## ST1155A

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# Low-saturation, Low-voltage Bi-directional Motor Driver





#### ST1155A

## Low-saturation, Low-voltage Bi-directional Motor Driver

#### **General Specifications**

The device is a two-channel low-saturation bi-directional motor driver IC. The design is optimal for stepper-motor applications, such as cameras, printers, FDDs, or other portable devices.

#### **Features and Benefits**

- Low voltage operation ( $V_{DD \, min} = V_{S1 \, min} = V_{S2 \, min} = 1.5 V$ )
- Low saturation voltage (Upper transistor + low transistor residual voltage; 0.3V typ. at 400mA; 0.6V typ. at 750mA)
- Parallel connection ( two-channel driver: Upper transistor + low transistor residual; 0.4V typ. at 800mA)
- Separate control logic power supply and motor driver power supply
- High output sinking and driving capability
- Thin, highly reliable package (SOP-14)

#### **Pin Assignment**



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PIN NO.	PIN NAME	DESCRIPTION		
1	VDD	Power supply pin for controller.		
2	ENA1	Input pin that enable/disable drivers O1/O2.		
3	01	Output sinking / driving pin.		
4	VS1	Power supply pin for output driver O1/ O2.		
5	O2	Output sinking / driving pin.		
6	IN1	Input pin that determines driving mode		
7	GND	Ground pin		
8	NC	No connecting		
9	IN2	Input pin that determines driving mode.		
10	O4	Output sinking / driving pin.		
11	VS2	Power supply pin for output driver O3/ O4.		
12	O3	Output sinking / driving pin.		
13	ENA2	Input pin that enable/disable drivers O3/O4.		
14	GND	Ground pin		

## **Absolute Maximum Ratings** (Unless otherwise noted, $T_A$ = 25 $^{\circ}$ C)

Characteristic	Symbol	Rating	Unit
Supply Voltage	$V_{DD}$	5.5	V
Supply voltage	$V_S$	3.5	V
Input Voltage	$V_{IN}$	V <sub>DD</sub> +0.4	V
I <sub>O</sub> Peak Current (in parallel connection)	I <sub>OPeak</sub>	3	Α
Power Dissipation	$P_{D}$	800	mW
Operating Temperature Range	$T_OPR$	-40 ~ 125	°C
Storage Temperature Range	T <sub>STG</sub>	-65 ~ 150	°C

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## **Electrical Characteristic**

(Unless otherwise noted,  $T_A$ = 25  $^{\circ}$ C &  $V_{DD}$  =  $V_S$  = 3 $^{\circ}$ V)

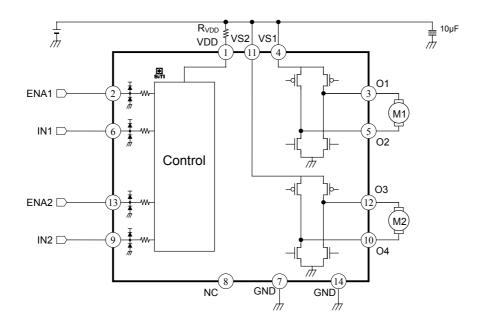
Characteristic	Sym.	0 1111	Limit			l lait
Characteristic		Condition	Min.	Тур.	Max.	Unit
Supply Voltage	$V_{DD}$		1.5	3	5.5	V
Supply Voltage	Vs		1.5	3	5.5	V
Supply Current	I <sub>DD0</sub>	$V_{ENA1, 2}$ =0V, $V_{IN1,2}$ =0V or 3V		0.1	10	$\mu$ A
( I <sub>DD</sub> + I <sub>S</sub> )	I <sub>DD1</sub>	$V_{ENA1, 2}$ =3V, $V_{IN1,2}$ =0V or 3V		0.05	0.5	mA
ENA1 / ENA2 / IN1 / IN2 Input Terminal ( $T_J = 25^{\circ}C$ )						
Input Voltage "H"	V <sub>IH</sub>	-	0.8*V <sub>DD</sub>	-	V <sub>DD</sub> +0.	V
Input Voltage "L"	V <sub>IL</sub>	-	-0.4	=	0.2*V <sub>DD</sub>	V
Input Current "H"	I <sub>IH</sub>	$V_{IN} = V_{DD}$	-	-	±5	$\mu$ A
Input Current "L"	I <sub>IL</sub>	V <sub>IN</sub> = 0 V	-	-	±5	$\mu$ A
O1 / O2 / O3 / O4 Output Terminal $(T_J = 25^{\circ}C)$						
	V <sub>OUT1</sub>	I <sub>OUT</sub> = 200 mA	-	0.2	0.3	V
	V <sub>OUT2</sub>	I <sub>OUT</sub> = 400 mA	-	0.3	0.6	V
Output Voltage	$V_{\text{OUT3}}$	I <sub>OUT</sub> = 750 mA	-	0.6	0.95	V
(upper + lower)	V <sub>OUT4</sub>	I <sub>OUT</sub> = 400 mA ( parallel connection )	-	0.2	0.35	V
	V <sub>OUT5</sub>	I <sub>OUT</sub> = 800 mA ( parallel connection )	-	0.4	0.7	V
Output Resistance	Ron	$V_{DD}$ = $V_{S}$ =3 $V$ , $I_{OUT}$ =400 mA	-	0.75	-	Ω
Output Sustaining Voltage	$V_{O(SUS)}$	I <sub>OUT</sub> = 400 mA	-	-	Vs	V



### **Truth Table**

IN1 / IN2	ENA1 / ENA2	01 / 03	02 / 04	Mode
L	Н	Н	L	Forward
Н	Н	L	Н	Reverse
Н	L	OFF	OFF	Standby
L	L	OFF	OFF	Standby

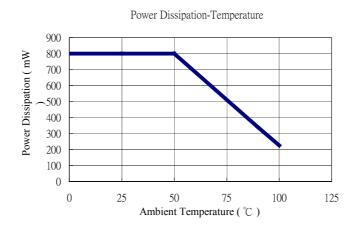
## **Block Diagram & Application Circuit**





## **Application Notes**

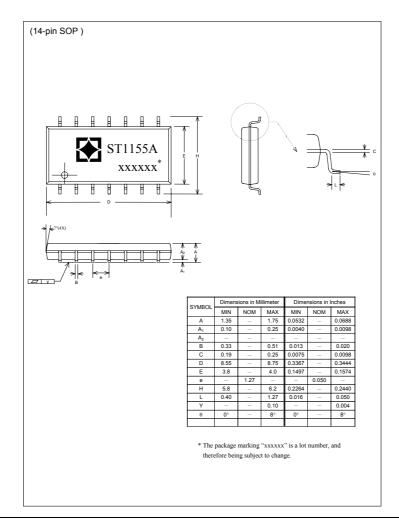
- $\Box$  To increase system stability, it is suggestion to connect a resistor R<sub>VDD</sub> about 470Ω between battery power and driver's VDD pin as shown on application circuit.
- □ In multiple power supply application, although power supply of control logic and motor driver are separated, the voltage of VDD pin must be lager than or equal to the voltage of VS1 and VS2 pin.
- The power dissipated by the IC varies widely with the supply voltage, the output current, and loading. It is important to ensure the application does not exceed the allowable power dissipation of the IC package. The recommended motor driver power dissipation versus temperature is depicted as follows:



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## Package Specifications(SOP-14)



The products listed herein are designed for ordinary electronic applications, such as electrical appliances, audio-visual equipment, communications devices and so on. Hence, it is advisable that the devices should not be used in medical instruments, surgical implants, aerospace machinery, nuclear power control systems, disaster/crime-prevention equipment and the like. Misusing those products may directly or indirectly endanger human life, or cause injury and property loss.

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