



Electromagnetism

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Lecture 12

Magnetic Force & Dipoles

Week 6





Last Lecture

We started Part II – Magnetism

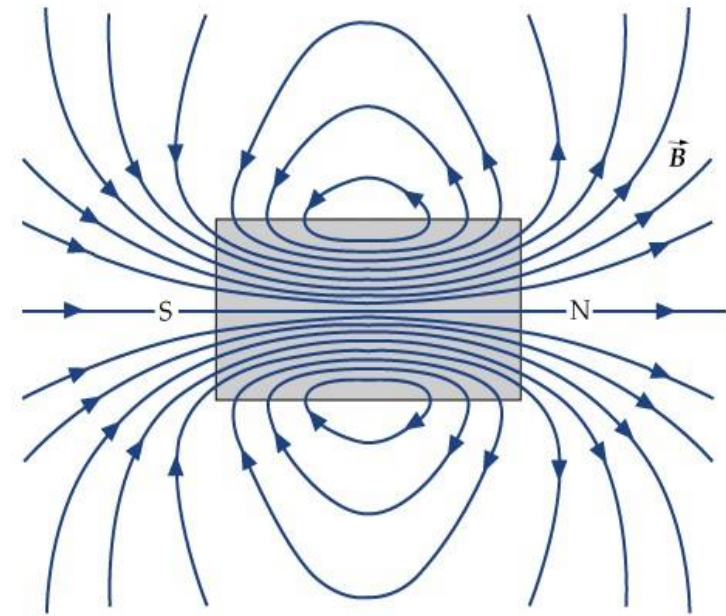
- Definition of Current
- Current Density
- Magnetic force on a moving charge
- The Lorentz Force
- Magnetic field lines

Gauss 's Law for Magnetism

- For E-fields, net electric flux: $\int_S \underline{E} \cdot d\underline{S} = \frac{Q_{enc}}{\epsilon_0}$
- But there are no magnetic monopoles so for magnetic fields:
- Net magnetic flux:

$$\int_S \underline{B} \cdot d\underline{S} = 0$$

(not much use for this course but
does form Maxwell's 2nd equation)



(a)

Summary

- A magnetic field \underline{B} is defined in terms of the force \underline{F}_m acting on a test particle with charge q and moving through the field with velocity \underline{v} :

$$\underline{F}_m = q \underline{v} \wedge \underline{B}$$

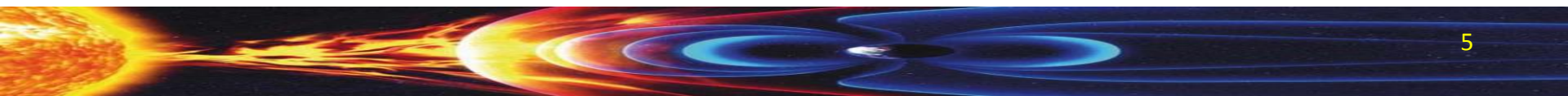
- The general case of both B-fields and E-fields is the Lorentz equation (Lorentz Force):

$$\underline{F} = q(\underline{E} + \underline{v} \wedge \underline{B})$$



This Lecture

- Special cases of magnetic force
- Force on current carrying conductor
- Current Loops and Magnetic Dipoles
 - Torque on magnetic dipole in B-field
 - Potential energy of magnetic dipole in B-field



Special Cases of Magnetic Force

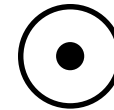
- $\underline{F}_m = q\underline{v} \wedge \underline{B}$
- Special cases:
- \underline{v} parallel to \underline{B} ($\underline{F}_m = q\underline{v} \wedge \underline{B} = 0$)
- \underline{v} perpendicular to \underline{B}
- \underline{v} makes an angle θ to \underline{B}

Direction of B-field

The direction of B field in sketches (in to and out of page)



B-field going in to
the page



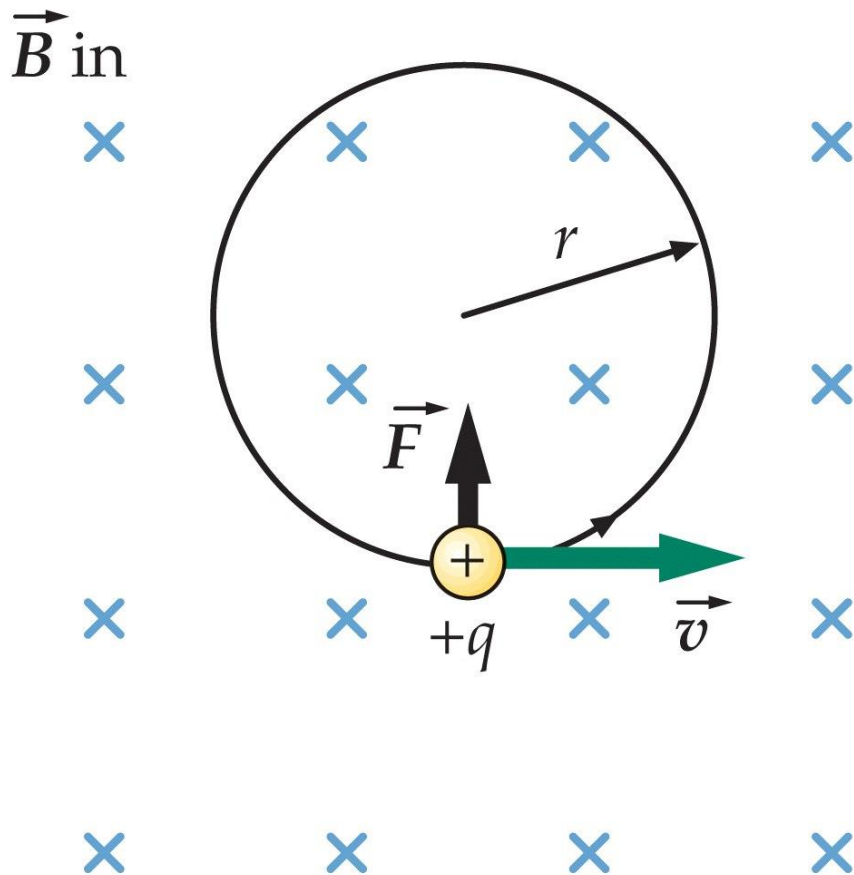
B-field coming out
of the page

i.e. like the back or front of a dart



\underline{v} Perpendicular to \underline{B}

- \underline{v} \perp \underline{B} \underline{F} \perp to the plane containing \underline{B} and \underline{v}



$$|\underline{F}_m| = |q\underline{v} \wedge \underline{B}| = qvB$$

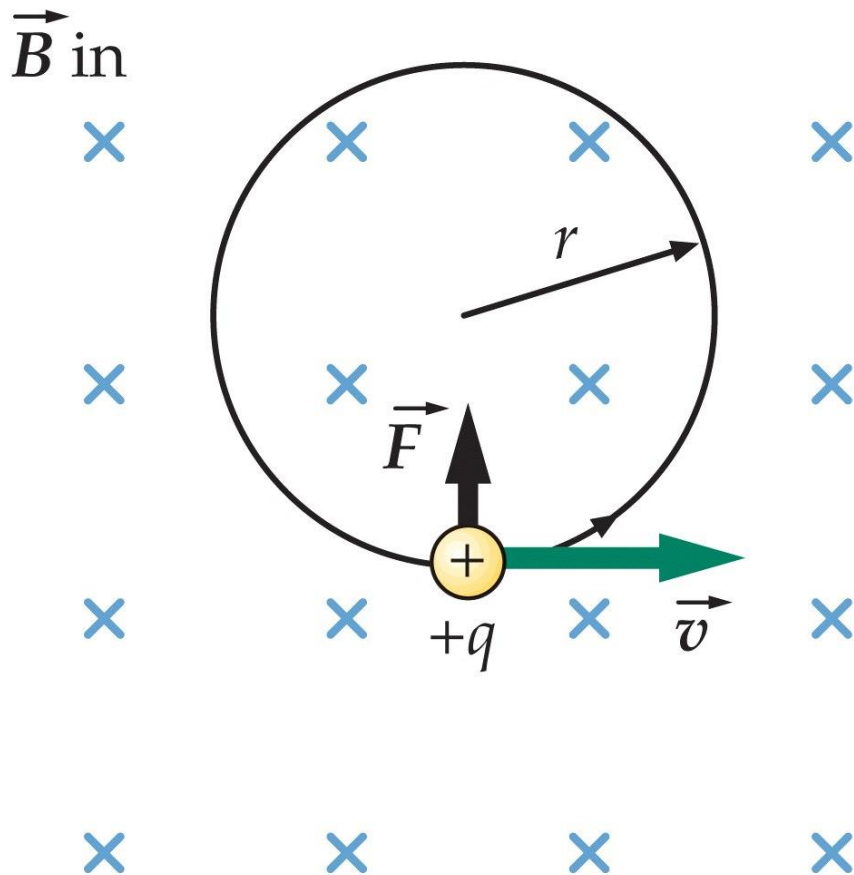
Gives circular motion
Equate forces:

$$qvB = \frac{mv^2}{r}$$

Use visualizer

V Perpendicular to **B**

- **V** \perp **B** **E** \perp to the plane containing **B** and **v**



$$r = \frac{mv}{Bq} = \frac{p}{Bq}$$

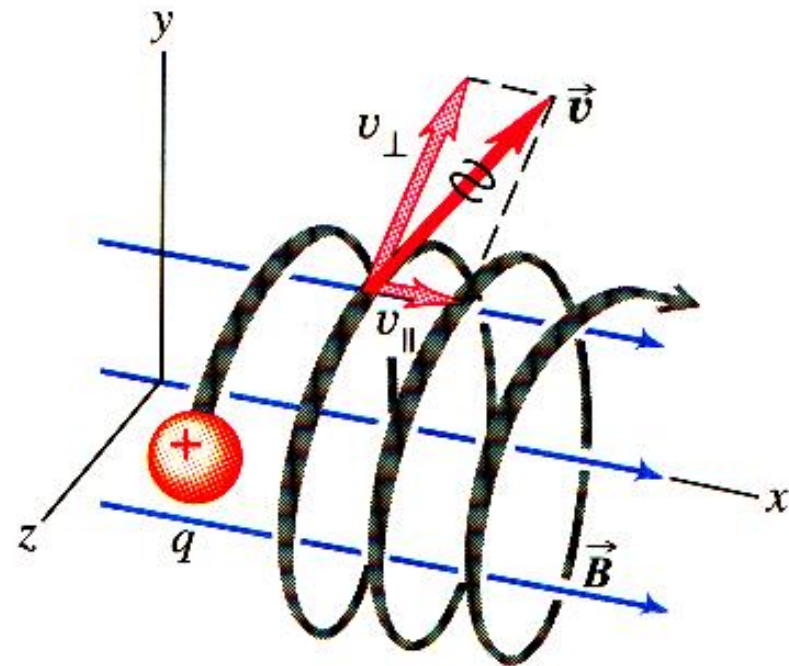
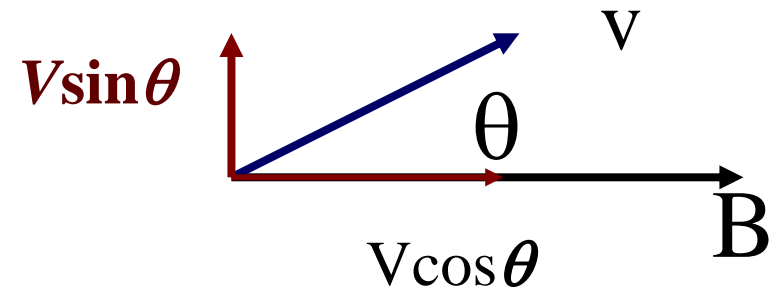
where p is momentum

$$\text{Also: } \frac{Bq}{m} = \frac{v}{r} = \omega$$

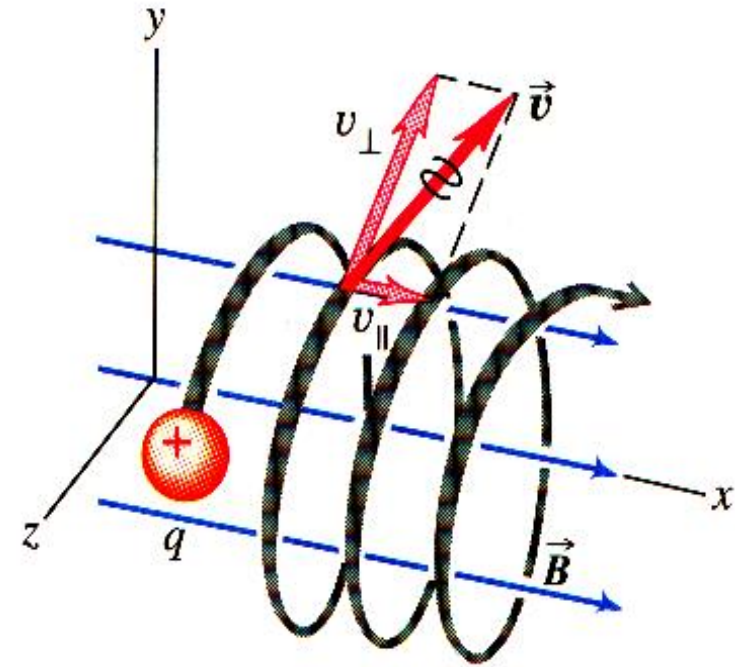
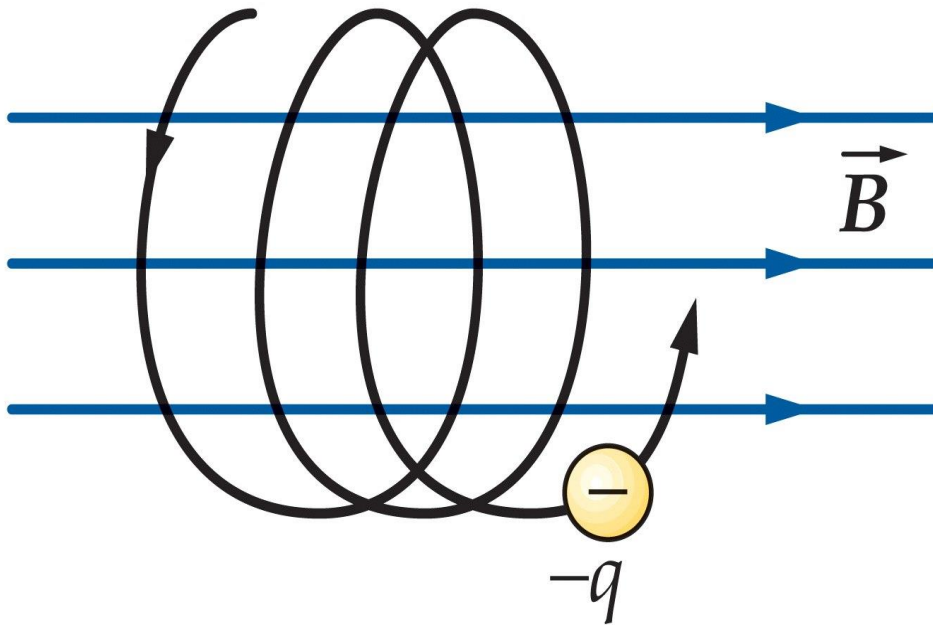
So frequency of "orbital motion": $f = \frac{\omega}{2\pi} = \frac{Bq}{2\pi m}$

v makes an angle θ with **B**

- a uniform circular motion (with “cyclotron angular frequency” $\omega = 2\pi/T$) in which it has the speed $V \sin\theta$ in a plane perpendicular to the direction of B .
- a steady speed of magnitude $V \cos\theta$ along the direction of B
- **Helical Motion**

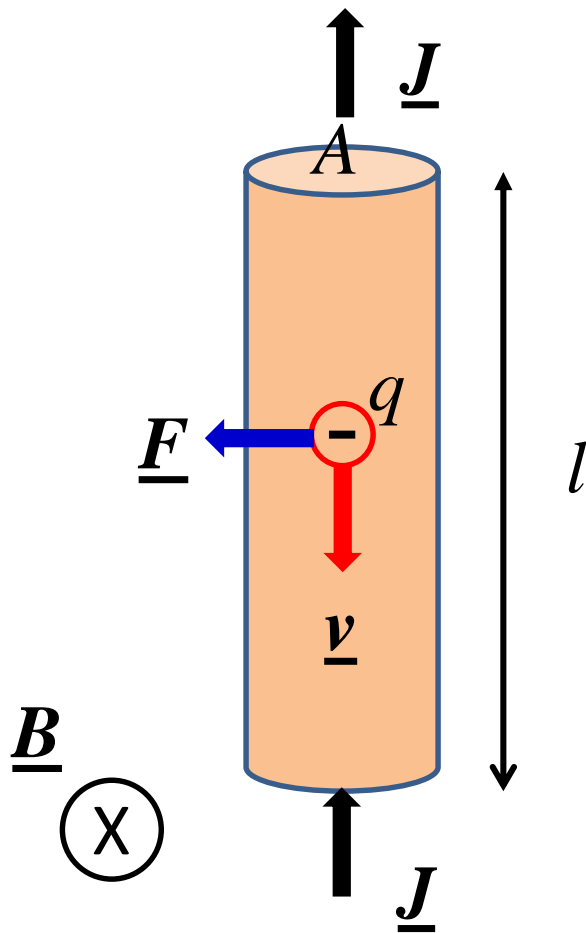


\vec{v} makes an angle θ with \vec{B}



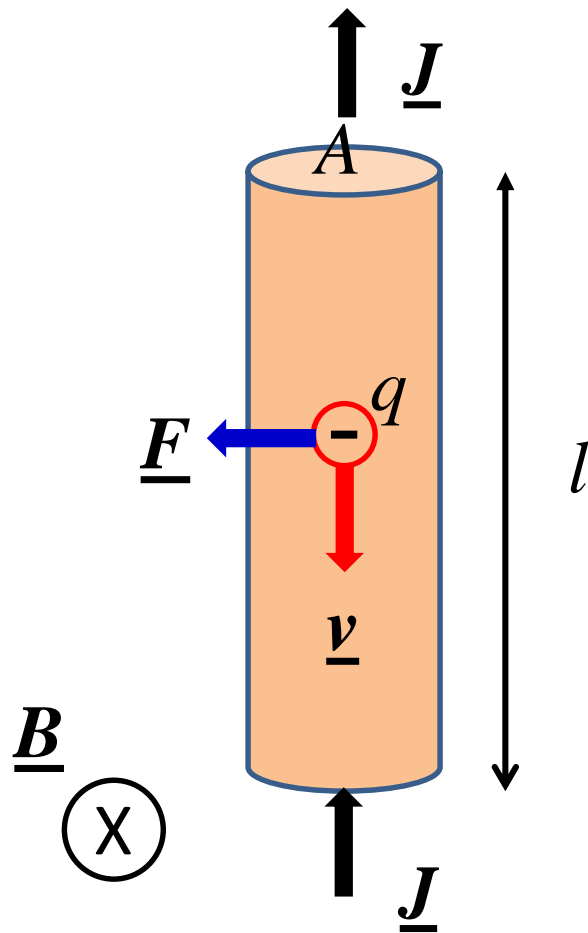
Looking along x direction, clockwise motion for $-q$,
anticlockwise motion for $+q$

Force on Current carrying Conductor



- Single charge $\underline{F}_m = q\underline{v} \wedge \underline{B}$
- N , number of charge carriers in volume Al is $N = nAl$
where n is charge number density
- Total force $\underline{F} = Nq\underline{v} \wedge \underline{B} = -nAle\underline{v} \wedge \underline{B}$
- But current: $\underline{I} = -nAe\underline{v}$
- So: $\underline{F} = l \underline{I} \wedge \underline{B}$ but by convention we define l as the vector \underline{l} as a scalar.

Force on Current carrying Conductor



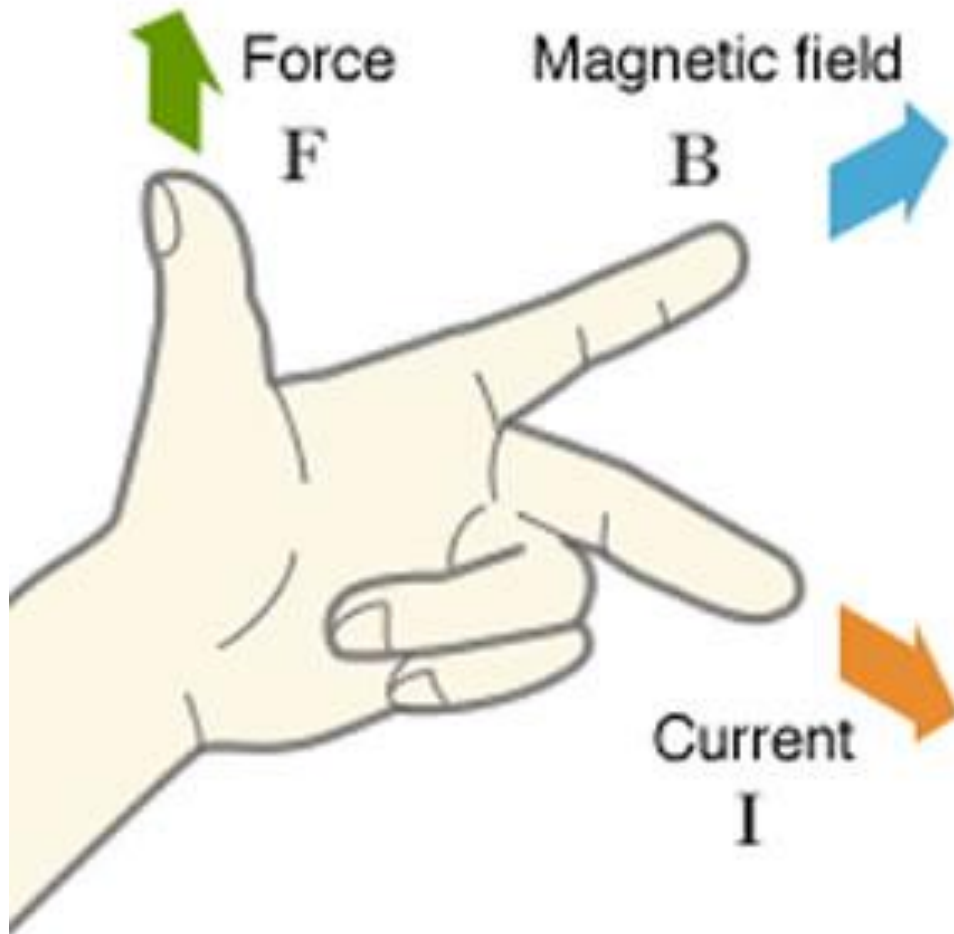
In general

$$\underline{F} = I \underline{l} \wedge \underline{B}$$

magnetic force on a straight wire segment.

The direction of \underline{l} is defined as the direction of the current I

Left Hand Rule



FBI

Force on Non-Straight Conductor

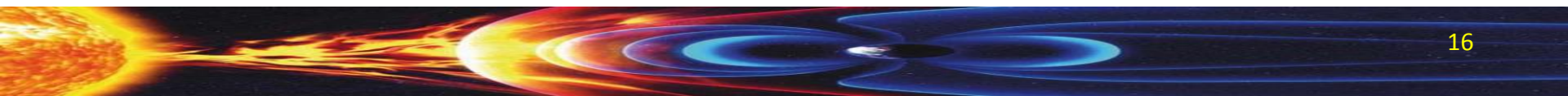
- If the conductor is not straight, consider individual segments and use:
- $\underline{\delta F} = I \delta \underline{l} \wedge \underline{B}$
- magnetic force on an infinitesimal wire segment
- Total force:
- $\underline{F} = \int_a^b I d\underline{l} \wedge \underline{B}$



Current Loops

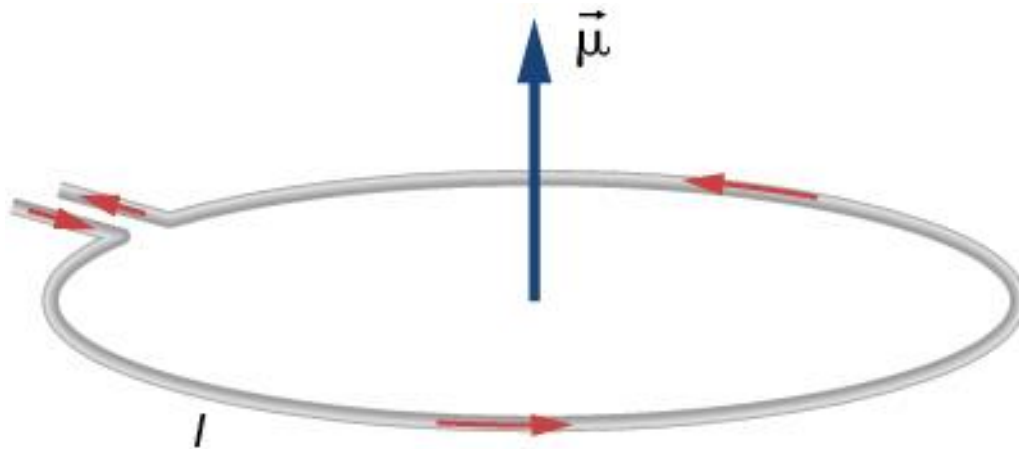
Magnetic Dipoles

Magnetic Dipole Moment



Magnetic Dipoles

A current loop is known as a Magnetic Dipole



(a) Current-carrying loop

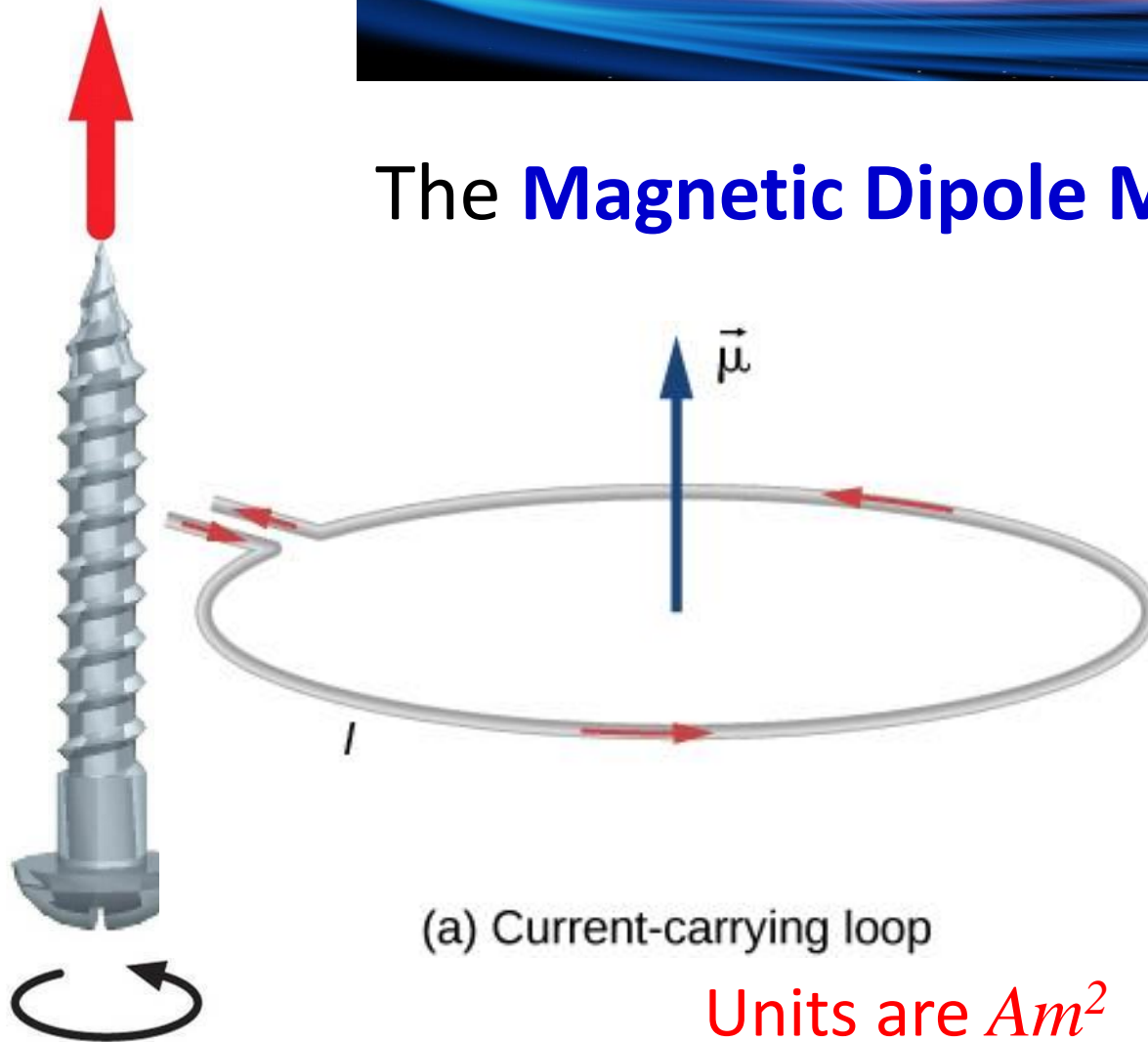
The magnitude of the of the **Magnetic Dipole Moment** is:
Current x Area of loop

$$\mu = I \times A$$

Magnetic Dipole Moment

The **Magnetic Dipole Moment** is a Vector

The area enclosed by the loop may be defined as a vector $\underline{A} = A\underline{\hat{n}}$ where $\underline{\hat{n}}$ is a unit vector normal to the area

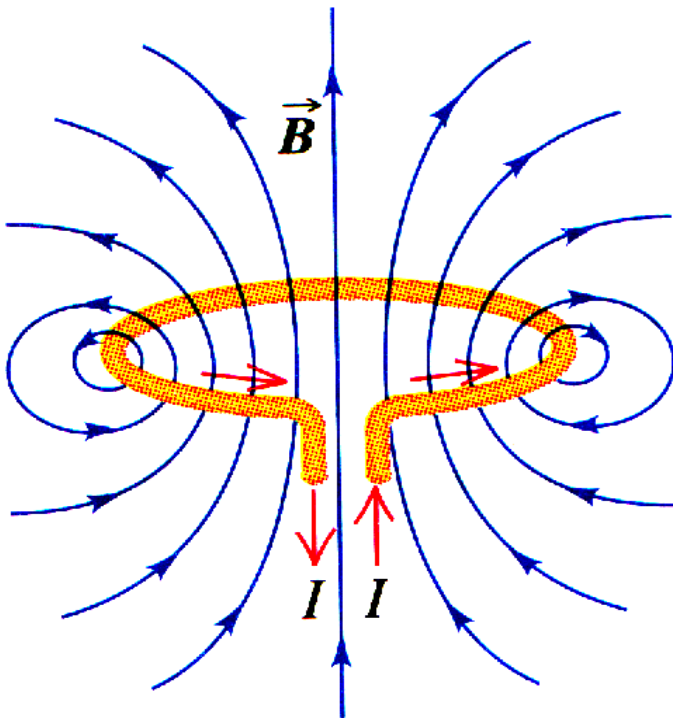


Units are Am^2

$$\underline{\mu} = I \underline{A}$$

Magnetic Dipole

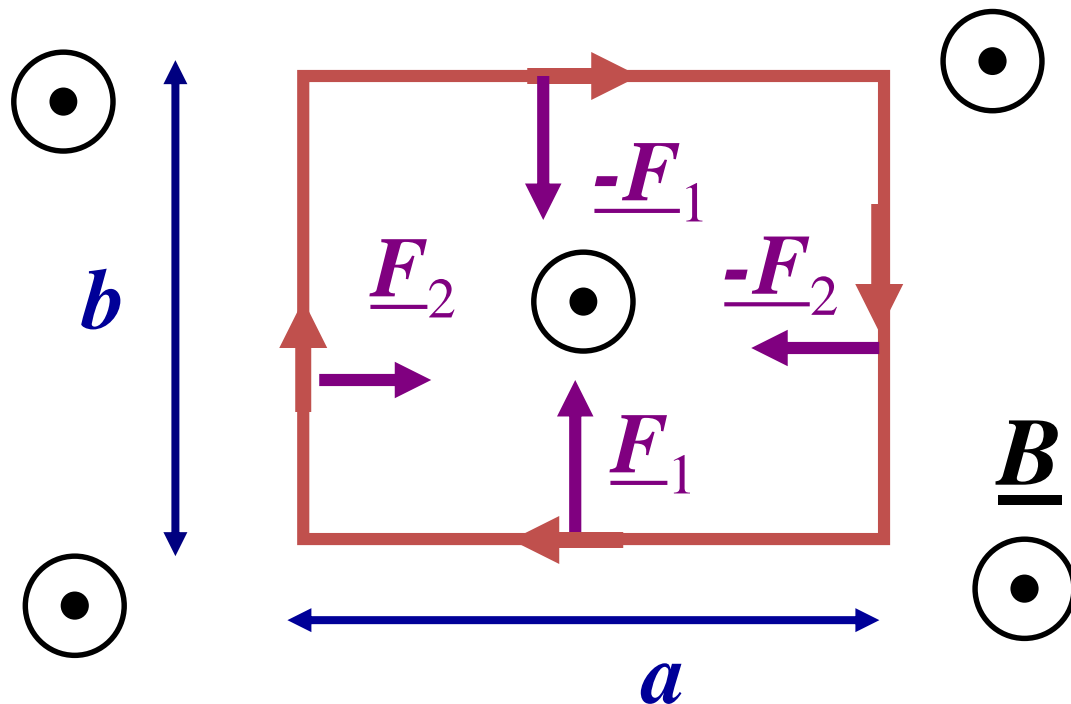
- A current loop produces a magnetic field, similar to that produced by a tiny bar magnet.



- We will cover B-fields produced by currents in the next lecture.

Current Loop in B-field

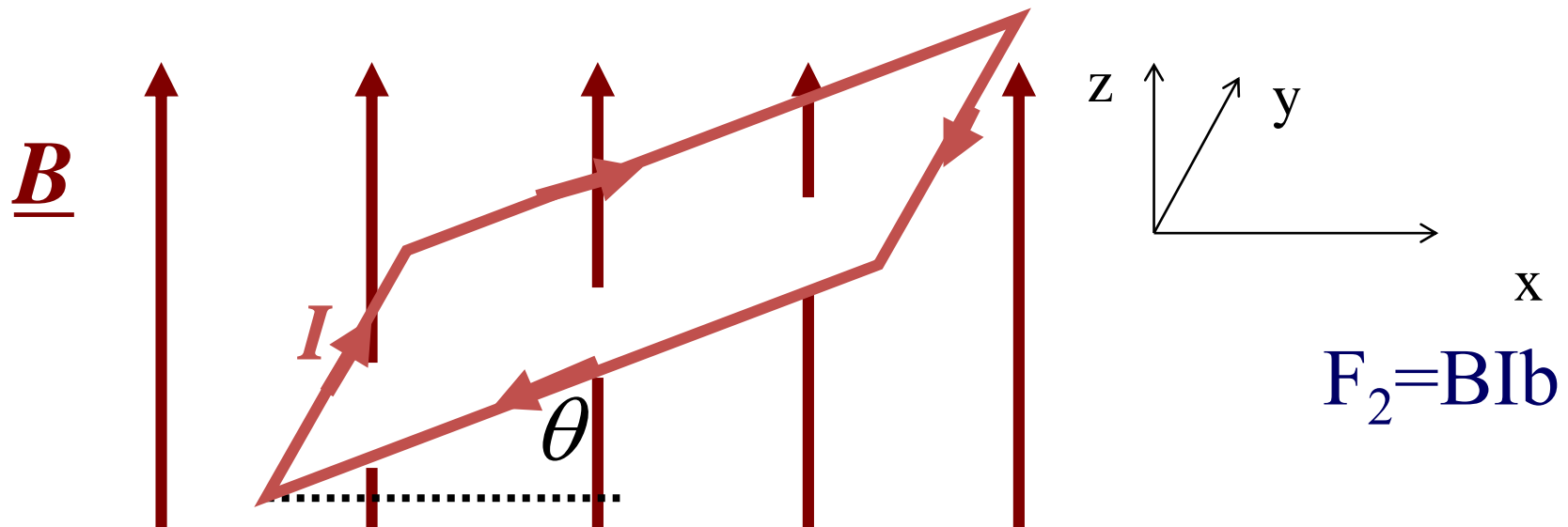
- Consider a current loop in a B-field (coming out of the page).



No net force
No net Torque

Torque on Current Loop

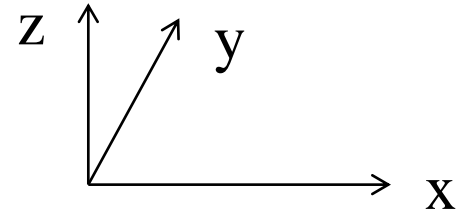
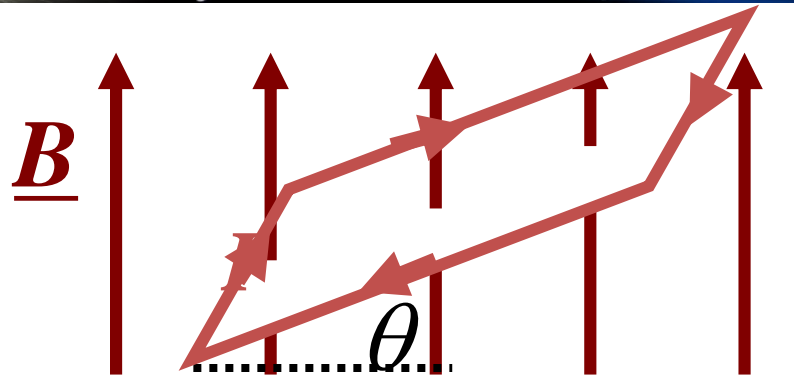
- Now consider loop at an angle to x-axis



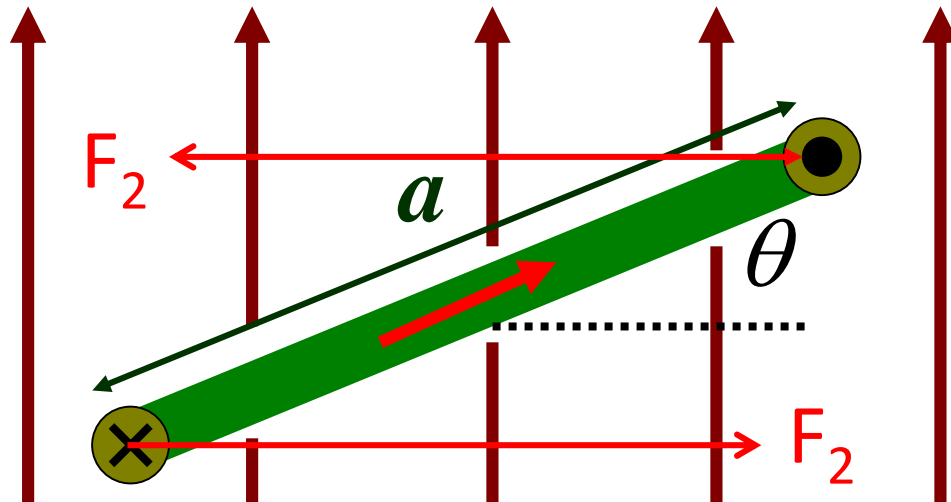
b parallel to y

a makes an angle θ to x

Torque on Current Loop



Cross-sectional view

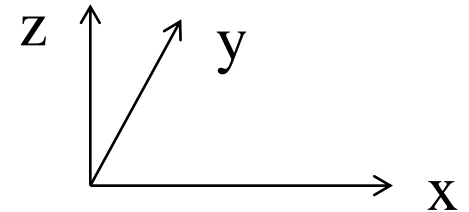
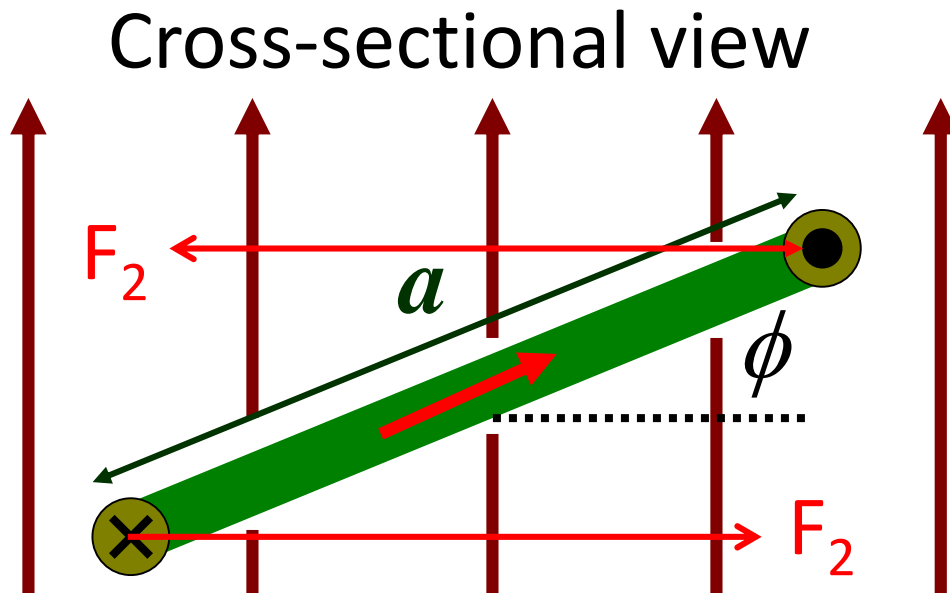


$$F_2 = B I b$$

$$\text{Torques: } \underline{\tau} = \underline{r} \wedge \underline{F}$$

$$\tau = a F_2 \sin \theta$$

Torque on Current Loop



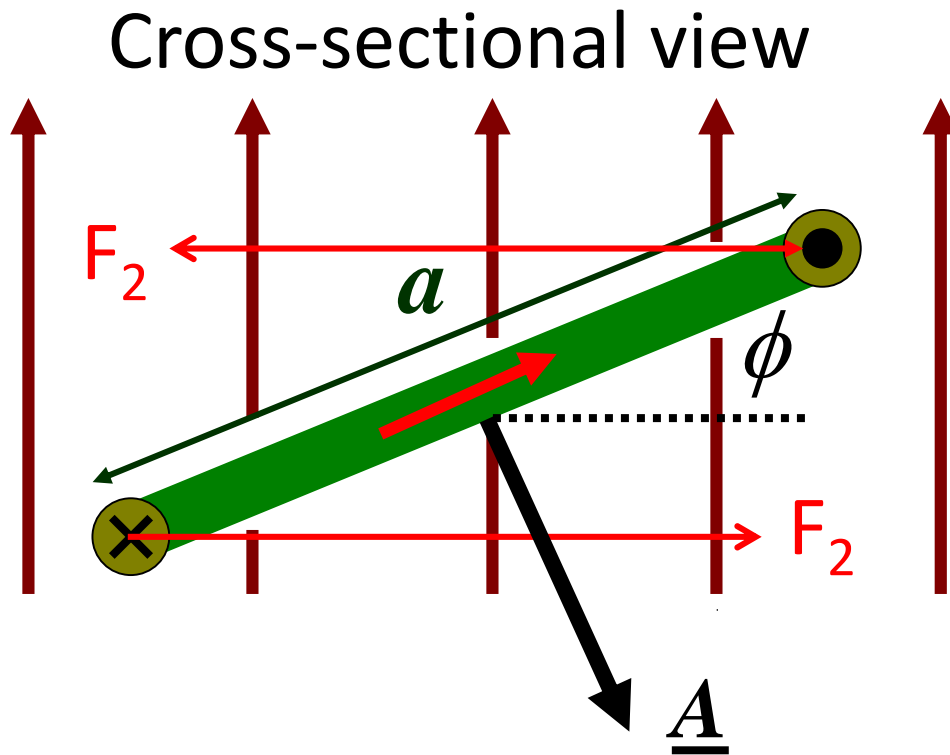
$$F_2 = B I b$$

$$\text{Torques: } \underline{\tau} = \underline{r} \wedge \underline{F}$$

$$\tau = a F_2 \sin \theta$$

$$\text{So } \tau = a (B I b) \sin \theta = B I a b \sin \theta = B I A \sin \theta$$

Torque on Current Loop



$$\tau = BIA \sin \theta$$

$$\underline{\tau} = I \underline{A} \wedge \underline{B}$$

Torque on Current Loop

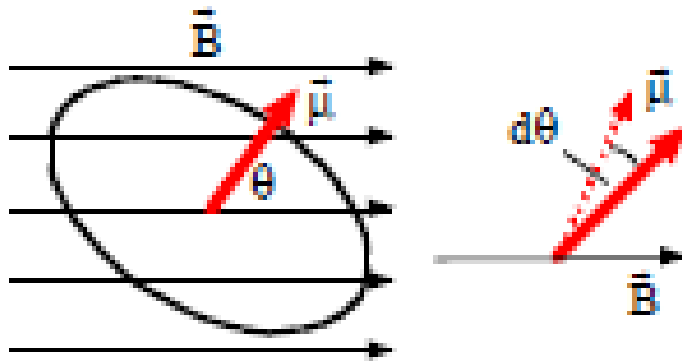
$$\underline{\tau} = I \underline{A} \wedge \underline{B}$$

- True for loops of any shape
- But magnetic dipole moment
- So torque on any current loop

$$\underline{\mu} = I \underline{A}$$

$$\underline{\tau} = \underline{\mu} \wedge \underline{B}$$

Potential Energy of Magnetic Dipole in B-field

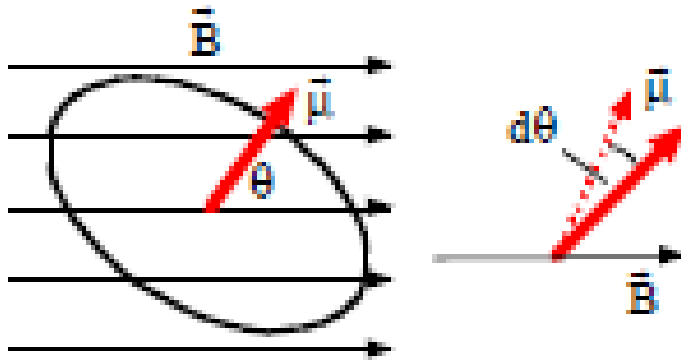


Work done in moving dipole by a small angle, $\delta\theta$:

$$\delta W = \tau \delta\theta$$

- Torque is in the direction of decreasing θ so:
- $\delta W = - \mu B \sin \theta \delta\theta$
- work done is equal to *decrease* in potential energy: $\delta U = - \delta W = \mu B \sin \theta \delta\theta$

Potential Energy of Magnetic Dipole in B-field



$$\delta U = -\delta W = \mu B \sin \theta \delta \theta$$

$$U = \mu B \int \sin \theta d\theta$$

$$U = -\mu B \cos \theta + C$$

Define $U = 0$ when $\theta = \pi/2$

- So : $U = -\mu B \cos \theta$ i.e.

$$U = -\underline{\mu} \cdot \underline{B}$$

Comparison between Magnetic & Electric Dipoles

Electric Dipole

$$\underline{p} = q \underline{a}$$

$$\underline{\tau} = \underline{p} \wedge \underline{E}$$

$$U = -\underline{p} \cdot \underline{E}$$

Magnetic Dipole

$$\underline{\mu} = I \underline{A}$$

$$\underline{\tau} = \underline{\mu} \wedge \underline{B}$$

$$U = -\underline{\mu} \cdot \underline{B}$$



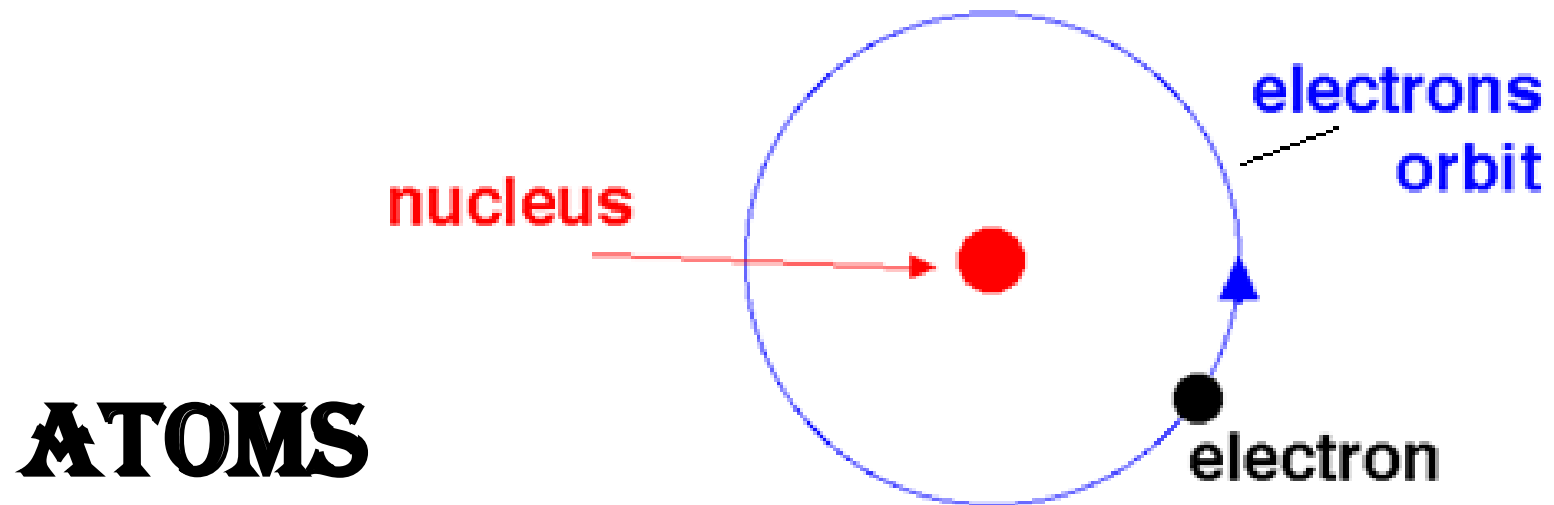
Example

- A square coil with sides equal to 20 cm carries a current of 2 A . It lies on the $Z=0$ plane in a B-field = $(0.5\mathbf{i} + 0.2\mathbf{k})\text{ T}$ with the current anti-clockwise when viewed from a point on the +ve z-axis. The coil has 5 turns of wire.
1. What is the magnetic moment of coil?
 2. What is the torque
 3. What is the potential energy

Time to use the visualizer

Dipoles in Nature

- Molecules behave like electric dipoles
- What in nature behaves like a magnetic dipole?



Summary

- Force on a length l of a current carrying conductor (where \underline{l} is defined to be in the dir^n of current flow)

$$\underline{F} = I \underline{l} \wedge \underline{B}$$

- Magnetic Dipole moment:

$$\underline{\mu} = I \underline{A}$$

- Torques on magnetic dipole:

$$\underline{\tau} = \underline{\mu} \wedge \underline{B}$$

- Potential energy of magnetic Dipole:

$$U = -\underline{\mu} \cdot \underline{B}$$