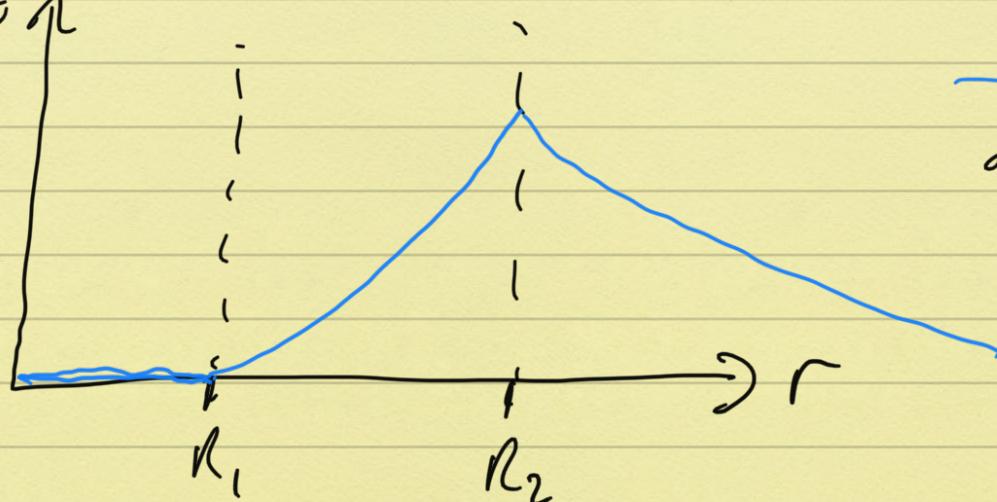


## Lecture 16 - revision for weeks 1-6

(Continued)

Ex 16.3

(b)



$$d_1 < r < d_2$$

$$E = E_0 \left( r^2 - \frac{R_1^3}{r} \right)$$

$$\text{at } r = d_2, E = 0.$$

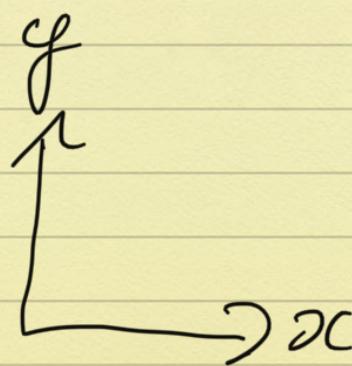
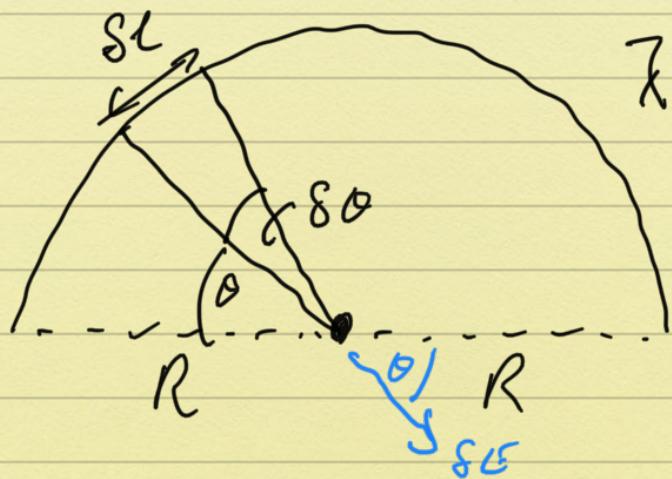
(c)

$$V \quad (r > R_2) \quad E = \frac{\rho_0}{3\epsilon_0} \left( R_2^3 - R_1^3 \right) \frac{1}{r}$$

$$V = - \frac{\rho_0}{3\epsilon_0} \left( R_2^3 - R_1^3 \right) \int \frac{dr}{r}$$

$$= - \frac{\rho_0}{3\epsilon_0} \left( R_2^3 - R_1^3 \right) \ln r + C$$

$$\boxed{E \propto 16 \cdot 4}$$



$$\begin{matrix} \rightarrow \\ \downarrow \end{matrix} \begin{matrix} \delta E_x \\ \delta E_y \end{matrix}$$

Coulomb's law.

$$\delta E = \frac{\lambda \delta l}{4\pi \epsilon_0 R^2}$$

By symmetry  $\Delta C$ -component cancels out leaving just a  $y$ -component in the negative  $y$ -direction.

Just consider magnitude:

$$\delta E_y = \frac{\lambda \delta l}{4\pi \epsilon_0 R^2} \sin \theta$$

$$\sin \theta = \frac{\delta l}{R} \Rightarrow \delta l = R \sin \theta$$

$$\delta E_y = \frac{\lambda \delta \phi}{4\pi \epsilon_0 R} \sin \theta$$

$$|E| = \frac{\lambda}{4\pi \epsilon_0 R} \int_0^\pi \sin \theta d\theta$$

$$= \frac{\lambda}{4\pi \epsilon_0 R} \left[ -\cos \theta \right]_0^\pi$$

$$= \frac{\lambda}{4\pi \epsilon_0 R} \times 2 = \frac{\lambda}{2\pi \epsilon_0 R}$$

$$\underline{E} = - \frac{\lambda}{2\pi \epsilon_0 R} \underline{\hat{y}}$$







