

Using Vulkan with Rust via Ash: A Samples Tutorial

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0.1

1 Setup

Make sure:

1. you have the rust compiler installed: <https://www.rust-lang.org> (I am going to assume you've gone through the basics of Rust)
2. you have the Vulkan SDK installed: <https://www.lunarg.com/vulkan-sdk/>

2 A note about C-ish for those unfamiliar with it

C-ish my catchall term for C/C++. For some parts of this guide, I am going to assume you know the following (and I think you would not need more than an hour to figure these things out):

- how `structs` and `enums` defined in C-ish, and what `typedef` does
- what a `pointer` is, and how it is related to C-ish `arrays`
- the syntax of a C-ish `functions`
- what a `bit mask` is, and how it's `used in C-ish`

If you can answer all these questions, you're good to go:

- what is `void`?
- why is a C-ish pointer evil compared to a Rust reference?
- what is `NULL`?
- why will you sometimes see `int*` written as the type for an array of `ints`?
- what is a function prototype?
- where is a function's return type and the type of its arguments, indicated in its prototype?

- do you know what a bit mask is in a broad sense (no need for details)?

I think these are good things to know, since you’re dealing with a Rust crate that is a wrapper around a C-ish interface. A lot of the documentation on Vulkan is in C-ish, and this documentation is good to read because:

- it tells you what C-ish analogues you need to look for in the Ash source code/documentation, when exploring Ash
- lets you read the basics of Vulkan tutorials that operate in C-ish, in case you need to read about some stuff outside the scope of this tutorial

3 Introduction

Vulkan provides an interface between your application and a Vulkan-compatible physical device installed in your system, which the application wants to use for highly-parallel computation typical of graphics tasks, but also useful elsewhere. Vulkan can interface with many different types of physical devices:

- the CPU of your system
- [a software abstraction running on top of the CPU](#)
- special purpose hardware for highly-parallel computing, e.g. a GPU;
- many CPUs configured to share data with each other
- et cetera

Note that each one of these physical devices also have some associated memory, where instructions, input data, and output data may be stored. Vulkan allows your application to interface with many varieties of physical devices, regardless of the details of each physical device’s configuration, as long as the physical device provides a Vulkan-compatible “driver”, which would be a piece of software that provides a Vulkan interface to the underlying hardware. Thus, as an application programmer, you only need to worry about interfacing your application with Vulkan, while the drivers handle interfacing Vulkan with the hardware.

Note that the driver doesn’t do anything beyond helping Vulkan pass instructions to the hardware, so verifying whether the instructions you send make sense, or whether the resulting data from a computation is not garbage, is your task. However, during development of your application, you can specify additional software *layers* between your application’s “loader” (i.e. its Vulkan communication object) and the physical device’s driver, which can help to debug and verify the correctness of the instructions you are passing through the loader. You can choose to turn on and off these loaders as you wish.

Let’s now take a closer look at the loader, which is more specifically called an “instance”. When you first create the instance, it searches your system for physical devices with Vulkan-compatible drivers, and enumerates these for you, so that you can choose which physical device(s) you would like to work with. Once you have chosen specific physical devices,

you can describe more specifically which features of each physical device you would like to use (e.g. 64-bit floats, or 32-bit floats?). Each physical device can then be abstracted into “logical devices”, which is a software represent subsets of a physical device’s resources. For example, let us say your application needs to do some graphics calculations, and some simulation related calculations: so to organize your physical device(s)’ computing resources, you could set one logical device to deal with the graphics, and the other logical device could be set to deal with calculations. Thus, specification of logical devices is an abstraction that helps you organize computing resources. Each logical device allows you to create “queues”, which are selected from “queue families”. Queues organize the communication of data from your application (e.g. computation instructions, or some data to be manipulated) to the physical device’s driver, and they also organize communication of data from your physical device to your application (e.g. results of computations, or status of the physical device’s computing efforts). Queue families represent specialization of queues: queues to handle data (memory) transfers, queues to handle instruction transfer, etc. Note that sometimes, only certain queue families may be available on certain physical devices (and their availability may indicate what role the physical device is specialized for), but common physical devices tend to support all commonly used queue families. Finally, we may also take advantage of functionality provided by Vulkan “extensions”, which are API extensions that provide common functionality for some often-occurring Vulkan use-cases (e.g. graphics display).

We are interested in using Rust to write our application, but the Vulkan API is written in C, so we use [Ash](#), which is a lightweight (thus unsafe) Rust wrapper around Vulkan. This document will teach you how to use Vulkan through Ash, by helping you build a series of small programs (“samples”) which iterate upon each other towards a final product (displaying a cube).

4 An Overview of Vulkan’s Abstraction System over Physical Devices: Instances, Logical Devices and Queues

A Vulkan *instance* is a software object (with C-ish type `VkInstance`) which your application uses to interact with Vulkan-compatible physical devices which are represented as members of the instance. Commands from your application are passed through a Vulkan instance into a *queue* (each associated with a logical device abstracting a subset of the physical device’s resources) which pipes to and from the physical device.

Note that since an instance is a software abstraction, if necessary, one could have several instances interacting with one physical device, if it provides value to how your application abstracts your physical devices. For now though, we’ll focus on using one instance.

5 `init-instance.rs`

If we were using C-ish, an instance is created by calling the function `vkCreateInstance`, which has the prototype:

```
VkResult vkCreateInstance(  
    const VkInstanceCreateInfo* pCreateInfo,
```

```

const VkAllocationCallbacks*      pAllocator,
VkInstance*                       pInstance);

```

Let's take this apart:

- return type `vkResult`: a C-ish `enum`, which contains a bunch of constants indicating the result of different Vulkan commands: in this case, success (i.e. successful creation of an instance), or some sort of a failure;
- argument `pCreateInfo`: a pointer to a `VkInstanceCreateInfo` struct;
- argument `pAllocator`: a pointer to a `VkAllocationCallbacks` struct whose members contain various functions you might have written to help the physical device organize its memory usage—we will tend to go simple, and not provide anything, in which case the physical device will use its default memory management routines;
- argument `pInstance` an “opaque pointer” to an instance (an opaque pointer is a C-ish concept which provides a pointer to a data structure, but the pointer cannot be used to query details of the data structure, nor can it be de-referenced)

Let's now have a closer look at `VkInstanceCreateInfo` struct definition, which has some members typical to many other Vulkan “info struct”s:

```

typedef struct VkInstanceCreateInfo {
    VkStructureType      sType;
    const void*          pNext;
    VkInstanceCreateFlags flags;
    const VkApplicationInfo* pApplicationInfo;
    uint32_t             enabledLayerCount;
    const char* const*   ppEnabledLayerNames;
    uint32_t             enabledExtensionCount;
    const char* const*   ppEnabledExtensionNames;
} VkInstanceCreateInfo;

```

A brief description of the members:

- `sType`: indicates the type of the info struct, in this case `VK_STRUCTURE_TYPE_INSTANCE_CREATE` this is useful because in C, you might sometimes get a typeless (`void*`) pointer to a particular struct, and to determine what kind of struct it is, you could query the `sType` field
- `pNext`: another typical info struct member, usually set to `NULL`, and can be used to pass additional structs (whose type will be defined by the `sType` field), sometimes needed by API extensions
- `flags`: currently no flags defined, set to 0
- `pApplicationInfo`: pointer to a `VkApplicationInfo` struct which we will study next

- `ppEnabledLayerNames`: in this tutorial, we will not be using layers, so we can set this to `NULL`
- `enabledLayerCount`: length of the `ppEnabledLayerNames` list, should be zero if `ppEnabledLayerNames` is `NULL`
- `ppEnabledExtensionNames`: at this point in the tutorial, we are not using extensions, so we'll be setting this to `NULL`
- `enabledExtensionCount`: length of the `ppEnabledExtensionNames` list

The `vkInstanceCreateInfo` struct contains a `VkApplicationInfo` struct which has the following definition:

```
typedef struct VkApplicationInfo {
    VkStructureType    sType;
    const void*        pNext;
    const char*         pApplicationName;
    uint32_t            applicationVersion;
    const char*         pEngineName;
    uint32_t            engineVersion;
    uint32_t            apiVersion;
} VkApplicationInfo;
```

This struct is meant to provide some information regarding your application; a brief overview of its members:

- `sType`, `pNext`: common features of many Vulkan info structs, see the `vkInstanceCreateInfo` struct's member overview, as these are the same;
- `pApplicationName`, `applicationVersion`, `pEngineName`, `engineVersion`: fields that you may fill out if you desire to annotate general report/debugging data, or if you want a tip a driver with specific behaviour for your application implemented;
- `apiVersion`: this field communicates the major, minor, and patch levels of the Vulkan API used by the application; we'll be using `VK_API_VERSION_1_0` (major is 1, minor is 0).

With these prototypes in mind, let's see how we can use Vulkan through Ash. Open up `/init-instance/src/main.rs`, and:

- note comments explaining what `use` statements, if you need some clarification
- note the `unsafe` block
- note how for fields like `pApplicationName` we create a `std::ffi::CString` and then pass it "raw" (i.e. as a pointer) by calling `as_ptr`
- note how `vk::StructureType` is used to fill out `s_type` fields

- can you explain how the `flags` field is filled out? (hint: look up the definition of the `vk::InstanceCreateInfo` struct in [Ash's documentation](#) and then answer: what type is `flags`? How is the `std::Default` trait implemented for it?)
- to actually use Vulkan, we first initialize an `ash::Entry` struct which contains the supporting infrastructure to allow Rust to interface with Vulkan's C implementation
- the `ash::Entry` struct also has some `impls` which put syntactic sugar around calling functions like `vkCreateInstance`, in particular the function `create_instance`—can you find where that function is implemented? (hint: open up [Ash's documentation](#), and 1) figure out where the `EntryV1_0` trait is defined, 2) figure out where `Entry<V>` is defined, and 3) how is the `EntryV1_0` implemented for `Entry<V1_0>`?)
- note how we have to manually destroy the instance once we're done

To see everything in action:

```
cargo run --bin init-instance
```

6 enumerate-devices.rs

Now that we know how to initialize an instance, let us learn how to use it to enumerate the physical devices on our system. In general, obtaining a list of stuff is a fairly common operation in Vulkan, so there's a generalized pattern behind what we want to do on the C side of things. Say you have a function `getListData` to get a list of some stuff from some instance of a struct `aStruct`:

- `getListData` will have prototype:

```
vkResult get_list_data(
    vkSomeStruct      aStruct,
    uint32_t*         pCount,
    vkStuff*          pStuff,
);
```

- get a pointer to some memory set aside for an unsigned 32 bit integer, and call it `pCount`
- call `getListData(aStruct, pCount, NULL)`—the `NULL` pointer for `pStuff` indicates that we don't yet know how many things will be in the list, so we want that information to be put in the memory pointed to by `pCount`, and if the `vkResult` we get back after the call indicates success, `pCount` will point to an integer representing the number of `vkStuff` we need to set aside memory for
- set aside appropriate memory for the list of `vkStuff` (now that we know the count), and get a pointer to that list called `pStuff`

- call `getListData(aStruct, pCount, pStuff)`—this time, because `pStuff` is not `NULL`, and the `getListData` will fill out the list pointed to by `pStuff`, instead of writing information about the count

Thus, based on this model, the function prototype for `vkEnumeratePhysicalDevices` should look familiar:

```
VkResult vkEnumeratePhysicalDevices(
    VkInstance          instance,
    uint32_t*           pPhysicalDeviceCount,
    VkPhysicalDevice*   pPhysicalDevices);
```

Assume we have a `VkInstance` called `instance` at hand and a pointer to memory where we can store an unsigned integer `pPhysicalDeviceCount`. Then, we would:

1. call `vkEnumeratePhysicalDevices(instance, pPhysicalDeviceCount, NULL)`—if `VkResult` indicates success, then `pPhysicalDeviceCount` now points to an integer denoting the number of physical devices available
2. allocate enough memory for a list of `VkPhysicalDevices` containing `*pPhysicalDeviceCount` items (in C-ish the list would be of type `VkPhysicalDevice*`), and call it `pPhysicalDevices` (the preceding `p` indicates “pointer” in C-ish naming conventions)
3. call `vkEnumeratePhysicalDevices(instance, pPhysicalDeviceCount, pPhysicalDevices)`—if `VkResult` indicates success, then our list `pPhysicalDevices` should be properly filled out with the `VkPhysicalDevices`.

How would we do this in Rust? The `ash::Instance` struct has an `impl` function `ash::Instance::enumerate_physical_devices`, which calls `vkEnumeratePhysicalDevices` for us and returns a vector of `vk::PhysicalDevices`. Have a look at how it works: [gist link for annotated enumerate_physical_devices](#). To find the source for yourself, go to Ash’s documentation for `ash::Instance`, and click the appropriate `[src]` links. You can see that under the hood, Ash follows exactly the pattern we noted above.

Have a look at `enumerate-devices.rs`, where we query for the list of the physical devices on our system, and print out how many we found. So, to figure out how many physical devices are on your system run `enumerate-devices.rs`:

```
cargo run --bin enumerate-devices
```

7 init-device.rs

7.1 init-device-0.rs

So far, we know how to create an instance, which allows our application to communicate with underlying physical devices that provide a Vulkan-compatible driver. In particular, we know how to use the instance to query if there are any such physical devices.

The rest of this tutorial is assuming you found at least one physical device on your system. If you haven’t found one, do you have Vulkan-compatible drivers installed for your

CPU/GPU, and is your CPU/GPU new enough to support Vulkan functionality? You'll have to do some trouble shooting here.

Assuming that you have found at least one such physical device, we will now learn how to create the logical device abstraction over this physical device. Recall that the logical device allows us to eventually create queues which pass data between your application and the physical device.

For the sake of simplicity, we'll just choose the first (perhaps only) device we've found. Let's ask the physical device what sort of queue families it supports. We do so by calling the C function `vkGetPhysicalDeviceQueueFamilyProperties` which has prototype:

```
void vkGetPhysicalDeviceQueueFamilyProperties(
    VkPhysicalDevice      physicalDevice,
    uint32_t*             pQueueFamilyPropertyCount,
    VkQueueFamilyProperties* pQueueFamilyProperties);
```

Note that this function has the same organization as a function which can either give information about the number of some objects of interest, or provide a list of the same objects of interest. In the last section, we discussed how such a function would be used, and we simply need to repeat that process in order to get a list of `VkQueueFamilyProperties`.

Again, similar to `ash::Instance::enumerate_physical_devices` discussed in the last section, Ash makes our life easy by giving us an `impl` function on `ash::Instance` which does performs the details of getting a list of `vk_sys::QueueFamilyProperties`: `ash::Instance::get_physical_device_queue_families`. If you examine its source (recall how we found the source for `ash::Instance::enumerate_physical_devices`) you'll see the similarities between the functions. Upon a successful call to `get_physical_device_queue_families` we get a `Vec<vk_sys::QueueFamilyProperties>`.

What's inside C-ish `VkQueueFamilyProperties`?

```
typedef struct VkQueueFamilyProperties {
    VkQueueFlags      queueFlags;
    uint32_t          queueCount;
    uint32_t          timestampValidBits;
    VkExtent3D        minImageTransferGranularity;
} VkQueueFamilyProperties;
```

```
typedef enum VkQueueFlagBits {
    VK_QUEUE_GRAPHICS_BIT = 0x00000001,
    VK_QUEUE_COMPUTE_BIT = 0x00000002,
    VK_QUEUE_TRANSFER_BIT = 0x00000004,
    VK_QUEUE_SPARSE_BINDING_BIT = 0x00000008,
} VkQueueFlagBits;
```

We'll only look at some of the members in detail for now:

- `queueCount`: unsigned integer specifying how many queues this device has
- `vkQueueFlags` is a bit mask of one or more `VkQueueFlagBits` specifying the capabilities of the queues in this family (e.g. graphics queues specialize in handling graphics-related

operations, while transfer queues specialize in transferring data between application and device).

The bit mask stuff is also important in Rust-land. Ash has a special type for the bits, `ash::types::QueueFlags`, which allow bitwise operations on them too. So, here's what's going on with the bit mask stuff:

- converting from hexadecimal to binary:

<code>0x1</code>	\rightarrow	<code>000<u>1</u></code>	Graphics
<code>0x2</code>	\rightarrow	<code>00<u>1</u>0</code>	Compute
<code>0x3</code>	\rightarrow	<code>0<u>1</u>00</code>	Transfer
<code>0x4</code>	\rightarrow	<code><u>1</u>000</code>	Sparse

- so if I gave you a flag `0xF`, in binary that is `1111`, and this would mean that that queue family supports Graphics, Compute, Transfer, and Sparse operations
- but if I gave you `0x5`, in binary that is `0101`, this would mean that the queue family only supports Graphics and Transfer operations

To test whether a particular bit is set (i.e. is 1), we can use the `subset impl` for `ash::types::QueueFlags`. See how `get_queue_family_supported_ops` function tests for this in `init-device-0.rs`. Also, note that before the program panics intentionally, care is taken to ensure that any instances we create are destroyed with the help of the `unsafe` function `destroy_instance_and_panic`.

When you run `init-device-0.rs`, you should see a print out of all the queue families supported by the first physical device in the list of physical devices available to you.

7.2 `init-device-1.rs`

In the last section, we described `init-device-0.rs`, which allowed us to print out a list of queue families available for one physical device on our system. In `init-device-1`, we will iterate upon `init-device-0`, and choose a physical device which has a queue family with graphics capability (recall that the ultimate aim of the samples progression is to display a cube, which is undoubtedly a graphics operation).

Once we choose the appropriate physical device, and the appropriate queue family from the device, we will set about creating a *logical device*, which will have a queue from the queue family of interest. Here's a broad outline of the steps we'd follow if we were using the C-ish API:

1. fill out a `VkDeviceQueueCreateInfo` struct based on queue family selected for each queue we want to create (i.e. we would form a list of such structs)
2. fill out a `VkDeviceCreateInfo` struct, which amongst other members, has `pQueueCreateInfos`: a pointer to a list of `VkDeviceQueueCreateInfo` structs (one for each queue we want to create)

3. call `vkCreateDevice`, with the `VkDeviceCreateInfo` struct we filled out as one of the structs, to create a `vkDevice` upon success
4. perform any tasks we need to with the resulting `vkDevice`
5. destroy the device

From now on in this tutorial, whenever you read “device” without qualification, assume it means “logical device”. I will always refer to a physical device as “physical device”.

Let’s have a look at `VkDeviceQueueCreateInfo`:

```
typedef struct VkDeviceQueueCreateInfo {
    VkStructureType      sType;
    const void*          pNext;
    VkDeviceQueueCreateFlags flags;
    uint32_t             queueFamilyIndex;
    uint32_t             queueCount;
    const float*         pQueuePriorities;
} VkDeviceQueueCreateInfo;
```

Relevant members of this struct are:

- `flags`: for future (as in, future versions of Vulkan) use, set to 0 in the present
- `queueFamilyIndex`: the index of the queue’s queue family properties in the list of `vkQueueFamilyProperties` for the physical device we will create a logical device for;
- `queueCount`: the number of queues we’d like to create (shouldn’t be greater than the number of queues supported by the physical device for this queue’s queue family properties!)
- `pQueuePriorities`: a list of `queueCount` normalized floating point values (i.e. floats between 0.0 and 1.0), denoting the relative priority of each queue we’re creating. Higher values indicate a higher priority (0.0 is lowest, 1.0 is highest), and within the physical device, queues with higher priority will have a higher chance of being allotted more processing time than queues with lower priority; more on this later

Let’s have a look at :

```
typedef struct VkDeviceCreateInfo {
    VkStructureType      sType;
    const void*          pNext;
    VkDeviceCreateFlags  flags;
    uint32_t             queueCreateInfoCount;
    const VkDeviceQueueCreateInfo* pQueueCreateInfos;
    uint32_t             enabledLayerCount;
    const char* const*   ppEnabledLayerNames;
    uint32_t             enabledExtensionCount;
    const char* const*   ppEnabledExtensionNames;
    const VkPhysicalDeviceFeatures* pEnabledFeatures;
} VkDeviceCreateInfo;
```