

Minimum Spanning Trees

Algorithms: Design and Analysis, Part II

Problem Definition

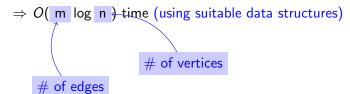
Overview

Informal Goal: Connect a bunch of points together as cheaply as possible.

Applications: Clustering (more later), networking.

Blazingly Fast Greedy Algorithms:

- Prim's Algorithm [1957; also Dijkstra 1959, Jarnik 1930]
- Kruskal's algorithm [1956]



Problem Definition

vertices edges

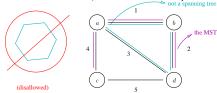
Input: Undirected graph G = (V, E) and a cost c_e for each edge $e \in E$.

- Assume adjacency list representation (see Part I for details)
- OK if edge costs are negative

Output: minimum cost tree $T \subseteq E$ that spans all vertices.

i.e., sum of edge costs

I.e.: (1) T has no cycles, (2) the subgraph (V, T) is connected (i.e., contains path between each pair of vertices).



Standing Assumptions

Assumption #1: Input graph G is connected.

- Else no spanning trees.
- Easy to check in preprocessing (e.g., depth-first search).

Assumption #2: Edge costs are distinct.

- Prim + Kruskal remain correct with ties (which can be broken arbitrarily).
- Correctness proof a bit more annoying (will skip).



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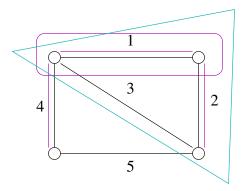
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Prim's MST Algorithm

Example

 $[\mathsf{Purple}\ \mathsf{edges} = \mathsf{minimum}\ \mathsf{spanning}\ \mathsf{tree}]$

(Compare to Dijkstra's shortest-path algorithm)



Prim's MST Algorithm

- Initialize $X = \{s\}$ [$s \in V$ chosen arbitrarily]
- $T = \emptyset$ [invariant: X = vertices spanned by tree-so-far T]
- While $X \neq V$
 - Let e = (u, v) be the cheapest edge of G with $u \in X$, $v \notin X$.
 - Add e to T
 - Add v to X.

While loop: Increase # of spanned vertices in cheapest way possible.

Correctness of Prim's Algorithm

Theorem: Prim's algorithm always computes an MST.

Part I: Computes a spanning tree T^* . [Will use basic properties of graphs and spanning trees] (Useful also in Kruskal's MST algorithm)

Part II: T^* is an MST. [Will use the "Cut Property"] (Useful also in Kruskal's MST algorithm)

Later: Fast $[O(m \log n)]$ implementation using heaps.



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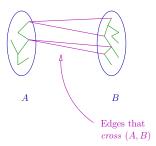
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Correctness of Prim's Algorithm (Part I)

Cuts

Claim: Prim's algorithm outputs a spanning tree.

Definition: A <u>cut</u> of a graph G = (V, E) is a partition of V into 2 non-empty sets.



Quiz on Cuts

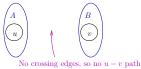
Question: Roughly how many cuts does a graph with *n* vertices have?

- A) n C) 2^n (for each vertex, choose whether in A or in B)
- B) n^2 D) n^n

Empty Cut Lemma

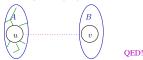
Empty Cut Lemma: A graph is <u>not</u> connected $\iff \exists$ cut (A, B) with <u>no</u> crossing edges.

Proof: (\Leftarrow) Assume the RHS. Pick any $u \in A$ and $v \in B$. Since no edges cross (A, B) there is no u, v path in $G. \Rightarrow G$ not connected.



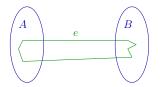
(\Rightarrow) Assume the LHS. Suppose G has no u - v path. Define $A = \{ \text{Vertices reachable from } u \text{ in } G \}$ (u's connected component) $B = \{ \text{All other vertices} \}$ (all other connected components)

Note: No edges cross cut (A, B) (otherwise A would be bigger!)



Two Easy Facts

Double-Crossing Lemma: Suppose the cycle $C \subseteq E$ has an edge crossing the cut (A, B): then so does some other edge of C.



Lonely Cut Corollary: If e is the only edge crossing some cut (A, B), then it is not in any cycle. [If it were in a cycle, some other edge would have to cross the cut!]

Proof of Part I

Claim: Prim's algorithm outputs a spanning tree. [Not claiming MST yet]

Proof: (1) Algorithm maintains invariant that T spans X [straightforward induction - you check]



- (2) Can't get stuck with $X \neq V$ [otherwise the cut (X, V X) must be empty; by Empty Cut Lemma input graph G is disconnected]
- (3) No cycles ever get created in T. Why? Consider any iteration, with current sets X and T. Suppose e gets added. Key point: e is the first edge crossing (X, V X) that gets added

Key point: e is the first edge crossing (X, V - X) that gets added to $T \Rightarrow$ its addition can't create a cycle in T (by Lonely Cut Corollary). QED!



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Correctness of Prim's Algorithm (Part II)

Correctness of Prim's Algorithm

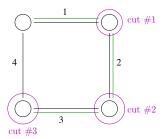
Theorem: Prim's algorithm always outputs a minimum-cost spanning tree.

Key Question: When is it "safe" to include an edge in the tree-so-far?

The Cut Property

CUT PROPERTY: Consider an edge e of G. Suppose there is a cut (A, B) such that e is the cheapest edge of G that crosses it. Then e belongs to the MST of G.

Turns out MST is unique if edge costs are distinct



Cut Property Implies Correctness

Claim: Cut Property \Rightarrow Prim's algorithm is correct.

Proof: By previous video, Prim's algorithm outputs a spanning tree T^* .

Key point: Every edge $e \in T^*$ is explicitly justified by the Cut Property.

- $\Rightarrow T^*$ is a subset of the MST
- \Rightarrow Since T^* is already a spanning tree, it must be the MST

QED!



Minimum Spanning Trees

Algorithms: Design and Analysis, Part II

Proof of the Cut Property

The Cut Property

Assumption: Distinct edge costs.

CUT PROPERTY: Consider an edge e of G. Suppose there is a cut (A, B) such that e is the cheapest edge of G that crosses it. Then e belongs to the MST of G.

Proof Plan

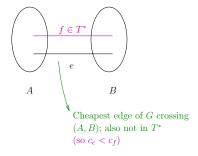
Will argue by contradiction, using an exchange argument. [Compare to scheduling application]

Suppose there is an edge e that is the cheapest one crossing a cut (A, B), yet e is not in the MST T^* .

Idea: Exchange e with another edge in T^* to make it even cheaper (contradiction).

Question: Which edge to exchange e with?

Attempted Exchange



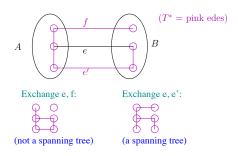
Note: Since T^* is connected, must construct an edge $f(\neq e)$ crossing (A, B).

Idea: Exchange e and f to get a spanning tree cheaper than T^* (contradiction).

Exchanging Edges

Question: Let T^* be a spanning tree of G, $e \notin T^*$, $f \in T^*$. Is $T^* \cup \{e\} - \{f\}$ a spanning tree of G?

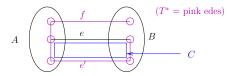
- A) Yes always
- B) No never
- C) If e is the cheapest edge crossing some cut, then yes
- D) Maybe, maybe not (depending on the choice of e and f)



Smart Exchanges

Hope: Can always find suitable edge e' so that exchange yields bona fide spanning tree of G.

How? Let C = cycle created by adding e to T^* .



By the Double-Crossing Lemma: Some other edge e' of C [with $e' \neq e$ and $e' \in T^*$] crosses (A, B).

You check: $T = T^* \cup \{e\} - \{e'\}$ is also a spanning tree.

Since $c_e < c_{e'}$, T cheaper than purported MST T^* , contradiction.



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Fast Implementation of Prim's Algorithm

Running Time of Prim's Algorithm

- Initialize $X = \{s\}$ [$s \in V$ chosen arbitrarily]
- $T = \emptyset$ [invariant: X = vertices spanned by tree-so-far T]
- While $X \neq V$
 - Let e = (u, v) be the cheapest edge of G with $u \in X$, $v \notin X$.
 - Add e to T, add v to X.

Running time of straightforward implementation:

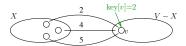
- O(n) iterations [where n = # of vertices]
- O(m) time per iteration [where m = # of edges]
- $\Rightarrow O(mn)$ time

BUT CAN WE DO BETTER?

Prim's Algorithm with Heaps

[Compare to fast implementation of Dijkstra's algorithm] Invariant #1: Elements in heap = vertices of V - X.

Invariant #2: For $v \in V - X$, key[v] = cheapest edge (u, v) with $i \in X$ (or $+\infty$ if no such edges exist).



Check: Can initialize heap with $O(m + n \log n) = O(m \log n)$ preprocessing.

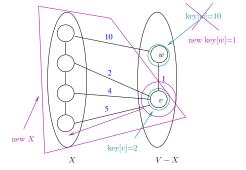
To compare keys n-1 Inserts $m \ge n-1$ since G connected

Note: Given invariants, Extract-Min yields next vertex $v \notin X$ and edge (u, v) crossing (X, V - X) to add to X and T, respectively.

Quiz: Issue with Invariant #2

Question: What is: (i) current value of key[v] (ii) current value of key[w] (iii) value of key[w] after one more iteration of Prim's

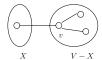
algorithm?



- A) 11, 10, 4 C) 2, 10, 1
- B) 2, 10, 10 D) 2, 10, 2

Maintaining Invariant #2

Issue: Might need to recompute some keys to maintain Invariant #2 after each Extract-Min.



Pseudocode: When v added to X:

- For each edge $(v, w) \in E$:
 - If $w \in V X \to \text{The only whose key might have changed}$ (Update key if needed:)
 - Delete w from heap
 - Recompute $key[w]:=min\{key[w], c_{vw}\}$
 - Re-Insert into heap

Subtle point/exercise:

Think through book-keeping needed to pull this off

Running Time with Heaps

- Dominated by time required for heap operations
- (n-1) Inserts during preprocessing
- (n-1) Extract-Mins (one per iteration of while loop)
- Each edge (v, w) triggers one Delete/Insert combo [When its first endpoint is sucked into X]
- \Rightarrow O(m) heap operations [Recall $m \ge n-1$ since G connected]
- $\Rightarrow O(m \log n)$ time [As fast as sorting!]