

Algorithms: Design and Analysis, Part II

Local Search

The Maximum Cut Problem

The Maximum Cut Problem

Input: An undirected graph G = (V, E).

Goal: A cut (A, B) – a partition of V into two non-empty sets – that maximizes the number of crossing edges.

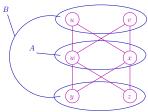
Sad fact: NP-complete.

Computationally tractable special case: Bipartite graphs (i.e., where there is a cut such that all edges are crossing)

Exercise: Solve in linear time via breadth-first search

Quiz

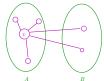
Question: What is the value of a maximum cut in the following graph?



- A) 4
- B) 6
- C) 8
- D) 10

A Local Search Algorithm

Notation: For a cut (A, B) and a vertex v, define $c_v(A, B) = \#$ of edges incident on v that cross (A, B) $d_v(A, B) = \#$ of edges incident on v that don't cross (A, B)



Local search algorithm:

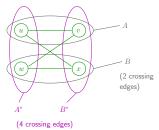
- (1) Let (A, B) be an arbitrary cut of G.
- (2) While there is a vertex v with $d_v(A, B) > c_v(A, B)$:
 - Move v to other side of the cut [key point: increases number of crossing edges by $d_v(A,B) c_v(A,B) > 0$]
- (3) Return final cut (A, B)

Note: Terminates within $\binom{n}{2}$ iterations [+ hence in polynomial time].

Performance Guarantees

Theorem: This local search algorithm always outputs a cut in which the number of crossing edges is at least 50% of the maximum possible. (Even 50% of |E|)

Tight example:



Cautionary point: Expected number of crossing edges of a random cut already is $\frac{1}{2}|E|$.

Proof: Consider a random cut (A, B). For edge $e \in E$, define $X_e = \left\{ \begin{array}{ll} 1 & \text{if } e \text{ crosses } (A, B) \\ 0 & \text{otherwise} \end{array} \right.$ We have $E[X_e] = \Pr[X_e = 1] = 1/2$. So $E[\# \text{ crossing edges}] = E[\sum_e X_e] = \sum_e E[X_e] = |E|/2$. QED

Proof of Performance Guarantee

Let (A, B) be a locally optimal cut. Then, for every vertex v, $d_v(A, B) \le c_v(A, B)$. Summing over all $v \in V$:

$$\sum_{v \in V} d_v(A, B) \le \sum_{v \in V} c_v(A, B)$$
counts each non-crossing edge twice
counts each crossing edge twice

So:

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2 \cdot [\# \text{ of non-crossing edges}] \le 2 \cdot [\# \text{ of crossing edges}]
2 \cdot |E| \le 4 \cdot [\# \text{ of crossing edges}]
\# \text{ of crossing edges} \ge \frac{1}{2} |E| \text{ QED!}
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The Weighted Maximum Cut Problem

Generalization: Each edge $e \in E$ has a nonnegative weight w_e , want to maximize total weight of crossing edges.

Notes:

- (1) Local search still well defined
- (2) Performance guarantee of 50% still holds for locally optimal cuts [you check!] (also for a random cut)
- (3) No longer guaranteed to converge in polynomial time [non-trivial exercise]



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Local Search

Principles of Local Search

Neighborhoods

Let X = set of candidate solutions to a problem.

Examples: Cuts of a graph, TSP tours, CSP variable assignments

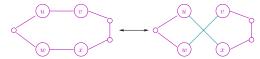
Key ingredient: Neighborhoods

- For each $x \in X$, specify which $y \in X$ are its "neighbors"

Examples: x, y are neighboring cuts \iff Differ by moving one vertex

x, y are neighboring variable assignments \iff Differ in the value of a single variable

x, y are neighboring TSP tours \iff Differ by 2 edges



A Generic Local Search Algorithm

- (1) Let x =some initial solution.
- (2) While the current solution *x* has a superior neighboring solution *y*:

Set x := y

(3) Return the final (locally optimal) solution x

FAQ

Question: How to pick initial solution x?

Answer #1: Use a random solution.

 \Rightarrow Run many independent trials of local search, return the best locally optimal solution found.

Answer #2: Use your best heuristics

(i.e., use local search as a postprocessing step to make your solution even better).

Question #2: If there are superior neighboring y, which to choose?

Possible answers: (1) Choose at random, (2) biggest improvement, (3) more complex heuristics.

Question #3: How to define neighborhoods?

Note bigger neighborhoods \Rightarrow slower to verify local optimality, but fewer (bad) local optima

Answer: Find "sweet spot" between solution quality and efficient searchability.

Tim Roughgarden

FAQ II

Question: Is local search guaranteed to terminate (eventually)?

Answer: If X is finite and every local step improves some objective function, then yes.

Question: Is local search guaranteed to converge quickly?

Answer: Usually not. [though it often does in practice] (see "emacthed analysis")

"smoothed analysis")

Question: Are locally optimal solutions generally good approximations to globally optimal ones?

Answer: No. [To mitigate, run randomized local search many times, remember the best locally optimal solution found]



Local Search

The 2-SAT Problem

Algorithms: Design and Analysis, Part II

2-SAT

Input:

- (1) *n* Boolean variables x_1, x_2, \ldots, x_n . (Can be set to TRUE or FALSE)
- (2) m clauses of 2 literals each ("literal" = x_i or $\neg x_i$)

Example:
$$(x_1 \lor x_2) \land (\neg x_1 \lor x_3) \land (x_3 \lor x_4) \land (\neg x_2 \lor \neg x_4)$$

Output: "Yes" if there is an assignment that simultaneously satisfies every clause, "no" otherwise.

Example: "yes", via (e.g.) $x_1 = x_3 = TRUE$ and $x_2 = x_4 = FALSE$

(In)Tractability of SAT

- 2-SAT: Can be solved in polynomial time!
- Reduction to computing strongly connected components (nontrivial exercise)
- "Backtracking" works in polynomial time (nontrivial exercise)
- Randomized local search (next)
- 3-SAT: Canonical NP-complete
- Brute-force search $\approx 2^n$ time
- Can get time $pprox \left(\frac{4}{3}\right)^n$ via randomized local search [Schöning '02]

Papadimitriou's 2-SAT Algorithm

Repeat $\log_2 n$ times:

- Choose random initial assignment
- Repeat $2n^2$ times:
 - If current assignment satisfies all clauses, halt + report this
 - Else, pick arbitrary unsatisfied clause and flip the value of one of its variables [choose between the two uniformly at random]

Report "unsatisfiable"

Key question: If there's a satisfying assignment, will the algorithm find one (with probability close to 1)?

Obvious good points:

- (1) Runs in polynomial time
- (2) Always correct on unsatisfiable instances



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Local Search

Random Walks on a Line

Random Walks

Key to analyzing Papadimitriou's algorithm:

Random walks on the nonnegative integers (trust me!)

Setup: Initially (at time 0), at position 0.



At each time step, your position goes up or down by 1, with 50/50 probability.

[Except if at position 0, in which case you move to position 1 with 100% probability]

Quiz

Notation: For an integer $n \ge 0$, let $T_n =$ number of steps until random walk reaches position n.

[A random variable, sample space = coin flips at all time steps]

Question: What is $E[T_n]$? (your best guess)

- A) $\Theta(n)$
- B) $\Theta(n^2)$
- C) $\Theta(n^3)$
- D) $\Theta(2^n)$

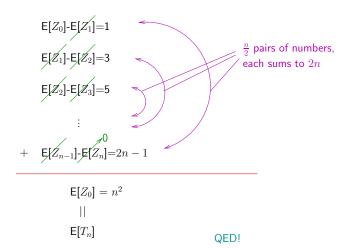
Coming up: $E[T_n]=n^2$.

Analysis of T_n

Let Z_i = number of random walk steps to get to n from i. (Note $Z_0 = T_n$ Edge cases: $E[Z_n] = 0$, $E[Z_0] = 1 + E[Z_1]$ For $i \in \{1, 2, ..., n-1\}$ 1/2 $(1+E[Z_{i-1}])$ 1/2 $(1+E[Z_{i+1}])$ $E[Z_i] = Pr[go left] E[Z_i | go left] + Pr[go right] E[Z_i | go right]$ $= 1 + \frac{1}{2}E[Z_{i+1}] + \frac{1}{2}E[Z_{i-1}]$ Rearranging: $E[Z_i] - E[Z_{i+1}] = E[Z_{i-1}] - E[Z_i] + 2$

Finishing the Proof of Claim

So:



A Corollary

Corollary: $\Pr[T_n > 2n^2] \le \frac{1}{2}$. (Special case of Markov's inequality)

Proof: Let
$$p$$
 denote $\Pr[T_n > 2n^2]$. $\geq 0 \geq 2n^2$

We have $n^2 = E[T_n]$

by last claim $= \sum_{k=0}^{2n^2} k \Pr[T_n = k] + \sum_{k=2n^2+1}^{\infty} k \Pr[T_n = k]$
 $\geq 2n^2 \Pr[T_n > 2n^2]$
 $= 2n^2 p$.

 $\Rightarrow p \leq \frac{1}{2}$ QED!



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Analysis of Papadimitriou's Algorithm

Papadimitriou's Algorithm

n = number of variables

Repeat $log_2 n$ times:

- Choose random initial assignment
- Repeat $2n^2$ times:
 - If current assignment satisfies all clauses, halt + report this
 - Else, pick arbitrary unsatisfied clause and flip the value of one of its variables [choose between the two uniformly at random]

Report "unsatisfiable"

Obvious good points:

- (1) Runs in polynomial time
- (2) Always correct on unsatisfiable instances

Satisfiable Instances

Theorem: For a satisfiable 2-SAT instance with n variables, Papadimitriou's algorithm produces a satisfying assignment with probability $\geq 1 - \frac{1}{n}$.

Proof: First focus on a single iteration of the outer for loop.

Fix an arbitrary satisfying assignment a^* .

Let $a_t = \text{algorithm's assignment after inner iteration } t$ $(t = 0, 1, ..., 2n^2)$ [a random variable]

Let $X_t =$ number of variables on which a_t and a^* agree.

 $(X_t \in \{0,1,\ldots,n\})$

Note: If $X_t = n$, algorithm halts with satisfying assignment a^* .

Proof of Theorem (con'd)

Key point: Suppose a_t not a satisfying assignment and algorithm picks unsatisfied clause with variables x_i, x_j .

Note: Since a^* is satisfying, it makes a different assignment than x_i or x_j (or both).

Consequence of algorithm's random variable flip:

- (1) If a^* and a_t differ on both $x_i \& x_j$, then $X_{t+1} = X_t + 1$ (100% probability)
- (2) If a^* and a_t differ on exactly one of x_i, x_j , then $X_{t+1} = \begin{cases} X_t + 1 & (50\% \text{ probability}) \\ X_t 1 & (50\% \text{ probability}) \end{cases}$

Quiz: Connection to Random Walks

Question: The random variables $X_0, X_1, \ldots, X_{2n^2}$ behave just like a random walk of the nonnegative integers except that:

- A) Sometimes move right with 100% probability (instead of 50%)
- B) Might have $X_0 > 0$ instead of $X_0 = 0$
- C) Might stop early, before $X_t = n$
- D) All of the above

Completing the Proof

Consequence: Probability that a single iteration of the outer for loop finds a satisfying assignment is $\geq \Pr[T_n \leq 2n^2] \geq 1/2$

Thus:

$$\text{Pr[algorithm fails]} \leq \text{Pr[all log}_2 \, n \text{ independent trials fail]}$$

$$\leq \left(\frac{1}{2}\right)^{\log_2 n}$$

$$= \frac{1}{n}. \qquad \text{QED!}$$