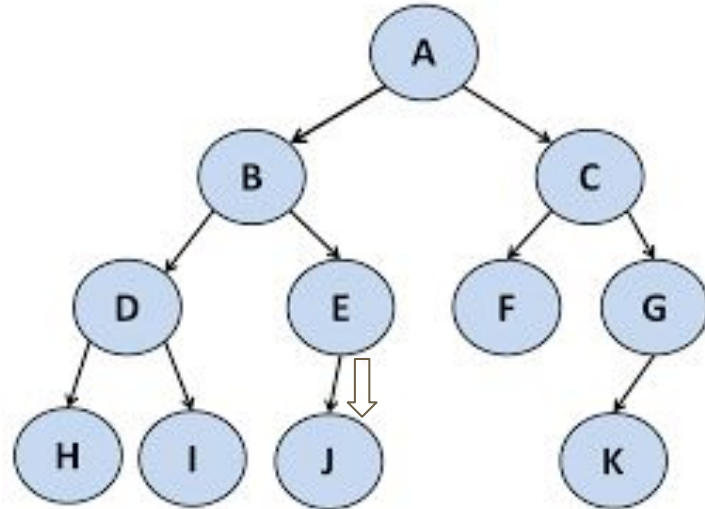
Goal: J

Current: J

Visited: [A, B, D, H, I, E, J]

As Current = Goal, the program should return the path to the goal:

[A, B, E, J]



# Breadth First Search vs. Depth First Search

## BFS

- requires more memory
- Returns the shortest path to the goal

## DFS

- performs quicker
- DFS is not guaranteed to find/return an answer

# Conclusion

- Time Complexity -  $O(n)$
- List Search
  - Linear/Sequential Search
  - Binary Search
- Graph Search
  - Breadth First Search
  - Depth First Search
- Exercises
- Code Review

# AAR / Questions