# ps6\_matlab

November 7, 2018

## 1 Problem Set 6

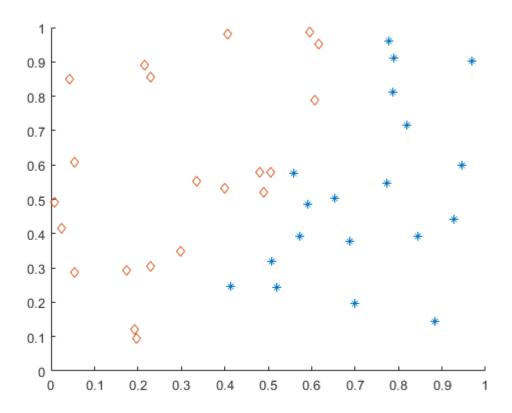
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#### 1.0.1 **Problem 3**

### Input Data:

```
In [1]: rand('seed', 314);
    x = rand(40, 1); y = rand(40, 1);
    class = [ 2*x < y+0.5 ] + 1;
    A1 = [ x(find(class==1)) , y(find(class==1)) ];
    A2 = [ x(find(class==2)) , y(find(class==2)) ];
    figure(1 ); hold on;
    plot(A1(:, 1),A1(:,2), '*', 'MarkerSize', 6 );
    plot(A2(:, 1),A2(:,2), 'd', 'MarkerSize', 6 );</pre>
```



## Call to CVX:

Warning: A non-empty cvx problem already exists in this scope. It is being overwritten.

> In cvxprob (line 28)
 In cvx\_begin (line 41)

Calling SDPT3 4.0: 40 variables, 3 equality constraints For improved efficiency, SDPT3 is solving the dual problem.

num. of constraints = 3
dim. of linear var = 40

```
*************************
  SDPT3: Infeasible path-following algorithms
*************************
version predcorr gam expon scale_data
           1
                 0.000
   NT
                         1
it pstep dstep pinfeas dinfeas gap
                                      prim-obj
                                                   dual-obj
                                                               cputime
0|0.000|0.000|8.2e+01|9.5e+00|4.0e+03|-4.000000e+02
                                                  0.000000e+00| 0:0:00| chol 1 1
1|0.664|0.958|2.7e+01|4.8e-01|1.3e+03|-2.302054e+02 0.000000e+00| 0:0:01| chol 1
2|0.947|1.000|1.5e+00|8.6e-03|5.3e+01|-2.867473e+01
                                                  0.000000e+00| 0:0:01| chol 1
3|0.988|1.000|1.7e-02|8.6e-04|6.4e-01|-3.431845e-01
                                                  0.000000e+00| 0:0:01| chol 1
4|0.989|1.000|1.9e-04|3.6e-03|7.1e-03|-3.794117e-03
                                                  0.000000e+00| 0:0:01| chol 1 1
                                                  0.000000e+00| 0:0:01| chol 1
5|0.989|1.000|2.2e-06|4.7e-05|8.1e-05|-4.272904e-05
6|0.989|1.000|2.4e-08|4.3e-07|8.9e-07|-4.698507e-07
                                                  0.000000e+00| 0:0:01| chol 1 1
                                                  0.000000e+00| 0:0:01| chol 1 1
7|0.972|1.000|6.7e-10|4.8e-09|2.9e-08|-9.053445e-09
8|0.970|1.000|2.0e-11|1.3e-10|9.5e-10|-2.134723e-10 0.000000e+00| 0:0:01|
 stop: max(relative gap, infeasibilities) < 1.49e-08
number of iterations
primal objective value = -2.13472264e-10
       objective value = 0.000000000e+00
gap := trace(XZ)
                      = 9.51e-10
relative gap
                      = 9.51e-10
actual relative gap
                    = -2.13e-10
rel. primal infeas (scaled problem)
                                    = 2.03e-11
rel. dual
                                    = 1.34e-10
rel. primal infeas (unscaled problem) = 0.00e+00
                                    = 0.00e+00
rel. dual
norm(X), norm(y), norm(Z) = 4.9e-11, 5.8e+01, 8.7e+01
norm(A), norm(b), norm(C) = 9.2e+00, 1.0e+00, 7.3e+00
Total CPU time (secs) = 0.99
CPU time per iteration = 0.12
termination code
DIMACS: 2.0e-11 0.0e+00 4.9e-10 0.0e+00 -2.1e-10 9.5e-10
Status: Solved
```

Optimal value (cvx\_optval): +2.13472e-10