

# Benjamin Reinhardt

Innovation, Intensity, and Tenacity for robotics, augmented reality, and reprogrammable hardware  
<http://benjaminreinhardt.com> | [reinhardt@alumni.caltech.edu](mailto:reinhardt@alumni.caltech.edu) | 513.703.3332

## EDUCATION

### CORNELL UNIVERSITY

PhD Mechanical Engineering,  
 Computer Science Minor  
 Expected May 2015 | Ithaca, NY  
 Focus: Space Robotics  
 NASA Space Technology Research  
 Fellow  
 Lester B. Knight Fellow

### CALTECH

BS Mechanical Engineering and  
 History  
 2010 | Pasadena, CA  
 GPA 3.7

## LINKS

Github:// [bzreinhardt](#)  
 LinkedIn:// [benjaminzreinhardt](#)  
 YouTube:// [SeigeEngineer](#)  
 Twitter:// [@ben\\_reinhardt](#)  
 Quora:// [Benjamin-Reinhardt](#)

## TECHNOLOGY XP

### ATOMLAND

• Embedded hardware • Sensor Fusion  
 • Machine Tools • 3D Printers • Motor  
 Controllers

### BITLAND

• MATLAB • Python • C • Solidworks  
 • Point Cloud Library • C++ • HTML •  
 ROS • Java (Rusty)

## PROJECTS

• SLAM, PF, and RRT control on a  
 Roomba  
 • Amphibious Robots  
 • Two Story Trojan Horse  
 • Choreographed lightsaber battles  
 • Restarted elevator-riding tradition  
 • Kinect-based robot grasp detector  
 • Trebuchets  
 Ditch Day Adventure Hunt:  
 • Auto-collapsing concrete wall  
 • Reverse geocache box • 12-ft ice  
 climbing wall • Electric clue-Palantir •  
 Light-connection maze

## EXPERIENCE

### NASA AMES | Guest Scientist, Intelligent Robotics Group

Summer 2014 | Mountain View, CA

- Designed and fabricated a prototype robotic inspector to demonstrate new actuators.
- Demonstrated actuator operation on a low-friction air table.
- Updated a visual tracking system to include wireless hardware-in-the-loop control.

Summer 2013 | Mountain View, CA

Controls engineer building a room-sized 6-DOF microgravity simulator

- Designed and implemented controller that translated force inputs to accurate zero-g dynamics
- Implemented a learning algorithm to run automated tests that adjusted the system model and tuned gains

### NASA JPL | Technology Research Fellow, Robotics Group

Summer 2012 | Pasadena, CA

- Created and simulated new control algorithms for an induction-based spacecraft actuator.
- Designed and built experiment to characterize eddy-current forces for actuation.

### AEROVIRONMENT INC. | Research Initiative Intern

Summer 2009 | Monrovia, CA

- Built a photovoltaic rig for powering aquatic robots. Tested the rig in a fish tank and the open ocean.
- Built a model of wind flow over large buildings from experimental data.
- Ran thermal tests on UAV components.

### VIRTUAL LUNG PROJECT | Research Assistant

Summer 2008 | UNC Chapel Hill

- Developed simulations of cilia-driven fluid flow in the lungs.

## RESEARCH

### CORNELL SPACE SYSTEMS DESIGN STUDIO | Graduate Student + Lab Manager

Summer 2010 – Present | Ithaca, NY

Induction-based Locomotion for Orbital Robotics

- Built a probabilistic design/controller generation algorithm that outperformed the human baseline.
- Developed simulation framework and visualizer for electromagnetic spacecraft actuators.
- Built fast algorithms to calculate eddy-current forces for dynamic actuation.
- Mentored year-long masters projects and senior projects.
- Rebuilt lab website for modernity and mobile friendliness.

## PUBLICATIONS

Please see <http://benjaminreinhardt.com/pages/papers/>