


```

bitset<MAX_SIEVE + 10> bs;
vi primes;

void sieve(ll upperbound) {
    _sieve_size = upperbound + 1;
    bs.set();
    bs[0] = bs[1] = 0;
    for (ll i = 2; i <= _sieve_size; ++i)
        if (bs[i]) {
            for (ll j = i * i; j <= _sieve_size; j += i)
                bs[j] = 0;
            primes.push_back((int)i);
        }
}

bool isPrime(ll N) { // works for N <= (last prime in primes)^2
    if (N <= _sieve_size) return bs[N]; // O(1) sieve check for small primes
    for (int i = 0; i < (int)primes.size(); ++i) // brute force for larger
        if (N % primes[i] == 0) return false;
    return true; // more time if N is prime!
}

```

Java BigInteger

```

BigInteger.ZERO // constants
i.mod(m) // base number conversion
i.isProbablePrime(10) // Probabilistic prime testing
i.gcd(k)
x.modPow(y, n) // calculate x^y mod n

```

Combinatorics

$$C(n, 0) = C(n, n) = 1$$

$$C(n, k) = C(n-1, k-1) + C(n-1, k)$$

Catalan numbers

1. $Cat(n)$ Count the number of distinct binary trees with n vertices.
2. Count number of expressions counting n correctly matched pairs of parentheses.
3. Count ways a convex polygon can be triangulated.

$$Cat(0) = 1$$

$$Cat(n+1) = \frac{(2n+2)(2n+1)}{(n+2)(n+1)} * Cat(n)$$

Cycle Finding

TODO

Game Theory

TODO

Linear Diphantine Equation

TODO

DP

LIS $O(n \log n)$

```

vi lis(vi a) {
    int L[MAX];

    vi dp(a.size());

    int lis = 0;
    for (int i = 0; i < a.size(); ++i) {
        // LIS ending at a[i] is at length pos + 1
        int pos = lower_bound(L, L + lis, a[i]) - L;
        L[pos] = a[i];
        dp[i] = pos + 1;

        if (pos + 1 > lis) {
            lis = pos + 1;
        }
    }

    return dp; // Return lis array
}

```

Data structures

Union Find

```

class UnionFind { // rank ordered with path compression
public:
    UnionFind(int n) {
        rank.assign(n, 0);
        p.assign(n, 0);
        set_size.assign(n, 1);
        num_sets = n;
        for (int i = 0; i < n; ++i)
            p[i] = i;
    }

    int find_set(int i) { return (p[i] == i) ? i : (p[i] = find_set(p[i])); }
    bool is_same_set(int i, int j) { return find_set(i) == find_set(j); }
    void union_set(int i, int j) {
        if (!is_same_set(i, j)) {
            --num_sets;
            int x = find_set(i), y = find_set(j);
            if (rank[x] > rank[y]) {
                p[y] = x;
                set_size[x] += set_size[y];
            }
            else {
                p[x] = y;
                set_size[y] += set_size[x];
                if (rank[x] == rank[y]) rank[y]++;
            }
        }
    }
}

```

```

    }
    int num_disjoint_sets() { return num_sets; }
    int size_of_set(int i) { return set_size[find_set(i)]; }
private:
    vi rank, p, set_size;
    int num_sets;
};

Segment Tree

class SegmentTree { // Max range query. Change >= to <= for min.
    vi st, a;

    int n;
    int left(int p) { return p << 1; } // Same as binary heap
    int right(int p) { return (p << 1) + 1; }

    void build(int p, int l, int r) { // O(n log n)
        if (l == r)
            st[p] = 1;
        else {
            build(left(p), l, (l + r) / 2);
            build(right(p), (l + r) / 2 + 1, r);
            int p1 = st[left(p)], p2 = st[right(p)];
            st[p] = (a[p1] >= a[p2]) ? p1 : p2; // Build max
        }
    }

    int rmq(int p, int l, int r, int i, int j) { // O(log n)
        if (i > r || j < l) return -1; // outside of range
        if (l >= i && r <= j) return st[p]; // inside range

        int p1 = rmq(left(p), l, (l + r) / 2, i, j);
        int p2 = rmq(right(p), (l + r) / 2 + 1, r, i, j);

        if (p1 == -1) return p2;
        if (p2 == -1) return p1;
        return (a[p1] >= a[p2]) ? p1 : p2; // Return max inside
    }

    // Support for dynamic updating. O(log n)
    int update_point(int p, int l, int r, int idx, int new_value) {
        int i = idx, j = idx;
        if (i > r || j < l)
            return st[p];

        if (l == i && r == j) {
            a[i] = new_value;
            return st[p] = 1;
        }

        int p1, p2;
        p1 = update_point(left(p), l, (l + r) / 2, idx, new_value);
        p2 = update_point(right(p), (l + r) / 2 + 1, r, idx, new_value);
    }
};

```

```

        return st[p] = (a[p1] >= a[p2]) ? p1 : p2; // Max query
    }
public:
    SegmentTree(const vi &a) {
        a = _a; n = (int) a.size(); // Copy for local use
        st.assign(4 * n, 0); // Large enough of zeroes
        build(1, 0, n - 1);
    }

    // Return index of max O(log n)
    int rmq(int i, int j) { return rmq(1, 0, n - 1, i, j); }

    // Update index to a new value.
    int update_point(int idx, int new_value) {
        return update_point(1, 0, n - 1, idx, new_value);
    }
};

```

Graph

Kruskal MST

```

// use union find class
int kruskal_mst(vector<pair<int, ii> > &EdgeList, int V) {
    int mst_cost = 0;
    UnionFind UF(V);
    for (int i = 0; i < EdgeList.size(); ++i) {
        pair<int, ii> front = EdgeList[i];
        if (!UF.isSameSet(front.second.first, front.second.second)) {
            mst_cost += front.first;
            UF.unionSet(front.second.first, front.second.second);
        }
    }

    return mst_cost;
}

```

Bipartite check

```

bool is_bipartite(int s) {
    qi q; q.push(s);
    vi color(n, INF); color[s] = 0;
    while (!q.empty()) {
        int u = q.front(); q.pop();
        for (int j = 0; j < (int)adjs[u].size(); ++j) {
            ii v = adjs[u][j];
            if (color[v.first] == INF) {
                color[v.first] = 1 - color[u];
                q.push(v.first);
            }
            else if (color[v.first] == color[u]) {
                return false;
            }
        }
    }
}

```

```

    }
}
return true;
}

```

Maximum Bipartite Cardinality Matching

```

vector<vi> AdjList; // initialize
vi match, vis;

int aug(int l) { // return 1 if augmenting path is found, 0 otherwise
    if (vis[l]) return 0;
    vis[l] = 1;
    for (int j = 0; j < (int)AdjList[l].size(); ++j) {
        int r = AdjList[l][j];
        if (match[r] == -1 || aug(match[r])) {
            match[r] = l;
            return 1;
        }
    }
    return 0;
}

// in main
int MCBM = 0; // result
match.assign(V, -1);
for (int l = 0; l < n; ++l) {
    vis.assign(n, 0);
    MCBM += aug(l);
}

```

Articulation points and bridges

```

void articulationPointAndBridge(int u) {
    dfs_low[u] = dfs_num[u] = dfsNumberCounter++; // dfs_low[u] <= dfs_num[u]
    for (int j = 0; j < (int)AdjList[u].size(); ++j) {
        ii v = AdjList[u][j];
        if (dfs_num[v.first] == UNVISITED) {
            dfs_parent[v.first] = u;
            if (u == dfsRoot) rootChildren++;

            articulationPointAndBridge(v.first);

            if (dfs_low[v.first] >= dfs_num[u])
                articulation_vertex[u] = true;
            if (dfs_low[v.first] > dfs_num[u])
                printf(" Edge (%d,%d) is a bridge\n", u, v.first);
            dfs_low[u] = min(dfs_low[u], dfs_low[v.first]);
        }
        else if (v.first != dfs_parent[u]) // a back edge and not direct
            cycle
            dfs_low[u] = min(dfs_low[u], dfs_num[v.first]);
    }
}

```

```

// in main
dfsNumberCounter = 0;
dfs_num.assign(V, UNVISITED);
dfs_low.assign(V, 0);
dfs_parent.assign(V, 0);
articulation_vertex.assign(V, 0);
printf("Bridges:\n");
for (int i = 0; i < V; ++i)
    if (dfs_num[i] == UNVISITED) { // special case for root
        dfsRoot = i; rootChildren = 0;
        articulationPointAndBridge(i);
        articulation_vertex[dfsRoot] = (rootChildren > 1);
    }
// articulation_vertex contains Articulation Points

```

Dijkstra

```

vector<vector<ii> > AdjList; // pair<node, cost>
int V, E, s, t;

int dijkstra(int s, int t) { // variant will leave duplicate nodes in queue
    vi dist(V, INF);
    dist[s] = 0;
    priority_queue<ii, vector<ii>, greater<ii> > pq;
    pq.push(ii(0, s));
    while (!pq.empty()) {
        ii front = pq.top(); pq.pop();
        int d = front.first, u = front.second;
        if (d > dist[u]) continue; // important check
        for (int j = 0; j < (int)AdjList[u].size(); ++j) {
            ii v = AdjList[u][j];
            if (dist[u] + v.second < dist[v.first]) {
                dist[v.first] = dist[u] + v.second; // relax
                pq.push(ii(dist[v.first], v.first));
            }
        }
    }
    return dist[t];
}

```

Bellman Ford

```

int bellman_ford(int s, int t) { // O(VE) when using adj list
    vi dist(V, INF); dist[s] = 0;
    for (int i = 0; i < V - 1; ++i) // relax all edges V-1 times
        for (int u = 0; u < V; ++u)
            for (int j = 0; j < (int)AdjList[u].size(); ++j) {
                ii v = AdjList[u][j]; // record SP spanning here if needed
                dist[v.first] = min(dist[v.first], dist[u] + v.second);
            }

    return dist[t];
}

```

```

// check if there exists a negative cycle
bool hasNegativeCycle = false;
for (int u = 0; u < V; ++u)
    for (int j = 0; j < (int)AdjList[u].size(); ++j) {
        ii v = AdjList[u][j];
        if (dist[v.first] > dist[u] + v.second) // if still possible
            hasNegativeCycle = true;           // then neg cycle exists
    }

```

Euler Tour

```

list<int> cyc; // list for fast insertion in middle

void EulerTour(list<int>::iterator i, int u) {
    for (int j = 0; j < (int)AdjList[u].size(); ++j) {
        ii v = AdjList[u][j];
        if (v.second) {
            v.second = 0; // mark as to be removed
            for (int k = 0; k < (int)AdjList[v.first].size(); ++k) {
                ii uu = AdjList[v.first][k]; // remove bi-directional
                if (uu.first == u && uu.second) {
                    uu.second = 0;
                    break;
                }
            }
            EulerTour(cyc.insert(i, u), v.first);
        }
    }
}

// inside main
cyc.clear();
EulerTour(cyc.begin(), A); // cyc contains euler tour starting at A
for (list<int>::iterator it = cyc.begin(); it != cyc.end(); ++it)
    printf("%d\n", *it); // the Euler tour

```

Edmond Karp

```

// setup res, s, t, AdjList as global variables
int res[MAXN][MAXN], mf, f, s, t;
vi p;
vector<vi> AdjList; // Don't forget backward edges!

void augment(int v, int minEdge) { // traverse BFS spanning tree from s to t
    if (v == s) { f = minEdge; return; } // record minEdge in a global
    variable f
    else if (p[v] != -1) {
        augment(p[v], min(minEdge, res[p[v]][v]));
        res[p[v]][v] -= f; res[v][p[v]] += f;
    }
}

int edmond_karp() {

```

```

mf = 0;
while (1) { // run bfs
    f = 0;
    bitset<MAXN> vis; vis[s] = true; // bitset is faster
    queue<int> q; q.push(s);
    p.assign(MAXN, -1); // record the BFS spanning tree, from s to t
    while (!q.empty()) {
        int u = q.front(); q.pop();
        if (u == t) break; // stop bfs if we reach t
        for (int j = 0; j < (int)AdjList[u].size(); ++j) { // faster with
            AdjList
            int v = AdjList[u][j];
            if (res[u][v] > 0 && !vis[v])
                vis[v] = true, q.push(v), p[v] = u;
        }
    }
    augment(t, INF);
    if (f == 0) break; // we cannot send any more flow, terminate
    mf += f;           // we can still send a flow, increase the max
                        flow!
}
return mf;
}

```

Flood Fill

```

// need grid, R, C
int dr[8] = { 1, 1, 0, -1, -1, -1, 0, 1 };
int dc[8] = { 0, 1, 1, 1, 0, -1, -1, -1 };

// Return size of CC
int floodfill(int r, int c, char c1, char c2) {
    if (r < 0 || r >= R || c < 0 || c >= C) return 0;
    if (grid[r][c] != c1) return 0;

    int ans = 1; // Because vertex (r, c) has c1 as its color
    grid[r][c] = c2; // Color it
    for (int d = 0; d < 8; ++d)
        ans += floodfill(r + dr[d], c + dc[d], c1, c2);
    return ans;
}

```

Topological Sort

```

vi ts; // Result in reverse order
void topo(int u) {
    seen[u] = 1; // Init to false
    for (int i = 0; i < (int)adj_list[u].size(); ++i) {
        ii v = adj_list[u][i];
        if (!seen[v.first])
            topo(v.first);
    }
    ts.push_back(u);
}

```

```

}

// use
ts.clear();
// init seen to false
for (int i = 0; i < n; ++i)
    if (!seen[i]) topo(i);

Strongly Connected Components

vi dfs_num, dfs_low, S, visited;

void tarjanSCC(int u) {
    dfs_low[u] = dfs_num[u] = dfsNumberCounter++; // dfs_low[u] <= dfs_num[u]
    S.push_back(u); // stores u in a vector based on order of visitation
    visited[u] = 1;
    for (int j = 0; j < (int)AdjList[u].size(); ++j) {
        int v = AdjList[u][j];
        if (dfs_num[v.first] == UNVISITED)
            tarjanSCC(v.first);
        if (visited[v.first])
            dfs_low[u] = min(dfs_low[u], dfs_low[v.first]);
    }

    if (dfs_low[u] == dfs_num[u]) { // if this is a root (start) of an SCC
        printf("SCC %d:", ++numSCC); // this part is done after recursion
        while (1) {
            int v = S.back(); S.pop_back(); visited[v] = 0;
            printf(" %d", v);
            if (u == v) break;
        }
        printf("\n");
    }
}

// in main
dfs_num.assign(V, UNVISITED);
dfs_low.assign(V, 0);
visited.assign(V, 0);
dfsNumberCounter = numSCC = 0;
for (int i = 0; i < V; ++i)
    if (dfs_num[i] == UNVISITED)
        tarjanSCC(i);

```

Chinese Postman

```

// Weight of euler tour in connected graph.
// Need to fill d[][] with min cost between any two nodes. Do floyd warshall
// before.
int memo[1 << MAX]; // dp bitmask memo structure

// Min cost of increasing by one the degree of set of the given odd vertices,
// to make them even.
int min_cost(int s) {

```

```

    if (s == 0) return 0;
    if (memo[s] != 0) return memo[s];

    int best = -1;

    int x = 0; // Choose our first node to switch as the first node with odd
                // values we can find.
    while (((s >> x) & 1) == 0) ++x; // x = number of trailing zeros

    // Try to combine with all other odd value nodes.
    for (int y = x + 1; y < n; ++y) {
        if ((s >> y) & 1 == 0) continue;

        int comb = s ^ (1 << x) ^ (1 << y); // Switch off the selected nodes.

        // Cost will be to combine these two nodes + combining the rest.
        int cost = d[x][y] + min_cost(comb);

        if (best == -1 || cost < best)
            best = cost;
    }

    return memo[s] = best;
}

```

String

Knuth-Morris-Pratt

TODO

Edit Distance

TODO

LCS

TODO

Suffix Trie

TODO

Geometry

TODO

Convex Hull

TODO