

linear_regression.py

```
001 # Main-Script
002 # #####
003
004 # This python script automatically launches all other python scripts in the
005 # right order and computes the entire task.
006
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011
012 # #####
013
014 # Import of Libraries
015 # -----
016
017 import main as settings
018 # import string as st
019 # import random as r
020 # import re
021 # from turtle import position
022 # from scipy import interpolate
023 # from concurrent.futures import process
024 # from turtle import position
025 import numpy as np
026 import math as m
027 # import sys
028 import os
029 # import matplotlib.pyplot as plt
030 # from scipy.fft import fft, fftfreq
031 # from scipy import signal
032 # import multiprocessing as mp
033 # import copy
034 import lib_trajectory as t
035 from sklearn.neural_network import MLPRegressor
036
037
038 # -----
039 # Debugging-Settings
040
041 verbose = True # Shows more debugging information
042
043
044 # Functions
045 # -----
046
047 def write_text(filename, text):
048     """
049     This function writes text to a file.
050
051     Args:
052         filename (str): Name of the file
053         text (str): Future content of the file.
054     """
055     if(verbose):
056         print(f'[INFO] Writing text to "{filename}"')
057     with open(os.path.join("data", filename), "w") as f:
058         f.write(f'{text}')
059     return(None)
060
061
062 # Classes
063 # -----
064
065
066 # Beginning of the Programm
067 # -----
068
069 if __name__ == '__main__':
070     # Dataset-Information
071     projectnames = settings.project_filenames
072     dataset_length = settings.trajectories_per_project # Number of datasets per project-name
073     trainingset_length = settings.datasets_per_trajectory # Number of training-datasets per trajectory
074
075     # Import of individual trajectories
076     for dataset_index, projectname in enumerate(projectnames):
077         for trajectory_index in range(dataset_length):
078             trajectory_ground_truth =
079             t.lines_import(f'trajectory_{projectname}_{trajectory_index+1:05d}_ground-truth.csv') # Ground
080             truth data for training
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079
080     # Importing Training-datasets
081     trajectories_measured = []
082     for trainingset_index in range(trainingset_length):
083
084         trajectories_measured.append(t.lines_import(f'trajectory_{projectname}_{trajectory_index+1:05d}_t
085             raining_{trainingset_index+1:05d}.csv'))
086
087         # Preparing training-data
088         data_groundtruth = []
089         data_measured = []
090         for trainingset_index in range(trainingset_length-1):
091             for measurement_index, gt_line in enumerate(trajectory_ground_truth):
092                 data_groundtruth.append([gt_line.x1(),
093                                         gt_line.y1(),
094                                         gt_line.x2(),
095                                         gt_line.y2()])
096                 data_measured.append([measurement_index,
097                                     trajectories_measured[trainingset_index]
098                                     [measurement_index].x1(),
099                                     trajectories_measured[trainingset_index]
100                                     [measurement_index].y1(),
101                                     trajectories_measured[trainingset_index]
102                                     [measurement_index].x2(),
103                                     trajectories_measured[trainingset_index]
104                                     [measurement_index].y2(),
105                                     trajectories_measured[trainingset_index]
106                                     [measurement_index].delta_x(),
107                                     trajectories_measured[trainingset_index]
108                                     [measurement_index].delta_y(),
109                                     trajectories_measured[trainingset_index]
110                                     [measurement_index].direction(),
111                                     trajectories_measured[trainingset_index]
112                                     [measurement_index].length()])
113             data_groundtruth = np.array(data_groundtruth)
114             data_measured = np.array(data_measured)
115
116         # Training ML
117         mlpr = MLPRegressor(hidden_layer_sizes=(5, 5), solver='adam', max_iter=50000, verbose=True,
118                             random_state=1, learning_rate="adaptive", tol=1e-10)
119         mlpr.fit(data_measured, data_groundtruth)
120         write_text(f'result_{projectname}_{trajectory_index+1:05d}_ml-model.txt', mlpr.coefs_)
121
122         # Preparing validation-data
123         validation_data = []
124         for measurement_index, line in enumerate(trajectories_measured[-1]):
125             validation_data.append([measurement_index,
126                                   line.x1(),
127                                   line.y1(),
128                                   line.x2(),
129                                   line.y2(),
130                                   line.delta_x(),
131                                   line.delta_y(),
132                                   line.direction(),
133                                   line.length()])
134         validation_data = np.array(validation_data)
135
136         # Validating ML
137         ml_prediction = mlpr.predict(validation_data)
138
139         # Export Prediction
140         predicted_trajectory = []
141         for i, e in enumerate(ml_prediction):
142             predicted_trajectory.append(t.Line(e[0], e[1], e[2], e[3]))
143         t.lines_export(predicted_trajectory, f'result_{projectname}_{trajectory_index+1:05d}_ml-
144             prediction.csv')

```