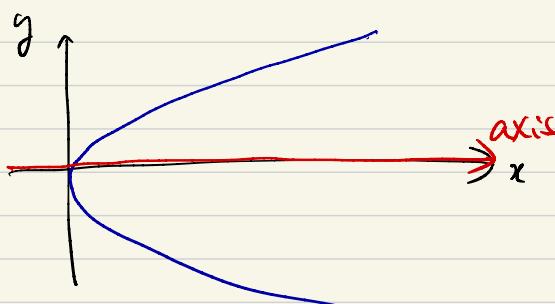


Lecture 1. Conics, invariants, center

1. Standard Conics

(1) Parabola $y^2 = 4ax$

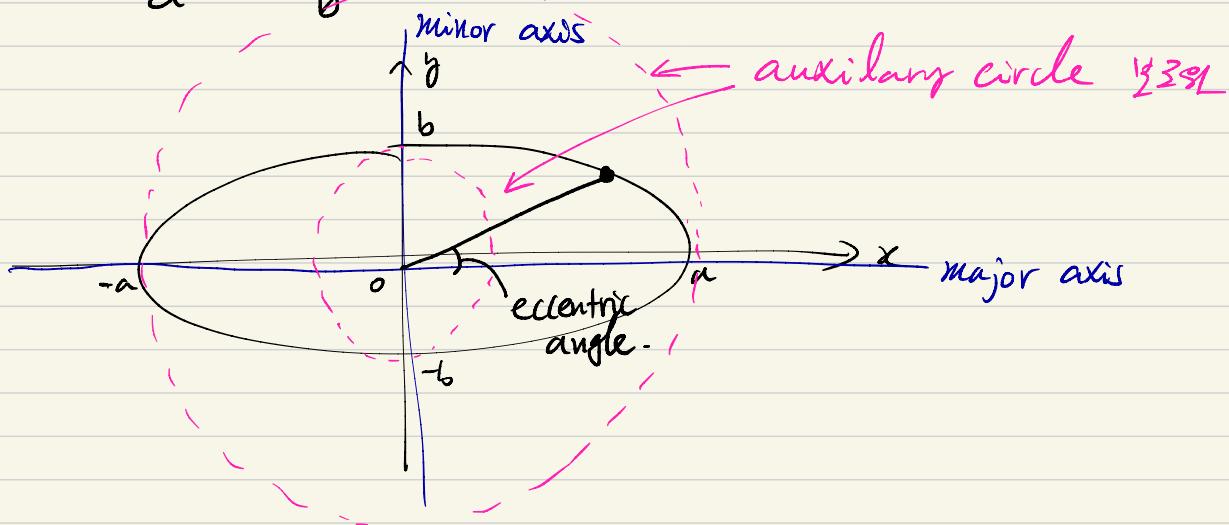
Def: Let $a > 0$. The Standard parabola with modulus a is

$$y^2 = 4ax.$$


(2) Ellipse $\frac{x^2}{a^2} + \frac{y^2}{b^2} = 1$

Def: Let $a > b > 0$. The Standard real ellipse with moduli a, b is

$$\frac{x^2}{a^2} + \frac{y^2}{b^2} = 1.$$

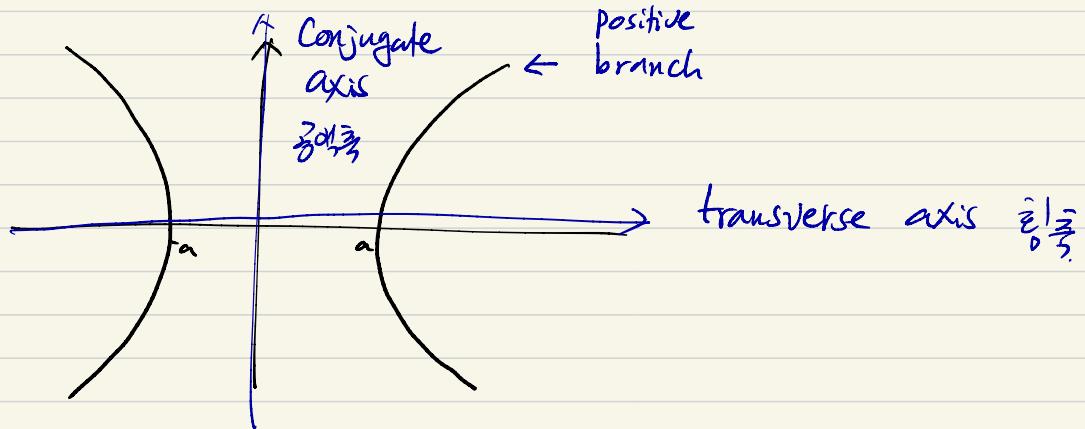


Note In our definition, circles are not ellipses, but circles are obtained by taking limits $b \rightarrow a$

(3) Hyperbola 双曲线

Def: Let $a, b > 0$. The standard hyperbola with moduli a, b is the conic

$$\frac{x^2}{a^2} - \frac{y^2}{b^2} = 1$$



2. Matrices and invariants

Def: A quadratic function $Q: \mathbb{R} \times \mathbb{R} \rightarrow \mathbb{R}$
 $(x, y) \mapsto Q(x, y)$

such that

$$Q(x, y) = ax^2 + 2hxy + by^2 + 2gx + 2fy + c.$$

E.g. The unit circle $x^2 + y^2 = 1$ can be viewed as the set

$$\mathcal{Z}(Q) = \left\{ (x, y) \in \mathbb{R} \times \mathbb{R} : Q(x, y) = x^2 + y^2 - 1 = 0 \right\}$$

Two quadratic functions Q_1, Q_2 are scalar multiples of each other ^{A.7.4.1} if $Q_1 = \lambda Q_2$ for some $\lambda \in \mathbb{R} \setminus \{0\}$

Def: A conic is a set of quadratic functions each of which is a scalar multiple of the other.

$$Q_1 = x^2 + y^2 - 1$$

$$Q_{2000} = 2000x^2 + 2000y^2 - 2000$$

$$Q_{2025} = 2025x^2 + 2025y^2 - 2025$$

$$Q_{-3} = -3x^2 - 3y^2 - 3$$

Conic

Def Let $Q(x, y) = ax^2 + 2hxy + by^2 + 2gx + 2fy + c$ be a conic.

The trace invariant T is $a + b$

The delta invariant δ is $ab - h^2$

The discriminant Δ is $a(bc - f^2) + h(fg - hc) + g(hf - gb)$

Note Matrix interpretation.

Need to know what determinants are.

행렬식

What is Matrix? A rectangular arrangement of numbers

$$\begin{pmatrix} 2 & 3 & 7 \\ 1 & 5 & 0 \end{pmatrix} \rightarrow 1\text{행} \quad \begin{pmatrix} i & 0 & 0 \\ 0 & i & 0 \\ 0 & 0 & i \end{pmatrix}$$

10_{2x3} 20_{2x3} 30_{3x1}

2개행 \times 3개열

2 \times 3 행렬

3 \times 3 행렬

$$\begin{pmatrix} 1 \\ 2 \\ 3 \\ 4 \\ 5 \end{pmatrix}$$

행렬의 연산

$$\lambda \cdot \begin{pmatrix} a & b \\ c & d \end{pmatrix} = \begin{pmatrix} \lambda a & \lambda b \\ \lambda c & \lambda d \end{pmatrix}$$

$$\begin{pmatrix} a & b \\ c & d \end{pmatrix} + \begin{pmatrix} x & y \\ z & w \end{pmatrix}$$

$$\begin{pmatrix} 5 \\ 1 \end{pmatrix} \times \begin{pmatrix} 1 \end{pmatrix} \text{ 행렬}$$

$$= \begin{pmatrix} a+z & b+y \\ c+w & d+w \end{pmatrix}$$

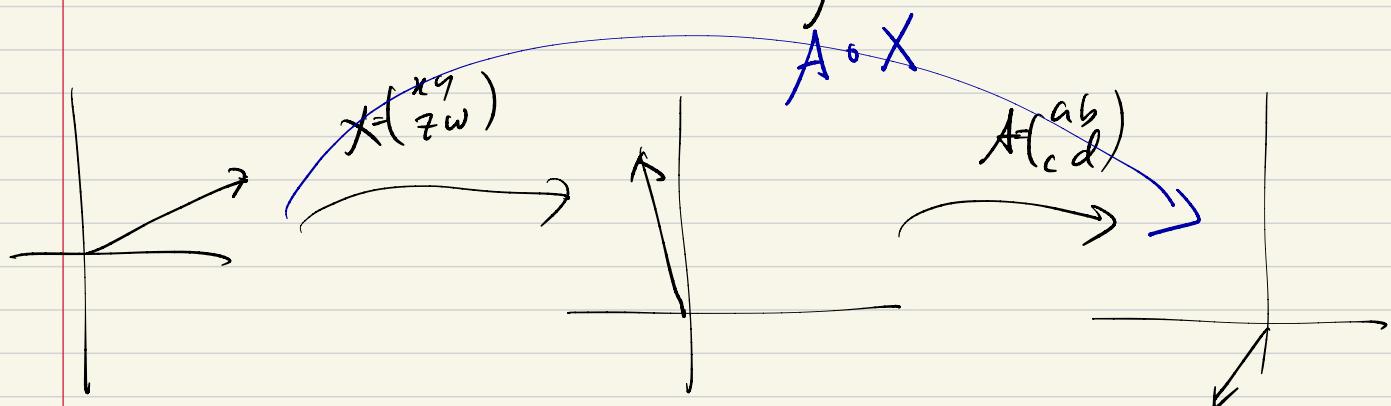
정의의 2

$$\begin{pmatrix} a & b \\ c & d \end{pmatrix} \begin{pmatrix} z \\ w \end{pmatrix} = \begin{pmatrix} az & bw \\ cz & dw \end{pmatrix}$$

Useless!

!!

$$\begin{pmatrix} az + bz & az + bw \\ cz + dz & cz + dw \end{pmatrix}$$



Homework: Convince Yourself: Matrix addition is commutative
and associative.

정답은 같다.

정답은 같다.

Also, Matrix multiplication is associative. However,
matrix multiplication is not commutative. Find an example.

Matrix inverse? For example in \mathbb{R} , knowing $x \div y$
means knowing y satisfying $x \cdot y = 1$

Let A be an $n \times n$ matrix its inverse A^{-1} is a matrix satisfying

$$A A^{-1} = I_n = \begin{pmatrix} 1 & & & \\ & 1 & & \\ & & \ddots & \\ & & & 1 \end{pmatrix}$$

identity matrix

Exercise Find $\begin{pmatrix} x & y \\ z & w \end{pmatrix}$ such that $\begin{pmatrix} a & b \\ c & d \end{pmatrix} \begin{pmatrix} x & y \\ z & w \end{pmatrix} = \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}$

Answer $\begin{pmatrix} x & y \\ z & w \end{pmatrix} = \frac{1}{ad - bc} \begin{pmatrix} d & -b \\ -c & a \end{pmatrix}$

Def If $A = \begin{pmatrix} a & b \\ c & d \end{pmatrix}$, $|A| = ad - bc$
or $\det(A)$

$$A = \begin{pmatrix} a_{11} & a_{12} & a_{13} \\ a_{21} & a_{22} & a_{23} \\ a_{31} & a_{32} & a_{33} \end{pmatrix}$$

$$|A| = +a_{11}(a_{22}a_{33} - a_{23}a_{32})$$

$$-a_{12}(a_{21}a_{33} - a_{23}a_{31})$$

$$+a_{13}(a_{21}a_{32} - a_{22}a_{31})$$

$$\begin{pmatrix} + & - & + \\ - & + & - \\ + & - & + \end{pmatrix}$$

$n \times n$ 행렬

2×2 행렬의 모든 원소 $\propto n!$

Matrix interpretation of invariants.

Let $Q(x, y) = ax^2 + 2hxy + by^2 + 2gx + 2fy + e$

Associated matrix

$$A = \begin{pmatrix} a & h & g \\ h & b & f \\ g & f & c \end{pmatrix}$$

: Symmetric matrix.

$$z = (x \ y \ 1)$$

$$Q(x,y) \stackrel{\text{You check!}}{=} \begin{pmatrix} x & y & 1 \end{pmatrix} \begin{pmatrix} a & h & g \\ h & b & f \\ g & f & c \end{pmatrix} \begin{pmatrix} x \\ y \\ 1 \end{pmatrix}$$

$1 \times \Delta$

$\Delta \times \delta$

$\delta \times \Delta$

Let's look at

$$\begin{pmatrix} a & h & g \\ h & b & f \\ g & f & c \end{pmatrix}$$

Aside: $A = (a_{ij})$
 $i, j \leq n$
 $a_{11} + a_{22} + a_{33} + a_{44} + \dots + a_{nn}$
 $=: \text{trace}(A)$

$$\tau \quad \text{trace} \left(\begin{matrix} a & h \\ h & b \end{matrix} \right)$$

$$\delta \quad \det \left(\begin{matrix} a & h \\ h & b \end{matrix} \right)$$

$$\Delta \quad \det A$$

Note: The invariants τ, δ, Δ are not invariant under scalar multiplication. However, the following important equalities and inequalities remain invariant:

$$\begin{array}{lll} \tau = 0 & \delta = 0 & \Delta \neq 0 \\ \tau \neq 0 & \delta > 0 & \Delta = 0 \\ & \delta < 0 & \end{array}$$

$$\begin{aligned} Q &\sim \lambda Q \\ (\because \tau &\sim \lambda \tau) \\ \delta &\sim \lambda^2 \delta \\ \Delta &\sim \lambda^3 \Delta \end{aligned}$$

Examples (1) $Q(x, y) = x^2 + y^2 - 1$

Associated matrix

$$\begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & -1 \end{pmatrix}$$

$\tau = 2 \quad \tau = 2$
 $\delta = 1 \quad \delta = 1$
 $\Delta = -1 \quad \Delta = 0$
 $\zeta = 2$
 $\varsigma = 1$
 $\Delta = 1$

$$(2) Q(x,y) = y^2 - 4ax \quad a > 0$$

Associated matrix

$$\begin{pmatrix} 0 & 0 & -2a \\ 0 & 1 & 0 \\ -2a & 0 & 0 \end{pmatrix} \quad t = 1$$

$$f = 0$$

$$\Delta = -4a^2 \neq 0$$

$$(3) Q(x,y) = \frac{x^2}{a^2} + \frac{y^2}{b^2} - 1 \quad \begin{array}{l} \text{ellipse } \delta > 0 \\ \text{hyperbola } \delta < 0 \end{array}$$

Associated matrix

$$\begin{pmatrix} \frac{1}{a^2} & 0 & 0 \\ 0 & \frac{1}{b^2} & 0 \\ 0 & 0 & -1 \end{pmatrix}$$

$$C = \frac{1}{a^2} + \frac{1}{b^2}$$

$$\Delta = \frac{-1}{a^2 b^2} > 0$$

$$\Delta \neq 0$$

$\Delta \neq 0$	$\left\{ \begin{array}{l} \delta > 0 \\ \delta = 0 \\ \delta < 0 \end{array} \right.$	<u>Standard</u>	<u>General</u>
	$\delta > 0$	ellipse	ellipse
	$\delta = 0$	parabola	parabola
	$\delta < 0$	hyperbola	hyperbola

Def: A comic Q is said to be degenerate if $\Delta = 0$

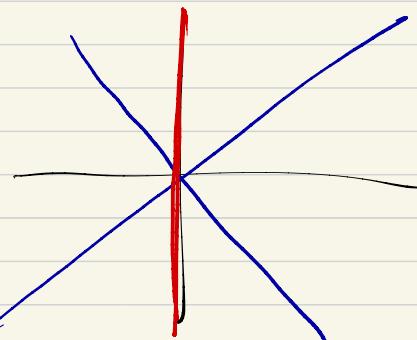
Examples (of degenerate Conics)

$$Q(x,y) = \bigcirc$$

$$Q(x,y) = x^2 - y^2$$

$$Q(x,y) = x^2$$

$$Q(x,y) = x^2 + y^2 : \text{irreducible.}$$



3. Reducible Conics

A line L: $ax+by+c=0$

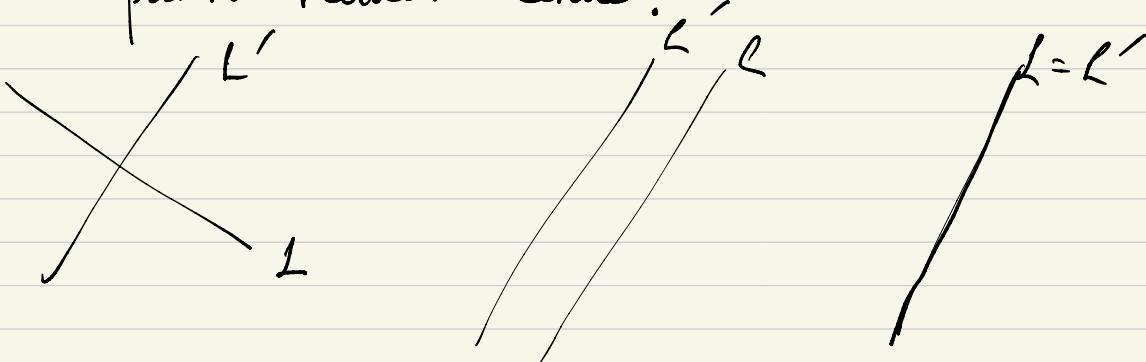
Def: A conic Q is reducible if there exists L, L' : lines such that $Q = LL' (= (ax+by+c)(a'x+b'y+c'))$.

Here L, L' are called components of Q and

$Q = \bigcirc$ is the Joint Equation of L, L' .

Otherwise, Q is irreducible.

What are possible reducible conics?



Exercise IS $Q(x,y) = x^2 - xy - 2y^2 + 2x + 5y - 3$ a reducible conic?

$$Q(x,y) = (x-y+\alpha)(x-2y+\beta) + 3$$

부조정리

Bto

Lemma: Let Q be a conic and L a line not parallel to the y -axis. Then there is a unique line L' and a unique quadratic function $J(x)$ s.t.

$$Q(x, y) = L(x, y) L'(x, y) + J(x)$$

증명

Theorem (Component lemma) Suppose every point on the line L lies on Q : a conic. Then Q must be a reducible conic. i.e. there exists L' a line such that

$$Q = L L'$$

Proof: Assume L : not parallel to y -axis.

$$Q = L L' + J(x) \quad \text{for some } L', J(x)$$

In the assumption, s.t. $L(x, y) = 0 \Rightarrow Q(x, y) = 0$

Therefore $J(x) \equiv 0$ for every $x \in \mathbb{R}$

$$Q = L L' \quad \square$$

Sketch of proof of Lemma : $L = \alpha x + \beta y + r$ LL' 증거

$$L' = \alpha' x + \beta' y + r'$$

$$\begin{aligned} & y^2, xy, y \text{의 계수} \\ & \alpha \beta' \leftarrow \begin{array}{l} \downarrow \\ \alpha \beta' + \alpha' \beta \end{array} \quad \begin{array}{l} \downarrow \\ \beta \alpha' + \beta' \alpha \end{array} \end{aligned}$$

$Q(x,y)$ 의 2차 미분 V.I.2

$$\left\{ \begin{array}{l} \beta' = b \\ \beta' + \alpha \beta' = 2h \\ r \beta' + s \gamma' = 2f. \end{array} \right.$$

$$-\beta^3 = \det \begin{pmatrix} 0 & \beta & 0 \\ \beta & \alpha & 0 \\ 0 & r & \beta \end{pmatrix} \neq 0$$

$$A = \begin{pmatrix} a_{11} & a_{12} & a_{13} \\ a_{21} & a_{22} & a_{23} \\ a_{31} & a_{32} & a_{33} \end{pmatrix} \begin{pmatrix} x \\ y \\ z \end{pmatrix} = \begin{pmatrix} 1 \\ 2 \\ 3 \end{pmatrix}$$

has a unique sol

$$\therefore J(x) := Q(x,0) - L(x,0)L'(x,0).$$

$$\Leftrightarrow \det(A) \neq 0$$