

Brain Inspired Computing - Problem Set 1

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Exercise 1

- a) Let $A := F_u + G_w$, $B := F_u G_w - F_w G_u$ and $C := (F_u + G_w)^2 - 4(F_u G_w - F_w G_u)$. Assume $A > 0$. From the eigenvalue equation

$$\begin{aligned}\lambda_{\pm} &= \frac{1}{2}(F_u + G_w \pm \sqrt{(F_u + G_w)^2 - 4(F_u G_w - F_w G_u)}) \\ &= \frac{1}{2}(A \pm \sqrt{A^2 - 4B})\end{aligned}$$

we derive that if $C \geq 0$, $\lambda_+ > 0$ as well. If $C < 0$, λ_{\pm} can be expressed through $\lambda_{\pm} = r \pm i\omega$ with $r = A/2 > 0$. However, any positive λ leads to growth, which means that the model is not stable under these conditions. In the case of $C > 0$, we have a saddle or an unstable situation, depending on whether λ_- is positive or negative; in the case of $C < 0$ we have a growing spiral. Therefore, $A < 0$ must hold true. In the case of $C < 0$, this is enough, as any solution that satisfies $A < 0$ will lead to $\lambda_{\pm} = r \pm i\omega$ with $r < 0$. However, for $C > 0$, we need to make sure that $\lambda_+ < 0$ in any case. To satisfy this condition, $\sqrt{C} < \text{abs}(A) = \sqrt{A^2}$ must hold true. Expansion of C leads to $\sqrt{A^2 - 4B} < \sqrt{A^2}$. From this we can easily see that $F_u G_w - F_w G_u = B > 0$ must hold true.

- b) The fixpoints are $(-\frac{3}{2}, -\frac{3}{8})$ and $(0, \frac{15}{8})$, respectively. For the case of $I = 0$ we can simply calculate the conditions given above. We have

$$\begin{aligned}F_u &= 1 - u^2 \\ F_w &= -1 \\ G_u &= \epsilon * b \\ G_w &= -\epsilon * w\end{aligned}$$

which gives us

$$\begin{aligned}F_u + G_w &= 1 - u^2 - \epsilon * w \\ &= 1 - \frac{9}{4} + 0.1 * \frac{3}{8} \\ &= \frac{8 - 18 + 0.3}{8} \\ &= -\frac{9.7}{8} < 0\end{aligned}$$

and

$$\begin{aligned}F_u * G_w - F_w * G_u &= (1 - u^2) * (-\epsilon * w) - (-1 * \epsilon * b) \\ &= \epsilon(-\frac{5}{8} * \frac{3}{8} + \frac{3}{2}) \\ &= \epsilon(\frac{3}{2} - \frac{15}{64}) > 0\end{aligned}$$

Therefore the fixpoint for $I = 0$ is stable.

The nullcline of w is given through $G = 0 \Leftrightarrow w = a + b * u$. For $I = 15/8$ lets look at a point on the nullcline of w at coordinates $(u_0 + \delta u, a + b * (u_0 + \delta u))$ with $\delta u > 0, \delta u \ll 1$. As $u_0 = 0$, we get

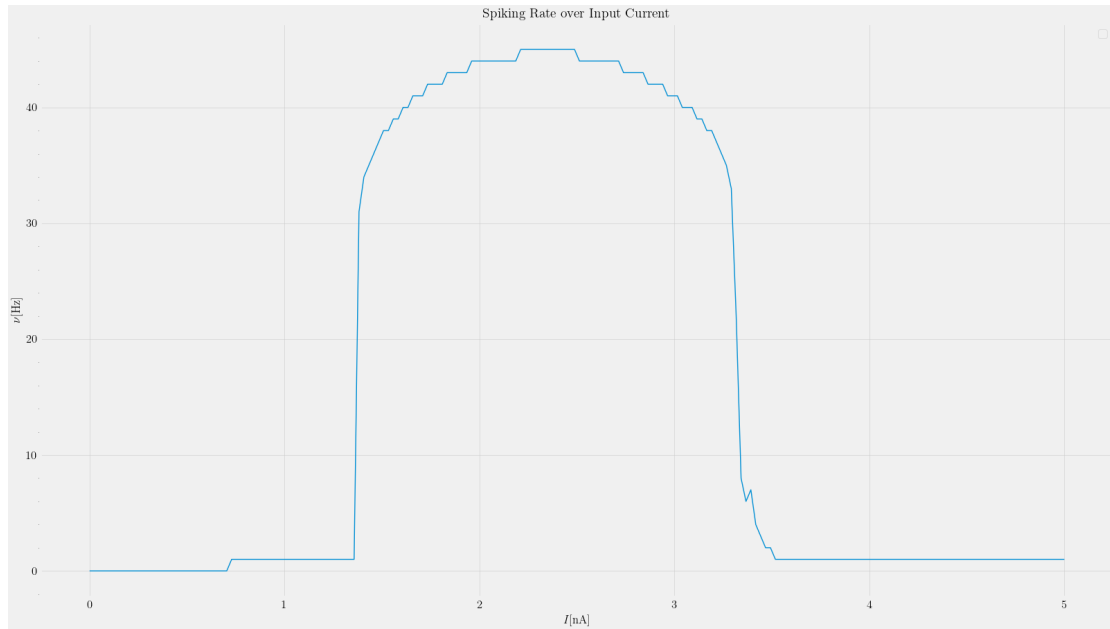
$$F = \delta u - \frac{\delta u^3}{3} - \frac{15}{8} + \delta u * \frac{3}{2} + \frac{15}{8}$$

$$\approx \frac{5}{2} \delta u > 0$$

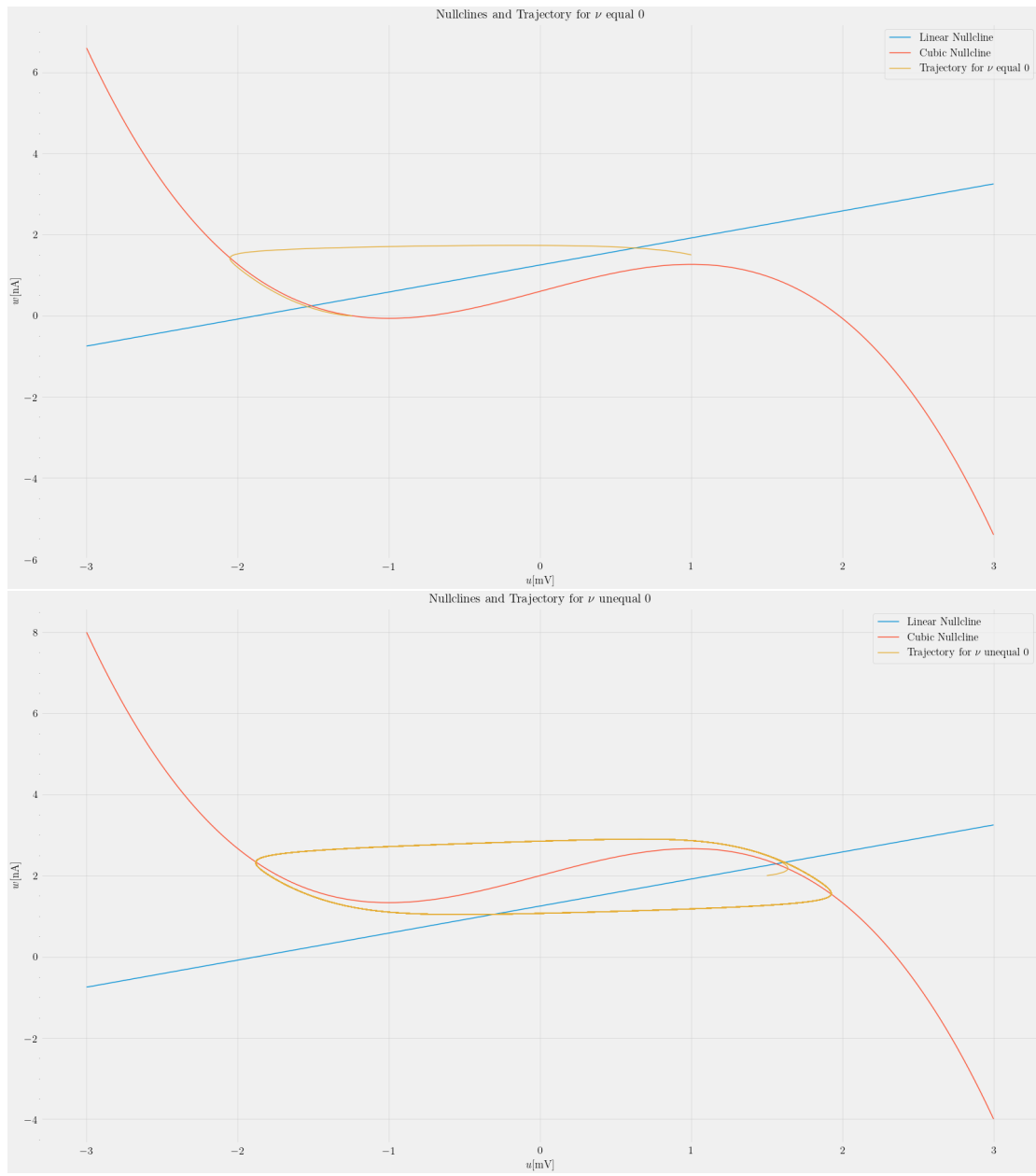
This means that the arrows point away from the fixpoint (at least on the nullcline) and the fixpoint is therefore not stable.

Exercise 3

a)



b)



Code

```
1  #!/usr/bin/env python3
2  # Set-up PGF as the backend for saving a PDF
3  import matplotlib
4  from matplotlib.backends.backend_pgf import FigureCanvasPgf
5  matplotlib.backends.register_backend('pdf', FigureCanvasPgf)
6  import textwrap as tw
7  from math import floor, log10
8  import numpy as np
9  import matplotlib.pyplot as plt
10 import copy
11 from scipy.integrate import odeint as integrate
12
13 #
14 # Settings and functions for the plots.
15 #
16 plt.style.use('fivethirtyeight')
17
18 pgf_with_latex = {
19     "pgf.texsystem": "xelatex",          # Use xetex for processing
20     "text.usetex": True,                 # use LaTeX to write all text
21     "font.family": "serif",              # use serif rather than sans-
22                                         serif
23     "font.serif": "Linux_Libertine",     # use Libertine as the font
24     "font.sans-serif": "Linux_Biolinum", # use Biolinum as the sans-
25                                         serif font
26     "axes.labelsize": 12,
27     "font.size": 12,
28     "legend.fontsize": 12,
29     "axes.titlesize": 14,                # Title size when one figure
30     "xtick.labelsize": 12,
31     "ytick.labelsize": 12,
32     "figure.titlesize": 14,              # Overall figure title
33     "pgf.rcfonts": False,                # Ignore Matplotlibrc
34     "pgf.preamble": [                    # Set-up LaTeX
35         r'\usepackage{fontspec}',
36         r'\setmainfont{Linux_Libertine}',
37         r'\usepackage{unicode-math}',
38         r'\setmathfont{Linux_Libertine}',
39     ]
40 }
41
42 matplotlib.rcParams['grid.color'] = '#cccccc'
43 matplotlib.rcParams['grid.linestyle'] = '-'
44 matplotlib.rcParams['grid.linewidth'] = 0.4
45 matplotlib.rcParams['ytick.minor.visible'] = 'True'
46 matplotlib.rcParams['ytick.minor.right'] = 'True'
47 matplotlib.rcParams['ytick.minor.size'] = '2.0'
48 matplotlib.rcParams['ytick.minor.width'] = '0.6'
49 matplotlib.rcParams.update(pgf_with_latex)
50
51 # Define function for string formatting of scientific notation
52 def sci_notation(num, decimal_digits=1, precision=None, exponent=None)
53     :
54     """
```

```

52     Returns a string representation of the scientific
53     notation of the given number formatted for use with
54     LaTeX or Mathtext, with specified number of significant
55     decimal digits and precision (number of decimal digits
56     to show). The exponent to be used can also be specified
57     explicitly.
58     """
59     if num == 0:
60         return '0'
61     if not exponent:
62         exponent = int(floor(log10(abs(num))))
63     coeff = round(num / float(10**exponent), decimal_digits)
64     if not precision:
65         precision = decimal_digits
66     if coeff - 1 < 10*(-decimal_digits):
67         return r"$10^{\{0:d\}}$".format(exponent)
68
69     return r"${0:.{2}f}\cdot 10^{\{1:d\}}$".format(coeff, exponent,
70         precision)
71
72 # Customize the given axis.
73 def cplot(axis, xlabel=None, ylabel=None, xscale='linear', yscale='
74     linear',
75         title=None, grid=False, tick_style=None, legend=True,
76         xlim=None, ylim=None):
77     axis.set_xlabel(xlabel)
78     axis.set_ylabel(ylabel)
79     axis.set_xscale(xscale)
80     axis.set_yscale(yscale)
81     axis.set_xlim(xlim)
82     axis.set_ylim(ylim)
83     axis.set_title(title)
84     if tick_style=='percent':
85         vals = axis.get_yticks()
86         axis.set_yticklabels(['{:.2%}'.format(x) for x in vals])
87     if tick_style=='sci-not':
88         vals = axis.get_yticks()
89         axis.set_yticklabels([sci-notation(x) for x in vals])
90     axis.grid(grid)
91     if legend:
92         axis.legend()
93
94 #
95 # Euler algorithm from previous exercise.
96 #
97 def euler_step(f, x, t, step_size):
98     dx = step_size * f(x,t)
99     x += dx
100    t += step_size
101    return x, t
102
103 def euler(f, step_size, t_sim, x_0=0, t_0=0):
104     x, t = [x_0], [t_0]
105     while t[-1] < t_sim:
106         x_t, t_t = euler_step(f, copy.deepcopy(x[-1]), copy.deepcopy(
107             t[-1]),
108             step_size)

```

```

106         x.append(x_t)
107         t.append(t_t)
108     return x, t
109
110 #
111 # FitzHugh-Nagumo
112 #
113 def fitzHugh_Nagumo(x, t):
114     epsilon, a, b = 0.1, 15.0/8.0, 3.0/2.0
115     u = x[0] - x[0]**3 / 3 - x[1] + x[2]
116     w = epsilon * (a + b * x[0] - x[1])
117     return np.array([u,w,0])
118
119 def spike_count(x):
120     counts, thresh = 0, 1.0
121     for i, y in enumerate(x):
122         counts += int(y < thresh and x[(i+1)%len(x)] > thresh)
123     return counts
124
125 def lin_nullcline(u):
126     a, b = 15.0/8.0, 3.0/2.0
127     return (u + a)/b
128
129 def cub_nullcline(u, c):
130     return u - u**3/3 + c
131
132
133 def plot_activation_function():
134     fig, axs = plt.subplots(1, 1, constrained_layout=True, figsize
135                             =(16,9))
136     counter = []
137     for i in np.linspace(0.0,4.0,200):
138         c = i
139         counter.append(spike_count(np.transpose(
140             euler(fitzHugh_Nagumo,0.1,1000,[-3.0/2.0,-3.0/8.0,i], 0)
141             [0])[0]))
142     axs.plot(np.linspace(0,5.0,200), counter, lw=1.0)
143     cplot(axs, xlabel=r'$I$ [nA]', ylabel=r'$\nu$ [Hz]',
144           title=r'Spiking_Rate_over_Input_Current', grid=True)
145     fig.savefig('activation-function.png')
146     fig.clf()
147
148 def plot_nullcline_trajectory(u_0, w_0, c, s):
149     fig, axs = plt.subplots(1, 1, constrained_layout=True, figsize
150                             =(16,9))
151     u = np.linspace(-3,3,800)
152     axs.plot(u, lin_nullcline(u), lw=1.0, label=r'Linear_Nullcline')
153     axs.plot(u, cub_nullcline(u, c), lw=1.0, label=r'Cubic_Nullcline')
154
155     x, t = euler(fitzHugh_Nagumo, 0.1, 500, [u_0, w_0, c], 0)
156     u, w, i = np.transpose(x)
157     axs.plot(u,w, lw=1.0, label=r'Trajectory_for_$\nu$'+s+'_0')
158     cplot(axs, xlabel=r'$u$ [mV]', ylabel=r'$w$ [nA]',
159           title=r'Nullclines_and_Trajectory_for_$\nu$'+s+'_0',
160           grid=True)
161     fig.savefig('nullcline-trajectory-'+s+'.png')
162     fig.clf()

```

```
159
160 if __name__=='__main__':
161     plot_activation_function()
162     plot_nullcline_trajectory(1.0, 1.5, 0.6, 'equal')
163     plot_nullcline_trajectory(1.5, 2.0, 2.0, 'unequal')
```